- Modeling the dispersal of polar cod (*Boreogadus saida*) and saffron cod (*Eleginus gracilis*) early
- life stages in the Pacific Arctic using a biophysical transport model
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Abstract

Polar cod (*Boreogadus saida*) and saffron cod (*Eleginus gracilis*) are the most abundant and ecologically important forage fishes in the Pacific Arctic marine ecosystem, yet little is known about their spawning locations or the habitats occupied by their early life stages (ELS). We developed a biophysical transport model coupled to a Pan-Arctic hydrodynamic ocean circulation model to identify potential spawning locations and examine connectivity between the northern Bering, Chukchi, and Beaufort seas. We simulated the growth and transport of newly hatched polar cod and saffron cod larvae until the early juvenile stage (to 45 mm in length) using circulation model hindcasts from 2004 – 2015. Analyses identified species-specific differences in dispersal trajectories, despite similar hatch times and locations. Strong interannual variability in growth and dispersal was linked to several global-scale climate indices, suggesting that larval growth and transport may be sensitive to environmental perturbations. Results show that polar cod spawned in the northern Chukchi Sea may be an important source of larvae for the Beaufort Sea and Arctic Basin, while observed larval aggregations in the Chukchi Sea likely originated in the northern Bering and southern Chukchi seas. This study provides new information about potential spawning times and locations for polar cod and saffron cod in the Pacific Arctic and helps to identify important ELS habitat. This knowledge can help improve the management of these species and, by examining how larval connectivity changes in response to changing environmental conditions, improve our ability to anticipate how these species may respond in a rapidly changing Arctic.

Keywords: *Boreogadus saida*, *Eleginus gracilis*, early life stages, growth, dispersal, connectivity, individual-based model

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1. Introduction

The Arctic is warming at an unprecedented rate. Surface air temperatures have increased at double the global rate (Screen and Simmonds, 2010) and this warming has also extended to the oceans, resulting in dramatic changes across Arctic ecosystems (Wassman et al., 2011; Huntington et al., 2020). The Pacific Arctic, in particular the Bering Strait region and the Chukchi 60 Sea, is warming rapidly, with water temperatures increasing by 0.43 $^{\circ}$ C per decade since 1990 (Danielson et al., 2020a). Sea-ice concentration, extent, and duration have also declined over this period, with an earlier spring ice retreat and delayed fall ice formation increasing the length of the open-water season by ~3 months (Comiso et al., 2008; Stammerjohn et al., 2012). Reduced ice cover, earlier ice melt, and greater freshwater inputs associated with warming in the Arctic are predicted to impact ecosystem dynamics via the poleward movement of boreal species and changes in marine productivity (Meredith et al., 2019). These changes will likely have a profound effect on the distribution and abundance of resident Arctic species. To better understand the consequences of these environmental changes, in this study we examine the early life stages (ELS) of polar cod (*Boreogadus saida*) and saffron cod (*Eleginus gracilis*), two of the most abundant and ecologically significant species in the Pacific Arctic marine ecosystem.

Polar cod and saffron cod play an important role in the transfer of energy to higher trophic levels, serving as key prey for piscivorous seabirds and marine mammals, as well as humans, in the northern Bering, Chukchi, and Beaufort seas (Whitehouse, 2011; Moore and Stabeno, 2015). In general, observational data for Arctic marine fishes are scarce and particularly so for their ELS, such as spawning locations, larval drift pathways, and juvenile nursery areas. Collections are mainly limited to the late spring and summer (but see Lafrance, 2009; Bouchard et al., 2016) due to the challenges and costs of sampling during winter and spring in the remote regions of the Arctic (e.g., difficulties of sampling under the ice, lack of sustained research efforts). As such, identifying major spawning locations of species that spawn under the ice during the winter, such as polar cod and saffron cod, resolving the movement and distribution of their ELS, and understanding their responses to variable climate conditions cannot be achieved through field studies alone.

Advective transport of eggs and larvae is known to play an important role in population 84 regulation of marine fishes and several studies have linked larval transport with variability in year-class strength (Bailey, 1981; Hollowed and Bailey, 1989; Wilderbuer et al., 2002; Govoni 2005; Mueter et al., 2006; Petrik et al., 2015, 2016). Modeling approaches, such as the use of biophysical models that can track and simulate the behavior of eggs and larvae, can provide insights into the movement of ELS and information that would otherwise be unavailable through conventional field sampling. Since eggs and larvae are relatively underdeveloped in the first few months of life, their dispersal is primarily governed by ocean circulation and can be tracked by simulating the transport of passive particles or particles with basic behaviors. Examples include temperature-dependent growth combined with size- or age-dependent vertical migrations, until the larvae grow to a size at which their movements are largely independent of the currents (Leis, 94 2007). The impacts of circulation on larval dispersal and recruitment has been successfully evaluated using hydrographic modeling approaches in a variety of marine systems (as reviewed in Miller, 2007), including the Gulf of Alaska and the Bering Sea (Hinckley et al., 1996; Parada et al., 2010; Duffy-Anderson et al., 2013; Vestfals et al., 2014; Petrik et al., 2015, 2016; Gibson et al., 2019).

The Chukchi Sea is a broad (> 500 km), shallow (~ 50 m deep), high-latitude shelf system that extends > 800 km northward from Bering Strait and is highly productive during the spring melt and open-water seasons (Grebmeier et al., 1988). The seasonally fluctuating Pacific-Arctic sea level gradient (Stigebrandt, 1984; Aagaard et al., 2006) drives the northward flow from the Bering Sea through the narrow (~85 km) and shallow (~50 m) Bering Strait. Water entering the Chukchi Sea is often classified into three water masses: cold, relatively saline, and nutrient-rich Anadyr Water (AW) in the west (Coachman et al., 1975; Sambrotto et al., 1984), seasonally present and relatively warm, low-salinity Alaskan Coastal Water (ACW) in the east, and a mixture of the two water masses, Bering Shelf Water (BSW) (Coachman et al., 1975), which originates primarily from 100 m isobath flow (Stabeno et al., 2018). Peak inflow through Bering Strait occurs during summer, bringing relatively fresh water, nutrients, heat, carbon, and organisms into the Chukchi and Beaufort seas (Wyllie-Echeverria et al., 1997; Weingartner et al., 2005; Woodgate et al., 2005a, b; Moore and Stabeno, 2015), while strong southward winds in winter reduce the northward flows (Woodgate et al., 2005a, b; Stabeno et al., 2018).

Inflow through Bering Strait moves across the Chukchi shelf along three main pathways: westward through Hope Valley towards Herald Canyon (Coachman et al., 1975; Weingartner et al., 2005; Woodgate and Aagaard, 2005; Pickart et al., 2010), eastward parallel to the Alaskan coastline into Barrow Canyon (Coachman et al., 1975), and through the Central Channel across the mid-shelf between Herald and Hanna Shoals (Weingartner et al., 2005) (Fig. 1). Flow across the shelf is highly variable and can be modified by local winds and other fluctuations, with particularly strong northerly winds capable of reversing the transport for periods of days to weeks (Coachman and Aagaard, 1981; Weingartner et al., 2005; Woodgate et al., 2005a, b; Danielson et al., 2014, 2017). Flow exits the Chukchi shelf through Barrow Canyon in the east (Coachman et al., 1975; Weingartner et al., 2005) or Herald Canyon in the west (Coachman et al., 1975; Pickart

et al., 2010). Water exiting through Barrow Canyon flows either westward along the Chukchi shelf break as the Chukchi Slope Current (Corlett and Pickart, 2017), or eastward into the Beaufort Sea along the shelf break and slope (Pickart, 2004). Low-salinity waters associated with river outflow and solar heating are transported northward during the summer and fall by the seasonal Alaska Coastal Current (ACC, Coachman et al., 1975). The water column cools to near freezing temperatures in the late fall and early winter and remains near the freezing point until late spring and early summer, when increasing solar radiation and the inflow of warmer water from the Bering Sea leads to rapid warming, melting of sea ice, and increased river discharge (Weingartner et al., 2005; Danielson et al., 2017, 2020a).

Fig. 1. Map of typical flow pathways of the northern Bering Sea, Chukchi Sea, and western

Beaufort Sea based on Danielson et al. (2020a) with water bodies and place names. Persistent

currents are shown with solid arrows; intermittent or poorly known flows are shown with dashed

arrows. KS denotes Kotzebue Sound and HV denotes Hope Valley. Depth isopleths are contoured with thin black lines at 25, 70, 100, and 200 m.

