1	Comprehensive evaluation of empirical algorithms for estimating land surface
2	evapotranspiration
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14	ABSTRACT
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16	Many empirical algorithms for obtaining evapotranspiration (ET) from vegetation indices (VIs)
17	have been developed, but there has been little work comparing these algorithms to each other
18	or deriving coefficients for them using large data sets for training and validation. Twelve
19	different vegetation index-based regression algorithms for retrieval of ET on a daily basis are
20	reviewed and evaluated here. New coefficients have been derived for four of these algorithms
21	using data from 181 Ameriflux and Fluxnet2015 sites and 1km MODIS subsets centered at each
22	site location. Algorithm validation with previously published and new coefficients was

23	performed using one year of data from each Ameriflux and Fluxnet2015 site. There was a wide					
24						
24	range of performance of these algorithms, with the median R ² by site in the 0.6 to 0.7 range,					
25	median root mean square error (RMSE) about 25 W/m ² and median bias within 10 W/m ² . When					
26	algorithm coefficients were re-derived, the RMSE and bias of the worst-performing algorithms					
27	were largely reduced, but R^2 was little changed. Agricultural and wetland sites had a low bias					
28	across most of the algorithms, and wetland sites had a higher RMSE. When several of the					
29	algorithms were re-tuned to obtain coefficients specific to each surface type, the biases of the					
30	agricultural and wetland sites were reduced to those more typical of other site types, and RMSE					
31	for agricultural and wetland sites was also reduced. The effects of linear interpolation of VIs to					
32	obtain daily LE and interpolation over periods of rapid VI change at agricultural sites were					
33	examined. No significant algorithm performance degradation was found in either case. It is					
34	recommended to use more detailed algorithms when possible, with inclusion of net radiation as					
35	a parameter along with VI at a minimum.					
36						
37	Research highlights:					
38	12 regression algorithms tested with MODIS VI, MODIS albedo, and Fluxnet tower data					
39	Median statistics of best algorithms: R ² 0.6 to 0.7, RMSE ~ 25 W/m ²					
40	Re-deriving coefficients reduced RMSE and bias for some algorithms					
41	Re-deriving coefficients improved performance for wetland and agricultural sites					
42						
43	Keywords: Evapotranspiration; remote sensing; vegetation index; regression algorithms;					
44	MODIS; Fluxnet					

45 1. Introduction

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1.1. Background and motivation

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Increasing demands are being made on water resources globally, and this trend is expected to 49 50 continue due to anticipated changes in global climate and hydrology (Field et al. 2014). 51 Evapotranspiration (ET) is a major component of the global water cycle and its measurement is also used in water resources, agricultural, and ecosystem health monitoring. Determination of 52 53 ET on global and regional scales is crucial to understanding trends in the global hydrological 54 cycle (Zeng et al. 2012; Jiménez et al. 2011; Jung et al. 2010; Wang et al. 2010b) and regional 55 impacts of global hydrological change (e.g. Du et al. 2017; Spinoni et al. 2017; Garner et al. 56 2017; Haileslassie et al. 2009).

57

58 A broad review of LE measurement methods has been performed by Wang and Dickinson 59 (2012). Two frequently used methods can provide ET on scales of tens of meters. Weighing 60 lysimeters provide the most direct measurement of ET, and are used to calibrate ET found 61 through other methods (Liu et al. 2017; Hirschi et al. 2017). The frequently-used method for 62 obtaining LE presented in the Food and Agricultural Organization of the United Nations (FAO) 63 Irrigation and Drainage Paper 56 (R. G. Allen 1998) (FAO56) depends only on meteorological 64 observations and crop coefficients estimated based on surface conditions. The FAO56 method 65 has the advantage of not depending on any instruments besides those used to collect standard 66 weather observations. The lysimeter and FAO56 methods are most useful for estimating ET

over scales where meteorological and land cover conditions are relatively uniform, such as thatof an individual agricultural field.

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70 ET measurements from eddy correlation flux towers such as the Fluxnet network (Baldocchi et 71 al. 2001) typically have footprints on the order of hundreds of meters. This spatial scale is 72 convenient for many purposes, including validation of ET obtained through remote sensing. 73 There is an issue with energy balance closure (Foken 2008) for flux tower measurements, which 74 is usually resolved by assuming conservation of energy at the surface and a consistent Bowen 75 ratio between measured and actual sensible and latent heat fluxes. With this correction, flux 76 tower measurements are estimated to be accurate within 20% or less (Perez-Priego et al. 2017; 77 Hirschi et al. 2017; Wang and Dickinson 2012). However, they are limited in their applicability 78 due to their relatively small scale and restricted areal coverage, as well as by the significant 79 overrepresentation of northern hemisphere midlatitude sites. In addition, there are many sites 80 with temporal records of a few years or less, and where there is no ongoing data collection. As 81 a result, there is a great deal of interest in remote sensing of ET at larger spatial scales and in 82 more remote areas.

83

There are many remote sensing methods for retrieving ET available (Zhang et al. 2016; Wang and Dickinson 2012; Kalma, McVicar, and McCabe 2008) The methods available require various combinations of visible and infrared band data or their derived products such as albedo, land surface temperature, or vegetation index. They also differ in the degree to which the land surface energy and moisture transport processes are modeled explicitly, and with which

formulations. Some models, such as SEBAL and its descendants (Bastiaanssen et al. 1998), are based on finding the latent heat transfer rate from the surface (LE = λ ET, with ET of 1 mm/ day = LE of 26.3 W/m²) residual of the surface energy balance

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- 93

 $LE = R_n - H - G \tag{1}$

94

95 where R_n is the net radiation at the surface, H is the sensible heat transfer rate, and G the rate 96 of change in ground heat storage. These models consider the entire soil and canopy surface in 97 bulk (one source models) or treat the soil and canopy separately (two source models). Energy 98 balance residual models rely on thermal band observations as indicators of surface 99 temperature. The two source time integrated model TSTIM, later renamed ALEXI (Anderson et 100 al. 2007; Anderson 1997), relies on multiple daily surface temperature measurements, as a 101 smaller range of surface temperature is indicative of greater moisture availability. 102 103 The Penman-Monteith formulation of turbulent heat transfer (Monteith 1965) is used as a basis 104 for other methods of retrieving LE from remote sensing, such as that of Mu et al. (2011), now 105 used to generate the global MOD16 product from MODIS data. The earlier Penman (1948) 106 formulation was used as a basis for the model developed by Wang et al. (2010a). Another 107 turbulent flux parameterization, the Priestley-Taylor formula (Priestley and Taylor 1972) has 108 been used in combination with net radiation and vegetation indices (Yao et al. 2015, 2013; 109 Fisher et al. 2008) to obtain ET. In the case of the Yao et al. (2015, 2013) and Wang et al.

