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2	Integrating abundance and diet data to improve			
3	inferences of food web dynamics			
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Abstract

1. Both population abundances and chemical tracers are useful tools for studying consumer-resource interactions. Food web models parameterized with abundances are often used to understand how interactions structure communities and to inform management decisions of complex ecological systems. Unfortunately, collecting abundance data to parameterize these models is often expensive and time-consuming. Another approach is to use chemical tracers to estimate the proportional diets of consumers by relating the tracers in their tissues to those found in their food sources. Although tracer data are often inexpensive to collect, these diet proportions provide little information on the per-capita consumption rates of consumers. Here, we show how coupling these data sources leads to better estimates of consumption rates.

23 2. Our modeling approach integrates traditional multispecies population abundance 24 models with proportional diet estimates. We used simulations to determine whether inte-25 grated food web datasets were more informative than the standard abundance datasets and 26 demonstrated the use of our integrated approach by estimating consumption rates of hump-27 back whales (*Megaptera novaeangliae*) in the western Gulf of Alaska using abundances 28 coupled with stable isotopes as a tracer.

3. Our simulations demonstrated that integrated models improved the ability to resolve alternative hypotheses about the functional response and yielded more precise parameter estimates relative to standard food web models. The integrated data approach was especially informative under low sample sizes or high process variance. Our application of the integrated modeling approach to humpback whales indicated that fish averaged about 25% of whale diets, though this proportion declined over the course of the study. We also found that traditional abundance model estimates of humpback whale consumption were non-estimable and that the integrated food web model led to estimable consumption rates.

4. Our results show that integrating stable isotopes and abundance datasets provides an exciting way forward for parameterizing multispecies models in data-limited systems.

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We expect that future developments of these integrated approaches will extend current food web theory by allowing ecologists to study predation dynamics over seasonal time scales and at the individual level.

Keywords: integrated modeling | functional response | multispecies modeling | ecological
 tracers | stable isotopes | nonlinear time series | food web model

44 Background

Food web models allow ecologists to study how interspecific interactions drive the emergent complexity of communities (Thompson *et al.*, 2012). These models have revealed important relationships between biodiversity and ecosystem stability (May, 1972) and have practical applications for understanding the sensitivity of populations to the indirect effects of management decisions (Yodzis, 1998). Unfortunately, the difficulties inherent in parameterizing food webs limit both our ability to study the patterns of complex natural systems and the empirical applications of these models.

Collecting abundance data, which is commonly used to parameterize dynamic food web 52 models (e.g., Ives et al., 2003), is time-intensive and costly, as both predator and prey must be 53 surveyed. The sampled populations are also often a subset of all the relevant biotic and abiotic 54 factors in the system. Standard abundance models rely on using correlations between abun-55 dances through time to infer consumption rates. This approach has the potential to misidentify 56 the influence of factors such as unsampled populations and climate factors as direct interactions 57 between the sampled populations. A classic example of this phenomenon is apparent compe-58 tition, in which two negatively correlated populations appear to be competing but instead are 59 regulated by a consumer (Holt, 1977). 60

Bioenergetics modeling is another approach sometimes used to obtain consumption rates

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for multispecies models. This method uses routinely collected data to partition the energy ob-62 tained from food to an individual's growth, metabolism, and waste products (Ney, 1993). In the 63 few cases where validation of this approach is possible, estimates have routinely overestimated 64 consumption, sometimes by several orders of magnitude (Chipps & Wahl, 2008). One previous 65 study has coupled stable isotopes with bioenergetics models to determine prey consumption 66 (Caut et al., 2006). This approach, while useful, suffered from similar issues as standard bioen-67 ergetics models. Thus it is not clear that the bioenergetics approach is currently capable of 68 producing reliable consumption rates for multispecies models. 69

Direct measurements of individual diet through the use of ecological tracers has proven to be 70 a breakthrough in nutritional ecology (Phillips & Gregg, 2001; Galloway et al., 2015; Kartzinel 71 et al., 2015). Stable isotopes, in particular, have been used to estimate the trophic position of 72 species (Vander Zanden et al., 1999), the proportional diets of consumers (Phillips & Gregg, 73 2001), and parameterize ecological networks (Yeakel et al., 2012). Unfortunately, ecological 74 tracers such as stable isotopes have been of limited use for understanding food web dynamics as 75 they only measure diet proportions, which contain information on relative consumption, rather 76 than the per-capita consumption values necessary to model the effect of predators on their prey. 77 In this study, we propose a new integrated modeling approach for parameterizing food webs. 78 We show how to combine population abundance data collected at multiple trophic levels with 79 proportional diets of consumers, derived from stable isotopes, to estimate the functional re-80 sponse of consumers. Combining multiple independent data sources mirrors integrated methods 81 in population demography, which have successfully been used to parameterize complex models 82 (Schaub *et al.*, 2007). Our approach constrains consumption estimates to be consistent with 83 both the observed population dynamics and diets thus leading to predictions that are consistent 84 with empirical dynamics. 85