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Building on previous modeling efforts for walleye pollock (*Gadus chalcogrammus*) in the eastern Bering Sea (Petrik et al., 2015, 2016) and using an ocean circulation model for the Arctic region, we developed biophysical transport models parameterized for larval and early juvenile stages of polar cod and saffron cod. These models were used to simulate the growth and dispersal of their ELS in the northern Bering, Chukchi, and Beaufort seas to identify possible spawning locations, which are currently largely unknown, as well as examine connectivity between these regions. Several behavior scenarios were tested and modeled distributions were compared to known summer distributions of larvae and early juveniles from acoustic-trawl surveys conducted in 2012 and 2013 in the northern Bering and Chukchi seas. Selected behavior scenarios were then used to model their growth and dispersal from 2004 – 2015 to assess interannual variability relative to oceanographic and atmospheric conditions. In addition to providing important information about potential spawning areas and nursery habitats of polar cod and saffron cod, this research helps establish whether observed aggregations of larvae and early juveniles are likely to be retained in the Chukchi Sea, contributing primarily to local populations, or if they are likely to be transported from the northern Chukchi Sea into the Beaufort Sea, thereby serving as a source population for gadids in the Beaufort Sea. This research also provides valuable information about the growth and dispersal of Arctic gadids under variable climate conditions, which is important for understanding how these species respond to environmental perturbations and how their connectivity between the Chukchi and Beaufort seas may be impacted.

2. Methods

2.1. Circulation model

To realistically simulate the three-dimensional (3-D) circulation field and force the Lagrangian particle-tracking model, we used an implementation of the state-of-the-art, free-surface Regional Ocean Modeling System (ROMS; Shchepetkin and McWilliams, 2005) set up in a Pan-Arctic (PAROMS) configuration (Curchitser et al., 2013, Danielson et al., 2016, 2020b; Lovvorn et al., 2020). The domain of this coupled ocean/sea-ice numerical model spans the Arctic from the Bering Sea in the North Pacific to the North Atlantic. The horizontal resolution 170 varies from ~ 5 km south of the Aleutian Islands to ~9 km in the North Atlantic and is approximately 5.5 – 6.0 km in the Chukchi Sea. The 50-layer vertical coordinate system is based on terrain-following sigma-layers with finer resolution within the surface and bottom boundary layers. PAROMS is forced by NASA's Modern-Era Retrospective-Analysis for Research and Applications atmospheric reanalysis (Rienecker et al., 2011), with boundary conditions coming

from the Simple Ocean Data Assimilation (SODA, Carton and Giese, 2008) for 2008 and prior, and from the Hybrid Coordinate Ocean Model (HYCOM; Chassignet et al., 2009) for more recent years. Tidal forcing is provided by the Oregon State TOPEX/Poseidon Global Inverse Solution (Egbert and Erofeeva, 2002) and the sea ice field is based on the single-category Budgell ice model (Budgell, 2005). For surface fresh water flux, the model uses the method of Dai et al. (2009) south of the Yukon River and that of Whitefield et al. (2015) for the Arctic. A careful model-to-observation comparison of hindcast velocity, temperature, and salinity in the Chukchi and Beaufort seas found that the model exhibited appreciable skill in reproducing the mean velocity directions and magnitudes and the velocity variances at time scales from tidal to annual (Curchitser et al., 2013). The model also captured synoptic and seasonal temperature, salinity, and stratification variations. Offshore ice thicknesses in mid-winter were found by Curchitser et al. (2013) to generally be within 1 m of those estimated from the IceSat satellite missions (Kwok et al., 2009). Without restoring sea ice concentrations to observational data or data assimilation, the model reproduced approximately 50% of both the observed monthly and annual ice concentration anomalies (Curchitser et al., 2013). Additional model-data comparisons that demonstrate model fidelity in reproducing wind-driven SSH anomalies are provided in Danielson et al. (2020b).

Output from the PAROMS 2004 – 2015 hindcast was saved as daily averages to force the offline particle-tracking model, as described below. Specifically, the particle-tracking model used PAROMS-generated velocities, temperature, and salinity.

2.2 Particle tracking

To simulate advective transport and growth of larvae, we developed individual-based models (IBMs) for polar cod and saffron cod using the particle tracking tool TRACMASS, which calculates Lagrangian trajectories from Eulerian velocity fields (Döös, 1995). The TRACMASS model is run offline using stored daily output from PAROMS integrations, thus it is less computationally expensive and allows for more calculations of trajectories in comparison to those made online within the circulation model. TRACMASS runs on the 3-D PAROMS grid and solves the trajectory path through each grid cell with an analytical solution of a differential equation, which depends on the horizontal and vertical velocities at the grid cell walls (Döös, 1995). TRACMASS has been used in atmospheric and oceanic studies (Drijfhout et al., 2003; Döös and Engqvist, 2007), as well as for modeling the dispersal of fish and invertebrate larvae (Jacobi and Jonsson, 2011; Berglund et al., 2012; Petrik et al., 2015, 2016). The particle-tracking time step used in TRACMASS was 1 hour and sub-grid scale

turbulence was incorporated by adding a random horizontal turbulent velocity to the horizontal

velocity from PAROMS to each trajectory and each horizontal grid wall at every time step (Döös 210 and Engqvist, 2007). A horizontal diffusion value of $4 \text{ m}^2 \text{ s}^{-1}$ was used, based on the relationship between diffusion and model resolution defined in Okubo (1971). Model output of position (latitude and longitude), temperature, salinity, and larval length (see Section 2.3 below) was saved at daily intervals. In addition to particle trajectories, TRACMASS calculated surface light as a function of latitude, longitude, date, and time of day for behavior scenarios that included diel vertical migrations (DVM). While TRACMASS had impermeable boundary conditions at the coast, the incorporation of diffusion into the model allowed for beaching of simulated particles. Trajectories of particles that beached were no longer tracked in the model. Particles rebounded from ice.

We based the number of particles released for each dispersal simulation on the method described in Petrik et al. (2015). In that study, the number of particles released at each time and location (number of simulation repetitions) was determined by calculating the fraction of particles 222 at four random locations downstream of the initial start locations. The minimum number of 223 particles for which those fractions did not change appreciably was determined, with 10 particles per 10 m depth increment per spawning location deemed appropriate for producing stable results (Petrik et al., 2015). For our study, we doubled the number of particles, given that the Chukchi Sea is shallower than the Bering Sea, releasing 10 particles per 5 m depth increment at each PAROMS grid point within each release location (Table 1). Due to the lack of information available about the vertical distributions of post-hatch polar cod and saffron cod larvae in the water column at the time of this study, simulated larvae were released every 5 m from the surface to the bottom. Since saffron cod spawn in close proximity to the bottom (Chen et al., 2008) and their eggs are demersal and adhesive (Berg, 1949; Wolotira, 1985), spawning and hatching locations were assumed to be identical, with dispersal simulations reflecting dispersal from their spawning grounds. For the initial simulations, the minimum and maximum number of particles released were 15,480 and 289,220, respectively, for a total of 623,510 particles released across all locations on each simulation date (Table 1).

Table 1. Hypothesized spawning and/or hatching areas of polar cod (*Boreogadus saida*) and

saffron cod (*Eleginus gracilis*), region, number of PAROMS grid points, and number of particles

released for each dispersal simulation.

2.3. Biological model

2.3.1. Growth

Temperature-dependent growth rates have recently been estimated for larval polar cod and saffron cod in the laboratory (Koenker et al., 2018; Laurel et al., 2018; B. Laurel, National Oceanic and Atmospheric Administration (NOAA), unpublished results). These data provide the information necessary for parameterizing models such as the one presented in this study and provide temperature-dependent growth and developmental rates from the newly hatched larvae to ~25 mm for polar cod and 10 mm for saffron cod. All growth models were based on food 'unlimited' scenarios.

2.3.1.1. Polar cod

Egg stage: Despite the availability of a temperature-dependent equation for egg development, simulations were initialized at the time of hatching due to uncertainties about where in the water column polar cod eggs occur (e.g., whether they are frozen into the sea ice (Yudanov, 1976) or float at the ice-water interface) and uncertainties about the ability of the PAROMS model to accurately capture small-scale under-ice flow dynamics. Currently, sea ice in PAROMS is modeled as a flat-bottomed surface; however, sea ice is a complex surface that can vary dramatically across even short distances, with ice keels in the Chukchi Sea regularly exceeding 261 20 m in depth (Hauri et al., 2018). Thus, in an attempt to minimize uncertainties in drift trajectories and ensure more realistic growth and transport of ELS, simulations were restricted to the post-hatch period.

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317 \t\t\t Growth (mm day-1) = 0.0902 * log(T) - 0.0147
$$

 Fig. 2. Temperature-dependent growth rates (in mm day⁻¹) used to model growth of (a) polar cod (*Boreogadus saida*) and (b) saffron cod (*Eleginus gracilis*) early life stages in the individual-322 based models (IBMs). Growth rates for polar cod yolksac (hatch -10 m) and feeding ($10-25$ mm) larvae in the model were based on those derived in Koenker et al. (2018), while early

juvenile growth (25 – 45 mm) was based on Laurel et al. (2017). The growth rate for saffron cod yolksac larvae (hatch to 10 mm) was based on unpublished data (B. Laurel, NOAA). For growth of saffron cod preflexion larvae to early juveniles (10 – 45 mm), the walleye pollock (*Gadus chalcogrammus*) growth model described in Porter and Bailey (2007) was used, as a saffron cod-specific growth model for larger sizes is not available and walleye pollock exhibit similar growth (B. Laurel, NOAA, personal communication).

