

1 **Estimating Wave Attenuation at the Coastal Land Margin with a GIS Toolbox**

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3 **Madeline R. Foster-Martinez^{a,1*}, Karim Alizad^b, Scott C. Hagen^{a,c,d}**

4

5 ^a Center for Coastal Resiliency, Louisiana State University; 124B Sea Grant, Baton Rouge, LA 70803, US

6 ^b Belle W. Baruch Institute for Marine and Coastal Sciences, University of South Carolina; Columbia, SC
7 29208, US

8 ^c Department of Civil and Environmental Engineering, Louisiana State University; 3255 Patrick F. Taylor,
9 Baton Rouge, LA 70803, US

10 ^d Center for Computation and Technology, Louisiana State University; 1079 Digital Media Center
11 Baton Rouge, LA 70803, US

12

13 *corresponding author, Telephone: +1 504-782-2172

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15 **Email addresses:** M.R. Foster-Martinez (mrfoster@uno.edu); K. Alizad (alizad@sc.edu); S.C. Hagen (shagen@lsu.edu)

16

17
18 ¹Present address: Pontchartrain Institute for Environmental Sciences, University of New Orleans; 2000
19 Lakeshore Drive; Rm 1036 Geology-Psychology; New Orleans, LA 70148, US

20

21 **Abstract**

22 Wave attenuation is a key process that impacts activities at the coastal land margin and is an ecosystem
23 service provided by many natural landscapes. Traditional modelling tools for wind wave attenuation re-
24 quire advanced expertise to apply. We present an alternative, GIS-based option for estimating wave at-
25 tenuation, the Wave Attenuation Toolbox (WATTE). The outputs are a map of wave height transmission
26 as a percentage of the original wave height and a line demarking the extent of wave exposure onshore.
27 WATTE supports a variety of inputs, ranging from outputs of ecological and landscape evolution models
28 to remote sensing data, and past, present, and future conditions can be analyzed. The present version of
29 WATTE models wave attenuation as an exponential decay process, and a recommendation table for ex-
30 ponential decay constants is derived from previous studies. Three examples of applying WATTE to marsh
31 environments are described.

32

33 **Key Words**

34 Wave attenuation; GIS toolbox; Coastal process; Marsh; Ecosystem services; Participatory modeling

35

36 **Software Availability**

37 Name: Wave Attenuation Toolbox

38 Developer: M. Foster-Martinez (contact information above)

39 Year: 2020

40 Software required: ArcMap 10.3 or later with Spatial Analyst extension. Optional features require the
41 Advanced license.

42 Language: Python

43 Size: 32 KB

44 Availability: A digital object identifier (DOI) will be assigned to the toolbox code, and the code will be
45 made publicly available on Github (GNU General Public License v3) if the manuscript is accepted for pub-
46 lication.

47 Cost: Free

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49

50 **1. Introduction**

51 Wind-waves largely determine the form and function of the coastal land margin. About half the total en-
52 ergy for all natural coastal processes (*i.e.* biological, chemical, and physical processes) come from waves
53 (Leigh et al., 1987; Short, 2012). Wave energy is dissipated in the nearshore primarily through breaking
54 and encountering frictional elements. Natural coastal ecosystems and structures attenuate wave action,
55 including mangroves (Abuodha & Kairo, 2001; Ilman et al., 2016), coral reefs (Hughes et al., 2018),
56 seagrass beds (Guannel et al., 2016; Waycott et al., 2009), marshes (Crosby et al., 2016; K. Bromberg
57 Gedan et al., 2009; Gedan et al., 2011), and oyster reefs (Wiberg et al., 2018). Anthropogenic activity has
58 indirectly and directly altered the patterns of wave energy. Marine structures (*e.g.* breakwaters, sea
59 walls, revetments, etc.) directly prevent wave penetration in some areas, while enhancing wave reflec-
60 tion and increasing wave energy in others (Reeve et al., 2018). Land conversion for shoreline develop-
61 ment and the effects of climate change have damaged and decreased the area of vegetated coastal eco-
62 systems by as much as 50% since mid-twentieth century (Duarte et al., 2013). At the same time, the use
63 of natural and nature-based features (NNBFs) for coastal protection is gaining recognition for being cost-
64 effective and providing multiple benefits (Bridges et al., 2015; Narayan et al., 2016; Sutton-Grier & San-
65 difer, 2018). As changes in the coastal land margin continue to occur, it is important to understand and
66 communicate the impacts on wave energy.

67 Here, we have created a Geographic Information Systems (GIS) toolbox that estimates and maps wave
68 attenuation. The present version of the toolbox is built for estimating wave attenuation through
69 marshes; however, it could be readily adapted to other coastline types (*e.g.* mangroves, seagrass beds,
70 kelp forests). The toolbox leverages existing datasets from a range of sources including remote sensing
71 and coastal landscape evolution models, allowing for analysis of past, present, and future conditions. By
72 using a simple algorithm, the toolbox does not require advanced expertise to apply and remains accessi-
73 ble to a range of stakeholder groups (*e.g.* local resource managers, agencies, and non-profits). The fol-
74 lowing sections provide background on wave attenuation and modeling tools and describe the toolbox
75 algorithm. We present three examples that illustrate potential uses of the toolbox, followed by discus-
76 sion and conclusions.

77 **2. Background**

78 **2.1. Wave Attenuation through Marsh Vegetation: Processes, Measurement, and Modeling**

79 Wave energy is a function of wave height (*i.e.* the vertical distance between the crest and trough of a
80 wave); waves with larger wave heights have greater energy. As waves move onshore, many dissipative
81 processes are at work, such as wave breaking and friction due to bottom roughness, but on healthy veg-
82 etated shorelines, encountering vegetation is the primary energy dissipation mechanism under normal
83 conditions (*i.e.* non-storm) (Guannel et al., 2015; I. Möller et al., 1999). Vegetation has the greatest im-
84 pact on waves with shorter wave periods (*i.e.* < 1 min) (Paquier et al., 2016; van Rooijen et al., 2016),
85 which include wind-generated sea-swell and infragravity waves (Munk, 1950).

86 The amount waves are attenuated across a marsh can vary greatly between sites or even at the same
87 site under different conditions (Koch et al., 2009; Pinsky et al., 2013). Greater attenuation is observed
88 when vegetation occupies a greater proportion of the water column, which can be due to increased
89 stem density, width, or height (Peruzzo et al., 2018). That proportion can change over the course of a
90 tidal cycle, as the ratio of the water depth to vegetation height changes, or between vegetation patches
91 with varying characteristics (*e.g.* stem density, width, and stiffness). Therefore, a range of attenuation
92 that can be expected at a site is more meaningful than one single value.

