

# A simple water clarity-turbidity index for the Great Lakes

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## Abstract

There are a multitude of satellite-derived water clarity and turbidity indicators to support the decision making of environmental managers and policy makers. However, water quality dynamic ranges addressed by these indicators can differ significantly, subjecting non-expert users to potential pitfalls. Here we propose a satellite water clarity-turbidity index (CTI) as a simplified way to capture major changes in water clarity/turbidity across all water types in the Great Lakes. The CTI is defined to merge key information from three prerequisite variables derived from Visible Infrared Imaging Radiometer Suite (VIIRS) measurements, namely, the Secchi disk depth, the particulate backscattering coefficient, and the nephelometric turbidity, which are suitable for clear, intermediate, and turbid waters, respectively. Application to the Great Lakes shows that with one parameter, the CTI can illustrate major spatial and temporal patterns that are not entirely visible with each of the three original indicators alone. Using the CTI, we identified significant decrease in water turbidity in Lakes Michigan and Huron from 2000 to 2005, during which daily variability of CTI in August initially spiked and then gradually decreased most likely owing to diminishing whitening events. The CTI is a convenient and holistic assessment tool for water quality management.

*Keywords:* Satellite, remote sensing, water quality, Secchi disk depth, backscattering coefficient, nephelometric turbidity units

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1 **1. Introduction**

2 Water clarity and turbidity associated with light transmissivity are im-  
3 portant water quality indicators that can be estimated from satellite data  
4 using various proxy variables. Commonly used proxies include the Secchi  
5 disk depth,  $Z_{sd}$ , the particulate backscattering coefficient,  $b_{bp}(\lambda)$ , diffuse  
6 attenuation coefficient of downwelling irradiance,  $K_d(\lambda)$ , and turbidity in  
7 nephelometric turbidity units (NTU),  $T_n$  (Zheng and DiGiacomo, 2017). It  
8 is important to note that no single variable fits all water types with respect  
9 to covarying with changes in water quality; each individual variable has an  
10 optimal dynamic range. For example, the Secchi Depth  $Z_{sd}$  is well suited  
11 for clear waters but its magnitude tends to diminish in turbid waters. With  
12 errors and uncertainties which are inherent to satellite data, highly turbid  
13 waters are practically indistinguishable using only  $Z_{sd}$ . For a similar reason,  
14 it is also difficult to evaluate turbidity of clear waters using the nephelomet-  
15 ric turbidity  $T_n$ . Perhaps a good question to ask is, why estimate turbidity  
16 for waters with little turbidity, or likewise estimate clarity when there is  
17 essentially no clarity?

18 Therefore, effective application of these satellite products requires knowl-  
19 edge about their applicable dynamic range and what is actually "fit for pur-  
20 pose". This could overwhelm water quality managers and policy makers who  
21 may not have all the necessary technical expertise or more so the time to  
22 adequately research all available options. As a result, water quality man-  
23 agers often collect only those measurements proscribed by legal mandates,  
24 and typically these result predominantly if not solely from traditional field  
25 measurement programs. Although satellite data alone will not provide an-  
26 swers to all the issues or problems encountered by environmental managers  
27 and policy makers, space-based observations do provide invaluable synoptic  
28 coverage with frequent temporal revisits to robustly assess changes in envi-  
29 ronmental states (Schaeffer et al., 2013). Therefore, a simple but broadly  
30 applicable satellite-based product merging multiple variables might be more  
31 readily utilized and more informative for the decision making (Mouw et al.,  
32 2015). In practice, an effective, synergistic decision-making framework could  
33 include strategic leveraging of low-cost and timely satellite data to identify  
34 priority locations, followed by field sampling activities that target the pri-  
35 ority locations to provide more precise and legally compliant measurements,

36 particularly at depth and also to provide parameters that cannot be mea-  
37 sured from space (e.g., nutrients and pathogens). In other words, the satellite  
38 data provide routine and synoptic coverage, allowing for timely assessments  
39 of ecological changes, including identification of anomalous regional and local  
40 "hot-spots" and other areas that might warrant more in depth examination.

41 Towards this goal, we developed a framework that addresses the turbid-  
42 ity/clarity of a wide range of water types ranging from clear to highly turbid  
43 waters by merging  $Z_{sd}$ ,  $b_{bp}(\lambda)$ , and  $T_n$ . The framework is demonstrated using  
44 data from the Great Lakes which is the largest surface freshwater system in  
45 the world by total area with great range of variability in water turbidity.  
46 In addition, the anthropogenic environment and aquatic ecosystems of the  
47 Great Lakes have in places and over time been impaired by pollution and  
48 invasive species; the CTI may facilitate and prioritize restoration activities.

## 49 2. Data and Methods

50 The remote-sensing reflectance,  $R_{rs}(\lambda)$ , data covering the Great Lakes  
51 region were obtained from three satellite missions: Visible Infrared Imaging  
52 Radiometer Suite (VIIRS)-SNPP (2011-2019), Moderate Resolution Imaging  
53 Spectroradiometer (MODIS)-Aqua (2002-2019), and MODIS-Terra (2000-  
54 2019). Daily Level-2 VIIRS-SNPP granule data with "science quality" were  
55 processed by the NOAA Ocean Color Science Team (reprocessing version,  
56 SCI.OC04.0\_V1.21) and are available on the NOAA CoastWatch website  
57 (coastwatch.noaa.gov). Daily Level-2 MODIS-Aqua and -Terra data were  
58 obtained from the NASA's Goddard Space Flight Center Ocean Biology  
59 Processing Group using the Level 1&2 Browser on [oceancolor.gsfc.nasa.gov](http://oceancolor.gsfc.nasa.gov).  
60 Data were reprocessed in 2018 (version "R2018.0"). Both VIIRS and MODIS  
61 data were produced with the atmospheric correction using a near-infrared  
62 band as the basis for making the "black-pixel" assumption. To avoid ice  
63 contamination, most data used in this study were collected during warm  
64 seasons from May to September unless otherwise noted.

