
1 **Automated Sea Ice Concentration Analysis History at NCEP**

2 **1996-2012**

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ABSTRACT

4
5 In the years since the first implementation of sea ice concentration analysis, the analysis
6 system has evolved. While the basics remain the same, there have been many changes in
7 details – weather filtering, which instruments are used, how they are used, land masks, and
8 so forth have all changed somewhat or very much. This note documents the evolution of
9 the system from 1996, when the original note was published, until 2012, the date of the last
10 major changes to the system.

List of Acronyms

AMSR-E	Advanced Microwave Scanning Radiometer
BUFR	Binary Universal Form for Representation of Meteorological Data
CAFTI	Committee Assessment of Forecast Technique Improvement
CFS	Climate Forecast System
CFSRR	Climate Forecast System Reanalysis and Reforecast
CIS	Canadian Ice Service
DMSF	Defense Meteorological Satellite Program
EMC	Environmental Modelling Center
EOS	Earth Observing System
ERS	European Remote Sensing Satellite
FNMOCC	Fleet Numerical Meteorology and Oceanography Center
GFS	Global Forecast System (successor to MRF)
GRIB	Gridded Binary – WMO standard for exchange of gridded fields
GTS	Global Telecommunication System
HDF	Hierarchical Data format – EOS standard for exchange of gridded fields
ISLSCP	International Land Surface Climatology Project
MMAB	Marine Modeling and Analysis Branch (successor to OMB)
MRF	Medium Range Forecast (succeeded by GFS)
NARR	North American Reanalysis and Reforecast
NASA	National Aeronautics and Space Administration
NCAR	National Center for Atmospheric Research
NCEP	National Centers for Environmental Prediction
NESDIS	National Environmental Satellite Data Information Service
NIC	National Ice Center
NOAA	National Oceanic and Atmospheric Administration
NSIDC	National Snow and Ice Data Center
NWS	National Weather Service

OI	Optimal Interpolation
OMB	Ocean Modelling Branch
RTG	Real-Time, Global
SDR	Satellite Data Record
12 SMMR	Scanning Multichannel Microwave Radiometer
SSMI	Special Sensor Microwave/ Imager
SSMI-S	Special Sensor Microwave/ Imager - Sounder
SST	Sea Surface Temperature
WMO	World Meteorological Organization

13 **1. Introduction**

14 The original operational automated sea ice analysis system was documented in (Grumbine
 15 1996). Much has changed since then, and this document will describe the current operational
 16 system (as of 19 June 2012) with some reference to changes which occurred in the interim.

17 The automated sea ice analysis is important within the National Centers for Environmen-
 18 tal Prediction (NCEP) because models and other analysis systems require information about
 19 the ice cover in order to do their work. This includes the Global Forecast System (GFS)
 20 (Lord et al. 2007), WAVEWATCH III(tm) wave model (Tolman 1991; Tolman et al. 2002),
 21 Climate Forecast System (CFS) (NCEP/EMC/GCWMB 2011), and sea surface temperature
 22 analysis systems (1 degree OI (Reynolds and Smith 1994), quarter degree OI (Reynolds et al.
 23 2007), RTG low and high resolution (Thiebaux et al. 2003; Gemmill et al. 2007). Further,
 24 much use is made by other groups, including within NESDIS for sea surface temperature
 25 analysis (Reynolds et al. 2002).

26 Given the purpose of NWS, the best possible forecasts, and best possible forecast guid-
 27 ance, algorithms and data sources have been chosen to that end. A consequence is that as
 28 either changes, users more concerned with climate will see some discontinuities, e.g. (Screen
 29 2011).

30 **2. Satellite History**

31 In order to produce an analysis automatically, it is important to use information which
32 is available day or night, as the polar night is 6 months long, and which can be used in the
33 presence of clouds, as the polar regions are often cloudy (Huschke 1969).

34 Visible wavelengths are, therefore, not as desirable as microwave because of both night
35 and cloud concerns. Even infrared is questionable, due to cloud concerns. Though work is
36 in progress to develop algorithms which address this (starting with, e.g., Emery and Fowler
37 in (Cavalieri et al. 1992)). Microwaves, on the other hand, pass readily through clouds and
38 are emitted from the surface regardless of day/night concerns. Instruments which have been
39 available in NCEP operations include the SSMI and AMSR-E. SSMI-S from the DMSP F-
40 16, F-17, and F-18 are now available, but current algorithms in NCEP cannot be applied
41 unmodified to F-16 and F-18 SSMI-S, as their observations are discrepant from F-17's. Work
42 is proceeding to develop and implement the needed modifications.

43 Table 1 provides the listing of satellites which have been available (and their dates), and
44 the dates during which they were actually used in NCEP operations or pre-operations.

45 **3. Satellite Algorithms**

46 *Original Implementation*

47 The original implementation used the NASA Team Algorithm (Cavalieri et al. 1992).
48 This algorithm uses observations from 19 GHz (horizontal and vertical polarization – H and
49 V) and 37 GHz (H and V) to compute the sea ice concentration. Weather filtering (more
50 in next section) is done using 22 GHz V, 37 GHz V, and 19 GHz V. This algorithm was as
51 good as any and better than most when originally implemented operationally in NCEP in
52 1997 (e.g. see analysis by (Andersen 2000)).

53 There was, however, concern about low bias to sea ice concentrations in the Antarctic.

54 Consequently, the NASA Team2 algorithm was developed (Markus and Cavalieri 2000). This
55 had little effect on sea ice extent computations, but sea ice area was increased by several
56 percent over the southern hemisphere ((Screen 2011) for some issues).

57 Table 2 gives the listing of dates for when and which algorithms were in use.

58 *NCEP Modified high resolution algorithm*

59 This algorithm was developed in 2000-2001 in response to requests for higher resolution
60 sea ice analysis. At that time, the instrument in use was the SSMI. The Team 1 concentration
61 algorithm uses information from 19 GHz channels, which have a footprint of approximately
62 50 km radius (Cavalieri et al. 1992). Though data are reported from the instrument every 25
63 km, which was the grid spacing of the analysis (25.4 km), the reality of the 50 km footprint
64 is easily seen in the smoothness of analyzed concentration fields, and in the great distance
65 from shore to which land contamination could be seen. Among other things, this rendered
66 it impossible to analyze ice concentrations over large inland water bodies like Great Slave
67 Lake.

68 Therefore, this modification was to use only information from the highest resolution
69 channels from the SSMI – the 85 GHz channels (V + H polarization), which had a footprint
70 of about 12.7 km. Consequently a new analysis grid, of 12.7 km resolution, was implemented
71 (the August, 2004 implementation), with the modified algorithm.