2.3.2. Vertical behavior

Vertical behaviors selected for polar cod were based on values obtained from the literature (Borkin et al., 1986; Bouchard et al., 2016) and from laboratory observations (B. Laurel, NOAA, unpublished results). Similar behaviors were used for the saffron cod simulations, as no information on the vertical distribution of saffron cod larvae is currently available. Five different vertical behavior scenarios were developed and tested: (1) passive (neutrally buoyant) individuals at all stages; (2) surface-oriented individuals such that all stages move to the middle of the 10-m surface layer at 5 m; (3) passive yolksac larvae where older stages move progressively deeper in 339 the water column: preflexion/flexion larvae $(5 - 10 \text{ m})$, transformation $(10 - 15 \text{ m})$ and early juveniles (20 m); (4) surface-oriented yolksac larvae and older individuals that move progressively deeper in the water column; and (5) surface-oriented yolksac larvae and transformation and early juvenile stages that make diel vertical migrations (DVMs) to the middle of the surface layer (5 m) at night (Table 2). For DVM, day was defined as times when surface light was greater than zero.

Table 2. Model parameters for different behaviors tested for polar cod (*Boreogadus saida*) and saffron cod (*Eleginus gracilis*). Passive = passive (neutrally buoyant) individuals of all stages; Surface = surface-oriented individuals of all stages; Passive & ontogeny = passive yolksac and 349 preflexion larvae with late larvae and early juveniles moving deeper with ontogeny; Surface & ontogeny = surface-oriented yolksac and preflexion larvae with late larvae and juveniles moving deeper with ontogeny; DVM = surface-oriented yolksac and preflexion larvae with late larvae and early juveniles making diel vertical migrations (DVMs) between specified depths during the day, and 5 m during the night. *wmax* = maximum vertical swimming speed, nb =neutrally buoyant, trans = transformation, early juv. = early juvenile.

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358 Vertical swimming speed (*w*) was parameterized for both polar cod and saffron cod as:

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360 $w = w_{max} * (-tanh(0.2 * (z - z_{pref})))$

 $W_{max} = 0.3 * L_{larya} * 10^{-3}$ where *Llarva* is larval length (mm). The swimming speed of fish larvae is often overestimated in IBMs (Peck et al., 2006); therefore, we chose a maximum speed of 0.3 body-lengths s⁻¹ as a conservative estimate for sustained swimming. This value aligns well with that used to model polar cod growth in the Greenland Sea and Baffin Bay (Thanassekos and Fortier, 2012) and is comparable to swimming speeds used in studies of Atlantic cod (*Gadus morhua*) larvae (Sundby and Fossum, 1990; Björnsson, 1993; Vikebø et al., 2007). **2.4. Simulations 2.4.1. Release locations and hatch dates** Larvae were released from several hypothesized hatching locations based on information from a review of the literature, anecdotal evidence, and known areas of retention in the region (Craig et al., 1982; Wolotira, 1985; Sunnanå and Christiansen, 1997; A. Whiting, Native Village of Kotzebue, personal communication). In total, nine locations were selected from which to initialize the dispersal simulations: the Gulf of Anadyr, St. Lawrence Island, Norton Sound, Bering Strait, Chukotka Peninsula, Kotzebue Sound, Cape Lisburne, Hanna Shoal, and Barrow Canyon (Table 1). Ellipses were created around the hypothesized hatching locations (Fig. 3) using ArcGIS 10.4 (ESRI, 2017) and simulations were initialized from all PAROMS grid points falling within each ellipse. Points on land were excluded.

where *z* is depth (m), *zpref*(m) is the preferred depth (middle of depth range or day-time/night-time

363 preferred depths), and the maximum vertical swimming speed, w_{max} (m s⁻¹), is

Fig. 3. Map of polar cod (*Boreogadus saida*) and saffron cod (*Eleginus gracilis*) hypothesized spawning and/or hatching locations used to develop the biophysical transport models. All 9 locations were used for the initial dispersal simulations to select plausible release locations. Areas highlighted in red were used to test 5 different behavior scenarios against 2012 and 2013 Arctic Ecosystem Integrated Survey acoustic-trawl survey observations. Simulations for 2004 through 2015 were initiated from the Bering Strait and Chukotka Peninsula locations for polar cod, and the Bering Strait and Kotzebue Sound locations for saffron cod.

In other Arctic seas, peak hatching of polar cod eggs occurs in May and June (Yudanov, 1976; Bouchard and Fortier, 2008), though it can occur as early as December and January in regions warmed by large inputs of fresh water and as late as August in colder regions (Bouchard and Fortier, 2011). In the Chukchi Sea, hatching can occur as late as July (Wyllie-Echeverria et al., 1997). Initial particle releases were based on a hatch date calculated from the midpoint of when polar cod were encountered in the Chukchi Sea portion of the Arctic Eis survey in 2013. The approximate hatch date was estimated by back-calculating from the average length of age-0 402 polar cod observed in the survey $(\sim 35.2 \text{ mm})$ using the regression of length on hatch date in Bouchard and Fortier (2011). This method resulted in an estimated hatch date of Julian day 72.5 (± 31.5 days SD), with most larvae hatching around early to mid-March (Marsh et al., 2019). Initially, simulated larvae hatched every two weeks from 15 February through 15 May, for a total of 7 hatching events in each year. Simulations were conducted separately for each release location and each hatch date. Results from the initial simulations suggested that larvae did not have sufficient time to achieve the lengths observed in the field, therefore, hatch dates were 409 expanded to include the 1st and 15th day of each month from 1 January through 15 May for a total of 10 polar cod hatching events in each year. This range of hatch dates was also supported by otolith-derived ages of polar cod collected during the Arctic Eis survey (Z. Chapman, University of Alaska Fairbanks, personal communication) and allowed simulated fish lengths to better match field observations. The same range of hatch dates was used for the saffron cod simulations.

2.4.2. Particle tracking

Particle trajectories were tracked forward in time. While tracking particles backward in time can be used to identify potential source locations (e.g., Christensen et al., 2007; Calò et al., 2018), processes such as physical diffusion are not reversible in time (Batchelder, 2006). Backtracking can be complicated by ontogenetic development and the active behavior of larvae due to the stochastic and nonlinear nature of these processes (Christensen et al., 2007). Backtracking may be more suitable for short-duration simulations, but is less effective in shallow, 422 nearshore regions with strong flow–bathymetry interactions (Batchelder, 2006, Bauer et al., 2013). Although inefficient and computationally expensive (Batchelder, 2006; Christensen et al., 424 2007), tracking particles forward in time can be used to evaluate retention in suitable areas, transport to nursery grounds, or loss to unfavorable habitats (Christensen et al., 2007). Given the shallow Chukchi shelf (~ 50 m deep), the long drift duration (see Section 2.4.3. below), and the incorporation of diffusion and behavior in our simulations, backtracking was not implemented. The feasibility of tracking fish larvae backwards from observed distributions for several months was uncertain and may have resulted in overly broad distributions. Furthermore, backtracking in TRACMASS did not allow for active behavior of the particles at the time of publication.

2.4.3. Duration of simulated drift

Growth and dispersal of larvae were simulated until 1 September, the midpoint of the Arctic Eis survey, so that the simulated distribution and size composition during summer could be compared to the observed distributions and size compositions in the 2012 and 2013 Arctic Eis acoustic-trawl surveys. Polar cod and saffron cod transition from pelagic juveniles to more demersally-oriented juveniles at approximately 35 – 45 mm (ICES CM, 1988) and between 39 – 60 mm (Wolotira, 1985), respectively, with enhanced swimming abilities that are difficult to capture in an IBM, thus fish larger than 45 mm in length were excluded from further analysis.