86 Methods

We demonstrate our integrated modeling approach in two ways. First, we simulated the discrete-87 time dynamics of a consumer-resource interaction. We fit two types of models to these simu-88 lated datasets, abundance and integrated data models (described in detail below). This com-89 parison allowed us to investigate how well each of the data models performed in both model 90 selection and parameter estimation. Second, we fit the abundance and integrated models to data 91 collected on humpback whales (Megaptera novaeangliae) and their prey in the western Gulf of 92 Alaska using continuous-time models. These continuous-time models illustrate how to account 93 for isotopic turnover in tissues occurring due to tissue replacement. 94

95 Models

96 Dynamical models

⁹⁷ In this section, we describe two sets of models that can be used to describe how the processes of ⁹⁸ population growth and regulation as well as interspecific interactions drive community dynam-⁹⁹ ics. The following section then describes how to connect these models to the data we collect.

The first set of difference equations is used to simulate time series of population abundances and of proportional diets. Discrete-time models may not be biologically realistic for many predator-prey processes they are often reasonable approximations, and for simulation studies they have the additional advantage that they are fast to simulate. The second set of models are continuous-time models of predation that we fit to a dataset of humpback whales and their prey. We use these continuous models to highlight how to the incorporate isotopic turnover of tissues.

Our system of difference equations contain a predator (P) and two prey (N_1, N_2) :

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$$P(t+1) = \left[\varepsilon_1 N_1(t) \left(1 - e^{-g_1(P(t), N_1(t), N_2(t))}\right) + \varepsilon_2 N_2(t) \left(1 - e^{-g_2(P(t), N_1(t), N_2(t))}\right) + P(t)e^{-\mu}\right] e^{\sigma_P Z_P(t)}$$

$$N_1(t+1) = \left[r_1 N_1(t)e^{-s_1 N_1(t) - g_1(P(t), N_1(t), N_2(t))}\right] e^{\sigma_1 Z_1(t)}$$

$$N_2(t+1) = \left[r_2 N_2(t)e^{-s_2 N_2(t) - g_2(P(t), N_1(t), N_2(t))}\right] e^{\sigma_2 Z_2(t)}.$$
(1)

The reproductive rate and strength of density dependence of each prey population is given by r107 and s, respectively. The density-independent mortality rate of the consumer is given by μ . Pop-108 ulations are subjected to process error at each time step, Z(t), drawn from a standard normal 109 distribution scaled by σ , the standard deviation. This error can be interpreted as temporal vari-110 ation in the reproductive rate (Ferguson & Ponciano, 2015). The term, $1 - e^{-g(P(t), N_1(t), N_2(t))}$, 111 is the probability that an individual in the prey population does not escape consumption, while 112 the efficiency of converting prey to new enemies is given by ε . Here we examined discrete-time 113 equivalents of the type I and type II functional response. For a discrete-time type I response 114 , $g(P(t), N_1(t), N_2(t))$ is given by cP(t), where c is the per-capita consumption rate of the 115 predator on the prey. For the type II response of the predator on the first prey population it is 116 $\frac{c_1P(t)}{1+c_1h_1N_1(t)+c_2h_2N_2(t)}$ (Mills & Getz, 1996) and the functional response for the second prey pop-117 ulation is given by $g_2(P(t), N_1(t), N_2(t)) = \frac{c_2 P(t)}{1 + c_2 h_2 N_2(t) + c_1 h_1 N_1(t)}$. Parameters used to simulate 118 system 1 are given in Table 1. 119

A discrete-time system is appropriate for host-parasite interactions or predator-prey interactions when the sampling frequency is high relative to reproductive and consumption rates. However, continuous-time models may be more suitable for many other systems. We consider such a continuous-time process in our analysis of a data set of humpback whales and their prey (data described in Section). This system is

$$\frac{N_{\text{fish}}}{dt} = r_{\text{fish}} N_{\text{fish}} - c_{\text{fish}} P N_{\text{fish}}$$

$$\frac{N_{\text{zoo}}}{dt} = r_{\text{zoo}} N_{\text{zoo}} - c_{\text{zoo}} P N_{\text{zoo}}.$$
(2)

The growth rates of fish and zooplankton are given by r_{fish} and r_{zoo} , while the per-capita consumption rates of fish and zooplankton by whales are given by c_{fish} . The yearly abundances of fish (N_{fish}), zooplankton (N_{zoo}), and whales (P) We did not build an explanatory model of within-year changes in humpback whales (P) because we assumed that this slow-growing population did not change throughout the feeding season and that changes between years may reflect factors other than limitation by prey, such as humpback whale's relatively recent release from commercial harvest (Gabriele *et al.*, 2017).

132 Data models

In this section, we describe how to fit food-web models using either abundance data or abundance data coupled with proportional diet data. Parameterizing these models with abundance data is a well-developed approach (see Ives *et al.*, 2003; Koen-Alonzo & Yodzis, 2005), however linking information about the proportional diets to these dynamics is novel. This link is achieved by understanding that the proportional diet is the total number of prey of a certain type consumed in a given time period relative to all of the predators consumption in that period. The number of consumed prey is given by the integral of the functional response.