72 The principles used in developing the modification were that the new version could use
73 only 85 GHz, so as to retain highest possible resolution, and it had to remain very near the
74 analysis given by the reference algorithm (Team 1 to August 2006, Team2 since then, for
75 SSMI use). A number of candidate parameters were tried. The parameter which gave the
76 best results, in linear regression against the reference algorithm, in areas the reference can
77 be expected to be most reliable, was one of the Stokes' parameters for polarized radiation
78 – $\sqrt{T_{85V}^2 - T_{85H}^2}$. Correlations are always in excess of 0.9 with the Team1 reference.
79 Since the higher resolution is seeing more detail, we do not expect perfect correlation.

80 Let H represent the brightness temperature at 85 GHz horizontal polarization, and V be
81 brightness temperature at 85 GHz vertical polarization. Trial functions were:

82 H

83 V

84 V-H

85 V+H

86 V/H

87 V*H

88 V*V

89 H*H

90 V*(V-H)

91 (V-H)/V

92 (V+H)/V

93 (V-H)*(V+H) -> V² - H²

94 sqrt(V² - H²)

95 The points where the reference algorithm is computed, to have a basis to estimate the
96 day's regression parameters for the sea ice cover, are points poleward of 60 degrees, and
97 which are more than 100 km from land (the approximate range of land contamination).

98 Figures 1 and 2 show the Arctic and Antarctic changes in area and extent when changing
99 the AMSRE lookup tables from the operational to planned for operational implementation
100 (pre-launch table vs. latest table [Cavalieri and Markus, personal communication, 2010]).
101 Area is much more sensitive than extent. Area is the area of ice on the ocean. Extent is
102 computed in grid cells – the total area of any grid cell with any ice is added for extent.
103 Extent is therefore always larger than area.

104 Table 2 gives the dates of each algorithm which was used in operations. Some additional
105 dates regarding the operational analysis system are:

106 March 1996 – Approved for operational implementation by CAFTI

107 September 1997 – Original Operational Implementation
108 February 1998 – Used in global atmospheric model
109 September 1999 – Cray fire

110 4. Filtering and Quality Control

111 a. Coarse Quality Control

112 Prior to attempting to use the weather filters for the sea ice concentration algorithm,
113 coarse quality control bounds are applied. These apply to the brightness temperatures
114 themselves, but also the locations and surface flags. Limits are given in Table 3. If any data
115 on a scan (SSMI, AMSR-E) or spot (SSMI-S) are bad, then the entire scan is declared 'bad'
116 and it is ignored. Source code for this is in file process_bufcr.C. Also $H > V$ is considered
117 bad.

118 b. Weather filtering on the grid

119 The traditional weather filter used for the NASA Team and NASA Team2 (Gloersen and
120 Cavalieri 1986) algorithms is overloaded, in the sense that it is used both to indicate areas
121 that do not have sea ice, and areas where it might appear that there is sea ice, but the sensor
122 data have been corrupted by weather.

123 In this weather filter, we aim to separate the two functions. This will lead to 3 out-
124 comes for the filter – 'ocean', 'ice' (thence to compute the ice concentration using the ice
125 concentration algorithm), and 'weather'. 'weather' will now mean solely that the brightness
126 temperatures might be resulting from active weather systems. Separate from that, there
127 will be a flag for ocean directly from the filter. This is useful in the automated sea ice
128 concentration processing because 'weather' is considered a non-observation. After a suffi-
129 ciently long period of no observations, concentrations are set to zero (Grumbine 1996). With

130 changes from a strictly SSMI-based ice concentration system to one including the somewhat
131 different AMSR-E channels and filters, areas of sea ice are now being flagged as 'weather'
132 for extended periods – long enough to run in to this processing limit. With a flag devoted to
133 setting concentrations to zero when and where we are confident that they are, in fact, zero,
134 the age-based processing can be examined on its own and, hopefully, be tuned to methods
135 more appropriate to the newer instrument.

136 There are a number of candidate functions to test – critical temperature type functions
137 ($T > T_{crit}$, or $T < T_{crit}$), polarization ratio $(T_v - T_h)/(T_v + T_h)$, and gradient ratio $(T_{i-}$
138 $T_{-j})/(T_{i+} + T_{-j})$. The NASA Team and Team2 weather filter (Gloersen and Cavalieri 1986)
139 uses 0.045 as the limit for gradient ratio of 22 V to 19 V, and 0.05 for GR37LIM. For the
140 exhaustive search, I take the observed range of each function, split that in to 256 steps, and
141 evaluate the performance of each step.

142 There are three competing criteria for a good filter. It should never flag an observation
143 as ocean unless it truly is not ice (flagging 'ocean' over a land point is acceptable) (high
144 probability of detection, with low false alarm rate). It should only flag 'ice' over points
145 that truly are ice (again, high probability of detection with low false alarm rate). And it
146 should seldom flag points as weather (straight frequency should be low). This is, therefore,
147 a problem of multiobjective optimization (see discussion in, for example, (Eiben and Smith
148 2003)).

149 The resultant filter is:

```
150 If both water and ice filter are triggered: Weather Flag
151     else:
152 Water Flag: if (T19V - T19H) / (T19V + T19H) > -0.055 -> water
153     Ice Flag: if (T19V - T87V) / (T19V + T87V) > +0.2412 -> ice
154
155 If Ice Flag: compute sea ice concentration
```

156 *c. A Posteriori filtering*

157 It is common for sea surface temperature analyses (e.g. (Reynolds and Smith 1994;
158 Reynolds et al. 2007; Thiebaux et al. 2003; Gemmill et al. 2007)) to use sea ice concentration
159 in their procedures. It is also common (Grumbine 1996; Fetterer et al. 2002, updated 2009;
160 editor) for sea ice concentration analyses to use sea surface temperature. This presents
161 a possibility for an 'incestuous' feedback, wherein a too-cold SST permits a point which
162 the weather filter failed to remove to become analyzed as ice. Then, since the ice analysis
163 identifies a point as ice, the next SST analysis uses that 'observation' to retain or cool even
164 further the water point. Such a feedback seldom occurs in practice, but it did do so in the
165 high resolution RTG analysis in summer of 2007 [R. Grumbine, personal observation].