65 As preprocessing, data were screened to remove quality issues and then  
66 gridded. Specifically, we rejected pixels flagged as high solar zenith ( $>75^\circ$ )  
67 or high sensor zenith ( $>60^\circ$ ) angles, or high glint which is where sun glint  
68 radiance normalized by the solar irradiance that reaches sea level is greater  
69 than 0.01 Wang and Bailey (2001); Mikelsons and Wang (2019). In addi-  
70 tion, the daily Level-2 data granules were reprojected into gridded format at  
71 750-m (VIIRS) and 1000-m (MODIS) resolutions, respectively, and monthly

72 composites for each individual band were calculated as the mean of all grid-  
73 ded daily images in each month. The final product of this preprocessing is  
74 monthly 2-D arrays of the VIIRS  $R_{rs}(\lambda)$  data at 410, 443, 486, 551, 638,  
75 and 671 nm, and MODIS  $R_{rs}(\lambda)$  data at roughly identical bands, i.e., 412,  
76 443, 469, 488, 547, 645, and 667 nm. Other MODIS ocean color bands were  
77 excluded from further calculations. Note that the VIIRS 638-nm band is not  
78 a regular ocean color band, but an "I-band" with 2 times higher spatial res-  
79 olution and roughly 1/3 signal-to-noise ratio (SNR). So each  $R_{rs}(638)$  value  
80 is aggregated from 4 I-band pixels and in this process its SNR is somewhat  
81 enhanced.

82 VIIRS [Chl-*a*] data are derived using an "OC3V" algorithm which is based  
83 on empirical reflectance ratio of blue-green bands available on VIIRS (Wang  
84 et al., 2017).

### 85 **3. Results and Discussion**

#### 86 *3.1. The Clarity-Turbidity Index*

87 We propose a clarity-turbidity index (CTI) framework to provide a sim-  
88 ple, qualitative measure of overall water quality across all Great Lakes waters  
89 ranging from clear to highly turbid. The CTI can be determined based on  
90 three satellite-derived variables, namely  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$ . In theory,  
91 these variables quantify different optical properties of water. When mea-  
92 sured in the field or laboratory  $Z_{sd}$  is affected by both light absorption and  
93 scattering, whereas  $b_{bp}(550)$  and  $T_n$  are only or mostly determined by light  
94 scattering in the backward and side angles. In the context of remote sensing,  
95 however, the magnitude of  $R_{rs}$  and everything derived from it are affected by  
96 both absorption and scattering, including the three variables discussed here.  
97 What is more important is to select a set of variables that can serve as robust  
98 indicators of total suspended matter for a broad range of water quality. In  
99 this regard, the three variables,  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$ , are carefully selected  
100 to account for clear, intermediate, and turbid waters, respectively, which also  
101 correspond to the general water types when uncertainties of these variables  
102 are the lowest. Below, we explain each variable in details and describe how  
103 the CTI framework is designed to ensure that the adopted information always  
104 comes from the variable with the lowest uncertainty.

105 There are many formulas to derive these three variables from  $R_{rs}(\lambda)$  (e.g.,  
106 for  $Z_{sd}$ , see Doron et al., 2011; Lee et al., 2015; Son and Wang, 2020, and ref-  
107 erences cited therein). Users of our approach may select the most appropriate

108 formulas as they see fit. For the purpose of demonstrating the framework  
 109 of CTI, here we use a widely adopted formula given by Lee et al. (2015) to  
 110 derive  $Z_{sd}$ :

$$Z_{sd} = \frac{1}{2.5K_d(\lambda_{min})} \ln \left( \frac{|0.14 - R_{rs}(\lambda_{min})|}{0.013} \right) \quad (1)$$

111 , where  $K_d(\lambda)$  is the vertically averaged spectral diffuse attenuation coeffi-  
 112 cient, and  $\lambda_{min}$  is the light wavelength with minimum  $K_d(\lambda)$ , i.e., where light  
 113 can penetrate the deepest into the water column. Following Lee et al. (2015),  
 114  $K_d(\lambda)$  was calculated from the spectral light absorption,  $a(\lambda)$ , and backscat-  
 115 tering coefficients,  $b_b(\lambda)$ , which were calculated with the Quasi-Analytical  
 116 Algorithm (QAA) version 6 (Lee et al., 2013).

117 Although the accuracy of this  $Z_{sd}$  algorithm may require further valida-  
 118 tion in turbid waters (e.g., Yin et al., 2021), for clear waters with  $Z_{sd} > 10$   
 119 m which is its main application scenario here, the percent-wise agreement  
 120 among various other  $Z_{sd}$  algorithms were shown to be better (Doron et al.,  
 121 2011), i.e., less uncertainties in general to use satellite-derived  $Z_{sd}$  compared  
 122 with turbid waters. For clear waters, this algorithm were demonstrated to  
 123 work well for waters from a broad geographical range (the US and China)  
 124 (Lee et al., 2015).

125 The particulate  $b_{bp}(550)$  is calculated simply by subtracting the pure wa-  
 126 ter contribution,  $b_{bw}(550)$ , from the QAA-derived total  $b_b(550)$ . The QAA  
 127 has been demonstrated to perform consistently well for a wide range of wa-  
 128 ters with intermediate turbidity across the world (Zheng et al., 2014; Mitchell  
 129 et al., 2014; Pitarch et al., 2020), and therefore tuning of QAA for the Great  
 130 Lakes intermediate waters is not essential. In fact, a refinement effort of QAA  
 131 using field data collected from Lake Superior yielded only negligible improve-  
 132 ment (Mouw et al., 2013). Note that the 550 nm here is a nominal band name  
 133 referring to the 551 nm for VIIRS and 547 nm for MODIS. The pure water  
 134 contribution  $b_{bw}(550)$  is calculated with the Water Optical Properties Pro-  
 135 cessor (WOPP) developed by Rottgers et al. (2011). In this calculation water  
 136 salinity was set to zero, and water temperature to 10 °C which is close to  
 137 the medians of monthly whole-lake average temperature of individual Great  
 138 Lakes from May to September (see [coastwatch.glerl.noaa.gov/statistic/](http://coastwatch.glerl.noaa.gov/statistic/)).