93 Field measurements of wave attenuation through marshes measure wave heights at multiple points
94 along a transect perpendicular to the shoreline (*e.g.* Jadhav & Chen, 2013; I. Möller & Spencer, 2002).
95 With known locations of instruments, the decrease in wave height per unit length along the transect can
96 be calculated. Underlying this method is the assumption that wave refraction causes the waves to cross
97 the marsh parallel to the shoreline (Komar, 1998).

98 The way wave attenuation is modeled depends on the application. Here, we chose to model it as an ex-
99 ponential decay (Kobayashi et al., 1993):

$$100 \quad W_T = H_1/H_0 = e^{-kx} \quad (\text{Eq. 1})$$

101 Where W_T is the fraction of wave height transmission; H is wave height; 1 and 0 subscripts denote the
102 location closer to onshore and offshore, respectively; k is the exponential decay constant; and x is the
103 cross-shore distance between H_1 and H_0 . This model requires minimal input (*i.e.* only k) and describes
104 field measurements well (Tempest et al., 2015 and references therein).

105 There are multiple other hydrodynamic models that include the effects of vegetation with varying levels
106 of complexity and applicable spatial scales. Large-scale models typically represent vegetation as bottom

107 friction and parameterize it via Manning's n (*e.g.* ADCIRC (Luettich Jr et al., 1992)). This representation is
108 appropriate for storm surge but is not as useful for wind waves, where vegetation is more directly im-
109 pactful. Models that do address wind wave-vegetation interaction often model vegetation as a drag
110 force, as originally described by Dalrymple et al. (1984). Examples include XBeach-VEG (Roelvink et al.,
111 2009; van Rooijen et al., 2015), SWAN-VEG (Simulating Waves Nearshore-Vegetation (Suzuki et al.,
112 2012)), and the InVEST (Integrated Valuation of Ecosystem Services and Tradeoffs) Coastal Protection
113 model (Guannel et al., 2015). These models require a drag coefficient for the vegetation, which has been
114 shown to vary with hydrodynamic conditions (*e.g.* Reynolds number (Möller et al., 2014) and Keulegan-
115 Carpenter number (Jadhav & Chen, 2013)). Other required inputs include vegetation parameters (*e.g.*
116 stem count) and wave parameters (*e.g.* wave number and height). Most of these models operate on a
117 mesh grid and need advanced expertise to run. They can be run to simulate past, present, or future con-
118 ditions (*e.g.* Hijuelos et al., 2019). The GIS toolbox presented in this paper is in no way intended to re-
119 place any of the aforementioned models, but rather, it is a simpler alternative that may be more suita-
120 ble for some communities' modeling and information needs.

121 **2.2. Related Tools for Coastal Planning**

122 Method frameworks have been created specifically for the assessment of natural systems for coastal
123 protection. For example, Osorio-Cano et al. (2017) describe a four stage process, beginning with param-
124 eterization of the natural system and ending with a coastal management plan. The framework includes
125 an assessment of wave attenuation using advanced numerical models (*e.g.* XBeach (Roelvink et al.,
126 2010)). Similarly, van Zanten et al. (2014) present a framework that uses information on the wave atten-
127 uation capacity of coral reefs to calculate their coastal protection value. For both frameworks, a lack of
128 site data or of model expertise could prevent a user group from completing the critical step of assessing
129 wave attenuation capacity and progressing in the framework.

130 The Coastal Protection Nearshore Wave and Erosion module of InVEST (Guannel et al., 2015; Tallis et al.,
131 2010) provides a framework and toolboxes that operate in a GIS environment. InVEST estimates the
132 value of coastal protection services for a range of coastal environments (*e.g.* Doughty et al., 2017;
133 Ruckelshaus et al., 2016) by using the damage averted (*i.e.* erosion) to assess value. It produces wave
134 attenuation estimates along a single cross-shore transect and requires detailed information, such as
135 cross-shore bathymetry and wave parameters, to run. Since its initial development, InVEST has evolved,

136 and this module is no longer being maintained by developers. However, the broad use of the module
137 demonstrates the overall need for this type of information.

138 **3. Methods**

139 This paper describes the **Wave Attenuation (WATTE) Toolbox**, a custom ArcGIS toolbox that is run within
140 ArcMap (ArcGIS, 2018). The code is open source and available for download (*note to editor and review-*
141 *ers: a DOI for the code will be available through Github after publication acceptance*). The present ver-
142 sion of WATTE estimates the decrease in wave height that occurs as waves cross through marsh vegeta-
143 tion using an exponential wave decay formulation (*i.e.* Eq. 1). WATTE uses an image of the region of in-
144 terest and simulates a process similar to how wave attenuation is measured in the field. The output is an
145 estimate of wave height transmission throughout the entire marsh.

146 **3.1. Toolbox Algorithm**

147 WATTE executes the following steps, which are illustrated in Figure 1.

- 148 • Inputs: The main inputs are a raster of the area of interest classified by land type (Figure 1a) and ex-
149 ponential decay constants for each marsh classification.
- 150 1. Identify the marsh-water interface: Each cell classification in the raster is converted to a polygon,
151 and the edges of the polygons are converted to polylines. A new line, the marsh-water interface line,
152 is created where marsh and water polylines intersect (black line Figure 1b).
- 153 2. Draw cross-shore transects: Transects, polyline features, are drawn perpendicular to the marsh-wa-
154 ter interface line, extending in both onshore and offshore directions. The transect length and spac-
155 ing are user-specified (white lines Figure 1b; Ferreira & Cooley, 2013).
- 156 3. Generate point features along each transect: The onshore direction of the transect is identified by
157 examining the classifications of the raster cells around the marsh-water interface. Point features are
158 generated along the onshore side at the user-specified interval (white dots Figure 1c).
- 159 4. Calculate wave height transmission: For each transect, starting at the point closest to the marsh-wa-
160 ter interface, the amount of wave height transmission is calculated at each point feature as follows:

$$161 \quad W_{T,1} = W_{T,0} e^{-kx} \quad (\text{Eq. 2})$$

162 Where 1 and 0 subscripts denote the point on the transect closer to onshore and offshore, respec-
163 tively, and x is the distance between the two points. The classification of the onshore point location

164 determines the k -value used (*e.g.* the yellow and green areas have different k -values in Figure 1).
165 The information is passed down each point on the transect so that the previous $W_{T,1}$ becomes $W_{T,0}$
166 (shaded dots Figure 1d).

167 5. Repeat Step 4 for each transect (Figure 1e).

168 6. Remove point clustering: The ends of transects along a convex coast can become bunched together.
169 To reduce point-clustering, points closer than half the point-spacing interval are compared in a pair-
170 wise fashion. The point farther from the marsh-water interface is removed. This process continues
171 until all points remaining are separated by at least half the point-spacing interval. This step is op-
172 tional and is only performed if this user has the Advanced ArcGIS license.