166 To reduce the possibilities for this feedback, an *A Posteriori* filter was developed (Grumbine
167 2009) and started in use for the CFSRR (Saha et al. 2010) and operational implementation
168 in October, 2011. This is still based on SST, but on climatological SST – any point which
169 has never been observed (in the (Reynolds et al. 2007), from 1984-2009) to be warmer than
170 the critical temperature (275.3) is always masked out of the sea ice analysis. This does leave
171 the possibility for the feedback, but experience shows that the weather filter is most effective
172 in the colder near-ice ocean than farther away. The area that did experience the feedback
173 in 2007 was the east coast of Japan.

174 *d. SST filtering*

175 Finally, the ice analysis is filtered against the current SST analysis. Water warmer than
176 275.3 K is deemed incapable of having an ice cover, as was the case in (Grumbine 1996). The
177 source, however, of the SST has changed through time. The original SST (1994-26 August
178 2004) was the daily 1 degree OI (Reynolds and Smith 1994). This was changed to the low
179 resolution (half degree) Real Time Global (RTG) SST (Thiebaux et al. 2003), through 10
180 August 2006. And the high resolution RTG (1/12th degree) SST (Gemmill et al. 2007) 11

181 August 2006 to present.

182 With the new (2010) *A Posteriori* filtering, the SST filter mainly affects only inland
183 water bodies that are not analyzed in OIv2 (Reynolds et al. 2007).

184 5. Gridding

185 a. *Earth Mapping*

186 The high resolution grid is 12.7 km on the polar stereographic "analyst's" grid, originally
187 25.4 km. The earth's equatorial radius is 6378.160 km, and its $eccen^2 = 0.006694604$. True
188 at 60 N or S. Latitudes and longitudes are computed by (Troisi 1994), and represent the
189 center of grid cells.

190 The high resolution latitude-longitude "modeller's" grid is 5 arcminutes, the low resolu-
191 tion grid is 30 arcminutes.

192 b. *Land Masking*

193 The land masks themselves were originally derived from a NESDIS land mask at 1/16th
194 degree (approximately 7 km) resolution (Grumbine 1996). This was good resolution for the
195 30' latitude-longitude files, and reasonable for the 25.4 km polar stereographic grids. It is
196 not as well-suited to the higher resolution files at 12.7 km polar stereographic and 5' (1/12th
197 degree) latitude-longitude. For this reason in the high resolution implementation of 2004,
198 though the land mask was initially derived from this data set as before, points which were
199 not entirely land-flagged (that is, not all the NESDIS points which would map into the given
200 grid cell were land) were left water for later analysis. The later analysis was to examine those
201 points which were near the land-flagged points, and which retained an 'ice cover' through
202 July-August in the northern hemisphere (away from places, like Hudson Bay, which might
203 have real ice covers in part of that time). Since land betrays a sea ice signature, and we

204 know that there's no sea ice in, say, the Aral Sea during August, this permits a more suitable
205 land mask to be developed even without having higher resolution data sources to draw from.
206 It also permitted us, as was known to be needed for the Aral Sea, to produce a land mask
207 which is appropriate to the current boundaries of lakes and coasts when lakes dry up or
208 ice shelves calve ice bergs (such as B-9 (Keys et al. 1990)) which are larger than the grid
209 resolution.

210 The drawback is that the NESDIS land mask itself erred on the side of flagging points
211 as land, and this process will tend to err even farther in that direction due to the footprint
212 (12.7 km) of the sensor used. Consequently, many lakes which are, in principle, large enough
213 to be resolved by the grid were left flagged as land. Nevertheless values in the lakes, such as
214 Baikal, Great Bear, Great Slave, which were considered resolvable could be used with much
215 more confidence.

216 For the current land masks, implemented operationally in August, 2008, two different
217 high resolution data sources were examined. One is a 0.5' land mask from (Hansen et al.
218 2000). The other is a coastline data file with spacings as fine as 200 m (Wessel and Smith
219 1996). With data sources this fine, the sea ice grids are coarse, and it is relatively easy to
220 decide mask values. For this generation of land masks, the basic (previously the only) land
221 mask is aimed at greatest geographic faithfulness, with no allowances for satellite sensors
222 and their foibles. The 5' and 12.7 km land masks are derived from the 0.5' land mask in
223 the same algorithm as from the original 3.75'. They are derived from the coastline files by
224 examining, grid point by grid point, whether the bounding polygon passes through the grid
225 cell (leading to a 'coast' flag), or the point is inside or outside the bounding curve (land flag
226 if inside a land polygon, etc.). Coast points are then resolved to land or water depending on
227 bathymetry/topography, and bathymetry/topography files are generated as well. For more
228 detail on this aspect, see (Grumbine 2012).

229 The land masks generated from those two data sets are quite similar, as would be hoped.
230 They do differ, though. The largest differences are in the ice shelf regions of Antarctica,

231 where the 0.5' mask (Hansen et al. 2000) leaves these points as water, while the coastline
232 files (Wessel and Smith 1996) consider them as land. For the purpose of performing ocean
233 surface analysis and modelling, ice shelves are more reasonably considered to be land so we
234 follow the coastline file. In the northern hemisphere, the differences are small. As I will
235 be using the shoreline curves in conducting my analysis procedures (sections Gridding Ice
236 Concentrations, and Inland Water Bodies), I use the land mask derived from them in the
237 northern hemisphere, too.

238 Both sources (Hansen et al. 2000; Wessel and Smith 1996) consider the Aral Sea to have
239 its mid-20th century size, which leaves a less than ideal grid.

240 Since the global analysis product is derived from the polar stereographic hemispheric
241 analyses, one further step is made. It was realized in developing sea ice cover for the North
242 American Regional Reanalysis (Mesinger et al. 2006) that there could be points on the target
243 grid which could not be filled directly from source information grids. This does not happen
244 with the current 5' and 12.7 km grids. But it is a point which must be verified with each
245 future update to the masks.

246 *c. Filling the Grids*

247 Each observation from the satellite is mapped against the polar stereographic grid and
248 added in a 'drop in the bucket' sense, as in (Grumbine 1996). The sea ice concentration (or
249 weather flag, as the case may be) is added to, and only to, the grid cell which is closest to
250 the observation's location. If there are multiple valid observations, the concentration is the
251 average of them. But if more than 1/3rd of the observations in a grid cell are 'weather', it
252 is flagged 'weather'.

253 The global grid is filled from the polar stereographic, again in drop in the bucket sense.
254 Each grid point in the polar stereographic is added to the nearest global grid point. There
255 are no points on the global grid which do not receive information from at least 1 grid point
256 on the polar stereographic grid. If multiple polar stereographic grid cells contribute to a

257 global grid, the concentrations (valid ice concentrations only) are averaged.