139 To calculate turbidity in nephelometric units,  $T_n$ , we used a formula based  
 140 on the magnitude of  $R_{rs}(645)$  (or 638 nm for VIIRS) from Dogliotti et al.  
 141 (2015):

$$T_n = \frac{228.1\pi R_{rs}(645)}{1 - \pi R_{rs}(645)/0.1641} \quad (2)$$

142 This formula was based on data from a diverse set of environments (European  
143 and South American coastal waters). In addition, it converges with other  
144 regression relationships obtained for various turbid water bodies in the world  
145 between  $T_n$  and  $R_{rs}(645)$  (see Fig. 9 in Zheng and DiGiacomo, 2017). This  
146 suggests that eq. 2 is robust and can be applied to the Great Lakes with  
147 relatively low uncertainty.

148 We also examined the use of  $T_n$  derived from reflectance at near-infrared  
149 (IR) bands (e.g., 860 nm) to account for more turbid waters but found it  
150 unnecessary because such waters are rare in the Great Lakes except outside  
151 of episodic sediment plume and algal bloom events. However, in many other  
152 coastal and inland waters where turbidity are much higher to the extent  
153 that  $R_{rs}$  at the 645-nm band is also saturated and no longer responding to  
154 turbidity variations, it is necessary to use a near-IR band to derive  $T_n$  more  
155 accurately (e.g., Dogliotti et al., 2015). This would require an atmospheric  
156 correction scheme using a shortwave-infrared band as a basis for making the  
157 “black-pixel” assumption.

158 Given  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$ , the CTI is determined based on threshold  
159 values of these variables as illustrated in Table 1 and Fig. 1A. Figure 1A  
160 shows the distribution of all monthly VIIRS data used in this study which  
161 comprise over two million samples. The MODIS data show similar patterns  
162 except that the  $T_n$  rarely exceeds 60 NTU (not shown). The first step is  
163 to separate the two endmember groups, i.e., clear waters and turbid waters.  
164 This is important because turbidity indicator  $T_n$  diminishes in clear waters  
165 and clarity indicator  $Z_{sd}$  diminishes in turbid waters, and as they diminish,  
166 they also lose the dynamic range to capture the variability of water quality  
167 (see right end of blue points and left end of red points in Fig. 1A). Based on  
168 the VIIRS data distribution, two threshold values of  $b_{bp}(550)$ , 0.01 and 0.1  
169  $\text{m}^{-1}$ , were selected to broadly categorize a given pixel into clear (CTI  $\leq 4$ ),  
170 intermediate (CTI 5), or turbid waters (CTI  $\geq 6$ ). The value of 0.01  $\text{m}^{-1}$   
171 happens to intercept with the upper bound of  $Z_{sd} - b_{bp}(550)$  distribution at  
172  $Z_{sd} \approx 10$  m, whereas the value of 0.1  $\text{m}^{-1}$  happens to intercept with the upper  
173 bound of  $T_n - b_{bp}(550)$  distribution at  $T_n \approx 15$  NTU. Therefore  $Z_{sd} = 10$  m is  
174 used as a threshold value to further separate the clearest (CTI  $\leq 3$ ) from the  
175 transitional clear-intermediate waters (CTI=4), and  $T_n = 15$  NTU is used  
176 to separate the intermediate-turbid (CTI=6) from the most turbid waters  
177 (CTI  $\geq 7$ ). For the clearest waters (CTI 1 through 3), the CTI is based solely  
178 on  $Z_{sd}$  with threshold values of 15 and 20 m, respectively; whereas for the  
179 most turbid waters (CTI 8 through 11), it is based solely on  $T_n$  with threshold

180 values of 30, 60, 100, 200, and 500 NTU, respectively. There are relatively  
181 few data points beyond 200 NTU so they were not shown in Fig. 1A to  
182 better illustrate other CTI indices.

183 The selection of these threshold values may make the CTI approach ap-  
184 pear arbitrary; nevertheless, it is the framework merging critical information  
185 from  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$  that is important. The CTI approach is essen-  
186 tially a discretization of  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$  data in their most applicable  
187 turbidity ranges. It transforms quantitative into qualitative information,  
188 while distilling and preserving dominant water quality information out of an  
189 overwhelmingly large amount of data, making it suitable for water quality  
190 managers and policy-makers to readily grasp general trends and patterns in  
191 both space and time. In addition, the way CTI is defined makes it a flexible  
192 approach. First, its applicable range of clarity/turbidity can be easily ex-  
193 panded; it could potentially cover much clearer (Gieskes et al., 1987; Doron  
194 et al., 2011; Lee et al., 2018, e.g., oceanic waters with  $Z_{sd}$  as deep as 70 m,) and  
195 much more turbid waters (Dogliotti et al., 2015, e.g.,  $T_n$  over 1000,).  
196 However, caution must be taken when dealing with special cases such as wa-  
197 ters with high turbidity or high concentrations of dissolved organic matter  
198 because the relationships among satellite-derived  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$  may  
199 depart significantly from those shown in Fig. 1A. Second, the choices of  
200 threshold values are flexible; users can easily change these thresholds as they  
201 see fit and easily trace each CTI back to the ranges of  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$   
202 through Table 1. The adjustment of various threshold values for Great Lakes  
203 waters can be made without the need to analyze additional satellite data. A  
204 user can simply make changes based on their own knowledge, e.g., beyond  
205 what  $T_n$  value poses a concern for environmental compliance, or in a trial-  
206 and-error fashion by keep tuning thresholds and examining the resultant CTI  
207 maps until the most insightful CTI patterns show up. In essence, the CTI  
208 provides a one-number metric for water quality managers and policy-makers  
209 to make quick evaluations without having to worry about technical details,  
210 particularly for regions where turbidity variation is large.

211 With respect to covering a large range of water turbidity/clarity, the com-  
212 bination of  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$  is a rather unique choice because replacing  
213 either  $Z_{sd}$  or  $b_{bp}(550)$  with other variables commonly used for clear to moder-  
214 ately turbid waters does not yield equally satisfying result. For example, we  
215 tried to use the mean surface diffuse attenuation coefficient,  $K_d(490)$ , in lieu  
216 of  $Z_{sd}$  or  $b_{bp}(550)$  but the distribution of data points is much less converged  
217 (Fig. 1B and C). Note that the  $K_d(490)$  data used here are provided in the

Index	Water type	$Z_{sd}[m]$	$b_{bp}(550)[m^{-1}]$	Turbidity [NTU]
1	Clear-3	20–25		
2	Clear-2	15–20		
3	Clear-1	10–15		
4	Clear-Intermediate	0–10	<0.01	
5	Intermediate		0.01–0.1	
6	Intermediate-Turbid		>0.1	<15
7	Turbid-1			15–30
8	Turbid-2			30–60
9	Turbid-3			60–100
10	Turbid-4			100–200
11	Turbid-5			200–500
12	Turbid-6			>500

Table 1: Definitions of clarity-turbidity indices based on satellite-derived  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$ . Blank means the corresponding variable is not used to define a specific index.