2.5. Data-model comparison with acoustic-trawl surveys

We used data on the abundance and length composition of larval (preflexion and flexion) and early juvenile polar cod and saffron cod (to 45 mm in length) from acoustic-trawl surveys conducted in the Chukchi Sea as part of the Arctic Eis program (Mueter et al., 2017) to compare with results from the IBMs developed in this study. In late summer 2012 and 2013, the Arctic Eis program conducted comprehensive ecosystem surveys of the U.S. northern Bering Sea and Chukchi Sea shelves (Mueter et al., 2017). Surveys began on 7 August in both years and progressed northward from Bering Strait along designated transects until reaching the Chukchi shelf break by the first week of September, after which sampling recommenced in Bering Strait and progressed southward to 60°N until the last week of September. Acoustic-trawl methods were used to estimate the abundance and distribution of pelagic organisms in the northern Bering and Chukchi seas (see De Robertis et al., 2017a, b for further details), and provide the best available information about the late summer distributions of age-0 polar cod and saffron cod in the region. The size and species composition of acoustic scatterers were estimated from a combination of surface trawls conducted at pre-determined stations and midwater trawls conducted in areas of high backscatter to convert the measurements of acoustic backscatter into animal abundances. A large Cantrawl rope trawl was used for all surface trawls and for midwater trawls in 2012, while a smaller modified-Marinovich trawl was used for midwater sampling in 2013. In 2013, a series of paired midwater trawls were conducted with the Cantrawl and modified-Marinovich trawls to determine the relative selectivity of the two gear types (De 461 Robertis et al., 2017a). Selectivity-adjusted estimates of abundance (fish $m²$) for 10-mm size classes of polar cod and saffron cod ranging from 5 – 305 mm in length were calculated along the acoustic track.

Field distributions of polar cod and saffron cod were compared to simulated distributions by overlaying a 30- x 30-km grid over the 2012 and 2013 Arctic Eis acoustic-trawl survey areas

466 (Fig. S1) in ArcGIS (ESRI, 2017). Survey abundance estimates of fish \leq 45 mm in length (all size classes ≤ 45 mm in length) were aggregated to each grid cell that overlapped with the survey area in each year. The aggregated abundance estimate for each cell was divided by the total survey 469 abundance to get the proportion of the survey observations of fish ≤ 45 mm in length occurring in each grid cell. A similar process was used to determine the proportion of the simulated larvae falling within each survey grid cell for each release location and each hatch date. The locations of 472 simulated polar cod and saffron cod \leq 45 mm in length at the end of the simulation (1 September) were plotted and only those that overlapped with the survey grid cells were included in the analysis. The proportion of the simulated distribution that fell within each survey grid cell was 475 calculated by dividing the number of simulated fish \leq 45 mm in length occurring in each grid cell by the total number of simulated fish falling within the survey area. Note that we chose to analyze release locations and hatch dates separately, as aggregating larval releases over space and time assumes that each release location and time contributes equally, which is almost certainly not the case as the numbers of eggs released and the survival of larvae (which was not modeled) can be expected to vary widely across time and space. While the correlations between observed and simulated particles from a particular release location and time are not expected to be high when multiple hatching events contribute to larvae observed in a given region, significant correlations - even if weak - would strongly suggest that a given release location and time may have contributed to the observed concentrations of larvae.

Initial passive particle trajectory simulations from the northern release locations (Cape Lisburne, Hanna Shoal, and Barrow Canyon) showed poor overlap with the Arctic Ecosystem Integrated Survey (Arctic Eis) acoustic-trawl survey grids (see De Robertis et al., 2017b) used to ground truth the model (see Section 2.5 below), with most particles being advected into the Beaufort Sea and Arctic Basin (Fig. S2). Similarly, particles from the Norton Sound release location had minimal overlap with the acoustic-trawl survey grid and were largely retained in the Bering Sea (Fig. S2). Therefore, subsequent simulations were initialized from the five remaining locations with greater overlap with the acoustic-trawl surveys in 2012 and 2013 (i.e., transport into or retention within the Chukchi Sea), allowing for comparisons between simulated distributions and field observations.

Correlations between simulated distributions and survey observations were calculated for each behavior scenario, spawning location, release date, and release depth using Pearson's Product Moment Correlation, for a total of 525 comparisons per species per year. Correlations were consistent across release depths and are therefore reported for the total, depth-integrated values only.

2.6. Interannual variability of simulated distributions

To examine how polar cod and saffron cod dispersal were influenced by variability in climate and oceanographic conditions, the IBMs were run for multiple years (2004 – 2015) over the full range of hatch dates from the release areas that produced the strongest correlations between observed and simulated distributions in 2012 and/or 2013. As simulations with surface-oriented behavior showed the strongest correlations between observed and simulated distributions for both species, this behaviour scenario was used to model polar cod and saffron cod dispersal between 2004 and 2015.

Simulated distributions on 1 September from 2004 – 2015 were compared using a center of gravity (COG) analysis in the R package SDMTools (R Core Team, 2018). Inertia, or the dispersion of simulated particles around the COG (Woillez et al., 2009), was calculated for each year, along with the standard deviations around the major and minor axes. This was done to test for trends in spatial dispersion, which may reflect changes in oceanographic and atmospheric circulation. For example, volume flow through Bering Strait has shown a strong, increasing trend over recent years (Woodgate et al., 2015; Woodgate, 2018). Geographic coordinates (latitude, longitude) were converted to projected coordinates using the North Pole Lambert Azimuthal Equal Area (LAEA) Alaska projection (EPSG: 3572, https://epsg.io/3572, accessed 16 September, 2019) prior to the inertia calculation to minimize the distortion in lengths, areas, and angles at the poles (Skopeliti and Tsoulos, 2013).

2.7. Correlations with climate indices

To examine how larval growth and connectivity may change under variable climate forcing, we developed COG indices from the simulation output. Anomalies were calculated as deviations from the mean latitude and longitude values for the 2004 – 2015 period normalized by the standard deviation. Larval indices were then compared to several climate indices thought to influence circulation in the Bering and Chukchi seas (Fig. S3). The large-scale climatic indices selected were the winter (December – February) Arctic Oscillation (AO) index, which represents 528 the first empirical orthogonal function (EOF) pattern of sea level pressure (SLP) from $20 - 90^{\circ}N$ regressed to the SLP anomaly time series (Thompson and Wallace, 1998); the Arctic Dipole (AD) index, which is the first EOF pattern of 70 – 90°N regressed to the SLP anomaly time series (Wu et al., 2006); and the Siberian-Alaskan (SA) index, which provides a measure of atmospheric circulation based on a correlation between sea ice cover and the 700 hPa geopotential height gradient between Siberia and Alaska, that can be used to estimate thermal conditions in the

Bering Sea and ice cover extent (Overland et al., 2002). All indices were obtained from NOAA's Bering Climate website (https://www.beringclimate.noaa.gov/data/index.php, accessed 6 June, 2019).

An index representing ice extent and timing of retreat (IER) was developed for 2005 – 2015 based on the findings of Okkonen et al. (2019), where sea ice areal extent and concentration from April 1 through the third week of August were compared to late August water masses encountered during surveys in Barrow Canyon. Okkonen et al. (2019) found that greater daily sea ice extents and slower/later sea ice retreats occurred in years when the August late season meltwater (LMW) volumes in Barrow Canyon were greater than the 2005–2015 mean (2006, 2008, 2009, and 2012–2014; IER index = 1 in this study), while smaller daily sea ice extents and faster/earlier sea ice retreats occurred in years when August LMW volumes were less than the 2005–2015 mean (2005, 2007, 2010, 2011, and 2015; IER index = 0 in this study).

Correlations between the annual climate indices and the annual COG anomalies between 2004 and 2015 from the selected spawning/hatching areas were calculated for all hatch dates using Pearson's Product Moment Correlation. Correlations with the SA index were calculated for 2004 – 2013, as data beyond 2013 were not available. Similarly, correlations with the IER index were only calculated for 2005 – 2015, as 2004 data were not available. All statistical analyses were carried out in R (R Core Team, 2018).

3. Results

We found variations in simulated lengths-at-age between hatching areas and hatch dates for both polar cod and saffron cod. Overall, polar cod larvae that hatched from more southerly locations (Gulf of Anadyr, St. Lawrence Island), attained a greater length at the end of the simulation than those originating from the more northerly hatching locations (Fig. 4 a, b). This difference was more apparent in larvae hatched earlier in the year compared to those that hatched at later dates. Differences in length were also evident between years, with more variability in both simulated and observed polar cod lengths in 2013 compared to 2012 (Fig. 4 a, b). Saffron cod were much smaller in size at the end of the simulation than polar cod (Fig. 4) due to faster growth of polar cod at low temperatures (Fig. 2). While saffron cod lengths differed between southerly and northerly hatching locations, the difference was not as great as that found for polar cod, again, likely due to slower growth of saffron cod at low temperatures. The difference in length remained fairly consistent across hatch dates in 2012, but was less apparent in 2013 (Fig. 4 c, d). Despite some overlap, simulated sizes based on lab-derived growth were smaller than the sizes

observed in the Arctic Eis acoustic-trawl survey (Fig. 4). This overlap was much greater for polar cod and nearly absent for saffron cod (Fig. 4).