258 **6. Reanalysis Fields**

259 Sea ice concentrations have been an important part of reanalysis efforts, including the
260 NCEP/NCAR Reanalysis (Kalnay et al. 1996), the North American Regional Reanalysis
261 (Mesinger et al. 2006), and the Climate Forecast System Reanalysis and Reforecast (Saha
262 et al. 2010). Each of these reanalyses has made use to some degree of the then-operational
263 approach to sea ice concentration analysis. A separate document will discuss each of these
264 in detail. Also see (Sellers et al. 1996) for the ISLSCP-I ice, mentioned in (Grumbine 1996).

265 A fundamental question in constructing any reanalysis sea ice cover is whether it is more
266 important to provide greatest stability in the ice treatment, or to provide the best estimates
267 possible at the time of the reanalysis, and for the dates of reanalysis. In these three, the
268 emphasis was placed on best possible fields, which does introduce some artefacts in the time
269 series such as sudden increase in Antarctic sea ice area (though not extent) when the Team2
270 algorithm was implemented (Screen 2011).

271 **7. Distribution**

272 The low resolution grids, both polar stereographic and latitude-longitude, are distributed
273 via GTS as KWBM OEXA88, OENA88, and OESA88 for global latitude-longitude, northern
274 hemisphere, and southern hemisphere, respectively.

275 Nonoperational web and ftp distribution has been available since October 1995, at <http://polar.ncep.noaa.gov/seaice/Analyses.html> (original name polar.wwb.noaa.gov). An-
276 imations of the most recent 30 days were added to the web site in December 1999. A
277 climatological reference was included July 2002 based on (Chapman and Walsh 1991) at
278 <http://polar.ncep.noaa.gov/seaice/Historical.html> along with saved monthly ani-
279

280 mations. A newer climatology, based on the CFSRR sea ice, is in preparation.

281 Operational ftp distribution of the current day's analysis is available at
282 `ftp://ftpprd.ncep.noaa.gov/pub/data/nccf/com/omb/prod/sice.YYYYMMDD`
283 where YYYYMMDD is the 8 digit year, month, day group.

284 There is currently no official NOAA archival site for these analyses. They are available
285 non-operationally at `ftp://polar.ncep.noaa.gov/cdas/archive` for the global grids, and
286 `ftp://polar.ncep.noaa.gov/ice/archive` for the hemispheric grids. These extend back
287 to the October, 1995 inauguration of the web site, but with some gaps due to its non-
288 operational status. The files are of the data as processed on that day, so there are the
289 discontinuities in content.

290 ISLSCP 1 sea ice fields are at `ftp://polar.ncep.noaa.gov/history/islscp1`

291 Reanalysis 1 sea ice fields are at
292 `ftp://polar.ncep.noaa.gov/history/ice/reanl.ice/`

293 NARR sea ice fields are at `ftp://polar.ncep.noaa.gov/history/ice/narr/`

294 CFSRR sea ice fields are at `ftp://polar.ncep.noaa.gov/history/ice/cfsrr/`

295 Each has greatest continuity of method up to the date of original implementation, and
296 follows what was operational (`ftp://polar.ncep.noaa.gov/cdas/`) thereafter. More detail
297 on reanalysis sea ice concentrations will follow in individual technical notes.

298 8. Conclusions

299 Maintaining and improving a sea ice concentration analysis system requires regular up-
300 dates to the system as satellites age, improved algorithms are developed, new satellites come
301 on line, and user needs expand. This document describes the moving target that has been
302 the operational sea ice concentration analysis system at NCEP for the past 16 years of its
303 operations. Further modifications will occur now that SSMI-S is being used, and AMSR-2
304 will soon be providing data. The next document will not be 16 years in the making!

305 While we are primarily concerned with sea ice concentrations for use on weather time
306 scales, whether by atmospheric, oceanic, or ice models, the multiple experiences at developing
307 ice fields for use in weather and climate reanalyses have pointed to a number of features useful
308 to even the weather analysis system. This includes the a posteriori ice filter, and obtaining
309 ice concentrations at points outside the analysis grid by correlation to points inside the grid,
310 or concentrations in areas which are unobserved for extended periods by such correlation.

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APPENDIX A

390

391

Source Code Evolution

392

a. Programs Involved

393

394 The job which controls the analysis is formerly J990, then named
395 JMRF_ICEDRFT2.sms.prod, and, with the 19 June 2012 implementation,
396 JSEAICE_CONCENTRATION_ANALYSIS. This then invokes script ex990
397 (then exmrf_icedrft2.sh.sms, now exseaice_concentration_analysis.sh.sms).

398 External to the sea ice processing itself are the bufrlib (NCEP 2012) and dumpjb (Woolen
399 2012), which are used to extract data from the NCEP operational BUFR tanks. 24 hours of
400 data centered on 00 UTC are requested, the analysis being for 00 UTC of the given day, and
401 a daily average. The run time of the program is 11:30 UTC, which means data are biased
402 slightly earlier than the nominal 00 UTC center.

403 The first program of the automated processing proper is seaice_ssmibufr, which extracts
404 data from the full bufr tank form and format and rewrites it to something more convenient
405 to the sea ice processing. Each instrument type has a corresponding program of this type
406 – seaice_amsrbufr, seaice_ssmisbufr. The original amsr decoder only used locations from
407 the low frequency channels. Loss of the instrument’s data in October 2011 prevented an
408 implementation using the high resolution channels’ individual locations. Original ssmibufr
409 only used low resolution channels’ locations. The 2004 implementation used high resolution
410 locations, repeating the low resolution channel information for each high resolution location.

411 Program seaice_seaissmi then constructs the high resolution sea ice analysis grids, north-
412 ern and southern hemispheres, for a given satellite (now, originally only for F-13, then for
413 all ssmi data it was given). This permits the option of producing separate grids for each
414 satellite and then combining or assimilating them.

415 If more than one instrument type is available, this pairing of `debufr/analyze` is and will
416 be repeated for each of them. Hence there was `seaice_amsbufr` and `seaice_seaiamsr`, and will
417 be `seaice_ssmisbufr` and `seaice_seaissmis`.

418 Next, the analyst grids from each instrument type are blended together in program
419 `seaice_blend`. The current approach is to treat all sources as equal, and use arithmetic
420 averages when more than one instrument is available, and use the one instrument's output
421 if only one is available. Since the 16 June 2012 implementation, 3 instruments are used –
422 (F-15, AMSR-E, F-17 – even though AMSR-E is not providing data, its grid of 'no data' is
423 ingested. In the future, AMSR2 will provide data, and this space will then be used.)