218 standard Level-2 VIIRS products from NOAA, which was derived following  
219 the approach by Wang et al. (2009) as opposed to the formula used to derive  
220  $Z_{sd}$  (Lee et al., 2015) shown above. In addition, water quality as indicated  
221 by  $K_d(490)$  is often inconsistent with that by  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$ , e.g., data  
222 points with high  $K_d(490)$  (suggesting high turbidity) but low  $b_{bp}(550)$  (sug-  
223 gesting low turbidity) (Fig. 1B), or low  $K_d(490)$  (suggesting low turbidity)  
224 but low  $Z_{sd}$  (suggesting high turbidity) (Fig. 1C). Such inconsistency on top  
225 of the large data spread makes it difficult to use  $K_d(490)$  to define CTI in a  
226 robust fashion (Fig. 1A).

227 Using the approach discussed above we mapped out the CTI for the Great  
228 Lakes using  $R_{rs}(\lambda)$  data from VIIRS-SNPP, MODIS-Aqua and -Terra, and  
229 made monthly composites for each sensor. Compared with  $Z_{sd}$ ,  $b_{bp}(\lambda)$ , and  $T_n$   
230 individually, the CTI exhibits a broader range of variability. Taking VIIRS  
231 data in April 2018 for example (Fig. 2), among the three original variables the  
232 clearest waters in central Lake Huron (white dashed circles) can only be seen  
233 in the  $Z_{sd}$  map, the most turbid waters in Lake Erie (black dashed circles)  
234 can only be seen in the  $T_n$  map, whereas the  $b_{bp}(550)$  map only highlights  
235 turbidity changes in moderately turbid waters (e.g., the Saginaw Bay, gray  
236 dashed circles). In contrast, the CTI map shows all main features across all



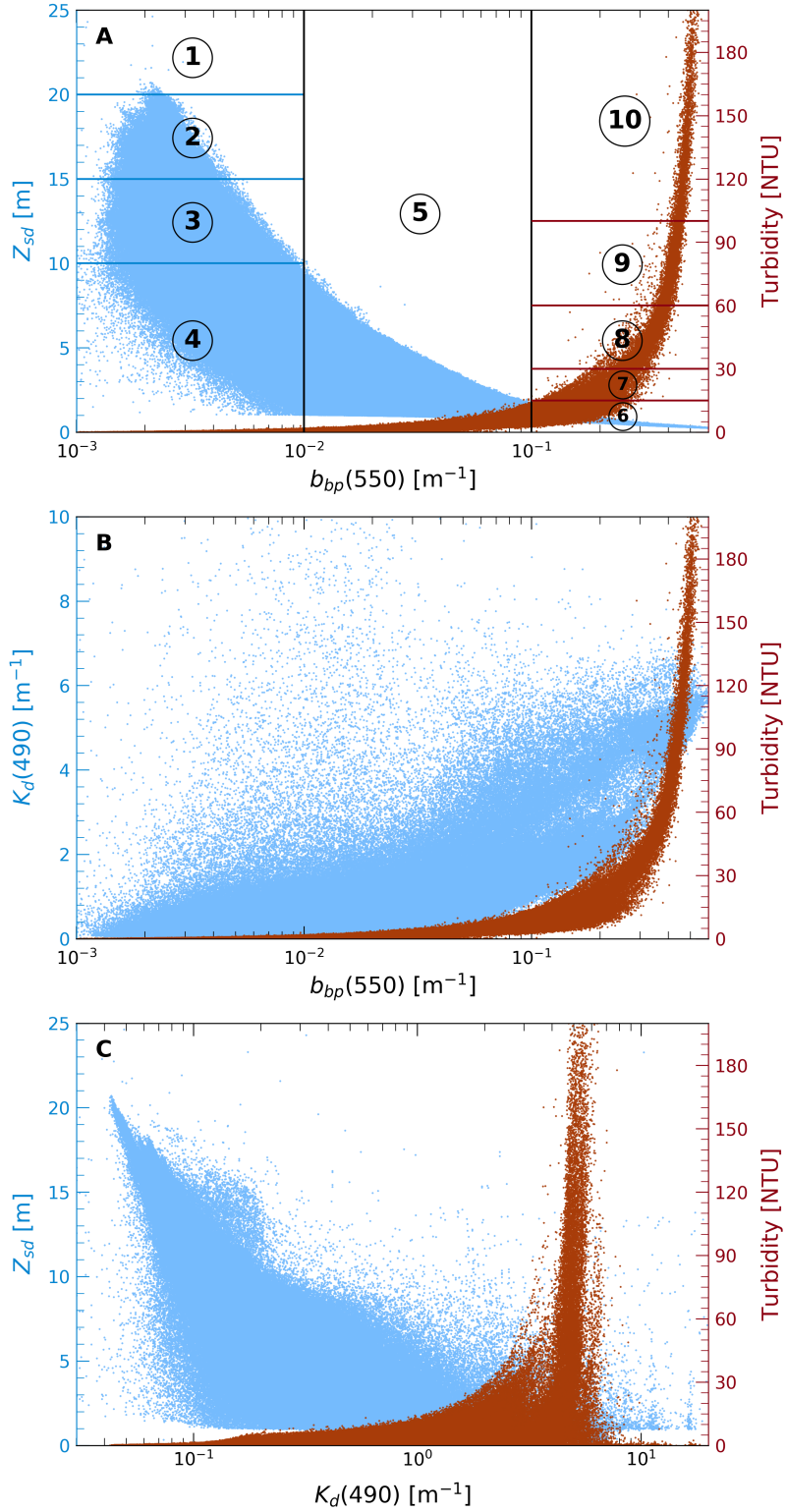


Figure 1: (A) VIIRS-SNPP monthly averaged  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$  data in the Great Lakes during 2012-2019 overlaid with clarity-turbidity indices (denoted by circled numbers). See Table 1 for numerical definitions. For comparison, an alternative variable,  $K_d(490)$ , is used to replace  $Z_{sd}$  (B) or  $b_{bp}(550)$  (C).