173

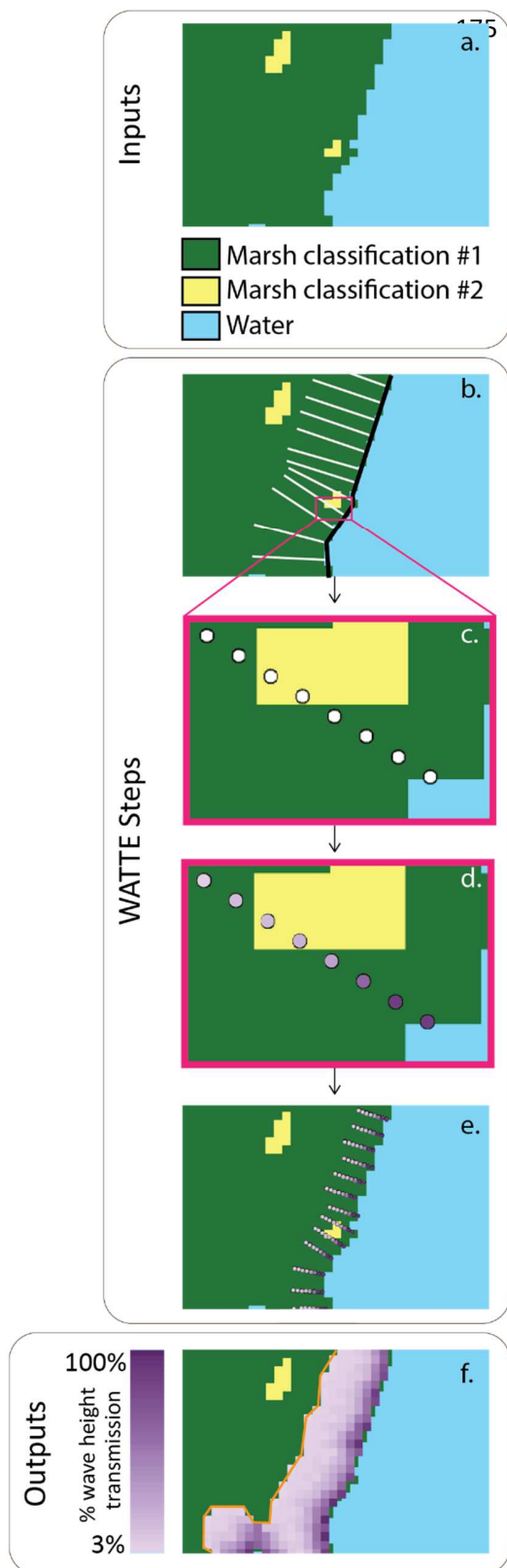


Figure 1: Required inputs, steps of the algorithm, and outputs for WATTE. Parts a through f are a generic example and illustrate the process. Areas in blue are water, and areas in green and yellow are two different marsh classifications. Please refer to Section 3.1 for details.

- 176 7. Interpolate the W_T values of all points: Inverse distance weighting or kriging is used to interpolate
177 between all points (Figure 1f). The interpolation method is selected by the user. The underlying
178 equation (Eq. 2) is one-dimensional, but by executing it at many points and interpolating between
179 them, the results appear two-dimensional.
- 180 • Outputs: The outputs are a raster of the percent wave height transmission and if the user has the
181 Advanced license of ArcGIS, a polyline bounding the area of wave influence (*i.e.* complete attenua-
182 tion line, orange line Figure 1f).

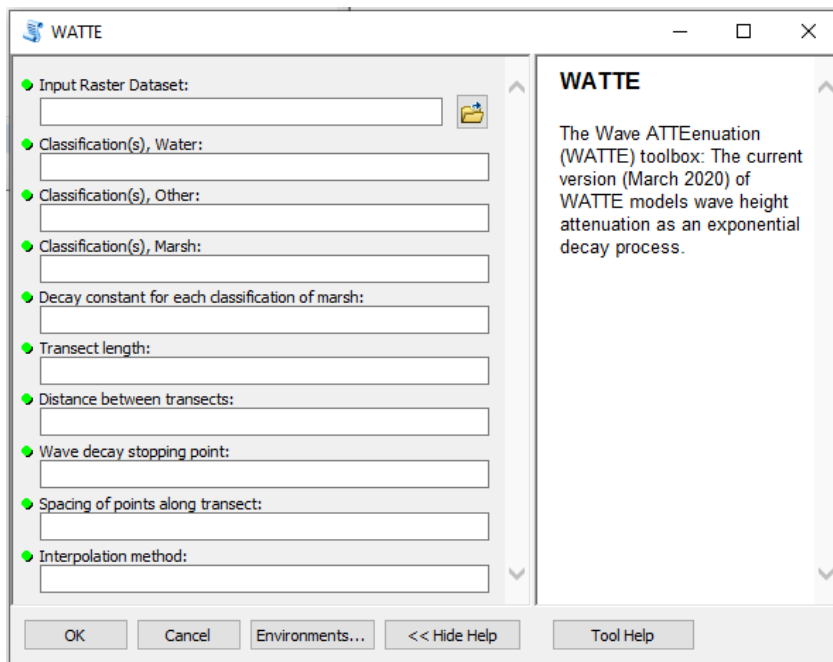
183 Each run of the WATTE toolbox simulates one set of conditions. We recommend performing multiple
184 runs, altering the exponential decay constants each time, to study a variety of conditions and bound the
185 wave attenuation estimates.

186 **3.2. Wave Attenuation Toolbox Development**

187 **3.2.1. Inputs**

188 The cells of the input raster must be classified as marsh, water, or other (examples shown in Figure 1a
189 and Figure 3). Marsh is defined as vegetated areas within the intertidal zone, and water is defined as ar-
190 eas within or below the intertidal zone that are void of vegetation. “Other” can be any non-inundated
191 landcover, such as forest or upland that is elevated above the tidal prism. At a minimum, the raster must
192 contain two classifications, marsh and water, but there can be unlimited classifications within the three
193 categories of marsh, water, and other. Classifications could correspond to any characteristics, such as
194 different vegetation species or different levels of biomass productivity. Possible sources of input rasters
195 include the National Wetland Inventory (NWI), data from remote sensing, or the output of land evolu-
196 tion models (*e.g.* marsh migration models like Hydro-MEM (Alizad, Hagen, Morris, Bacopoulos, et al.,
197 2016) and SLAMM (Park et al., 1986)). NWI maps and output from marsh migration models have the
198 advantage of already being classified. Data from remote sensing needs to be processed to classify each
199 raster cell, and there are existing methods for doing so (*e.g.* Farris et al., 2019; Ozesmi & Bauer, 2002).
200 The raster is not required to be a digital elevation model (DEM) or to contain any elevation information.
201 For the current version of WATTE, each marsh classification must be assigned an exponential decay con-
202 stant, k , which is input by the user. Ideally, k should be calculated from measurements of wave attenua-
203 tion at the site or an area with similar characteristics. If limited site information is available, the guid-
204 ance table described in Section 3.3 can be used to set the values.