424 A preliminary coarse filter is applied to these grids to prevent areas from being falsely
425 treated as sea ice. This is program `seaice_posteriori`, which uses a climatologically-based
426 grid of coldest ever-observed temperatures to filter out points which have not been observed
427 to be colder than 275.3 K (the cutoff used in `seaice_filtanal` below). Full description is in
428 (Grumbine 2009).

429 To preserve the original 25.4 km output, which is also sent over GTS – unlike the
430 12.7 km output – these higher resolution grids are downscaled by program `seaice_reduce`
431 (`seaice_north_reduce` and `seaice_south_reduce`, but the source code is identical – grid se-
432 lection is a compile-time option). The downscaling algorithm is to average all valid ice
433 concentrations in the 4 cells of the 12.7 km grid on to the corresponding cell of the 25.4 km
434 grid. Since even 1 water point on the 12.7 km grid will give a concentration on the 25.4, this
435 produces significantly more extensive lakes and bays on the 25.4 km grid than geography
436 would expect. Its virtue and reason is that if a downstream user has a somewhat different
437 land mask at 25 km than is derived in NCEP, they will still (probably) have a valid ice
438 concentration. The first modification was to put land flags directly in the output for points
439 which have no valid high resolution concentration. Land flags have also been put in the half
440 degree sea ice concentration analysis since 27 August 2004.

441 For quality control purposes, `seaice_toxpm` is also run on the data, to produce `xpm`

442 graphic files which are then converted to png or gif and placed on web service. (Again,
443 separate executables for each area and resolution, but only 1 source.) When seaice.reduce
444 started putting land flags on unfillable points, for the polar stereographic grids this also
445 meant unfillable because of having no data. For graphic consistency, seaice.toxpm was then
446 modified to show 'no data' on points that could not be filled and were not land in the land
447 mask file. The original color bar was an ugly scientist-derived bar. National Geographic
448 [personal communication, 1996] provided the bar that has been used since 1996. (See Nat
449 Geo May, 1996 for illustration.)

450 The binary output is converted to grib and GTS formatted files produced in seaice_psg.
451 (Mnemonic being polar stereographic grid.)

452 System utilities cnvgrib and wgrib2 were used until 16 June 2012 to construct grib2 out-
453 put from native grib1 output of seaice_psg. Program seaice_grib2 generates grib2 files for
454 all resolutions and projections. Input files seaice_pds and gds.(grid) provide the grid speci-
455 fication information to grib2. The original program was provided by Vera Gerald [personal
456 communication, 2011].

457 This concludes construction of the polar stereographic grids, which are oriented to 'sea
458 ice analysts' – people who understand the nature of the data, can accept data gaps (due
459 to no clear observation, or simply that the orbital passes did not cover an area), and can
460 accept false positives for ice. (The algorithm is not perfect, nor is the weather filtering in
461 the seaice_seaissmi program, so some points which are certainly not sea ice are nevertheless
462 called ice in these grids.)

463 For users who need complete coverage each day, and cannot afford those false ice points,
464 such as weather, wave, and ocean modellers, a global latitude-longitude grid at 5' resolution
465 is constructed. And from that, a 30' grid.

466 The most recent high resolution real-time global sea surface temperature analysis (Gem-
467 mill et al. 2007) is used for the filtering, with a critical temperature of 275.3 K. If the sst
468 analysis is warmer than this, ice is removed from the ice analysis. Program seaice_filtanal

469 applies this filter, and performs interpolation from the hemispheric polar stereographic an-
470 alyst's grids on to the global latitude-longitude grid. A version in the late 1990s had an
471 error, which was retained in a non-operational parallel run for the Hadley Center [Rayner,
472 personal communication 1999] as they'd developed a regression that corrected the error for
473 their climate interests.

474 Grid-filling is performed by `seaice_icegrid`, which replaces any data gaps in the above
475 global field with the previous day's analyzed values. In doing this, an age field is incremented
476 for every grid point which was persisted. If the age passes 16 days, the concentration is set
477 to zero. When instruments are performing moderately well, and data flow is not interrupted
478 for prolonged periods (both of which were false in May, 2009) this age is seldom reached.
479 The age limit was introduced in the 1990s because of some portions of the Antarctic which
480 are persistently cold (hence SST filtering would not remove false ice), and have persistently
481 heavy weather (hence false reports of ice occasionally being accepted in spite of the weather
482 filtering). Since the action of the original weather filter is to declare points 'weather', rather
483 than no ice, one day with a false observation could be persisted almost indefinitely through
484 days of no data, or of weather flags. This will be reconsidered for future implementations,
485 given the new weather filtering algorithm.

486 The 30' grid is produced from the 5' grid by `seaice_global_reduce`, by the same algorithm
487 as used in `seaice_north_reduce` et al.. Given the much larger ratio in resolutions, lakes are
488 much more extensive on the 30' grid than would be geographically faithful.

489 `seaice_global5minxpm` and `seaice_globalxpm` produce global graphic files as is done for
490 the polar stereographic grids.

491 `seaice_ice2grib` produces the grib1 output of the 30' grid. Since the August 2004 im-
492 plementation land has been flagged as such (1.57) in the 30' grib file. `seaice_ice2grib5min`
493 produces grib1 output of the 5' grid.

494 The 7 October 2011 implementation added some more extensive quality control diagnos-
495 tics than merely a graphic of the analysis:

496 seaice_monitor_c12th analyzes the 5' global grid for day to day changes in concentration
497 (output as pushpins for changes over 20% in seaice_monitor_\$PDY.kml), where PDY is the
498 analysis date in YYYYMMDD numerical format, and bulk statistics for yesterday versus
499 today's area and extent, variance in concentrations one day to the next, and the change in
500 global sea ice area from day to day, output to seaice_monitor.t00z.txt. Derived from old del,
501 delta, diff programs by way of 'all', then from ice_compare.

502 seaice_edge produces a very crude estimate of the northern hemisphere ice edge location.
503 It scans the global grid at each longitude, from the pole towards the equator. The 'edge' is
504 the latitude of the grid point where the concentration changes from nonzero (previously) to
505 zero (in the given cell).

506 Web Support

507 grid8 – program to print out xpm files for argument-specified domains. Originated for
508 interactive web service, but is general purpose.

509 *Include Files*

510 *ssmi.h*

511 include file that was intended to be general to the instrument, but, over time, incorporated
512 ice-specific things. Eventually SDR-related code was removed.