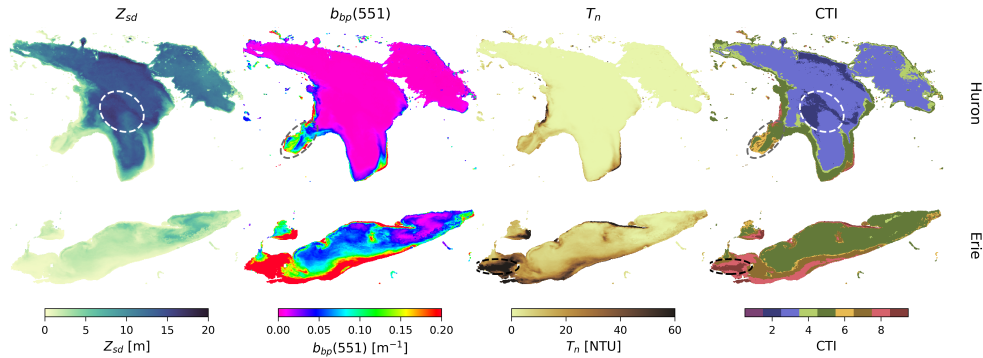


Figure 2: Comparison between maps of VIIRS-derived  $Z_{sd}$ ,  $b_{bp}(\lambda)$ , and  $T_n$  and the CTI using Lakes Huron and Erie in April 2018 as an example.

237 water types ranging from the clearest to the most turbid.

### 238 3.2. General Trends

239 Next, we examined the consistency of CTI derived from VIIRS-SNPP,  
 240 MODIS-Aqua and -Terra by comparing the CTI values derived from the 3  
 241 different sensors. For brevity we selected one month from each season (spring,  
 242 summer, and fall) and calculated the lakewide average CTI. Figure 3 shows  
 243 that the agreement among the three sensors is generally very good particu-  
 244 larly for the two MODIS sensors which exhibit almost identical results.  
 245 VIIRS-derived CTI values are systematically larger than the MODIS coun-  
 246 terparts but they generally follow the same trend, except a few outliers such  
 247 as Lake Superior in September 2014 and Lake Ontario in September 2015  
 248 which are associated with significantly different spectral shapes in VIIRS-  
 249 and MODIS-derived  $R_{rs}(\lambda)$ . The difference between VIIRS and MODIS  
 250 data are associated with the different atmospheric correction schemes used,  
 251 as indicated by a sensitivity test we did (not shown). In addition, the differ-  
 252 ence may also arise from the saturation of MODIS over bright water targets  
 253 (e.g. Land et al., 2018). Nonetheless, the inter-sensor disagreement repre-  
 254 sents only a small fraction of the entire dataset. Overall, the results suggest  
 255 that for clear and intermediate waters the CTI can be considered independ-  
 256 ent from sensor, algorithm, and data-processing system. For turbid waters  
 257 the VIIRS- and MODIS-derived CTIs can be significantly different owing to  
 258 the smaller dynamic range exhibited in the MODIS 645-nm band.

259 Figure 3 also shows that from the whole-lake standpoint, water quality  
260 in Lakes Michigan and Huron exhibits significant decadal changes. In par-  
261 ticular, dramatic CTI drop occurred around 2004, consistent with previous  
262 studies (e.g. Binding et al., 2015). Average CTI in May dropped from  $>4$   
263 in 2002–2003 to  $\sim 3.5$  in 2005 for Lakes Michigan and Huron (Fig. 3D,G).  
264 Average CTI in Lake Michigan dropped even more significantly in Septem-  
265 ber than in May from  $>4.5$  in 2001 to  $\sim 3.5$  in 2005 (Fig. 3F), but the same  
266 trend did not happen in Lake Huron. Another significant trend is found in  
267 July, when CTI kept dropping since 2000, reached the minimum in 2012 with  
268 a total drop of  $\sim 0.8$ , and bounced back by a total of  $\sim 0.7$  as of 2019 (Fig.  
269 3E,H). A similar trend was also found in Lake Superior in May (Fig. 3A), al-  
270 though the magnitude of variation is much smaller. Otherwise, CTI changes  
271 in the other three lakes, i.e., Lakes Superior, Erie, and Ontario over the past  
272 two decades (2000-2019) are mostly associated with interannual variability.  
273 Interestingly, Lake Ontario exhibits both the largest (in September, Fig. 3O)  
274 and the smallest (in July, Fig. 3N) interannual variability.

275 To further examine spatial patterns of water quality changes, we obtained  
276 quinquennial CTI maps using mean  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$  calculated every  
277 five years (Fig. 4). For this analysis we used only MODIS-Terra data which  
278 provides the longest time record (2000–2019). Note that MODIS-derived  $T_n$   
279 tends to be underestimated at higher turbidity levels compared with VIIRS.  
280 However, this is a minor issue for the purpose of this study because very tur-  
281 bid waters only account for a negligible portion of the Great Lakes. Figure  
282 4 confirms that the most significant change in CTI occurred in Lake Michi-  
283 gan and Huron and between the two periods of 2000–2004 and 2005–2009.  
284 Most areas in Lakes Michigan and Huron underwent a CTI drop by 1, and  
285 the biggest drop occurred in September in central southern Lake Michigan  
286 with a CTI drop by 2, from 5 (intermediate) to 3 (clear-1) (Fig. 4C,F). Af-  
287 ter this significant drop in water turbidity, Lake Huron and southern Lake  
288 Michigan continued to clear up during 2010–2019 whereas CTI of northern  
289 Lake Michigan stabilized. An intriguing spatial pattern is the decrease in  
290 CTI at relatively shallow locations in May. For example, the location of the  
291 clear waters with  $CTI = 2$  in Lakes Michigan and Huron (dark blue in Fig.  
292 4G,J) matches roughly with shallow bathymetry contours (not shown). This  
293 pattern might be associated with higher fraction of the water column cleared  
294 per day by invasive dreissenid mussels (Rowe et al., 2015), and in particular  
295 by quagga mussels in Lake Michigan (Nalepa et al., 2020) and Huron (Nalepa  
296 et al., 2018). The relationship between CTI and invasive mussels needs to be