(2010a) studies, the turbulent flux transfer parameterizations were used as a basis for formulasto which empirical regression coefficients were fitted.

112

113 There are also many simpler regression formulas that have been developed for estimation of

114 ET. It has been found (Jiménez et al. 2011) that empirical regression formulas can produce ET

values that are comparable in accuracy to more complex models, without as much

116 computational demand or requirements for specific expertise. Many of these regression

117 formulas are based on vegetation indices (VI), as reviewed by Glenn et al. (2010). The most

118 frequently used vegetation indices in ET algorithms are the normalized difference vegetation

119 index (NDVI) and enhanced vegetation index (EVI). These ratios between near infrared, red, and

120 blue band reflectances (ρ_{NIR} , ρ_{red} , and ρ_{blue} respectively) are as follows:

121

122 $NDVI = \frac{\rho_{NIR} - \rho_{red}}{\rho_{NIR} + \rho_{red}}$ (2)

123

124 $EVI = G_{EVI} \frac{\rho_{NIR} - \rho_{red}}{\rho_{NIR} + C_1 \cdot \rho_{red} + C_2 \cdot \rho_{blue} + L}$ (3)

125

126

The standard EVI product calculated from MODIS data has the constants G_{EVI}, C₁, C₂, and L set to
 values of 1.0, 6.0, 7.5, and 2.5 respectively.

129

130 Vegetation indices have several advantages for use in evapotranspiration algorithms. They are

available from multiple instruments and at resolutions down to tens of meters. They have a

132	high degree of consistency between instruments (Brown et al. 2006; Steven et al. 2003)							
133	Vegetation indices typically change on time scales of weeks to months, so interpolation can be							
134	used between observations separated by multiple days with some confidence. Algorithms that							
135	include a dependence on surface temperature are likely to be more responsive on shorter time							
136	scales, but the faster rate of change of surface temperature makes interpolation between							
137	observations more problematic. Overall, vegetation index-based methods have the advantages							
138	of simplicity, utility under a wide range of conditions, and resilience in the presence of data							
139	gaps.							
140								
141	Little work has been done evaluating these vegetation index-based algorithms under different							
142	conditions or comparing them to each other or to LE values derived through other methods.							
143	The goal of this paper is to provide a comprehensive evaluation of a range of VI- based							
144	evapotranspiration algorithms, identifying their strengths and weaknesses relative to each							
145	other.							
146								
147								
148	1.2. Description of VI-based algorithms to be evaluated							
149								
150	A number of authors have proposed formulas for LE based on vegetation indices, ranging from							
151	highly simplified, depending only on the VI value with no additional data, to more complex							
152	formulas requiring ancillary data such as net radiation, surface and atmospheric temperatures,							

and other meteorological variables. All formulas to be evaluated in this paper are summarizedin Table 1.

155

156 Table 1: Vegetation index based algorithms reviewed and compared, with full algorithm names

and short names used to identify the algorithms in the figures. Key to variables: NDVI-

158 Normalized difference vegetation index, EVI- Enhanced vegetation index, Rn- Net radiation at

159 surface, G- Ground heat storage, T_{a_avg} – Daily average atmospheric temperature, T_{a_max}- Daily

160 maximum atmospheric temperature, T_{a_dTr}- Daily atmospheric temperature range, T_{s_avg}- Daily

161 average surface temperature, T_{s_max}- Daily maximum surface temperature, T_{s_dTr}- Daily surface

162 temperature range, LE₀- Potential evapotranspiration, R_s- Incoming solar radiation at surface,

163 RH- relative humidity, es- Saturation water vapor pressure, ws- Wind speed, VPD- vapor

164 pressure deficit.

165

Algorithm	Short	Reference	Required input data
	name		
Yebra direct (ET)	YET	Yebra et al. (2013)	NDVI or EVI
Yebra evaporative fraction (EF)	YEF	Yebra et al. (2013)	NDVI or EVI, R _n , G
Helman exponential	HEx	Helman et al. (2015)	NDVI or EVI
Helman scaled	HSc	Helman et al. (2015)	EVI, T _{s_avg}
Wang 2007	W07	Wang et al. (2007)	NDVI or EVI, R_n , one of T_{a_avg} , T_{a_max} , T_{s_avg} , or T_{s_max}
Wang/Liang	WL	Wang and Liang (2008)	NDVI or EVI, R_n , T_{s_dTr} , one of T_{a_avg} , T_{a_max} ,

			T _{s_avg} , or T _{s_max}
Choudhury/ FAO56	Ch	Choudhury et al.	EVI, LE ₀
		(1994)	
		Allen et al. (1998)	
Kamble/ FAO56	Kmb	Kamble et al (2013)	NDVI, LE ₀
		Allen et al. (1998)	
Wang 2010	W10	Wang et al. (2010a)	NDVI or EVI, R _s , RH,
			e _s , ws, T _{a_avg}
Yao 2011	Y11	Yao et al. (2011)	NDVI, R _n , T _{a_avg} , T _{a_dTr}
Yao 2013	Y13	Yao et al. (2013)	NDVI, R _n , G, T _{a_avg} ,
			T_{a_dTr} or T_{s_dTr} ,
Yao 2015	Y15	Yao et al. (2015)	NDVI, R _n , G, T _{a_avg} , RH,
			VPD

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A total of 12 algorithms, based on 11 separate publications, are reviewed and evaluated in this
paper. For each algorithm, Table 1 gives a short name, the source publication(s), and required
input data. Some of the publications listed also include other algorithms that depend on remote
sensing parameters other than NDVI or EVI, but only the VI-based algorithms are included here.
Two of the algorithms, Yebra ET (Yebra et al. 2013) and Helman exponential (Helman et al.