Fig. 4. Simulated lengths of (a, b) polar cod (*Boreogadus saida*) and (c, d) saffron cod (*Eleginus gracilis*) larvae and early juveniles ≤ 45 mm in length located within the Arctic Ecosystem Integrated Survey acoustic-trawl survey area on 1 September (a, c) 2012 and (b, d) 2013. Simulations were initiated from five hypothesized areas on 10 hatch dates. Data presented are from simulations with surface-oriented behavior, which had the strongest correlations with the acoustic-trawl survey data. The dashed grey lines represent the minimum and maximum lengths estimated by the survey (to 45 mm). GA: Gulf of Anadyr; SLI: St. Lawrence Island; BS: Bering Strait; CP: Chukotka Peninsula; KS: Kotzebue Sound. The minimum, first quartile (Q1), median, third quartile (Q3), maximum, and outliers are represented.

3.1. Data-model comparison with acoustic-trawl surveys

We found distinct differences in larval distributions between the different behavior scenarios, particularly for those simulations with a passive component (Fig. S4). Behavior scenarios that included a surface component produced relatively similar distributions, especially 586 for the simulations with and without DVM for surface-oriented early larvae that moved deeper with ontogeny, which had almost identical distributions (Fig. S4, Tables 3 and 4). Simulated and observed polar cod larval distributions were not significantly correlated for any of the hatching locations in 2012, except for larvae with surface-oriented behavior that were released around

590 Bering Strait and the Chukotka Peninsula (Table 3). Significant positive correlations were also

591 found for simulations from the Chukotka Peninsula with all other behavioral scenarios except that

592 with DVM (Table 3). Earlier hatching larvae resulted in significant overlap with observed

593 distributions from the Bering Strait release location, while the correlations for the Chukotka

594 Peninsula simulations were significant across all release dates (Table 3). No significant

595 correlations were found between observed and simulated distributions of polar cod in 2013 (not

596 shown). 597

598 Table 3. Correlations between observed distributions of polar cod (*Boreogadus saida*, larvae and

599 early juveniles ≤ 45 mm in length) in the 2012 Arctic Ecosystem Integrated Survey acoustic-trawl

600 survey and simulated distributions on 1 September from 5 different behavior scenarios. Particles

601 were released at 5 locations (Gulf of Anadyr, St. Lawrence Island, Bering Strait, Chukotka

602 Peninsula, and Kotzebue Sound) on the 1st and 15th of each month from 1 January – 15 May.

603 ***p*-value < 0.05 (darker shading), *0.05 \leq *p*-value < 0.10 (lighter shading). *p* = p-value, n =

604 number of simulated larvae found within the survey grid.

605

606 607

608 For saffron cod, the simulations that produced results most similar to observed field 609 distributions in 2012 were those initiated from Bering Strait and Kotzebue Sound. Simulations initiated from Bering Strait were significantly correlated for all simulation behaviors across most simulation dates, while those initiated from Kotzebue Sound were significant across all behaviors and dates (Table 4). Early passive particle simulations from the Chukotka Peninsula (15 January – 1 March) were also marginally or significantly correlated with observations (Table 4). No significant correlations were found for other release locations. Similar to the 2012 results, most simulations in 2013 from Bering Strait and Kotzebue Sound produced distributions that were significantly correlated to observed distributions of saffron cod in the acoustic-trawl survey (not shown). For both 2012 and 2013 simulations, the majority of correlations were strongest for later release dates (Table 4 for 2012, not shown for 2013). Correlations with release depth did not reveal any patterns for either species, except for saffron cod simulations initiated in Kotzebue Sound, where correlations were significant for all release depths across all behaviors (not shown). Note that most release dates occurred in winter and spring months, when the shallow Chukchi and Bering shelf water columns exhibit relatively weak stratification. Hence, current-induced turbulent motions can readily redistribute passively floating plankton through the water column at this time of year.

Table 4. Correlations between observed distributions of saffron cod (*Eleginus gracilis*, larvae and

627 early juveniles \leq 45 mm in length) in the 2012 Arctic Ecosystem Integrated Survey acoustic-trawl

survey and simulated distributions on 1 September from 5 behavior scenarios. Particles were

released at 5 locations (Gulf of Anadyr, St. Lawrence Island, Bering Strait, Chukotka Peninsula,

and Kotzebue Sound) at bi-weekly intervals from 1 January – 15 May. ***p*-value < 0.05 (darker

631 shading), *0.05 $\leq p$ -value \leq 0.10 (lighter shading). $p = p$ -value, n = number of simulated larvae

found within the survey grid.

634

635 **3.2. Interannual variability in simulated distributions**

Large interannual variability in the COGs of simulated particles was found for polar cod, particularly for the Chukotka Peninsula release locations. The COG across simulation years (2004 – 2015) was located in the western portion of the Chukchi Sea, southwest of Herald Shoal (Fig. 5 a), similar to the centers of gravity in 2008, 2013, and 2015. For 2004 – 2006, the COGs shifted to the southwest, while that in 2012 was to the southeast (Fig. 5 a). In 2007, 2011, and 2014, particles were located further north compared to the 2004 – 2015 COG. In 2009, the COG was in the eastern portion of the Chukchi Sea, east of Herald Shoal, while in 2010, it was in the western Chukchi Sea, just south of Wrangel Island (Fig. 5 a). Most of the COGs for the Bering Strait release location were found in close proximity to Cape Lisburne, located north and south of the cape for the majority of the time series. The only exceptions were in 2005, when the COG was located near Herald Shoal, and in 2007, when it was farther north of Cape Lisburne compared to in other years (Fig. 4 a). The COGs of saffron cod released from the Bering Strait region were similar to those of polar cod and were mainly centered around Cape Lisburne (Fig. 5 b). In 2005, the COG was over Herald Shoal, while in 2007 it was located to the north of Cape Lisburne (Fig. 5 b). The COGs for particles released in Kotzebue Sound were found on the north side of the sound, located around Cape Krusenstern (Fig. 5 b), suggesting retention within Kotzebue Sound. 652

Fig. 5. Mean latitude and longitude of (a) polar cod (*Boreogadus saida*) and (b) saffron cod (*Eleginus gracilis*) larvae and early juveniles ≤ 45 mm in length on 1 September from 2004 – 2015. Simulations for polar cod were initiated from Bering Strait (green) and the Chukotka Peninsula (orange). Simulations for saffron cod were initiated from Bering Strait (green) and Kotzebue Sound (blue). Data from simulations with surface-oriented behavior are presented. Solid circles represent overall centers of gravity for 2004 – 2015, color coded to release location. Numbers in circles represent the last two digits of the simulation year. Ellipses represent particle release locations.

Polar cod inertia between 2004 and 2015 was highly variable for both the Bering Strait 665 and Chukotka Peninsula simulations (Fig. 6). Bering Strait had a mean inertia of $97,755 \text{ km}^2$ and 666 a SD of the major and minor axes of $\pm 260,074$ km² and $\pm 173,542$ km², respectively. The 667 Chukotka Peninsula had a mean inertia of 123,034 km² and a SD of the major and minor axes of \pm 668 283,059 km² and $\pm 207,150$ km², respectively. For Bering Strait releases, inertia declined 669 significantly over time (linear regression, LR: β = -5894, t_{10} = -3.129, p = 0.011), while it increased over time for simulations originating from the Chukotka Peninsula, although not 671 significantly (LR: β = 4914, t_{10} = 1.568, p = 0.148). Similar to polar cod, saffron cod inertia for 672 the Bering Strait release location was highly variable $(95,729 \pm 261,437)$ and 165,469 km²) and 673 declined significantly over time (LR: β = -5044, t_{10} = -2.611, p =0.026). Inertia for simulations

678 Fig. 6. Inertia (in km^2), which measures the dispersion of simulated particles around the center of gravity, for polar cod (*Boreogadus saida*) simulations from (a) Bering Strait and the (b) Chukotka Peninsula and saffron cod (*Eleginus gracilis*) simulations from (c) Bering Strait and (d) Kotzebue Sound from 2004 – 2015. Data from simulations with surface-oriented behavior are presented.

3.3. Correlations with climate indices

Significant correlations were found between latitudinal and longitudinal COG indices for both polar cod and saffron cod at the end of the simulation and several of the climate indices, although correlations were not consistent across release areas or dates (Tables 5, 6). Simulated

particles from the Bering Strait region for both species tended to have a more southern and eastern COG during years with a strong summer AD index, a weaker SA index, and more 689 extensive ice (IER index = 1). In most cases, these correlations were stronger for later release dates (March – May). Similarly, the COG of simulated polar cod released at the Chukotka Peninsula were further south and east when the summer AD and AO indices were high and ice was extensive and retreated later (IER index = 1). In contrast to Bering Strait releases, the COG of simulated particles from the Chukotka Peninsula, in particular early releases, occurred further south during years with a stronger SA index, as evidenced by negative correlations with latitude (Table 5). For saffron cod from the Kotzebue Sound release locations, environmental variability appeared to primarily affect the longitudinal COG of early releases but the latitudinal COG from later releases. Simulated particles from earlier release dates were displaced to the east during years with stronger AO and SA indices and a weaker winter AD index, all indicative of cold winters with heavy ice. Correlations with the latitudinal COG were variable and inconsistent (Table 6).