513 In place by early 1994, Oldest version 22 September 1995

514 Change 6 March 1997 to using a variable number of orbits

515 Add BUFR-related functions and types 27 May 1997

516 Start Remove SDR-related functions and types 18 November 1998

517 Complete the removal, and add HIRES flag 11 October 2001

518 *ssmiclass.h*

519 noodling on a class for managing observations

520 Begun by 20 November 1998 – develop a C++ class library for working with SSMI

521 Two version now – *ssmiclass.operations.h*, which has many operations, but little data,
522 and *ssmiclass.h*, which has a working set of data declarations but few operations. The
523 latter is operational.

524 *icegrids.h*

525 declarations of grids.

526 *icessmi.h*

527 include file for seaice-specific things (vs. *ssmi.h*, which is supposed to be general about
528 the SSMI instrument/DMSP platform). It includes mapping, function declaration for
529 nasa team, weather filter limits, and prototypes for ice avg, ice_add, ice_zero, getfld,
530 newfilt, pole_fill.

531 Defines data window, minconc, nodata, weather, bad_data, coast, land.

532 Define the elements for getfld

533 typedef for *ssmi*, *ssmi_tmp*

534 In place by early 1994, oldest version on hand 22 September 1995

535 Weather flag added 20 Feb 1996 – zeroing concentrations on weather caused erroneous
536 'no ice' conditions inside the Antarctic ice pack, especially, during the melt season.

537 Regression for antenna corrections, if needed, added 1 October 1996

538 Bufr versions added 27 May 1997

539 Record data counts 18 November 1998

540 pole_fill generalized 20 November 1998
541 ice_mask added + experiments/updates to pole_fill 29 December 1999
542 10 October 2001 Add hiresconc, oldssmi vs. smmi typedef polefill generalized to be
543 pole-insensitive (arguments)

544 *icessmi85.h*

545 Class used in developing original high resolution sea ice concentration approach.

546 Not used in operations.

547 Had Team1 algorithm embedded.

548 used by:

549 *all.C* – global processing on all candidates

550 *north.C* – northern hemisphere processing on all candidates

551 *south.C* – southern hemisphere

552 *toprocess1.C* – translate from BUFR to a processing format

553 *print85.c* – print out high resolution fields

554 *global.C* – global processing

555 *north.leastsq.C* – interactive version of code for testing

556 *glob.sh* – set up graphics for the hires tests

557 *daily.sh* – run each parameter type (above codes) daily

558 *Control Scripts + Data Files*

559 SSMI Team 2 algorithm files

560 8 -r--r----- 1 rmg3 wd2 518 Sep 23 2005 seaice_TBthark.tab
561 8 -r--r----- 1 rmg3 wd2 518 Sep 23 2005 seaice_TBowark.tab
562 8 -r--r----- 1 rmg3 wd2 518 Sep 23 2005 seaice_TBowant.tab
563 8 -r--r----- 1 rmg3 wd2 518 Sep 23 2005 seaice_TBfyark.tab
564 8 -r--r----- 1 rmg3 wd2 518 Sep 23 2005 seaice_TBfyant.tab
565 8 -r--r----- 1 rmg3 wd2 518 Sep 23 2005 seaice_TBccark.tab
566 8 -r--r----- 1 rmg3 wd2 518 Sep 23 2005 seaice_TBccant.tab

567 AMSR-E Team2 algorithm files

568 8 -r--r----- 1 rmg3 wd2 576 Aug 11 2010 seaice_TBccark.tab.amsr
569 8 -r--r----- 1 rmg3 wd2 744 Aug 11 2010 seaice_TBccant.tab.amsr
570 8 -r--r----- 1 rmg3 wd2 744 Aug 11 2010 seaice_TBfyark.tab.amsr
571 8 -r--r----- 1 rmg3 wd2 744 Aug 11 2010 seaice_TBfyant.tab.amsr
572 8 -r--r----- 1 rmg3 wd2 599 Aug 11 2010 seaice_TBowark.tab.amsr
573 8 -r--r----- 1 rmg3 wd2 599 Aug 11 2010 seaice_TBowant.tab.amsr
574 8 -r--r----- 1 rmg3 wd2 587 Aug 11 2010 seaice_TBthark.tab.amsr
575 8 -r--r----- 1 rmg3 wd2 587 Aug 11 2010 seaice_TBthant.tab.amsr

576 *Control Scripts*

577 *f13.jcl*

578 date management

579 get satellite data

580 decode from satellite format

581 make ice concentration grids – analyst grids

582 filter them and make modeller grids

606 385, 465 24.02 60.33

607

608 Southern hemisphere

609 1, 1 -36.90 -220.19

610 1, 355 -37.80 -120.76

611 345, 1 -31.09 -307.14

612 345, 355 -31.85 -31.88

613

APPENDIX B

614

615

Additional Comments

616 B-1 Prehistory: Original (1994) implementations had radius of the earth as 6738,
617 rather than 6378 km. Error found and fixed 13 September 1995.

618 B-2 Observation: The derived sea ice concentration is nearly the same whether one
619 computes the ice concentration for each brightness temperature observation set
620 in a cell and then averages those figures, or first averages the brightness temper-
621 atures and then computes a concentration from those.

622 B-3 Observation: The scaling of concentration is originally 0-100 (i.e. percentage
623 cover in the cell) but was changed to 0-1 (fraction of area covered) to accord
624 with grib standards. Archival users must currently beware of this.

625 B-4 Observation: The cumulative distribution of extent versus concentration, shown
626 in figure 3, is highly nonuniform. Only 10% of the extent has concentration less
627 than 50%, while 50% of the extent is in concentrations greater than 90%, using
628 the CFSRR sea ice

629 B-5 Applying the high resolution method to 37GHz gave better results than 85GHz
630 does. As it is only 25 km resolution itself, this was insufficient improvement for
631 the purpose at hand.