175 2015), depend on the vegetation index alone. These algorithms were trained using 16 Fluxnet

176 sites each. The Yebra algorithm sites were distributed over six different land cover types with

177 forest and cropland sites most common, while the Helman algorithms were developed

178 specifically for Mediterranean ecosystems with cropland and grassland sites most represented. 179 The Yebra ET formula 180 $LE_{YET} = a + b * VI$ 181 (4) 182 is a linear function of a vegetation index VI (NDVI or EVI), while the Helman exponential formula 183 184 $LE_{HEx} = a * \exp(b * VI)$ 185 (5) 186 is an exponential function of either NDVI or EVI. For each of these algorithms, regression 187 188 coefficients were found for NDVI and EVI separately. 189 190 The Yebra EF formula (Yebra et al. 2013) treats the evaporative fraction 191 $EF = LE/(R_n - G)$ 192 (6) 193 as a linear function of NDVI or EVI, resulting in 194 195 $LE_{YEF} = (R_n - G)(a + b * VI)$ 196 (7) 197

198 The Helman scaled algorithm (Helman et al. 2015), trained with the same data set as the 199 Helman exponential algorithm, depends on a EVI and daily mean surface temperature T_{s_avg}, 200 scaled according to: 201 $EVI_{scl} = EVI - b$ 202 (8) $LST_{scl} = c - (d * T_{s ava})$ 203 $if (LST/e) < LST_{scl}, \quad LST_{scl} = LST/e$ 204 205 206 then obtaining LE as the product of these scaled parameters: 207 $LE_{HSC} = a * EVI_{SC} * LST_{SC}$ 208 (9) 209 Wang et al. (2007) and Wang and Liang (2008) have published two empirical algorithms: 210 211 $LE_{W07} = R_n * (a_1 + a_2 * VI + a_3 * T)$ 212 (10)213 and $LE_{WL} = R_n * (a_1 + a_2 * VI + a_3 * T + a_4 T_{S dTr})$ 214 (11) 215 216 respectively. Eight sets of coefficients were derived for each of these formulas, for each 217 possible combination of MODIS NDVI or EVI, and average or maximum daily surface 218 temperature (T_{s_avg} , T_{s_max}), or average or maximum atmospheric temperature (T_{a_avg} , T_{a_max}). 219 The Wang and Liang (2008) formula also includes daily surface temperature range (Ts_dTr) as a

proxy for moisture availability. These formulas are based on the maximum correlations
between LE and other variables measured at eight Bowen ratio tower sites in the US Southern
Great Plains, and, in the case of Wang and Liang (2008), four additional eddy correlation tower
sites also in the US. In both studies, the strongest correlation was with net radiation, with VI
and temperature variables following.

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Two of the published formulas parameterize evapotranspiration as a function of the potential
evapotranspiration ET₀, or the equivalent latent heat transfer LE₀, defined as the ET that would
occur from a standardized, well-watered ground cover given a set of atmospheric conditions.
LE₀ is often derived from the standard surface conditions and the Penman-Monteith formula for
LE (Monteith 1965):

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(12)

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233
$$LE = \frac{\Delta(R_n - G) + \rho_a c_p \frac{VPD}{r_a}}{\Delta + \gamma \left(1 + \frac{r_s}{r_a}\right)}$$

232

234 where Δ is the derivative of saturation vapor pressure with temperature, ρ_a is the density of air, 235 c_p the specific heat of air at constant pressure, VPD the vapor pressure deficit (e_s – e_a, where e_s 236 is the saturation vapor pressure and e_a is actual vapor pressure), γ the psychrometric constant, 237 and r_s and r_a are bulk aerodynamic resistance factors characterizing surface and atmospheric 238 conditions respectively. A frequently-used formula for estimation of ET₀ is given in FAO56 (Allen 239 et al. 1998) After conversion to units of LE, the FAO56 formula becomes 240

241
$$LE_0 = 26.3 * \left[\frac{0.408\Delta(R_n - G) + \gamma \left(\frac{900}{T + 273}\right)ws * VPD}{\Delta + \gamma (1 + 0.34ws)} \right]$$

243 (13)

244 where ws represents wind speed.

245

246 Choudhury et al. (1994) combined observations of agricultural fields in an arid climate with 247 surface and radiative transfer modeling to obtain a transpiration coefficient as a function of 248 vegetation index. Glenn et al. (2010) proposed neglecting the bare soil evaporation in this 249 formula, resulting in a formula for LE in terms of LE₀: 250 $LE_{Ch} = LE_0 \left(1.0 - \frac{EVI_{max} - EVI}{EVI_{max} - EVI_{min}} \right)$ 251 (14) 252 253 Choudhury et al. (1994) suggested using EVI_{max} = 0.95 and EVI_{min}=0.05. 254 255 Kamble et al. (2013) suggested a linear function of NDVI for obtaining LE based on LE₀, and 256 derived coefficients based on agricultural sites in the US Great Plains: 257 $LE_{Kmb} = LE_0(a * NDVI - b)$ 258 (15) 259

260 Wang et al. (2010a) developed their formula based on the approach of Penman (1948),

estimating LE as consisting of two components, one controlled by available energy and another

262 by atmospheric resistance. They developed the regression formula

263

264
$$LE_E = \frac{\Delta}{\Delta + \gamma} R_s [a_1 + a_2 VI + RHD(a_3 + a_4 VI)]$$
(16)

265
$$LE_A = \frac{\gamma}{\Delta + \gamma} ws * VPD[a_5 + RHD(a_6 + a_7 VI)]$$

266
$$LE_{W10} = a_8(LE_E + LE_A) + a_9(LE_E + LE_A)^2$$

267

268 with an energy control component LE_E dependent on incoming shortwave flux R_s and an 269 atmospheric transmission control component LEA. RHD represents the relative humidity deficit 270 (as a function of relative humidity RH in percent: (100 – RH) / 100). This regression formula was 271 trained using 64 eddy correlation and Bowen ratio ground stations, with the goal of obtaining 272 globally-applicable coefficients. Unlike many of the other formulas, which contain an R_n or R_n – 273 G term as a measure of available energy at the surface, the Wang formula uses the incoming 274 solar radiation at the surface R_s. R_s may be measured directly, or estimated based on R_n, albedo, 275 temperature, and relative humidity through the formula given in Wang and Liang (2009). 276

The three Yao et al. formulas considered here (2015, 2013, 2011), like the Wang et al (2010)
model, are regressions based on pre-existing physical LE models. The Yao 2011 formula,

279 developed for drought monitoring from a two-source LE model and data from 22 flux tower

sites and global radiation and NDVI products, takes the form

281
$$LE_{Y11} = R_n^2(a_1NDVI - a_2) + R_n\left(a_3 + a_4T_{a_avg} + \frac{a_5}{T_{a_dTr}}\right) + R_nNDVI\left(a_6 + a_7T_a + \frac{a_8}{T_{a_dTr}}\right)$$
282 (17)

283 where T_{a_dTr} is the daily range of near-surface atmospheric temperature.