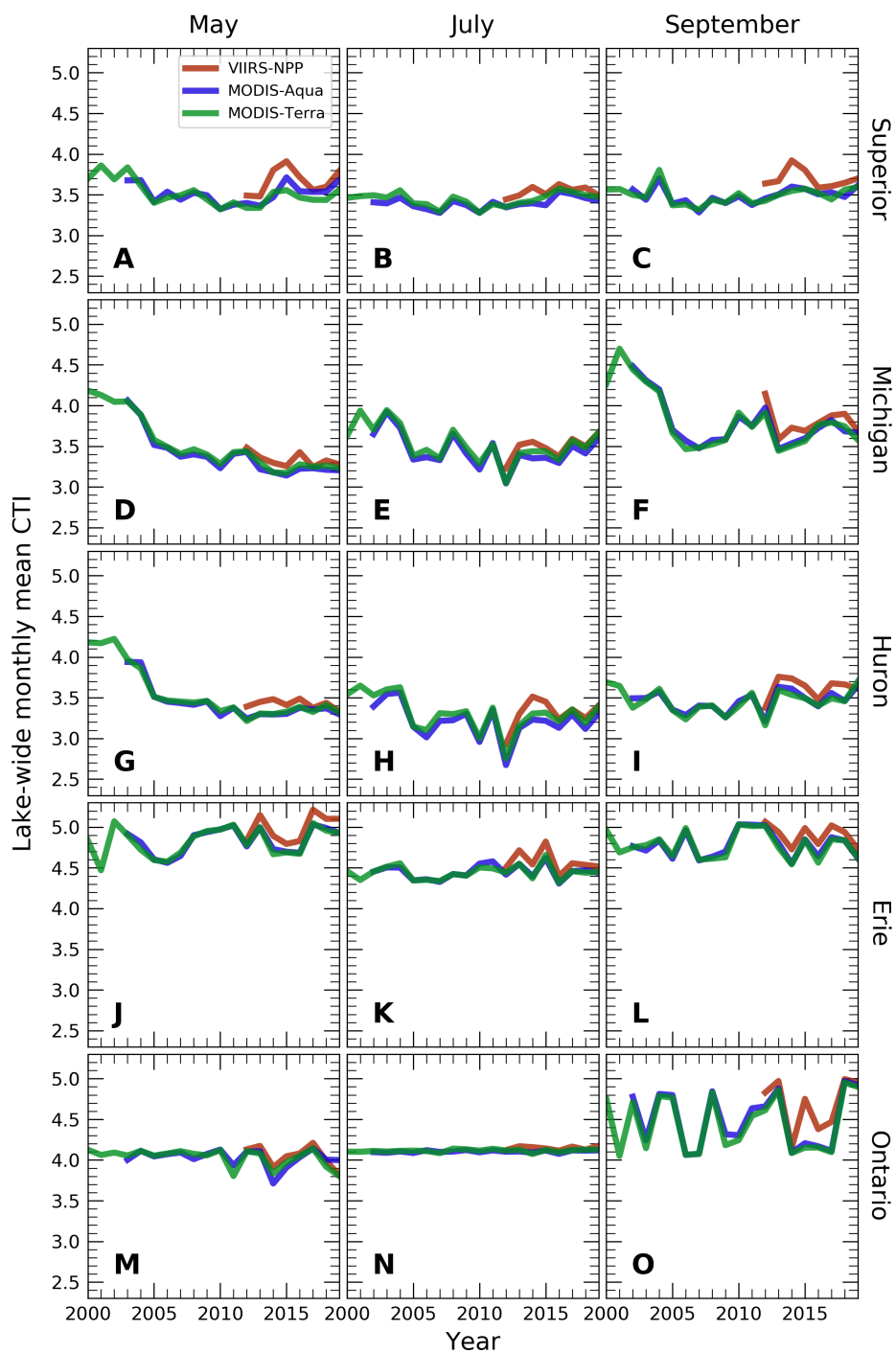


Figure 3: Lake-by-lake monthly mean clarity-turbidity index from 2000 to 2019 for May, July, and September.

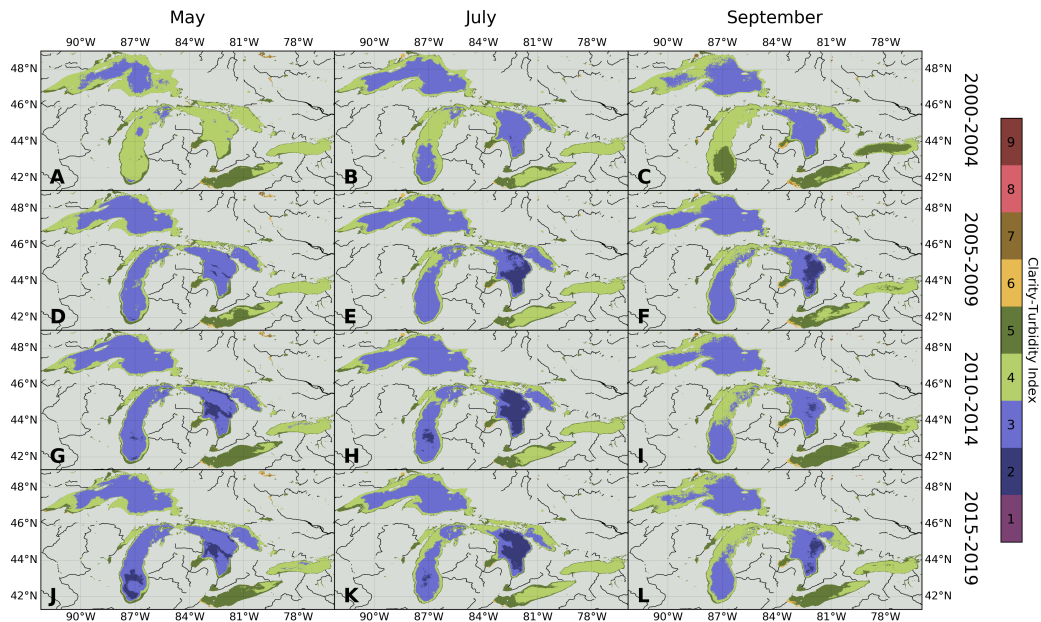


Figure 4: Quinquennial climatology of water clarity-turbidity index of the Great Lakes across spring, summer, and fall.