205 Although the transects are generated within the toolbox, the user must specify the length of the transects,
206 the distance between them, and the spacing of points along the transect. Figure 2 shows a screen-
207 shot of the WATTE user interface, where this information is specified by the user. The spacing of the
208 transects and of the points should be determined by the site characteristics and the resolution of the
209 raster. If a site has many different marsh classifications, closer spacing is needed as compared to a site
210 with only one or two marsh classifications. One point per raster cell is generally recommended. To be
211 conservative, the total length of the transect should be longer than what is expected for complete atten-
212 uation. For example, if observations at the site indicate wave action dies off about 100 m into the marsh,
213 then the transects should be at least 120 m, 20% greater.



214

215 *Figure 2: The user interface for the WATTE toolbox. Instructions for each input appear in the right panel as the user clicks*
216 *through. The inputs shown are described in Section 3.2.1.*

217

218

219 The wave calculation (Step 4) will continue moving inland along the points on the transect until one of
220 the following occurs: wave transmission, $W_{T,1}$ (Eq. 1), is below the user-defined threshold; the transect
221 point is on a non-marsh raster cell; or the full length of the transect is reached. In the example shown in
222 Figure 1, the wave transmission threshold is 3%. In other words, once the wave height is attenuated by
223 97%, the wave is considered completely attenuated and further decrease in wave height is not calcu-
224 lated. There is no information on bathymetry or topography within WATTE, and all areas classified as
225 marsh are possible areas for wave propagation. This simplification implies the water level scenario
226 should be sufficient to fully inundate the marsh, so the waves could theoretically propagate throughout
227 the marsh.

228 **3.2.2. Outputs**

229 The WATTE outputs are a raster of wave height transmission (*i.e.* the percent of original wave height)
230 and the complete attenuation line. This line demarks the extent of wave exposure onshore. If the wave
231 transmission reaches the threshold, the “wave” is considered completely attenuated, and the complete
232 attenuation line is generated. Any marsh farther onshore is not considered to be influenced by wave ac-
233 tion. The absence of this line in an area indicates it is within wave exposure. If the user does not have
234 the Advanced ArcGIS license, the complete wave attenuation line must be generated manually using the
235 WATTE output raster. Instructions for manually producing this line are included with the code.

236 The output raster values are 100% at the marsh-water interface and decrease moving inland. This per-
237 centage of wave height transmission can then be multiplied by an initial wave height to show the atten-
238 uation in terms of wave height. While two locations may have the same transmission percentage, they
239 may not experience the same wave energy due to their location within the area. Shores exposed to
240 greater fetch are likely to receive larger waves as compared to more sheltered areas. The transmission
241 calculation does not consider whether the area is exposed or sheltered.

242 **3.2.3. Assumptions and Uncertainty**

243 Within WATTE, it is assumed that wave height transformation through vegetation can be modeled as an
244 exponential decay (addressed in Section 2.1) and that waves are parallel to the marsh-water interface.
245 The second assumption is common in attenuation field measurements when the measurement locations

246 can be selected to better ensure it is true (*i.e.* locations where the bed slope does not vary greatly in the
247 cross-shore direction). Here, we extend it to all points along the marsh-water interface, which includes
248 coastlines with small channels. Wave attenuation results in these areas should be interpreted cau-
249 tiously. Due to limited fetch, it is unlikely that narrow channels contain sizable waves; however, flow in
250 marsh channels does tend to be perpendicular to the marsh edge (Temmerman et al., 2012), which sup-
251 ports applying this assumption.

252 WATTE has three main types of uncertainty: initial conditions, model, and parameter (Dietze, 2017). Ini-
253 tial condition uncertainty refers to how accurately the input raster represents conditions on the ground.
254 This uncertainty will vary greatly if the input is based on past or current conditions versus projected fu-
255 ture conditions. The model uncertainty is set by the formulation chosen for WATTE, exponential decay.
256 This model was chosen in part because it minimizes the number of parameters, thereby constraining the
257 parameter uncertainty. We focus on parameter uncertainty for the remainder of the document because
258 it comes from the choice of the exponential decay constant, k , which users can manipulate easily.

259 **3.3. Selection of Exponential Decay Constants**

260 As described in Section 3.2.1, an exponential decay constant is required for each marsh classification.
261 The following guidance table is provided to aid with this selection when wave attenuation measure-
262 ments or observations are not available (Table 1). Since k is the only parameter in the exponential decay
263 model, it contains all of the complexity of vegetation-wave interactions that causes differences in wave
264 attenuation. For this recommendation table, we distilled this complexity to two metrics: biomass and
265 inundation; both are often reported as influencing wave attenuation capacity (Shepard et al.,
266 2011). Within each of these two metrics, there are three classes (low, medium, and high), creating a total
267 of nine values of k .

268 Biomass is influenced by a range of factors; the low, medium, and high biomass categories capture dif-
269 ferences due to physical, biological, and geochemical processes. For example, seasonal shifts (Schoutens
270 et al., 2019), differing hydroperiods (Morris et al., 2002), and subsurface characteristics (Wilson et al.,
271 2015) have all been shown to create differences in biomass productivity and are represented by this
272 metric.

273 The inundation metric does not refer to the hydroperiod, but rather, to the water depth at which the
274 model will be run. Low inundation is when the water depth is low relative to the height of the vegeta-
275 tion, and the vegetation remains emergent. At the other end, high inundation is when the vegetation is
276 deeply submerged. Ratios of vegetation height to water depth (h_{water}/h_{veg}) have been given for each
277 category to guide the selection.

278 To populate Table 1, we compiled measured values of k from field studies of species within the *Spartina*
279 genus. Due to limited data availability, all species within the *Spartina* genus are grouped together. While
280 there are many non-*Spartina* species in marshes, there is more available *Spartina* data because this veg-
281 etation is common in the low marsh and interacts with waves. Laboratory studies were excluded be-
282 cause by design they often do not capture all of the physical processes at work.