284

The Yao 2013 and Yao 2015 formulas are both based on the Priestley-Taylor (Priestley and Taylor 1972) parameterization, where r_s and r_a are combined into an empirically determined coefficient α with a value of 1.26 representing a well-covered and watered surface and a function f(e) ranging from 0 to 1 representing constraints on LE:

289

290
$$LE = \alpha \left(\frac{\Delta}{\Delta + \gamma}\right) f(e) * (R_n - G)$$
(18)

291

The Yao 2013 formula represents each of four separate components of LE through individual Priestley-Taylor parameterizations. These are a canopy transpiration component LE_c, a soil evaporation component LE_s, and components for evaporation from wet canopy and soil surfaces, LE_{ic} and LE_{ws}:

 $LE_{Y13} = LE_c + LE_s + LE_{ic} + LE_{ws}$ ⁽¹⁹⁾

297

298
$$LE_c = \alpha \left(\frac{\Delta}{\Delta + \gamma}\right) (1 - f_{wet}) f_v f_T R_{nc}$$

299
$$LE_s = \alpha \left(\frac{\Delta}{\Delta + \gamma}\right) (1 - f_{wet}) f_{sm} (R_{ns} - G)$$

$$300 LE_{ic} = \alpha \left(\frac{\Delta}{\Delta + \gamma}\right) f_{wet} R_{nc}$$

$$LE_{ws=} \alpha \left(\frac{\Delta}{\Delta + \gamma}\right) f_{wet}(R_{ns} - G)$$

303 The parameters f_{sm} and f_T represent soil moisture and temperature constraints respectively, f_v is 304 fractional vegetation cover, f_{wet} is relative surface wetness, R_{nc} is net radiation to the vegetation 305 canopy, and R_{ns} is net radiation to the soil. These variables are in turn parameterized in terms of 306 vegetation index, daily average temperature, and daily temperature range. Separate sets of 307 coefficients were derived using atmospheric and surface daily temperature ranges.

308

309 The Yao (2015) formula, which is similar in its basis to that of Fisher et al. (2008), is also based 310 on the Priestley-Taylor equation, in this case with constraints on all sources of LE combined into 311 one formulation. It was also developed for global applications, and the coefficients were 312 trained with data from 240 Fluxnet sites.

313

314
$$LE_{Y15} = \phi \frac{\Delta}{\Delta + \gamma} (R_n - G) \left[a_1 + a_2 T_{a_a v g} + a_3 \left(\frac{RH}{100} \right)^{VPD} + VPD (a_4 NDVI - a_5) \right]$$
315 (20)

315

316

317 In summary, a range of formulas for obtaining LE from VI exist with different theoretical bases, 318 degrees of complexity, and other input variables required. Some have forms that have a 319 physical basis, but all ultimately depend on empirical regression for training of coefficients. In 320 most cases they were trained with a limited number of ground sites, so it is desirable to test 321 whether improvements can be made to their performance by using a larger training data set.

- 323
- 324 2. Data
- 325
- 326 2.1. Ground-based
- 327

328 A total of 184 flux tower sites were used, 119 from the Ameriflux network

329 (http://ameriflux.lbl.gov) and 65 from the Fluxnet2015 data set

330 (http://fluxnet.fluxdata.org/data/fluxnet2015-dataset/). All available sites with at least 3

331 continuous years of data were included. Most of the Ameriflux sites were within the United

332 States, with good representation of the latitude range and land cover types of the continental

333 US and Alaska. Eleven of the Ameriflux sites are Canadian, one Mexican, and one Brazilian. The

334 Fluxnet2015 sites are mostly in Europe with some in Asia and Africa, cover a wide range of

335 surface types and climates, but have the northern midlatitude bias typical of flux tower records.

A total of 1166 site-years of data from 181 sites was used. The global distribution of these sites

337 is shown in Figure 1. The IGBP surface types represented in the combined Ameriflux and

338 Fluxnet2015 data, the categories used for further analysis here, and the number of sites and

total site-years in each category are listed in Table 2.



342 Figure 1: Global distribution of flux tower sites used in this study. Colors of points indicate

343 number of years of data used from each site. Shapes of points indicate IGBP ecosystem type:

344 CRO- crop, CSH- closed shrubland, DBF- deciduous broadleaf forest, EBF- evergreen broadleaf

345 forest, ENF- evergreen needleleaf forest, GRA- grassland, MF- mixed forest, OSH- open

346 shrubland, SAV- savannah, WET- wetland, WSA- woody savannah

347 NOTE: Figure 1 should be in color electronically but not in print.

348

- Table 2: Land cover type categories used for algorithm evaluation, with IGBP classes included,
- 350 number of sites available, and total site-years of data used for each.

Category	Included IGBP	Number of sites	Total site-years
	classes		
Agricultural	CRO	23	115
Grassland	GRA	35	181
Deciduous	DBF, DNF, MF	29	228
Evergreen	EBF, ENF	50	392
Savannah	SAV, WSA	13	80
Shrub	CSH, OSH	18	76
Wetland	WET	13	94

The flux tower observations were preprocessed to obtain daily values of LE and all parameters required by the algorithms except for vegetation indices and albedo. For those days with at least 40 of 48 half hourly observations available for all variables, daily mean values of all required meteorological and energy balance variables were calculated. No modeled or gap-filled data were used, so days with insufficient flux tower data are not represented in our analysis. For atmospheric and surface temperatures, daily maximum and minimum values were also found and daily temperature ranges calculated. 2.2. Remote sensing

365 MODIS Terra NDVI and EVI products (MOD13Q1, Didan 2015) and Terra/Aqua combined 366 albedo (MCD43A, Schaaf and Wang 2015) time series were obtained for each site, for the same 367 time period as the available flux tower data where it overlaps with the MODIS record. Subsets 368 of each product were obtained from the Oak Ridge National Laboratory DAAC 369 (https://daac.ornl.gov/MODIS/modis.shtml) Standard QC screening was applied. A 1km subset 370 size was used, and all pixels that passed QC screening were included in calculations of mean 371 NDVI, EVI, and albedo. (Preliminary testing with 0 km (same pixel), 1 km, and 3 km subset sizes 372 indicated very little difference in LE algorithm results. Restricting included pixels to those with 373 the same surface type as the central pixel also had a negligible effect.) Under ideal conditions VI 374 is available every 16 days and albedo every 8 days, but longer data gaps exist in some locations 375 due to insufficient high-quality pixels. VI and albedo were both linearly interpolated to generate 376 daily time series. 377

378

379 3. Methods

380

Each model was first used to calculate LE (LE_{mod}) for each day where sufficient flux tower data was available at every site with the original published coefficients then compared against the ground observation LE (LE_{obs}). The coefficients for each algorithm were then re-derived using Levenberg-Marquardt fitting initialized with the published coefficient values. For purposes of algorithm evaluation, the last year of each site time series was reserved for testing and coefficients were trained with the remaining data. The algorithm evaluation results shown

387	below all use this division of training and test data. In addition, a set of coefficients for each
388	algorithm was derived using all available data, with results shown in Table 3. The coefficients
389	for each algorithm from its original publication are given in Table S1 in the Supplementary
390	Material.
391	
392	Table 3: Re-derived coefficients for each algorithm using all available data from all sites. For the
393	Yao (2013) and Yao (2015) algorithms, a set of coefficients was derived using a variable value of
394	the Priestley-Taylor coefficient $lpha$ and a constant $lpha$ of 1.26.