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TABLE 1. Availability and NCEP usage dates of satellites

Platform	Data Start	Data Cease	Used
SMMR	26 October 1978	20 August 1987	not used
SSMI F-8	9 July 1987	31 December 1991	not used
SSMI F-11	3 December 1991	30 September 1995	2/1994 - 5/1995 (pre-operational)
SSMI F-13	3 May 1995	19 November 2009	5/1995 - 11/2009
SSMI F-14		24 August 2008	8/2004 - 8/2008
SSMI F-15	15 March 2000	present	8/2004 - 5 March 2009 7 October 2011 - present
AMSR-E NASA-Aqua	19 June 2002	4 October 2011	13 May 2009 - 3 October 2011
SSMI-S F-16	not at NSIDC		not yet used
SSMI-S F-17	1 January 2007	present	19 June 2012 - present
SSMI-S F-18	not at NSIDC		not yet used
AMSR2 GCOM-W	May 2012 (launch)		not yet used

TABLE 2. Algorithms and their usage dates

Team 1 SSMI unmodified	to 8/2004
Team 1 SSMI w. NCEP modifications	to 8/2006
Team 2 SSMI w. NCEP modifications	all SSMI since (8/2006-9/2009, 10/2011-present)
Team 2 AMSRE	all AMSRE observations – 5/2009 to 10/2011
Team 1 SSMI-S	7/2012-present

TABLE 3. Quality control limits on brightness temperatures

SSMI	SSMI-S		AMSR-E		
19h	295	75	19h	305	75
19v	295	150	19v	295	150
			24h	285	100
22v	295	150	24v	285	150
37h	295	100	37h	285	100
37v	295	150	37v	285	150
85h	295	125	89h	285	135
85v	295	150	89v	285	135

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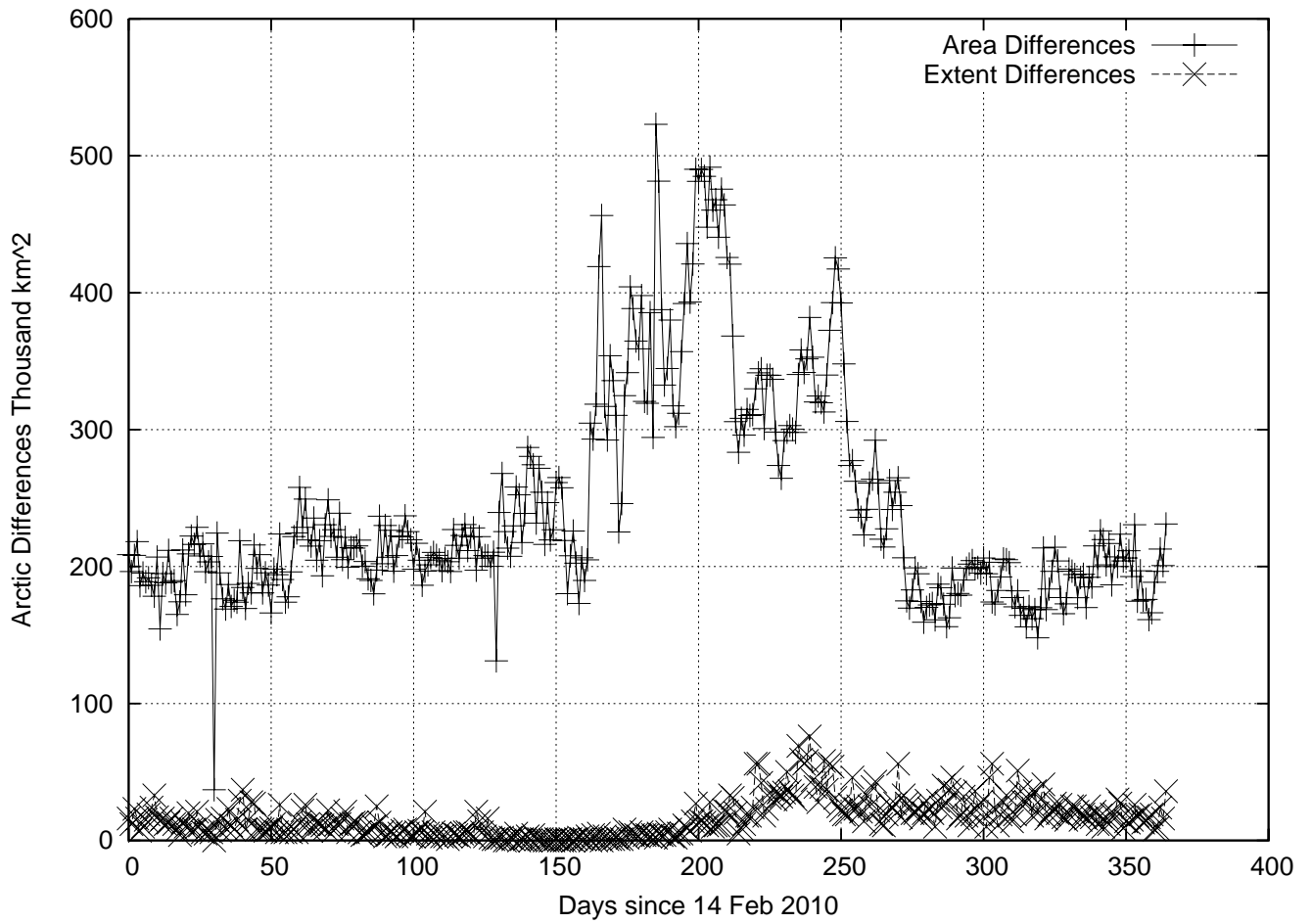