283 The available studies were sorted as containing low, medium, or high biomass density. The decay con-
284 stants in each biomass category were informed by three studies (cited in Table 1). Web Plot Digitizer
285 (Rohatgi, 2018) was used to extract data from published figures. The results from each study were orga-
286 nized by increasing water depth to vegetation height ratio. If this information was not provided, the ra-
287 tio was calculated from the given vegetation height, water depth, and/or site slope, even if the given
288 values were averages. The measured values of k were averaged in each of the nine categories to provide
289 the recommendations. There is an upper limit of 4 for the ratio of water depth to vegetation height.
290 There are limited measurements beyond this depth, as the impact of vegetation diminishes when deeply
291 submerged. The k -values provided span a wide range; using the values for medium biomass, the dis-
292 tance of marsh needed to reach 50% attenuation (*i.e.* half the wave height at the shoreline) varies from
293 13 m to 116 m for low and high inundation conditions, respectively.

294 To be clear, Table 1 is not required to run WATTE. The user can input any value for the exponential de-
295 cay constant. We recommend using location-specific data, if it is available. Regardless of the source of
296 the values, we suggest performing multiple runs using the upper and lower bounds of probable values.
297 For example, the combination of low productivity and high inundation gives the lowest amount of wave
298 attenuation, the most conservative result.

299 *Table 1: Guidance table for the selection of decay constants. Each of the nine categories contains the exponential decay con-*
300 *stant, k [1/m], which is the mean of the literature values; the number of data points used in the mean, n ; and the inter-quartile*
301 *range, IQR. ^a The studies used to inform the low-biomass values are Coulombier et al., 2012; Foster-Martinez et al., 2018 (win-*

302 ter dataset); Paquier et al., 2016. ^b The studies used to inform the medium-biomass values are Foster-Martinez et al., 2018 (sum-
 303 mer dataset); I. Möller, 2006; Ysebaert et al., 2011. ^c The studies used to inform the high-biomass values are Jadhav & Chen,
 304 2013; Knutson et al., 1982; Yang et al., 2012. [#]The number of data points is 2, making the IQR simply the difference between the
 305 values. *No data was available for high biomass-high inundation conditions, and the value was selected based on the trend for
 306 high biomass in the low and medium inundation categories.

		Inundation Level								
		Low			Medium			High		
h_{water}/h_{veg}		<1			≥1 & <2			≥2 & <4		
		k [1/m]	n	IQR	k [1/m]	n	IQR	k [1/m]	n	IQR
Biomass Level	Low ^a	0.035	2	0.001 [#]	0.021	19	0.011	0.001	12	0.004
	Medium ^b	0.055	7	0.059	0.030	10	0.035	0.006	5	0.010
	High ^c	0.107	6	0.121	0.090	14	0.120	0.015*	-	-

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308 4. Examples of WATTE Application

309 4.1. Example 1: Validation of Exponential Decay Constant Selection

310 The performance of WATTE results heavily depends on the selection of the exponential decay constants.
 311 In an effort to validate the provided guidance table, the values of k for the following example were se-
 312 lected from Table 1 and were based on a description of vegetation and measurement conditions alone.
 313 The results are then compared to the measured wave attenuation at the site.

314 Morgan et al. (2009) examined differences in functions between meadow and fringing salt marshes in
 315 Maine and New Hampshire, US. We use their measurements of wave attenuation at the Mousam River
 316 site, where the low marsh is dominated by *Spartina alterniflora*. These measurements were not used to
 317 inform the values in Table 1, making it an independent validation. To apply WATTE, we acquired an aer-
 318 ial image from 2009 of the study area taken by the National Agriculture Imagery Program (NAIP). The
 319 image was classified with a K-means approach (Duda & Canty, 2002) using Earth Resources Data Analysis
 320 System (ERDAS) IMAGINE software (ERDAS Imagine, 2018). By visual inspection, we determined that
 321 classifying the image with five categories accurately distinguished water, marsh, and non-marsh.

322 The five classes included two classes that were judged to be water, two classes of marsh, and one class
 323 of non-marsh (Figure 3). We selected two sets of k -values to bound the wave attenuation estimate. In-
 324 formed by descriptions of the vegetation and of the site given in Morgan et al. (2009), the biomass level

325 of the two marsh classes was varied, and the inundation level was kept the same (Table 2). We esti-
 326 mated the marsh class along the perimeter of the area to be higher productivity than the marsh class
 327 more common in the interior. For the wave-height transmission calculation, points were generated
 328 every 1 m along each transect due to the NAIP image resolution of 1 m. The transects were set to be 100
 329 m long and to occur every 10 m along the marsh-water interface.

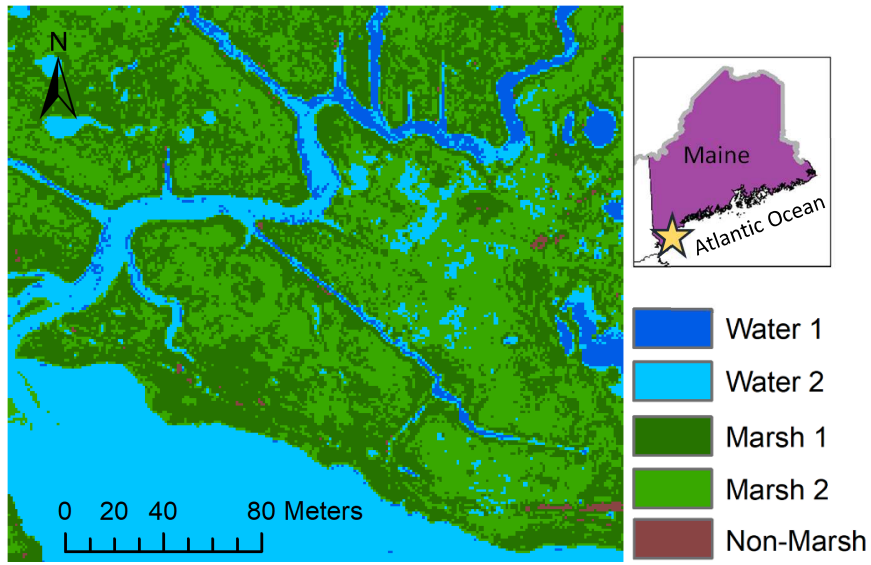
330 The average of three wave attenuation measurements were provided in Morgan et al. (2009). The re-
 331 sults from WATTE were extracted at the measurement location for comparison. The measured wave
 332 height decreased from an average of 10.9 cm at the shore to 8.4 cm at a point 5 m from the marsh edge,
 333 giving a wave height transmission of 77% (Morgan et al., 2009). Using WATTE, the lower estimate of
 334 wave-height transmission (higher attenuation) was 73%, and the upper estimate was 84%, accurately
 335 bounding the measured value. This result demonstrates the utility of the Table 1, as well as the necessity
 336 of running multiple cases to provide bounds on the results. Note, this case is over a short distance of 5
 337 m. The estimated distance needed to decay to a wave height of 5 cm, about 46% of original wave height,
 338 is 12 m for the upper bound and 21 m for the lower bound.