Algorithm	Short name	Version	Re-derived coefficients
Yebra ET	YET	NDVI	a = -0.4589, b = 81.7987
		EVI	a = -1.2841, b = 149.9876
Yebra EF	YEF	NDVI	a = 0.02867, b = 0.6131
		EVI	a = 0.04879, b = 1.0316
Helman exponential	HEx	NDVI	a = 13.3611, b = 2.0344
		EVI	a = 17.0592, b = 2.8873
Helman scaled	HSc		a = -1518.3715, b = 0.001387, c =
			33.6520, d = -1.1212,
			e = -4807.2619
Wang 2007	W07	EVI, T _{a_avg}	a _{1 =} -0.04417, a ₂ = 0.9481, a ₃ = 0.006516
		EVI, T _{a_max}	a ₁ = -0.06821, a ₂ = 0.9715, a ₃ = 0.005585
		EVI, T _{s_avg}	a ₁ = -0.02849, a ₂ = 1.0189, a ₃ = 0.004237
		EVI, T _{s_max}	a ₁ = 0.0004923, a ₂ = 1.0416, a ₃ =
			0.001707
		NDVI, T _{a_avg}	a ₁ = -0.09575, a ₂ = 0.5815, a ₃ = 0.007896
		NDVI, T _{a_max}	a ₁ = -0.1300, a ₂ = 0.5995, a ₃ = 0.006939
		NDVI, T _{s_avg}	a ₁ = -0.09734, a ₂ = 0.6438, a ₃ = 0.005862
		NDVI, T _{s_max}	a ₁ = -0.05442, a ₂ = 0.6493, a ₃ = 0.002534
Wang/Liang	WL	EVI, T _{a_avg}	a ₁ = 0.07223, a ₂ = 0.6681, a ₃ = 0.009505
			a ₄ = -0.009441
		EVI, T _{a_max}	$a_1 = 0.03066$, $a_2 = 0.6862$, $a_3 = 0.008800$,
			a ₄ = -0.009861
		EVI, T _{s_avg}	a ₁ = 0.08232, a ₂ = 0.7360, a ₃ = 0.008243,

			a ₄ = -0.01089
		EVI, T _{s_max}	a ₁ = 0.08224, a ₂ = 0.7293, a ₃ = 0.008534,
			a ₄ = -0.01610
		NDVI, T _{a_avg}	a ₁ = 0.05191, a ₂ = 0.3879, a ₃ = 0.01077,
			a ₄ = -0.01048
		NDVI, T _{a_max}	a ₁ = 0.0005417, a ₂ = 0.4030, a ₃ = 0.0101,
			a ₄ = -0.01097
		NDVI, T _{s_avg}	a ₁ = 0.04231, a ₂ = 0.4534, a ₃ = 0.009886,
			a ₄ = -0.01223
		NDVI, T _{s_max}	a ₁ = 0.04353, a ₂ = 0.4484, a ₃ = 0.01015,
			a ₄ = -0.01837
Choudhury/ FAO56	Ch		EVI _{min} = 0.02355, EVI _{max} = 0.6117
Kamble/ FAO56	Kmb		a = 1.0452, b = -0.08478
Wang 2010	W10	NDVI	a ₁ = -0.1387, a ₂ = 1.9938, a ₃ = 0.1542, a ₄
			= -2.1872,
			a ₅ = 54.5977, a ₆ = -79.8249, a ₇ =
			67.8465, a ₈ = 0.6891,
			a ₉ = -0.001150
		EVI	a ₁ = -0.06988, a ₂ = 3.1684, a ₃ = 0.05535,
			a ₄ = -3.2777,
			a ₅ = 60.6141, a ₆ = -99.1790, a ₇ =

			194.5842, a ₈ = 0.6498,
			a ₉ = -0.0009489
Yao 2011	Y11		a ₁ = -0.0009580, a ₂ = -0.0004328, a ₃ =
			0.03625, a ₄ = -0.003210,
			a ₅ = 2.0066, a ₆ = 0.5167, a ₇ = 0.02503, a ₈
			= -2.7852
Yao 2013	Y13	T _{s_dTr}	α = 0.7888, NDVI _{max} = 0.7052, NDVI _{min} = -
			0.08551,
			T _{opt} = 32.8330, dTr _{max} = 30.9849
		T_{a_dTr}	α = 0.9987, NDVI _{max} = 0.9198, NDVI _{min} = -
			0.3712,
			T _{opt} = 25.5854, dTr _{max} = 22.9378
		T_{s_dTr}, α	NDVI _{max} = 0.6486, NDVI _{min} = -0.2723, T _{opt}
		constant	= 141.0440,
			dTr _{max} = 10.9068
		T_{a_dTr}, α	NDVI _{max} = 1.1234, NDVI _{min} = -0.4696, T _{opt}
		constant	= 25.7667,
			dTr _{max =} 15.7136
Yao 2015	Y15		α = 1.6445, a ₁ = -0.002953, a ₂ =
			0.007440, a ₃ = 0.4299,
			a ₄ = 0.05653, a ₅ = 0.01933

			lpha constant	a ₁ = -0.003854, a ₂ = 0.009711, a ₃ =
				0.5611, a ₄ = 0.07379,
				a ₅ = 0.02523
396				
397				
398	For each site and algorith	m, RMSE	E, R ² , and bias wer	e calculated based on LE_{mod} and LE_{obs} , where
399	n is the number of days w	ith valid	data available:	
400				
402		RMS	$SE = \sqrt{\frac{\sum_{i=1}^{n} (LE_{mo})}{\sum_{i=1}^{n} (LE_{mo})}}$	$\frac{D_{od_i} - LE_{obs_i}}{n}^2$
401			·	(21)
403				
404		Bi	$as = \frac{\sum_{i=1}^{n} (LE_{mod})}{\sum_{i=1}^{n} (LE_{mod})}$	$\frac{h_{i}i - LE_{obs_{i}}}{n}$
405				(22)
406				
407				
408	$R^2 = \begin{cases} \frac{n}{\left[n\sum_{i=1}^n LE\right]} \end{cases}$	$\frac{\sum_{i=1}^{n} (L)}{\sum_{mod_{i}}^{2} - \sum_{i=1}^{n} (L)}$	$\frac{E_{mod_{i}}LE_{obs_{i}}) - \sum_{i=1}^{n} LE_{mod_{i}}^{2}}{\left(\sum_{i=1}^{n} LE_{mod_{i}}\right)^{2}}$	$\frac{\sum_{i=1}^{n} LE_{mod_{_i}} \sum_{i=1}^{n} LE_{obs_{_i}}}{\left[n \sum_{i=1}^{n} LE_{obs_{_i}}^{2} - \left(\sum_{i=1}^{n} LE_{obs_{_i}}^{2}\right)^{2}\right]}^{2}$
409				(23)
410				

411 These results were then used to generate boxplots by algorithm. Boxplots were generated

412 using all available sites, separately for the initial published and re-derived coefficients.