297 further investigated in future studies.

### 298 3.3. Case Studies

299 In the previous section we used monthly composite data to highlight  
 300 long-term trends of water quality changes in the Great Lakes. Water quality  
 301 managers are also interested to understand short-term water quality vari-  
 302 ability of waterbodies under their jurisdiction, which can be very dynamic.  
 303 In this section, we conduct two case studies to demonstrate the use of CTI  
 304 to studying water quality variability on a day-to-day basis. To characterize  
 305 this variability we tested several statistical metrics calculated for all daily  
 306 data sampled at each pixel within each month, which include the standard  
 307 deviation, the 1st-99th interpercentile range, and the 1st-3rd interquartile  
 308 range. After comparing features shown in these three error parameters, the  
 309 interquartile range, hereafter referred to as  $Q_3 - Q_1$ , was selected as the met-  
 310 ric to measure temporal variability of CTI, which gives a robust measurement  
 311 of the spread of daily retrievals without being subjected to the influence of  
 312 potential noise.

313 After examining the monthly time series of CTI  $Q_3 - Q_1$  from 2000 to

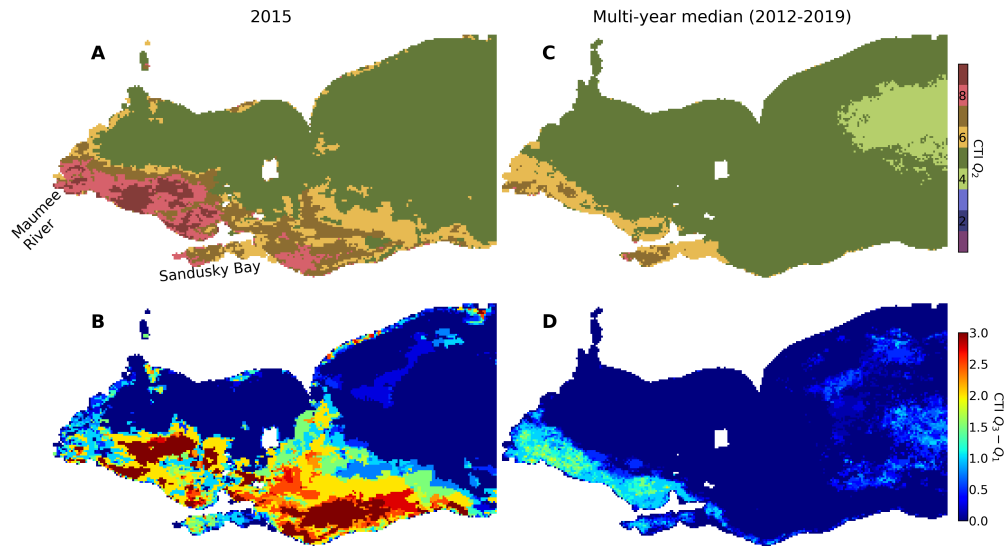


Figure 5: June median (A) and interquartile range (B) of daily CTI in western Lake Erie in 2015 derived from VIIRS-SNPP, compared with normal conditions as represented by the multi-year medians values of the same variables (C and D). See Fig. 6 for symbol definitions.

314 2019, we noticed two regions with large CTI fluctuations: Western Lake Erie  
 315 and Southern Lake Michigan. In June 2015, Western Lake Erie exhibited  
 316 abnormally high CTI in terms of both magnitude and variability (Fig. 5A,B)  
 317 compared with normal levels (Fig. 5C,D). Median CTI reached 9 off the  
 318 Maumee River mouth, whereas in normal years it is only 5. Daily variability  
 319 of CTI represented by  $Q_3 - Q_1$  exceeded 3 off the Maumee River mouths and  
 320 off the Sandusky Bay, compared to near zero in normal years. The dramatic  
 321 change in 2015 can be explained by significantly increased river discharge in  
 322 this area. For example, monthly mean streamflow of the Maumee River was  
 323 record-high in June 2015 (the 3rd greatest since 1939) (Stumpf et al., 2016),  
 324 which delivered significant amount of suspended sediments to Lake Erie.

325 In Southern Lake Michigan, August CTI exhibited a regime shift from  
 326 2000 to 2005, shifting from steadily Clear-Intermediate (4) to steadily Clear-  
 327 1 type (3) (top and middle panels in Fig. 6). During this period, both the  
 328 magnitude (top panel) and the variability ( $Q_3 - Q_1$ , middle panel) of CTI had  
 329 an initial surge in 2001 and then gradually decreased in the following years.  
 330 These trends cannot be explained by annual changes in [Chl-*a*] level (bot-

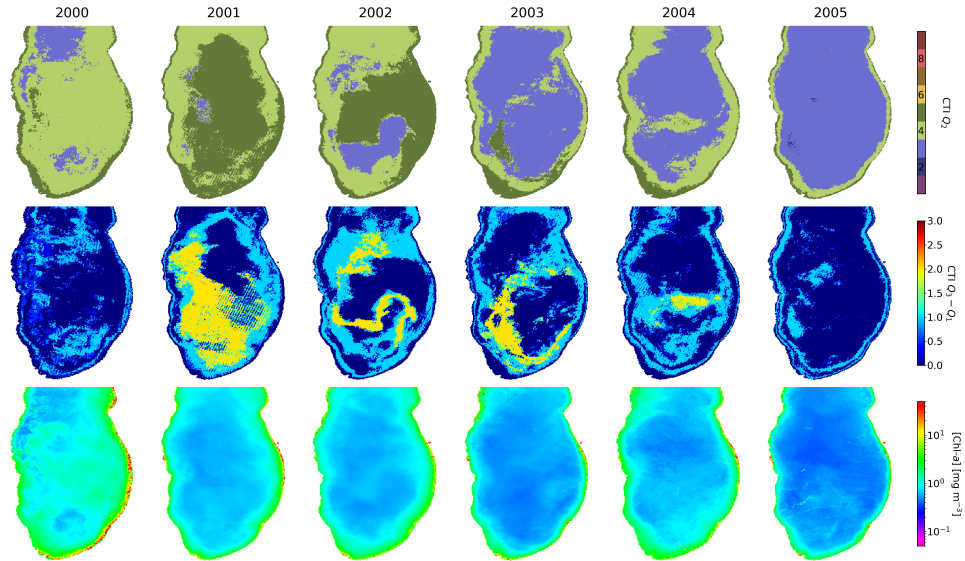


Figure 6: Monthly median (top panel) and interquartile range (middle panel) of daily clarity-turbidity index CTI derived from MODIS-Terra, in comparison to [Chl-*a*] (bottom panel) in southern Lake Michigan in August from 2000 to 2005.  $Q_1$ ,  $Q_2$ , and  $Q_3$  are the first, second, and third quartiles of all daily retrievals of the month.