339 *Table 2: Comparison measured and estimated percent of wave height transmission at Mousam River, ME.*

Case		Exponential Decay Constant $k [1/m]$		Transmission of Wave Height (%)
Morgan et al. (2009)		--		77%
WATTE Lower Bound	Marsh Class 1	High Biomass Medium Inundation	0.09	73%
	Marsh Class 2	Medium Biomass Low Inundation	0.055	
WATTE Upper Bound	Marsh Class 1	Medium Biomass Medium Inundation	0.03	84%
	Marsh Class 2	Low Biomass Low Inundation	0.035	

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345

Figure 3: NAIP aerial imagery (1 m resolution) of a section of the salt marsh at the Mousam River, Maine US (yellow star). The image was classified using ER-DAS Imagine software with five classes.

347 **4.2. Example 2: Application to Grand Bay, USA**

348 WATTE can be applied to large areas of coast. In this example, WATTE was used to analyze 274 km of
349 marsh-water interface in the Grand Bay estuary, which spans Mississippi and Alabama in the US. The in-
350 put raster is the output from Hydro-MEM (Alizad et al., 2018). Hydro-MEM is a marsh migration model;
351 it couples ADCIRC, a hydrodynamic model, with the Marsh Equilibrium Model (MEM), a biological
352 model, to project maps of marsh productivity (Alizad et al., 2016a; Alizad et al., 2016b). The Hydro-MEM
353 maps show five area classifications: water; upland, which is land elevated above the tidal prism; and
354 low, medium, and high productivity marsh.

355 Exponential decay constants were selected to simulate conditions at mean higher high water (MHHW)
356 and were based on vegetation and elevation measurements taken to run Hydro-MEM. The results show
357 that complete attenuation is reached about 70 m into the vegetated marsh (Figure 4). This high rate of
358 attenuation can be attributed to the high productivity vegetation along the marsh-water interface. How-
359 ever, many small islands or marsh fragments are less than 70 m wide and are completely subjected to
360 wave action. The wave action varies throughout the estuary with more exposed areas having a longer
361 fetch and receiving larger waves. The marsh in the western portion is more protected than the eastern
362 side, and the waves will differ even if the wave transmission percentage is the same. If typical wave
363 heights are known for the different areas, the percentages of wave transmission can be converted to
364 wave heights by multiplying them by the known wave height or wave statistic (*i.e.* root-mean-square or
365 significant wave height) at the shoreline. Note, these results have not been validated with in-situ meas-
366 urements, but rather, are provided to show that WATTE can be applied at larger scales. Stakeholders
367 can gain more information from the Hydro-MEM results by using them in WATTE.

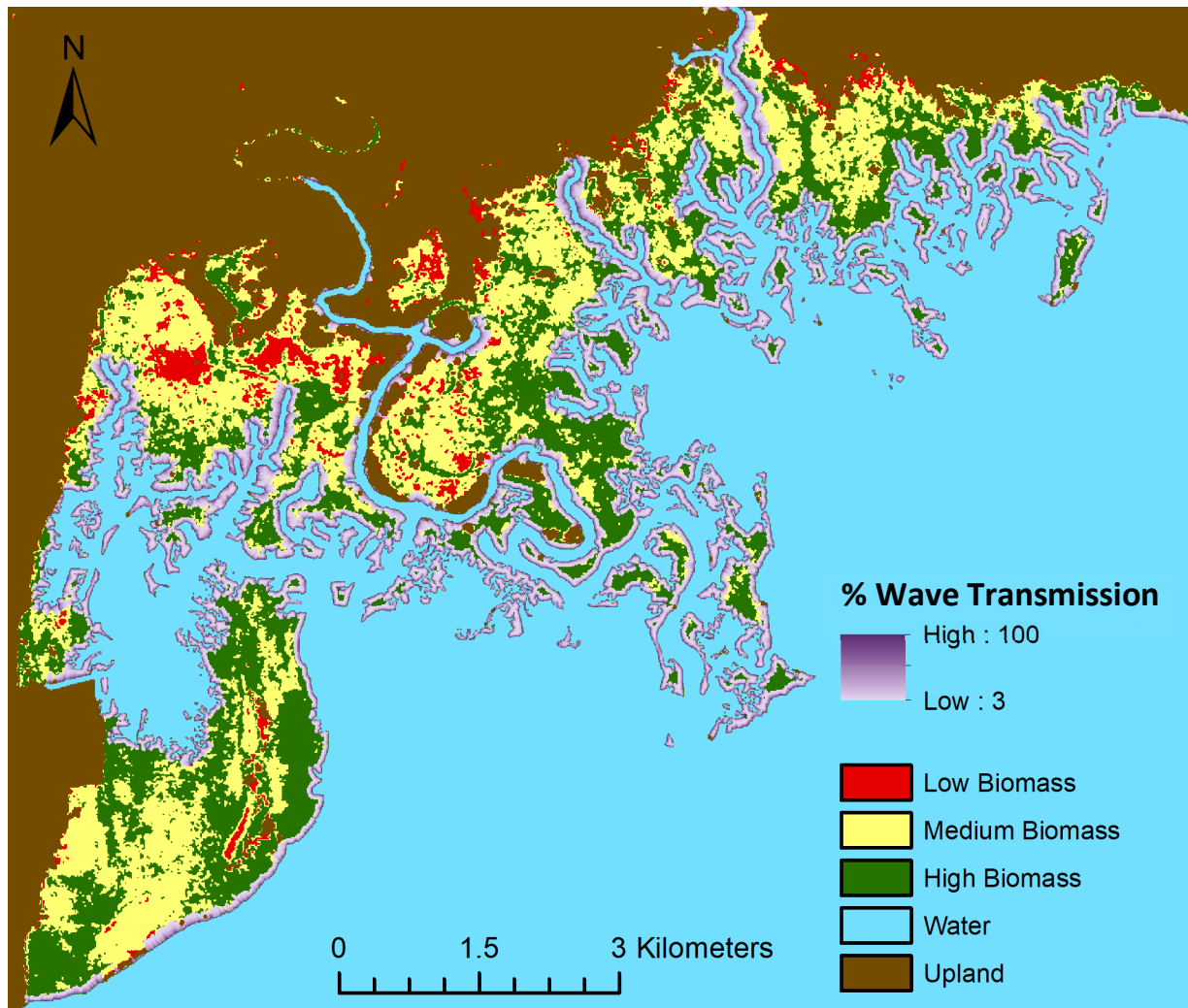


Figure 4: Base image is the result from Hydro-MEM in the Grand Bay region and the overlaid image (shades of purple) is the result from WATTE. This map covers 274 km of marsh-water interface. Grand Bay Estuary is located within the states of Mississippi and Alabama along the Gulf of Mexico in the US.