414	Similar statistical comparisons between algorithms were also conducted for the individual
415	surface types specified in Table 2. Based on the results from the analyses with all surface types,
416	four relatively well-performing algorithms with different theoretical bases (Yebra EF, Wang and
417	Liang, Wang 2010, and Yao 2013) were selected for this evaluation. Coefficients were re-
418	derived for each surface type using only data from sites with that type, again reserving the last
419	year of each site for testing. Boxplots similar to those for all types were generated with the
420	surface type specific coefficients and compared to results from the coefficients previously
421	derived from all available sites in order to evaluate whether use of data from only the same
422	surface type improved algorithm performance.

423

424 Two additional tests were made of algorithm performance. In order to test whether linear 425 interpolation was artificially improving algorithm statistics by introducing large numbers of non-426 independent data points, a subset of sites was selected and only data from the vegetation index 427 composite dates were considered. Statistics from only the composite dates were compared to 428 results including all days with sufficient flux tower data for each algorithm. An analysis was also 429 performed for agricultural sites to assess whether interpolation over periods with sudden 430 changes in vegetation index introduces error. To test for this effect, algorithm performance for 431 agricultural sites was evaluated with dates with steep vegetation index slope (> 0.015/ day in 432 NDVI or > 0.01/ day in EVI) excluded, then compared to agricultural site performance without 433 this exclusion.

434

436 4. Results analysis

437

4.1. Global comparison of algorithms and coefficient tuning

439

438

Boxplots of RMSE, R², and bias by site for all surface types and for the original and re-derived coefficients are shown in Figures 2, 3, and 4. The algorithms are arranged left to right roughly in order of increasing complexity and number of input variables required. Figure 2a shows that the Yebra ET and Helman scaled algorithms have the highest median RMSEs. It is notable that these algorithms are the only ones that do not have any dependence on R_n. The best performing algorithms have median RMSEs that cluster around 25-30 W/m² with the original coefficients.

447

Figure 2b shows the RMSE for all sites with the re-derived coefficients. All algorithms except Yao 2011 had similar or improved RMSE performance, with the best-performing models again having median RMSE in the 25-30 W/m² range. The most significant changes were for the Yebra and Helman algorithms, which have the simplest form and fewest required inputs. Most of the other algorithms had little change in median RMSE values, but RMSE tended to decrease for those algorithms that had higher RMSE using the original coefficients.

454

There are a significant number of outlier sites in the RMSE (Figure 2) and bias (Figure 4) results.
Further investigation showed that different sites were outliers for different algorithms with the

original coefficients (Figure 2a, 4a), with no systematic patterns apparent. With the re-derived
coefficients (Figure 2b, 4b), six sites were responsible for most of the outliers. These sites either
had 1 km subset areas that were unrepresentative of the area immediately surrounding the flux
tower or were wetland sites. Wetland sites have greater bias and RMSE than other sites, as
shown in Figure 5. The difference in performance between wetland sites and others is
discussed in greater detail below.

2b)



464 2a)



465

Figure 2: RMSE for each algorithm by site for all cover types. 2a) Using original published
coefficients. 2b) Using re-derived coefficients. Key to algorithms: YET - Yebra ET, YEF - Yebra EF,
HEx - Helman exponential, HSc - Helman scaled, W07 - Wang 2007, WL - Wang and Liang, Ch Choudhury/ FAO56, Kmb - Kamble/ FAO56, W10 - Wang 2010, Y11 - Yao 2011, Y13 - Yao 2013,
Y15 - Yao 2015

R² values for each site and algorithm are shown in Figure 3, with results for the original
coefficients shown in Figure 3a and for the re-derived coefficients in Figure 3b. The median R²
values for the best performing algorithms are between 0.6 and 0.7, with others, usually the
simpler algorithms, having significantly lower values. Unlike the results for RMSE, re-fitting the
coefficients did not have a strong impact on median R² or its distribution for any
of the algorithms.

- 478
- 479 3a)





480



482 coefficients. Algorithm legend on horizontal axis is the same as for Figure 2.

483

Bias values for all sites and algorithms are shown in Figure 4, with results for the original
coefficients in Figure 4a and for the re-derived coefficients in Figure 4b. The patterns here are
similar to those seen for RMSE, with the simpler algorithms, especially Yebra ET, usually having

the greatest absolute values of median bias with the original coefficients. Figure 4b shows that
re-fitting the coefficients reduced the absolute value of median bias for many of the algorithms
and reduced the range of bias values in many cases as well.

490

491	4a)	4t
491	4a)	41



492

Figure 4: Bias by site for all algorithms and land cover types. Results for original coefficients are
shown in Figure 4a, and for re-derived coefficients in Figure 4b. Algorithm legend on horizontal
axis is the same as for Figure 2.

496

497

498 4.2. Evaluation of algorithms by land cover type

499

500 In general, there was little difference in the patterns of RMSE, R², and bias performance when 501 the re-derived coefficients were used between surface types considered individually and what was shown in the previous section for all sites together. Exceptions to this overall pattern
include higher R² values for agricultural, deciduous, evergreen, and grassland sites than for all
sites considered together, and lower R² values for savannah, shrub, and wetland sites. There are
also differences in bias and RMSE for agricultural and wetland sites.

506

507 Bias differences for agricultural and wetland sites, and RMSE differences for wetland sites, are 508 shown below in Figure 5. Wetland sites (Figure 5a), and to a lesser degree agricultural sites 509 (Figure 5b), showed a consistent low bias across algorithms, with typical bias values of around 510 -25 W/m² for agricultural sites and -50 W/m² for wetland sites. The Yao 2011, Yao 2013, and 511 Yao 2015 algorithms had a less pronounced bias than the others for wetland sites, but not for 512 agricultural sites. In addition, RMSE for wetland sites was significantly higher than was typical 513 for other surface types, with values of around 40 W/m^2 or more not being unusual (Figure 5c). 514 The Yao algorithms had lower median RMSE, but RMSE was still relatively high for the sites 515 where it was greatest. 516 517 518 519 520

521 5a)

5b)











Figure 5: Bias and RMSE by site for those surface types where performance differed significantly
from all sites with globally-derived coefficients. Figure 5a: Bias for agricultural sites. Figure 5b:
Bias for wetland sites. Figure 5c: RMSE for wetland sites. Algorithm legend on horizontal axis is
the same as for Figure 2.