331 tom panel) which sometimes changed in the opposite way relative to CTI.  
 332 For instance, between 2000 and 2001 mean [Chl-*a*] in August decreased while  
 333 median CTI increased. However, this trend must be interpreted with caution  
 334 because the [Chl-*a*] here is derived from a reflectance band ratio algorithm  
 335 and is subject to contamination by other pigmented matter such as colored  
 336 dissolved organic matter. The most likely contributor to the trends in CTI  
 337 is most likely attributable to changes in frequency of whiting events, waters  
 338 laden with clouds of small calcite particles formed by precipitation of cal-  
 339 cium carbonate. In fact, true color images of Lake Michigan whiting events  
 340 in 1999 and 2001 were highlighted by NASA Earth Observatory as "Image of  
 341 the Day" on September 18, 2001 ([earthobservatory.nasa.gov/images/1768](http://earthobservatory.nasa.gov/images/1768)).  
 342 Historically, whiting events were common in Lake Michigan during warm  
 343 seasons in the 1970s (Strong and Eadie, 1978). However, X-ray scanning  
 344 analyses made for suspended particulate samples collected in Lake Michigan  
 345 in summer 2008, 2010, and 2012 show no indication of whiting events (Ef-  
 346 fler et al., 2013; Peng and Effler, 2015); specifically, either total suspended  
 347 particulate concentration or contribution of calcium carbonate to the total  
 348 are very low compared with typical whiting event levels. To the best of  
 349 our knowledge, whiting events in Southern Lake Michigan have not been  
 350 reported since 2001. Our results suggest that whiting events in Southern  
 351 Lake Michigan underwent a gradual decline during 2001–2005 (Fig. 6). The

352 2001 whiting events could well be the very last major episode of the whiting  
353 "show" in Lake Michigan.

354 It is worth noting that the regime shift of CTI is accompanied by a re-  
355 duction of [Chl-*a*] (lower panel, Fig. 6), although the two variables are not  
356 strongly correlated. The timing of these changes matches well with the rapid  
357 expansion of quagga mussels in Lake Michigan from 2000 to 2005 (Nalepa  
358 et al., 2020). It is highly likely that the filtering effect of quagga mussels  
359 leads to both the regime shift of CTI and the reduction of phytoplankton  
360 biomass. Dreissenid mussels can reduce the frequency and/or intensity of  
361 whiting events through direct calcium uptake (Barbiero et al., 2006). They  
362 could also alter whiting events by changing the abundance of cyanobacteria  
363 which are recognized as key players in the precipitation of calcium carbonate  
364 in marine and freshwater systems (Thompson and Des Marais, 1997; Dit-  
365 trich and Sibling, 2010; Kamennaya et al., 2012). Cyanobacteria promote  
366 whiting events by creating alkaline microenvironment surrounding the cells,  
367 serving as nucleation sites (Thompson and Des Marais, 1997), and exud-  
368 ing polysaccharides that have a strong potential to exchange protons with  
369 the surrounding environment (Dittrich and Sibling, 2010). More research is  
370 needed to answer the question of what mechanisms caused the decline of  
371 whiting events in Lake Michigan.

#### 372 4. Summary

373 The CTI developed here is a simple approach to make an approximate  
374 evaluation of water turbidity or clarity for any type of optically deep water  
375 body, i.e., as long as the water-leaving light is unaffected by reflection off the  
376 water bottom. It allows the evaluation of water quality to be "approximately  
377 right", as opposed to "precisely wrong" which may result from the adoption  
378 of a variable that is inappropriate for the waters of interest. Application of  
379 this approach to satellite data essentially generates dynamic water quality  
380 thematic maps from which significant water quality changes can be detected.  
381 However, CTI alone does not tell what is causing those changes; it should be  
382 viewed as an "alarm bell" warning that something is happening and is worth  
383 more in-depth examination with the aid of other sources of information.  
384 In this study, we show that the use of CTI allows the depiction of spatial  
385 gradients and temporal trends of water quality in the Great Lakes, and major  
386 turbidity drops in Lake Michigan and Lake Huron around 2004, a timing that  
387 matches the start of lake-wise infestation of invasive dreissenid mussels. We



388 also show that significant day-to-day variation in water turbidity can arise  
389 from high river streamflow and diminishing whiting events.

390 The CTI could be extended to other water bodies in the world, partic-  
391 ularly for regions where water clarity/turbidity spans a great range. Note  
392 that the CTI definition and the relationships among  $Z_{sd}$ ,  $b_{bp}(550)$ , and  $T_n$   
393 shown here (Fig. 1A, Table 1) only serve as an example. To achieve the  
394 most effective result, especially for waters with extreme optical properties  
395 such as high dissolved organic absorption, high suspended mineral concen-  
396 tration, high algal biomass, etc, it is recommended to redefine CTIs with new  
397 thresholds using remote-sensing data from the region of interest and based  
398 on practical needs of local water quality managers. In addition, caution must  
399 also be taken to ensure the quality of input data of  $R_{rs}(\lambda)$  for those opti-  
400 cally complex waters. We recommend the CTI approach to water quality  
401 managers and policy-makers whose intention is to seek holistic understand-  
402 ing from satellite data rather than conducting detailed quantitative analyses  
403 with them.

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409 policy, decision, or position on behalf of the NOAA or the U.S. Government.

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## Highlights

### **A simple water clarity-turbidity index for the Great Lakes**

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- A framework to extract water quality information from satellite data is proposed.
- The approach is applicable to a wide range of water types ranging from clear to turbid.
- It is a convenient tool to identify main changes in water quality with one single parameter.