368

369 4.3. Example 3: Projections with Future Sea-Level Rise

370 There is a large effort in the scientific community to understand and predict marsh change with sea-level
 371 rise (SLR) and other future environmental conditions (Passeri et al., 2015; Schuerch et al., 2018 and ref-
 372 erences therein). As marshes change, the associated ecosystem services also change. Applying WATTE to

373

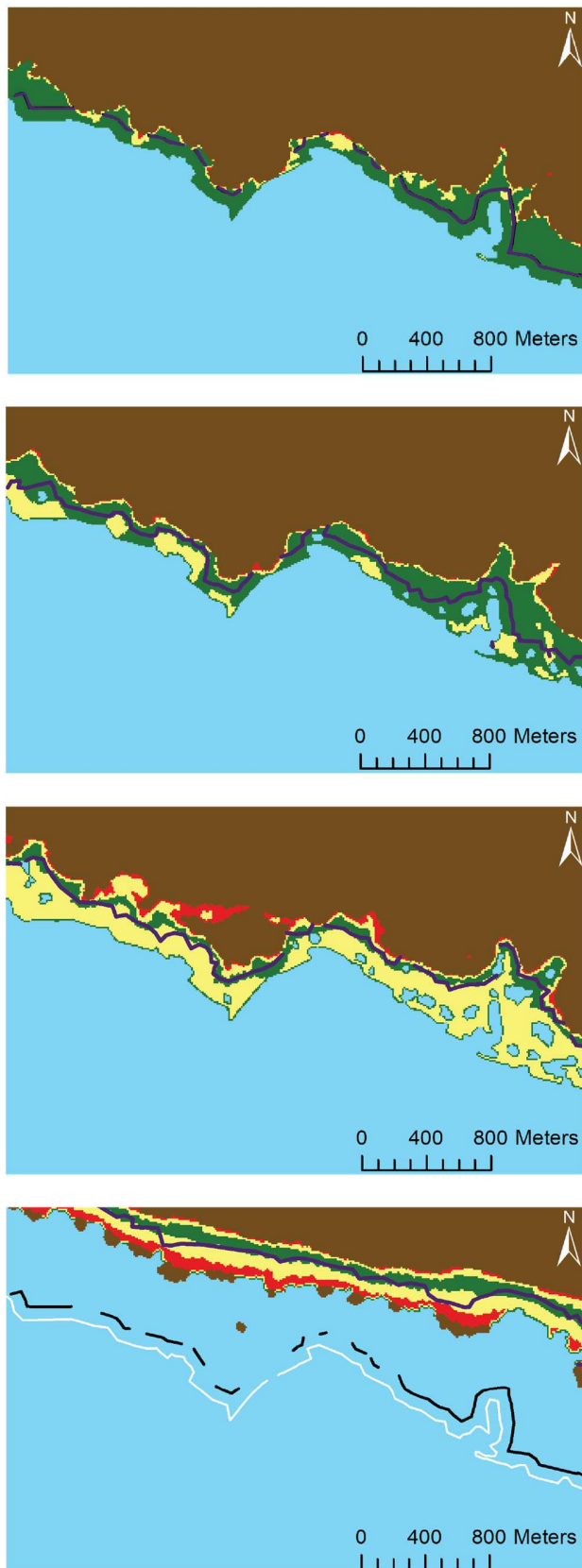


Figure 5: The base images are results from Hydro-MEM for a section of Grand Bay, AL. The results are from (a) 2010 with no SLR; 2050 with (b) intermediate-high SLR and (c) with high SLR; and (d) 2100 with high SLR. The purple line in all images indicates the line of complete attenuation, the extent of wave influence. White arrows in b and c indicate areas of upland exposed to wave action that are likely erosion-prone. White and black lines in d are the 2010 shoreline and line of complete attenuation, respectively. Please refer to the legend in Figure 4 for explanation of the colors.

375 these future projections allows for better understanding of how the ecosystem service of wave attenua-
376 tion will change in the future.

377 Hydro-MEM is one example of a model that projects marsh migration with SLR. We applied WATTE to
378 Hydro-MEM results from intermediate-high and high rates of SLR in an area of Grand Bay, Alabama
379 (Alizad et al., 2018). The complete attenuation line is shown for years 2010 (Figure 5a, no SLR), 2050
380 (Figure 5b, intermediate-high SLR; Figure 5c, high SLR) and 2100 (Figure 5d, high SLR). The rate of SLR
381 impacts the marsh migration pattern, and therefore, the wave attenuation pattern. With intermediate-
382 high SLR in 2050, the marsh retains high productivity, but the width of marsh narrows. For high SLR in
383 2050 and 2100, the marsh is largely composed of low productivity biomass; however, it increases in
384 width, and the inland portions of marsh are not as exposed to wave action. The areas where the upland
385 is exposed to wave action (indicated by white arrows in Figure 5) are more erosion-prone and could be
386 areas of targeted intervention. Figure 5d shows the marsh edge and complete attenuation line for 2010
387 overlaid on the high SLR results for 2100. The marsh retreat is apparent, as well as the widening of the
388 area influenced by waves.

389 Hydro-MEM results (Alizad et al., 2018) show that ponding occurs with high SLR in 2050 (Figure 5c). The
390 edges of these ponds are considered part of the marsh-water interface and are treated the same as the
391 marsh-water interface at the shoreline. Although waves being generated in interior ponds are likely
392 small, previous studies have shown that wind-generated shear stresses can lead to pond expansion, and
393 therefore, pond edges are included in WATTE (Day et al., 2011).

394 **5. Discussion**

395 **5.1. Evaluation of WATTE as a Participatory Modeling Tool**

396 By focusing on only the process of wave attenuation through marsh vegetation, WATTE can be used
397 within a variety of assessment methodologies and modeling frameworks. Its simplicity makes it suitable
398 for participatory modeling, where stakeholders are formally engaged in problem identification and anal-
399 ysis (Voinov et al., 2018). Due to the opportunity to learn and revise through process iteration, participa-
400 tory modeling is well-suited for addressing complex, environmental-management decisions (Stave,
401 2010), such as coastal protection plans and restoration activities. Tool selection should be tailored for
402 the particular project and stakeholders, as it is an important step in a successful application of the par-
403 ticipatory modeling process (Voinov & Bousquet, 2010).