Table 5. Correlations between latitude and longitude center of gravity (COG) anomalies of

simulated polar cod (*Boreogadus saida*, larvae and early juveniles ≤ 45 mm in length) on 1

September (2004 – 2015) and selected climate indices. AD: Arctic Dipole index, MAM: March,

April, May, JJA: June, July, August; AO: Arctic Oscillation index; SA: Siberian/Alaskan index

(2004 – 2013); IER: Ice extent/retreat index (2005 – 2015). Simulations were initiated from

Bering Strait and Chukotka Peninsula release locations using surface-oriented behavior. ***p*-

value < 0.05 (darker shading), *0.05 ≤ *p*-value < 0.10 (lighter shading). Red (blue) represents a

positive (negative) correlation.

714 Table 6. Correlations between latitude and longitude center of gravity (COG) anomalies of

715 simulated saffron cod (*Eleginus gracilis*, larvae and early juveniles ≤ 45 mm in length) on 1

716 September (2004 – 2015) and selected climate indices. AD: Arctic Dipole index, MAM: March,

717 April May, JJA: June, July, August; AO: Arctic Oscillation index; SA: Siberian/Alaskan index

718 (2004 – 2013); IER: Ice extent/retreat index (2005 – 2015). Simulations were initiated from

719 Bering Strait and Chukotka Peninsula release locations using surface-oriented behavior. ***p*-

720 value < 0.05 (darker shading), *0.05 ≤ *p*-value < 0.10 (lighter shading). Red (blue) represents a

721 positive (negative) correlation.

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When the five climate indices were compared over the 2004 – 2015 period, no obvious trends were noted (Fig. S3), though the summer AD index was negative from 2004 – 2012 (Fig. S3 b) and the SA index was positive between 2004 – 2008 (Fig. S3 d). Correlations between the climate indices were not significant (Table S1).

729

730 **4. Discussion**

Results of our biophysical transport modeling study suggest that the source of aggregations of polar cod and saffron cod larvae and early juveniles observed in the Chukchi Sea during the 2012 and 2013 Arctic Eis surveys were most likely from the northern Bering Sea or the southern Chukchi Sea. In particular, Bering Strait and the Chukotka Peninsula were identified as potential spawning and/or hatching locations of polar cod. Our findings support other research that has suggested the existence of a number of nearshore, shallow spawning grounds in the North American and Siberian Arctic (Craig et al., 1982; Thanassekos and Fortier, 2012; Logerwell et al., 2015). In addition, our results align well with those of Ponomarenko (1968) and Sunnanå and Christiansen (1997), which suggested that polar cod spawn in the northern Bering and southern Chukchi seas. For saffron cod, simulations that produced results most similar to observed field distributions were those initiated from Bering Strait and Kotzebue Sound. Saffron cod are

believed to spawn demersally under ice in shallow, nearshore areas (Morrow, 1980; Fechhelm et al., 1985; Wolotira, 1985; Johnson, 1995; Mecklenburg et al., 2002) and our results are supported by observations of saffron cod in spawning condition in nearshore areas along the coast, such as Kotzebue Sound (A. Whiting, Native Village of Kotzebue, personal communication). Strong and consistent correlations between field observations and modeled distributions across several behaviors and over a wide range of dates lends further support to the hypothesis that Kotzebue Sound is an important spawning habitat for saffron cod. Furthermore, correlations between simulated and observed saffron cod distributions were strongest from early April to mid-May. These results match well with the timing of peak hatching for saffron cod, which occurs in April and May, prior to the warming of coastal waters in the Arctic and northern Pacific (Wolotira, 1985).

Simulated distributions and sizes of polar cod overlapped with those estimated by the Arctic Eis program's acoustic-trawl survey in 2012, yet there was poor overlap in 2013, as evidenced by the lack of significant correlations with any of the release locations or dates in that year. A comparison of particle locations on 1 September showed strong variability in dispersal patterns between the two years, with reduced overlap of particles with the Arctic Eis survey grid in 2013 (18.72%) compared to 2012 (22.05%)(Fig. S1). In 2012, simulated particles on the Chukchi Shelf were concentrated along the Central Channel or the Western Pathway towards Herald Canyon. Additional concentrations were found along the Alaskan coastline and formed a thick band between Herald and Hanna shoals, which extended eastward towards the coast between Icy Cape and Wainwright, and towards the head of Barrow Canyon (Fig. S1). High concentrations of simulated larvae in this region are in agreement with other studies that have noted high abundances of polar cod ELS in the northern Chukchi Sea offshore of Wainwright (De Robertis et al., 2017b; Vestfals et al., 2019; Deary et al., in review). In contrast, simulated polar cod in 2013 were mainly distributed outside of the Arctic Eis survey grid (Fig. S1) and found mostly outside of the areas of the shelf that were occupied in 2012. There were some similarities between the two years, mainly along the Alaskan coastline and in the region between Herald and Hanna shoals, towards Icy Cape and Wainwright, although the band in 2013 was narrower (Fig. S5 – S6). Higher concentrations of simulated larvae and early juveniles were found in the western portion of the Chukchi Sea in 2013, along the Chukotka Peninsula and in Long Strait, with additional particles taking a more westward route towards Herald Canyon, over the northern Chukchi shelf, and across the shelf break compared to 2012. While the majority of particles (81.27%) were outside of the Arctic Eis survey area in 2013, limited ichthyoplankton sampling in the western and northern Chukchi Sea in 2004, 2009, and 2012 during the Russian-American

Long-Term Census of the Arctic (RUSALCA) program encountered high abundances of polar cod larvae and early juveniles in these areas, and as far west as the East Siberian Sea (Norcross et al., 2006; Vestfals et al., 2019; M. Busby, NOAA, unpublished results).

Simulated distributions of saffron cod from the Bering Strait release location were similar to those of polar cod (Fig. S7). Given that the starting locations and behavior scenarios were identical between species, the distributional differences can be attributed to the different temperature-dependent growth rates used for each species in the IBMs. As fish grow, changes in body length affect their swimming speed. This, in turn, affects their vertical position in the water column, and ultimately, the horizontal transport of their ELS through exposure to different flow schemes (Vikebø et al., 2005; Fiksen et al., 2007; Leis, 2007). Here, the slower growth rates of saffron cod would result in individuals being located in the surface layer for longer in comparison to polar cod. Particles from simulations initiated in Kotzebue Sound were consistently retained within the Sound or were advected northward along the Alaskan coastline (Fig. S8). Age-0 saffron cod are known to occupy shallow, nearshore habitats (Wolotira, 1985; Logerwell et al., 2015; De Robertis et al., 2017b) and have been found in high abundances from Kotzebue Sound to north of Cape Lisburne in late summer (De Robertis et al., 2017b; Vestfals et al., 2019). Recent surveys in the eastern Chukchi Sea in 2017 encountered high abundances of saffron cod larvae around Kotzebue Sound in late spring, though by late summer they were found in nearshore areas from northern Kotzebue Sound to around Cape Lisburne (Deary et al., in review). These findings, combined with our modeling results, suggest that saffron cod spawned in Kotzebue Sound are retained there or are transported northwards by currents to juvenile nursery habitats along the coast. Over time, fish have evolved to spawn in areas where bathymetric features and prevailing currents transport their larvae to or retain them within suitable nursery habitats (Iles and Sinclair, 1982; Bailey and Picquelle, 2002; Bailey et al., 2008; Duffy-Anderson et al., 2013). Satellite tracked drifters with near-surface drogues (Danielson and Whiting, 2016) and numerical modeling (Panteleev et al., 2013) show that a gyre forms in Kotzebue Sound, which was also evident in the PAROMS model output. Hence, the circulation in and around Kotzebue Sound may be especially conducive to larval retention and/or delivery to juvenile nursery habitats. The retentive nature of Kotzebue Sound is also supported by the results of our analyses, which showed COGs that were consistently located in northern Kotzebue Sound (Fig. 5 b), along with low inertia over the time series (Fig. 6 d).