FIG. 1. Changes to Arctic Area and Extent from change to lookup table

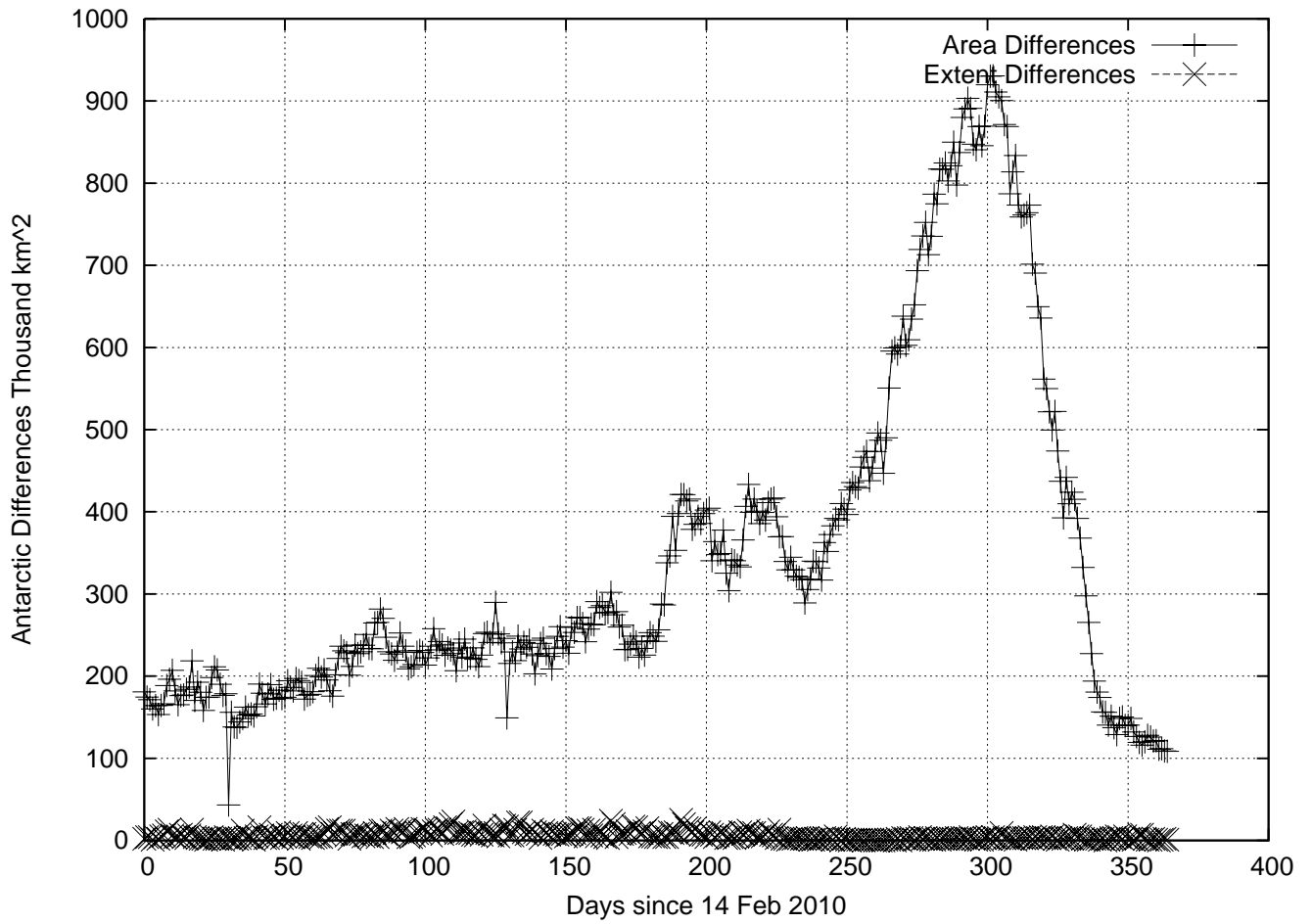


FIG. 2. Changes to Antarctic Area and Extent from change to lookup table

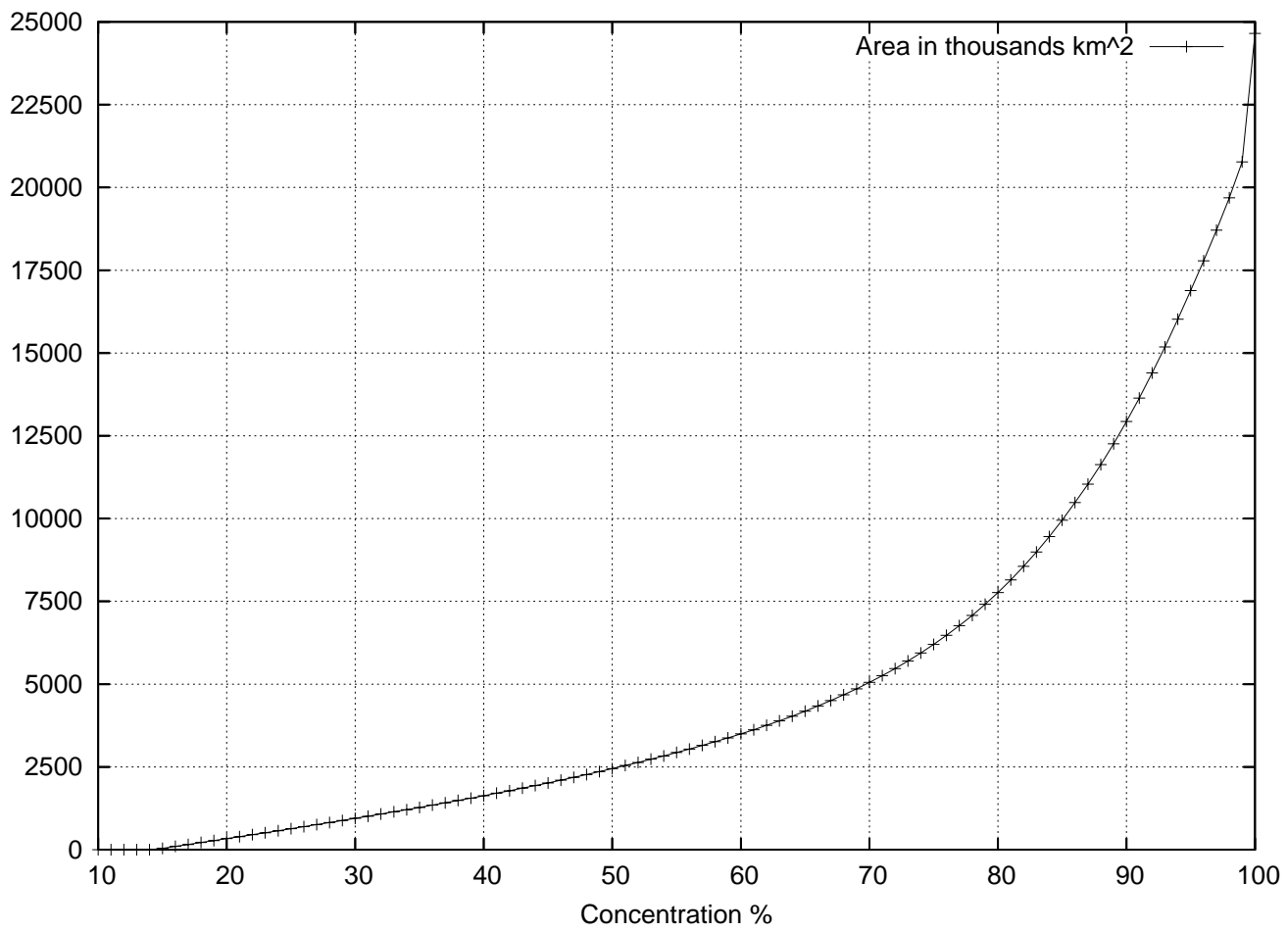


FIG. 3. Cumulative distribution function of concentrations