531

4.3. *Re-training of coefficients by surface type*

532

533 For the four algorithms tested (Yebra EF, Wang and Liang, Wang et al. 2010, and Yao et al. 534 2013), training with data from sites from only one surface type did not result in much change 535 from globally-trained coefficients for most surface types in most cases. (See Figures S1-S3 in 536 the Supplementary Material). The most pronounced exceptions occurred for bias and RMSE for 537 agricultural and wetland sites, paralleling the results when comparing those surface types to 538 the global results as described above. There were also modest improvements in RMSE for 539 deciduous, grassland, and savannah sites (Figures S1-b, S1-d, and S1-e), some modest increase 540 in R² for savannah and decrease in R² for deciduous sites (Figures S2-e and S2-b) and modest 541 reductions in absolute bias values for deciduous, grassland, and shrub sites (Figures S3-b, S3-d, 542 and S3-f). For evergreen sites, bias values became somewhat more negative (Figure S3-c). In all 543 other cases, there was little change to the statistics, or performance improved for some 544 algorithms and was reduced for others.

545

The results of surface type specific training for agricultural and wetland sites are shown in
Figures 6- 9. Figures 6 and 7 show a decrease in RMSE for agricultural sites and a reduction in
the maximum RMSE by site for wetland sites, Figure 8 shows a decrease in bias for agricultural
sites, and Figure 9 shows a decrease in bias for wetland sites.





551 Figure 6: RMSE for agricultural sites for Yebra EF (YEF), Wang and Liang (WL), Wang et al. 2010

552 (W10) and Yao et al. 2013 (Yao13) algorithms. For each algorithm, left box is for training with

553 data from all sites, and right box is for training with agricultural sites only.



Figure 7: RMSE for wetland sites. Algorithm labels on X axis are the same as for Figure 6. For
each algorithm, left box is for training with data from all sites, and right box is for training with
wetland sites only.





Figure 8: Bias for agricultural sites. Algorithm labels on X axis are the same as for Figure 6. For
each algorithm, left box is for training with data from all sites, and right box is for training with
agricultural sites only.





Figure 9: Bias for wetland sites. Algorithm labels on X axis are the same as for Figure 6. For each
algorithm, left box is for training with data from all sites, and right box is for training with
agricultural sites only.

567

568

569 4.4. Test of effect of linear interpolation of vegetation indices

570 The possibility that the statistical results of this analysis are being affected by the large number

- 571 of non-independent data points introduced by linear interpolation of vegetation indices was
- 572 tested. This was done using seven stations that each had a long data record, in order to obtain a
- 573 significant number (659) station-days where that were both a composite date and had
- 574 sufficiently complete Fluxnet records. These stations, listed in Table 4, also represent seven

- 575 different land cover types. The analysis was conducted for seven of the best-performing
- 576 algorithms.
- 577 Table 4: Stations used for comparison of results from all dates to day of composite only.

Station	Site ID	IGBP class
Audubon Ranch	US-Aud	Grassland (GRA)
Blodgett Forest	US-Blo	Evergreen needleleaf forest (ENF)
Lost Creek	US-Los	Wetland (WET)
Rosemount G21 conventional corn/ soy	US-Ro1	Cropland (CRO)
Santa Rita mesquite	US-SRM	Woody savannah (WSA)
Soroe	DK-Sor	Deciduous broadleaf forest (DBF)
Walnut Gulch Lucky Hills Shrub	US-Whs	Open shrub (OSH)

- 579 The results of this analysis are shown in Table 5. It was found that R² was higher and RMSE
- 580 lower when only the composite days were used. The bias was a few W/m² more negative in
- 581 most cases. These results could be because accuracy was lost through interpolation, or because
- 582 composites were taken on clear weather days and the algorithms performed better under
- those conditions. It appears not to be the case that the interpolation artificially improved the
- 584 apparent performance of the algorithms.
- 585 Table 5: Results of comparison between all dates and day of composite only.

Algorithm	RMSE all	RMSE	Bias all	Bias	R ² all	R ²
	days	composite	days	composite	days	composite
		days		days		

	(W/m²)	(W/m²)	(W/m²)	(W/m²)		days
Yebra EF (YEF)	32.628	28.871	-5.555	-8.038	0.474	0.619
Choudhury (Ch)	38.761	37.958	-17.583	-21.059	0.473	0.559
Wang 2010 (W10)	31.243	27.028	-5.581	-7.665	0.523	0.673
Wang and Liang (WL)	33.279	29.033	-6.809	-8.952	0.454	0.618
Yao 2011 (Y11)	33.850	29.000	6.432	4.137	0.432	0.586
Yao 2013 (Y13)	32.213	28.789	-6.776	-9.805	0.502	0.656
Yao 2015 (Y15)	31.830	26.886	-2.258	-2.914	0.489	0.657

587

588

4.5. Test of effect of rapid VI changes at agricultural sites

589 At agricultural sites, there are periods where vegetation indices change rapidly, notably at 590 harvest but also during greenup at the beginning of the growing season. The possibility that the 591 vegetation index interpolation might not be as accurate at those times and degrade algorithm 592 performance as a result was examined. The significance of this effect was tested using the 23 593 agricultural sites and seven algorithms. The median site RMSE, bias, and R² were found 594 excluding those times where absolute value of the slope of NDVI > 0.015/ day, or of EVI > 0.01/ 595 day, and compared against the results when all days were included. The results of this analysis 596 are shown in Table 6. The performance of the algorithms was not much different between the

597 cases, or slightly worse when the steep VI slope periods were excluded. It does not appear that

598 periods with steep VI slope are introducing additional error to the results for agricultural sites.

599 Table 6: Median site statistics of 23 agricultural sites, comparing results with and without

600 exclusion of steep slope in vegetation indices.

Algorithm	RMSE all days (W/m ²)	RMSE VI slope exclusion (W/m ²)	Bias all days (W/m ²)	Bias VI slope exclusion (W/m ²)	R ² all days	R ² VI slope exclusion
Yebra EF (YEF)	28.892	29.699	-38.533	-39.340	0.685	0.682
Choudhury (Ch)	36.017	36.651	-51.922	-54.332	0.622	0.616
Wang 2010 (W10)	23.459	24.557	-7.470	-9.063	0.645	0.647
Wang and Liang (WL)	30.560	31.386	-36.285	-37.540	0.694	0.692
Yao 2011 (Y11)	24.746	25.386	-22.921	-23.666	0.666	0.676
Yao 2013 (Y13)	29.944	31.098	-34.811	-35.823	0.664	0.664
Yao 2015 (Y15)	24.056	24.125	-25.712	-26.290	0.688	0.688

601

602 5. Discussion

603 There has been a significant amount of effort devoted to measurement of evapotranspiration

604 at regional to global scales, due to the parameter's importance for a wide range of applications.