The strong year-to-year variability in simulated distributions of polar cod and saffron cod suggests that transport of their early life stages is highly sensitive to variations in flow across the Chukchi shelf. Only simulations from Kotzebue Sound showed relatively consistent dispersal

patterns between years. Observed differences in simulated particle distributions across the broader Chukchi Shelf in 2012 and 2013 can be linked to differences in oceanographic and atmospheric conditions between the two years. In 2013, persistent northeasterly winds in late summer led to flow reversals over much of the northeast Chukchi Sea, which limited the northward extent of the ACC and advected Arctic waters onto the Chukchi Shelf via Barrow Canyon (Danielson et al., 2017). This is consistent with simulated particles following a more westward pathway along the shelf in 2013, compared to 2012 (Fig. S1). The inflow of Pacific waters through Bering Strait is bathymetrically steered along either Herald Canyon, the Central Channel, or along the Alaskan coast; however, this inflow can be driven towards the western 819 portion of the shelf during periods with easterly winds (Windsor and Chapman, 2004). Similarly, 820 Bond et al. (2018) described a stronger than normal flow pattern through Bering Strait, where a disproportionate portion of the flow travels northwest toward and beyond Wrangel Island rather 822 than joining the ACC, which they linked to anomalous winds from the east-northeast. Indeed, winds were more persistent from the northeast and annual transport through Bering Strait was 824 higher in 2013 (\sim 1.1 Sv) compared to 2012 (\sim 0.7 Sv) (Woodgate et al., 2015).

One curious aspect of the modeled larval aggregations was that they appeared to aggregate in long banded arrangements stretching from the Barrow Canyon region in the NE Chukchi Sea across the shelf toward the west. Examination of the model hydrographic fields in 2012 (Fig. S9) revealed that the larvae were accumulating in the vicinity of the ice-edge frontal zone (Fig. S9 a), which is delineated by a change of density (salinity (Fig. S9 e) and temperature (Fig. S9 c)) from the open water zone south of the marginal ice zone to under the pack ice. Recent investigations into the hydrographic structure associated with ice edge fronts and the melting of ice on the Chukchi shelf has revealed convergent zones associated with the ice and thermohaline fields (Lu et al., 2020a; 2020b). These frontal zones can extend several meters (up to 15 m) below the surface and likely provide enhanced feeding opportunities for surface-oriented larvae and early juveniles by maintaining them in close proximity to the ice edge, where they can take advantage of copepod production fueled by ice-edge phytoplankton blooms (Søreide et al., 2010; 837 Perrette et al., 2011), as well as the higher concentrations of food particles that tend to accumulate in convergent frontal zones (Bakun, 2006). For surface-oriented larvae, these frontal zones may act as a barrier to northward advection, however, this may not be the case for species that live at or migrate to depths below the vertical extent of the frontal zone. Much work remains to be done to determine to what extent polar cod larvae in the field are actually subject to the influences of 842 the convergent ice-edge fronts, but the combination of our work and the ice edge modeling study

raises many interesting questions, provides new testable hypotheses, and provides new ways to think about the early life stages of polar cod and other Arctic species.

Correlations between location indices derived from the simulation output and several 846 climate indices provide evidence that dispersal of polar cod and saffron cod ELS are likely sensitive to environmental forcing. During periods that were characterized by colder conditions in 848 the Pacific Arctic (i.e., a positive AO index, with a strong jet stream that retains cold air over the 849 polar region (Thompson and Wallace, 2000); a negative AD index, where more sea-ice remains in the western Arctic (Watanabe et al., 2006; Wu et al., 2006); a positive SA index, with anomalously strong northwesterly winds and heavy ice cover (Fang and Wallace 1994; Overland et al., 2002); and a greater ice extent and later ice retreat (Okkonen et al., 2019)), cod ELS were found farther south and east compared to periods that represented warmer conditions in the region. The findings of our study have important implications for polar cod and saffron cod connectivity between the Chukchi and Beaufort seas. Our results suggest that in warmer years with greater Pacific inflow and an earlier sea-ice retreat (e.g., 2005, 2010, and 2011 in Figs. S5 – S8), a higher proportion of larvae spawned in the northern Bering or southern Chukchi seas would be transported northwestward towards Herald Canyon and across the northern Chukchi shelf (see Okkonen et al., 2019, their Fig. 6B), which would result in a greater contribution to 860 populations in the northern Chukchi and western Beaufort seas. In contrast, during colder years with reduced Pacific inflow and a later ice retreat (e.g., 2006, 2009, and 2012 in Figs. S5 – S8), larvae would be advected along the ice edge towards the Alaskan coast, with a greater proportion of the population retained in the eastern Chukchi Sea (see Okkonen et al., 2019, their Fig. 6A). The timing and pattern of sea-ice retreat across the Chukchi shelf has been linked to the strength of the Pacific-Arctic pressure head, which is influenced by the strength and location of the 866 Beaufort Sea High pressure cell and its associated winds (Danielson et al., 2014; Okkonen et al., 2019). A stronger Pacific-Arctic pressure head (i.e., 2005, 2007, 2009, 2011, and 2015) was associated with greater northward volume and property fluxes along the Alaskan coast (i.e. a stronger Alaska Coastal Current), which promoted earlier ice retreat across the eastern Chukchi shelf (Okkonen et al., 2019). In contrast, a weaker pressure head (i.e., 2006, 2008, 2010, 2012 – 871 2014) was associated with lower volume and property fluxes along the Alaskan coast and slower, less directionally-biased ice retreat across the Chukchi shelf (Okkonen et al., 2019). Similarly, Luchin and Panteleev (2014) found that during warm years, the inflow of Pacific water through Bering Strait spread widely along the Siberian coast, with extensive transport through Herald Channel. In cold years, however, the inflow of warm Pacific water was reduced and mostly flowed along the Alaskan coast before exiting the shelf through Barrow Canyon. Thus, as

continued Arctic warming further impacts sea-ice extent and timing of sea ice retreat in the Chukchi Sea, we anticipate that polar cod and saffron cod ELS will be affected by concomitant changes in flow across the shelf, which will likely affect population connectivity between the northern Bering, Chukchi and Beaufort seas.

Simulations that produced saffron cod distributions most similar to Arctic Eis field observations were those initiated from Bering Strait and Kotzebue Sound, particularly those with a passive component. This result was not surprising, as saffron cod larvae grow slowly at low temperatures and as such, their dispersal is more likely to be affected by currents than by their behavior. However, larvae are not passive particles that drift along with currents and even first-feeding larvae have the ability to control temperature, salinity, light, turbulence and food concentrations by migrating vertically, which in turn contributes to their horizontal movement (Norcross and Shaw, 1984; Boehlert and Mundy, 1988; Hare and Govoni, 2005; Hurst et al., 2009). Late-stage larvae and pelagic juveniles have also been shown to have considerable control 890 over their speed, direction, and position in the water column (Olla et al., 1996; Leis and Carson-Ewart, 1997, 1999). Even slight differences in behavior can have long-term and large-scale consequences, since vertical positioning influences the drift trajectory of the larva, and thereby the physical environment it experiences along the way (Vikebø et al., 2007). Our simulation results showed that behavior did indeed have a strong effect on larval dispersal (Fig. S4, Tables 3 and 4). While detailed information about the vertical distribution of saffron cod larvae is not currently available, newly hatched larvae spend between 2–3 months as plankton before descending to the bottom in mid-summer, between 39 and 56 mm in length in the Pacific and 55 and 60 mm in the Arctic (Wolotira, 1985); larger age-0 fish can still be found in surface waters in late summer (Eisner et al., 2012). Similarly, polar cod larvae have been shown to be surface-oriented in the first few months of life (Spencer et al., 2020; B. Laurel, unpublished results), moving deeper as they develop (Borkin et al., 1986), with pelagic juveniles descending deeper in the water column in late summer, between 30 and 55 mm in length (Matarese et al., 1989; Ponomarenko, 2000; Bouchard and Fortier, 2011). Recent repeat acoustic surveys in the eastern Chukchi Sea from mid- to late-summer in 2019 indicated that age-0 polar cod moved deeper in the water column and underwent DVM as the season progressed (Levine et al., 2020). While these data were not available at the time of our study, this behavior was considered in our preliminary simulations, as previous research has shown that polar cod undergo DVM in other areas of the Arctic (Borkin et al., 1986; Bouchard et al., 2016). However, the sizes at which fish begin their DVM and the depths to which they migrate had to be estimated for the Chukchi Sea, which is shallower (< 40 m) than the other regions where DVM behavior has been observed. We

ultimately chose the surface-oriented behavior to model growth and dispersal from 2004 – 2005, as this behavior was most strongly correlated with observed distributions in the field, though the overall results and conclusions were similar when based on the more complex surface-oriented behavior for early larval stages that moved deeper with ontogeny (C. Vestfals, unpublished results). The new information provided by the repeat acoustic surveys on the depth distribution of 916 polar cod ELS, the sizes at which they begin to vertically migrate, and the depths to which they migrate (Levine et al., 2020) will be invaluable to future modeling efforts in the Chukchi Sea.