404 Voinov et al. (2018) compared 17 types of participatory modeling tools grouped by four modeling meth-
 405 ods; GIS was categorized as a quantitative modeling method with aggregated results. Compared to other
 406 tools, the greatest strength of GIS was the ability to represent spatial results, as could be expected. It
 407 was also judged to be strong in ease of communication and modification. GIS tended to be weak in areas
 408 where many tools were weak, such as in handling uncertainty and representing temporal results (Voinov
 409 et al., 2018). We address the lack of uncertainty by recommending users run WATTE multiple times to
 410 bound the results. Temporal results can be achieved, if data throughout landscape changes is available
 411 WATTE input; the time scale would then be that of the land evolution changes.

412 We evaluated WATTE based on the eight criteria detailed in Bagstad et al. (2013) (Table 3). These crite-
 413 ria were developed to evaluate the usability of decision-support tools for quantification of ecosystem
 414 services and have been used to evaluate tools similar to WATTE. Overall, WATTE performs well, as it is
 415 publicly available and provides quantitative results. It can be applied to a wide range of spatial scales;
 416 increasing the scale simply increases the run time. Since it requires ArcGIS software, we judged it to be
 417 moderate cost. It does not have a valuation component, and it would therefore need to be used in con-
 418 junction with another tool in order to make economic assessments (see Barbier et al. (2013) for an ex-
 419 ample). We expect WATTE to be useful for a range of groups performing research at the coastal land
 420 margin and interested in assessing patterns of wave attenuation by coastal vegetation, including aca-
 421 demic institutions, industry, community groups, and non-profits (e.g. The Nature Conservancy, Climate
 422 Central).

423 *Table 3: Application of evaluation criteria from Bagstad et al. (2013) to WATTE*

Criteria from Bagstad et al. (2013)	WATTE
Quantification and Uncertainty	Quantitative; uncertainty can be determined by varying inputs
Time Requirements	Low to Medium, depending on availability of existing data
Capacity for Independent Application	Yes, if user has access to ArcGIS
Level of Development and Documentation	Fully documented with examples
Scalability	Multiple scales
Generalizability	High, within vegetated shorelines

Nonmonetary and Cultural Perspectives	No valuation component	424
		425
Affordability, Insights, and Integration with existing environmental assessment		426
	Useful as a moderate-cost estimation of wave attenuation	427
		428
		429

430 **5.2. Strengths and Limitations**

431 A core strength of WATTE is that it can provide reasonable estimates of wave attenuation with limited
432 information. As illustrated in Example 1 (Section 4.1), the input raster can be derived from remote sens-
433 ing data, which is more available for coasts across the globe as compared to in-situ measurements. Re-
434 mote sensing is a valuable resource for work in under-studied locations and is gaining recognition for its
435 usefulness in wetland restoration and management (Ganju, 2019). The exponential decay constants can
436 be sourced from measurements in a different area with similar conditions, and they can be varied in
437 multiple runs of WATTE to test bounding cases. Having only one parameter to manipulate simplifies this
438 process. Of course, the more that is known about a site, the more can be done with the WATTE results.
439 For example, converting from percentages of wave transmission to wave heights requires an under-
440 standing of typical wave conditions throughout the site. It should be noted that users must be careful
441 not to extrapolate results to extreme conditions (*e.g.* storm surge), unless data from these conditions
442 was used to calculate the exponential decay constants.

443 The benefit of flexibility also comes at the price of not being mechanistic. In the measurements of expo-
444 nential decay constants, all processes are bundled together. For example, if the stem density changes,
445 that parameter cannot be adjusted independently the way it can be in a drag model. The same is true
446 for changes in slope, which impact shoaling and bed friction processes. Instead of being directly ad-
447 justed, the effect of these changes on the exponential decay constant first needs to be judged.

448 Similarly, not requiring a DEM, or any elevation information, removes a barrier to usage, but it creates
449 additional factors to consider in the interpretation of the results. As stated in Section 3.2.1, wave propa-
450 gation can occur in any area classified as marsh and cannot occur in areas classified as “other.” That is
451 why it is important to run a scenario where the marsh is fully inundated or to designate non-inundated
452 marsh areas as “other.” If running a low inundation scenario, unrealistic wave propagation could occur
453 where the marsh is dry. This result is likely not common because high attenuation occurs at low inunda-
454 tion, and waves are often completely attenuated before reaching higher elevations. Another limitation is

455 that each transect is independent. There is no interaction between waves along different transects, even
456 if those transects overlap. When points along different transects are clustered together, the points
457 closer to the marsh-water interface are preferentially kept in the interpolation to produce a conserva-
458 tive estimate of attenuation (Step 6 in Section 3.1).

459 **5.3. Future Applications**

460 Wave attenuation is just one of many ecosystem services performed by marshes. Coastal projects incor-
461 porating marshes as NNBFs are widely promoted (Bridges et al., 2015; Shepard et al., 2011; Sutton-Grier
462 et al., 2018), yet to properly evaluate NNBFs against other options, formal recognition of the ecosystem
463 services is necessary (Sutton-Grier et al., 2015). WATTE can quantify the service of wave attenuation to
464 provide a more complete picture. Future iterations of WATTE can expand applicable shoreline types. The
465 exponential decay model is appropriate for some; for example, Pinsky et al., (2013) calculated exponen-
466 tial decay constants for previous studies of wave attenuation through kelp, mangroves, and seagrasses,
467 and Lacy & MacVean (2016) found wave attenuation over mudflats follows exponential decay with de-
468 cay constants that are inversely related to depth squared. However, it is likely other models will need to
469 be added to WATTE to address all shorelines of interest. Since the code is open source, we are hopeful
470 others will modify and improve it to suit particular project needs.

471 **6. Conclusions**

472 The accelerating rate of sea level rise creates additional impetus to study how coastlines will change and
473 to communicate the findings to a broader audience. It is important to communicate not only how
474 marshes will change, but also, how the associated ecosystem services will change, some of which may
475 have direct impacts on the lives of coastal residents. Here, we focus on wave attenuation by marsh veg-
476 etation and have presented an ArcGIS toolbox, WATTE, to estimate wave height transmission along any
477 given marsh shoreline. While vegetation-wave interaction is highly complex, there is a general consen-
478 sus that wave heights exponentially decay as they pass through or over vegetation (Tempest et al., 2015
479 and references therein). We model wave attenuation as an exponential decay to keep the process and
480 its application simple. WATTE can be applied to create location-specific estimates without extensive
481 field measurements or advanced numerical models. The results from WATTE add information to existing
482 datasets, enhancing their value. These datasets may be sourced from observations collected previously,
483 current data, or projections of future conditions. Datasets can also be manipulated to reflect anticipated
484 changes resulting from coastal projects, and the results can help evaluate these projects, estimating

485 their impact on wave energy at the site. This information can be used to identify priority areas for con-
486 servation and restoration.

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