605 At these scales, remote sensing is required for at least some of the input data. A large number

606 of remote sensing methods to obtain LE have been developed, and the empirical methods 607 evaluated here are just a subset of those available. There has been a significant amount of work 608 evaluating different LE data sets at global (Jiménez et al. 2011; Mueller et al. 2011), and 609 regional scales (e.g. Mao and Wang 2017; Chen et al. 2014) The focus of these studies has 610 usually been on comparing different "families" of data sets (models vs. reanalyses vs. different 611 remote sensing techniques), but less work has been done comparing results within each 612 "family". The work done here was performed to fill in this gap for the "family" of regression-613 based models.

614

We found that most of the regression methods yielded useful estimates of LE with errors of similar magnitude to those from other methods. This is consistent with the results provided by the original developers of these algorithms (references given in Table 1) as well as with the intercomparison studies cited above and the evaluation of VI-based LE retrieval methods by Glenn et al. (2010). Aside from the effect of inclusion of net radiation as an input parameter, the differences in performance were relatively modest, consistent with Mueller et al. (2011), where the two regression-based models included in the comparison had similar results.

622

The finding that, while increasing the number of input variables included improved the results, the specific formulation of the regression formula did not, was somewhat surprising. However, this is consistent with the fact that a broad range of different LE algorithms with different theoretical bases are all able to work with some skill, with no particular formulation coming out ahead consistently. The finding that net radiation is the most significant forcing variable is

consistent with Badgley et al. (2015), who found that changing the source of net radiation data
used by a Priestley-Taylor model resulted in a greater change to its results than changing the
source of meteorological or vegetation index data. In addition, the finding of the high
significance of the net radiation variable is also consistent with Wang et al. (2007), who found a
greater correlation of flux tower LE measurements to net radiation than to temperatures or
vegetation indices.

634

The effect of land surface type on the performance of a range of empirical algorithms has not
been examined in detail before this study. We found that there was some variation in
performance, which is not unexpected, since different land cover types have different degrees
of annual variation in vegetation index, and probably different relationships between VI and LE.

640 A probable reason for the low bias in wetland sites is that evaporation from the surface makes 641 a more significant contribution to LE than for other site types, while vegetation indices are 642 more of an indicator of transpiration. Multiple studies (S. T. Allen et al. 2017; Runkle et al. 2014; 643 Malone et al. 2014) have shown that H is a much smaller component of the surface energy 644 budget than LE for wetland sites, and at least one study (Beigt et al. 2008) indicates that 645 sensible heating can make a positive contribution to available energy at a wetland site. High 646 values of LE relative to H are also seen in the wetland flux tower energy balance measurements 647 used in this study. In addition, S. T. Allen et al. (2017) have shown that release of stored energy 648 from the surface can contribute to available energy in the autumn season for a wetland. These 649 sources of energy are available for evaporation but not transpiration. Along with higher surface

moisture availability, these effects can result in high evaporative fraction and high rates of
evaporation relative to transpiration from wetlands. Vegetation indices are not a good indicator
of surface evaporation, as in the limiting case of open water where VIs are very low but surface
evaporation is high.

654

655 There are other variables, such as precipitation and soil moisture, that are strongly related to LE 656 but not incorporated into any of the regression formulas reviewed. It should be possible to 657 include precipitation and soil moisture from surface or microwave measurements, but it would 658 be important to consider scaling effects when using these data. Surface precipitation and soil 659 moisture measurements are in effect point measurements, limiting the possibilities for 660 upscaling. On the other hand, while the footprint of microwave observations is typically greater 661 than the resolution of vegetation indices. For example, the resolution of the microwave-based 662 Global Precipitation Measurement (GPM) is about 5 km. Global microwave soil moisture 663 observations are currently available at scales of around 25 km, although there are ongoing 664 efforts to downscale remote sensing soil moisture data sets, as reviewed by Peng et al. (2017). 665 If precipitation is used as an input variable, a lag effect must be considered as the moisture 666 made available in a precipitation event may remain available for several days. By contrast, soil 667 moisture is a more immediate measure of water availability and a lag effect would not be 668 expected.

669

670 Overall, the performance of the VI algorithms is consistent with what has been seen in previous671 work with those algorithms and with other methods for obtaining ET from remote sensing.

Where possible, it is preferable to use algorithms with more input data parameters and a more realistic basis to their parameterization, although the specifics of the underlying basis appear to matter little. Simpler algorithms can perform almost as well as more complex ones, but it is more important that they be tuned with appropriate training data. At a minimum, inclusion of R_n as a parameter along with VI is recommended wherever possible.

677

678 6. Conclusions

679 In this study, we have confirmed that many simple regression methods can work to obtain LE 680 on daily time scales with error levels comparable to those from more complex methods. We 681 have noted certain patterns in the performance of these algorithms. Increasing the number of 682 variables included in regression formulas tends to improve performance, although the specific 683 form of model used is not as significant. Those algorithms in which net radiation was one of the 684 input variables produced much less error than those that did not, as demonstrated by the 685 difference between the Yebra (2013) ET (YET) algorithm, and Yebra (2013) EF (YEF) algorithms, 686 which are very similar to each other except that YEF has net radiation as an input while YET 687 does not. (Figures 2, 3, 4). Tuning of the regression coefficients to the global data set improved 688 performance in most cases, which is also demonstrated in Figures 2-4. This improvement was 689 most significant for those models with fewer input variables. For wetland and agricultural 690 surface types, tuning with data specific to that surface type produced improved results (Figures 691 6-8), but this was not the case for other surface types.

692

693 There are multiple opportunities for adaptation and improvement of the methods evaluated 694 here. All of the input variables to the regression formulas are potentially available through 695 remote sensing (Liang 2007, Liang et al. 2012) or reanalyses, so there is the potential for 696 removing all dependence on ground-based observations. In addition, additional variables such 697 as soil moisture and precipitation that are not included in the set of empirical algorithms 698 evaluated here could be included in similar algorithms in the future if issues with spatial 699 resolution can be addressed. 700 701 Acknowledgements: This work is partially funded by NASA and NOAA grants. Funding for AmeriFlux data resources was provided by the U.S. Department of Energy's Office of Science. 702

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