While climate-driven changes in advective transport and mixing will affect the dispersal and ultimately the distribution of larvae, the temperatures they experience during the drift period will, in turn affect their growth rates and their survival (Vikebø et al., 2005, 2007). We found differences in simulated lengths on 1 September between release locations, hatch dates, and species. The greater lengths attained by larvae hatching in southern locations can be attributed to warmer temperatures in the Bering Sea, in general, which results in faster growth of larvae hatching there compared to the Chukchi Sea. In spring, solar heating and the inflow of warmer water from the Bering Sea leads to rapid warming in the Chukchi Sea. Thus, the temperature conditions experienced by larvae hatching at later dates are more similar between regions compared to those hatching during the winter months. While polar cod simulated lengths aligned 928 fairly well with fish ≤ 45 mm in length observed in the Arctic Eis acoustic-trawl survey, those for saffron cod did not, with much smaller simulated sizes than field estimates. The differences in simulated sizes between species result from assuming higher growth rates at lower temperatures for polar cod compared to saffron cod based on laboratory studies (Laurel et al., 2016; B. Laurel, unpublished results). The difference between observed and simulated lengths for saffron cod could have resulted from incorrectly specified growth in the IBM, incorrect temperatures in the model, strong size-selective mortality, incorrect assumptions about hatch dates, or other factors. It should be emphasized that the final estimates of acoustic-trawl survey abundance at length were sensitive to the selectivity parameters used in the calculations, particularly for the smallest size classes, which are poorly retained by the trawls (De Robertis et al., 2017a, b). In particular, 2012 938 abundance estimates for fish \leq 25 mm in length were effectively zero for both species across the entire survey region, which was most certainly due to the ineffectiveness of the Cantrawl gear at catching these smaller-sized fish, rather than a lack of presence of these sizes over the eastern Chukchi shelf. While use of the modified Marinovich trawl in 2013 improved the abundance estimates of fish in the 15 – 25 mm range, estimated abundances of fish < 15 mm remained at zero across the entire survey region, which clearly does not reflect their true abundance and distribution. Recent studies of polar cod and saffron cod ELS in the Chukchi Sea have found the

presence of larvae < 25 mm in length in the Arctic Eis survey area during late summer (Vestfals et al., 2019; Deary et al., in review). In other regions of the Arctic, polar cod lengths in late summer can vary in size from 10 mm for fish hatched late in July, to 50 mm for young-of-the-year fish hatched early in January (Bouchard and Fortier, 2011). Thus, our simulation results for polar cod from the northern hatching locations (Bering Strait, Chukotka Peninsula, Kotzebue Sound) and saffron cod, in general, may reflect sizes in the field not captured in the acoustic-trawl survey estimates. However, our models clearly underestimated growth in both species. Field-952 based estimates of polar cod growth range from $0.27 - 0.51$ mm day⁻¹ (Bouchard and Fortier, 2011; Vestfals et al., 2019; Deary et al., in review), which are higher than the laboratory estimates 954 used in this study (0.04 – 0.46 mm day⁻¹, Koenker et al., 2018; Laurel et al., 2017), particularly for smaller polar cod larvae and those growing at lower temperatures (Fig. 2). As only the survivors of size-based predation are encountered in field samples, which selects for faster growing individuals (Bailey and Houde, 1989; Litvak and Leggett, 1992), field-based growth estimates are often higher than those derived in the laboratory because fish larvae are known to grow and survive better on natural prey (Sargent et al., 1999; Evjemo et al., 2003).

The laboratory-derived growth rates used in our model likely underestimated saffron cod growth in the field, which contributed to the smaller simulated lengths compared to the lengths estimated by the Arctic Eis acoustic-trawl surveys. Unfortunately, a growth equation for larger stages of saffron cod is not currently available and we used growth of a related gadid, walleye pollock, to model growth in the IBM. While walleye pollock ELS exhibit linear growth similar to that of saffron cod (Porter and Bailey, 2007; B. Laurel, NOAA, personal communication), some component of saffron growth was not fully captured in our model. Saffron cod may have a specific size or thermal range at which growth increases exponentially, or a particular habitat factor may influence their growth. Growth of saffron cod might be slow and constant during early development, but this could be followed by a period of rapid acceleration in growth. For example, Pacific hake (*Merluccius productus*), another North Pacific gadiform with a similar trophic role to saffron cod, grow slowly in the first 3 months of life (< 30 mm SL), after which their growth accelerates (Bailey, 1982; Bailey et al., 1982; Woodbury et al., 1995). Saffron cod may also experience faster growth in nearshore regions, with under-ice river plumes in coastal areas providing a thermal refuge for developing eggs and larvae during winter and early spring via relatively warmer freshwater runoff (Bouchard and Fortier, 2011). The solar-heated waters in Kotzebue Sound, Norton Sound, and coastal areas to the south provide a major source of the heat to the Alaska Coastal Current (Coachman et al., 1975; Ahlnäs and Garrison, 1984) and may also provide a thermal habitat conducive for optimal growth in saffron cod. Indeed, temperatures in

Kotzebue Sound in July can exceed 12°C (Ahlnäs and Garrison, 1984), which exceeds thermal optima for some gadids, but is near the temperature of maximum growth for age-0 saffron cod 981 $(T_{\text{max}} = 14.8^{\circ}\text{C})$ found in the lab (Laurel et al., 2016).

There are some limitations to using observations from the 2012 and 2013 Arctic Eis acoustic-trawl survey to validate our simulation results. The acoustic-trawl surveys were limited in their spatial extent and did not cover the inshore region or more northern areas of the Chukchi and Beaufort seas, or the Arctic Basin. Polar cod and saffron cod larvae may be present in these locations, so without further sampling, it is important not to rule out the northern locations as potential spawning or hatching areas. Results from the initial passive particle simulations showed that polar cod larvae hatching from more northern locations (Cape Lisburne, Hanna Shoal, and Barrow Canyon) were transported into nearshore regions in the northern Chukchi and Beaufort seas, as well as into the Arctic Basin. Due to the lack of overlap between simulated larval distributions and the Arctic Eis survey grids, which prevented model validation with field observations, further simulations from these hatching locations were not explored. However, these northern spawning/hatching locations in the Chukchi Sea may be a source of larvae for the Beaufort Sea and Arctic Basin. Indeed, small polar cod and saffron cod larvae corresponding to the sizes observed in our preliminary simulations from northern hatch locations (see Fig. S2) were collected in August 2008 around Barrow Canyon (Logerwell et al., 2015) and in 2017, small polar cod larvae were collected beyond the Chukchi shelf break in late summer/early fall (M. Busby, NOAA, personal communication.). High abundances of age-0 polar cod may also be present in the western portion of the Chukchi Sea outside the Arctic Eis survey area, as suggested by our simulations. This is consistent with large aggregations of age-0 polar cod along the western edge of the survey area in 2017, and to a lesser extent in 2019 (A. De Robertis, NOAA, R. Levine, UW, personal communication).

The PAROMS model used to drive the polar cod and saffron cod IBMs has been shown to resolve important oceanographic processes [e.g. mean flows and flow variances, wind-driven currents, continental shelf waves, seasonality of ice, and annual volume, heat, freshwater, and ice transport (Curchitser et al., 2013, 2018; Danielson et al., 2016; Danielson et al., 2020) and biological covariates (Rand et al., 2018; Lovvorn et al., 2020). Although PAROMS has relatively fine resolution (e.g. front-resolving and eddy-permitting) for basin-scale models covering a region as broad as the whole Arctic, it undoubtedly fails to accurately reproduce some submesoscale dynamics that could be important in the transport of polar cod and saffron cod larvae to nursery areas. Nonetheless, we believe that our polar cod and saffron cod IBMs can improve our understanding about the growth, transport, and connectivity of these species in the

Pacific Arctic and provides an important framework for examining transport in other key arctic species.

5. Conclusions

We developed the first individual-based, biophysical transport models for polar cod and saffron cod in the Pacific Arctic, which we used to reproduce observed late summer distributions of their ELS in the Chukchi Sea. The results of this study provide important information about these key forage fishes. In particular, we have identified potential spawning locations and nursery habitats for larvae and early juveniles, and have shown how the growth and dispersal of their ELS change in response to variable climate forcing. The source of observed aggregations of polar cod on the Chukchi shelf appear to be from the northern Bering and southern Chukchi seas, while spawning locations in the northern Chukchi Sea may be a source population for the western Beaufort Sea. Kotzebue Sound appears to be both an important spawning and nursery area for saffron cod, as well as a source of larvae and juveniles to nearshore nursery areas. We found strong variability in dispersal patterns among years, which were linked to changes in oceanographic and atmospheric forcing. Observed variability in the dispersal of polar cod and saffron cod ELS is likely related to changes in the strength of the Pacific-Arctic pressure head, which influences the inflow of Pacific waters into the Chukchi Sea and the timing and pattern of sea ice retreat. Understanding how connectivity between the Chukchi and Beaufort seas may change in response to Arctic warming is important if we are to understand the stock structure and population dynamics of polar cod and saffron cod in the region. Such information is essential to spatial management of Alaska's Arctic marine ecosystems.

Declaration of Competing Interest

The authors declare that they have no known competing financial interests or personal

- relationships that could have appeared to influence the work reported in this paper.
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