Our first data model was informed using only the time series of abundances. This abundance model assumed that the population abundance at each time step followed a lognormal probability distribution representing fluctuations in the environment that were not accounted by our model. At each time step we conditioned abundance predictions on the previous time step, except for the first observation, which was only used to predict the second observation (following, Ferguson & Ponciano, 2014). In fitting the humpback whale dataset we also included the uncertainty in estimated abundances (P, N_{fish} , and N_{zoo}) as observation error. The full specification of this state-space model is given in Appendix S1.

Our second approach is an integrated data model that utilizes both the abundance and 148 proportional diet data to inform the models. The estimated dietary proportion data is linked 149 to abundances by recognizing that this proportion can be written in terms of the consumed 150 prey predicted by the functional response in the dynamical model. For the first prey popula-151 tion in a discrete-time system with type I functional response this proportion is, $p_1(t+1) =$ 152 $\frac{N_1(t)\left(1-e^{-c_1P(t)}\right)}{N_1(t)\left(1-e^{-c_1P(t)}\right)+N_2(t)\left(1-e^{-c_2P(t)}\right)}.$ We are particularly interested in applying this model to pro-153 portional diet data obtained from stable isotopes, where we may also need to account for iso-154 topic turnover, the time required for the isotopic composition of an animal to reflect its diet 155 (Vander Zanden *et al.*, 2015). In this approach the predicted diet at time t + 1 is the integrated 156 consumption of prey weighted by the isotopic turnover rate. This gives the diet proportion: 157

$$p_{1}(t+1) = \frac{\int_{t}^{t+1} e^{-\lambda(1-t)} f_{1}(P(t), N_{1}(t), N_{2}(t)) dt}{\int_{t}^{t+1} e^{-\lambda(1-t)} f_{1}(P(t), N_{1}(t), N_{2}(t)) dt + \int_{t}^{t+1} e^{-\lambda(1-t)} f_{2}(P(t), N_{1}(t), N_{2}(t)) dt},$$
(3)

where λ is the rate of isotopic turnover and the functions f_1 and f_2 are the functional responses of the predator for each of the two prey populations. When the turnover rate is very low such that $\lambda \approx 0$ this integral is the average proportional diet over the survey period. As the turnover rate increases this becomes a weighted average where more recently consumed items are more important.

We fit the predicted diet proportions to the observed diet proportions using a nonlinear logistic regression model with a mean given by the logit transform of the predicted proportion. The integrated log-likelihood is then the sum of the contributions from the logistic and the abundance time series models.

167 Simulation study

We used simulated data generated from dynamical system 1 to test how informative the addi-168 tion of proportional diet data is for parameter estimation and the ability to select the generating 169 model from a set of alternative hypotheses. We simulated data under each of the type I and type 170 II functional responses and fit both types of functional response as competing hypotheses to 171 the generated data. In these simulations, we assumed that isotopic turnover could be ignored. 172 This assumption is safe to make in scenarios when the turnover rate of the sampled tissue is 173 approximately zero over the sampling period in, for example, tissues such as hair that record 174 yearly diet. It could also be safe to make this assumption when changes in abundance between 175 sampling periods are small. We made this assumption primarily to reduce the amount of com-176 putation needed for these simulations but incorporating turnover will not change the relative 177 performance of these models. 178

Simulated time series were generated from system 1 for the type I and type II functional 179 response using low ($\sigma = 0.1$), medium ($\sigma = 0.25$), and high ($\sigma = 0.5$) levels of process error, 180 where we assumed the same value of σ for both prey and the predator populations. To generate 181 datasets, we first simulated 500 time steps to ensure that the populations reach stationarity. We 182 then selected sets of 10 to 100 observations from the end of the 500 samples, incrementing 183 over this range by 10 to explore the effects of sample size on inference. For each combination 184 of process variance/sample size/functional response we simulated 10,000 realizations of the 185 process and fit the abundance and integrated data models to each dataset. We fit both type I and 186 type II models to each simulated dataset. Models were fit in R using the nloptr package (Ypma, 187 2015) using a two-stage optimization procedure. We first used the global dividing rectangles 188 algorithm (Gablonsky & Kelley, 2001), following this up with the Nelder-Mead algorithm (Box, 189

¹⁹⁰ 1965) to achieve convergence.

For each fitted dataset, we calculated the Bayesian Information Criterion (BIC) for the 191 two competing functional response models to determine the most parsimonious model in the 192 set (Burnham & Anderson, 2002). We then calculated the proportion of times that the gen-193 erating model was selected by BIC using each data model for each process variance/sample 194 size/functional response combination. We also calculated the bias of parameter estimates on the 195 log-scale for each process variance/sample size/functional response combination. We note that 196 the number of time points sampled is not equal to the sample size. For the abundance model 197 with ten-time points, the total sample size is the 9-time points predicted by the model for each 198 of the three populations sampled for a total sample size of 27. The integrated model has the 199 sample size of the abundance data set plus the number of diet proportions used. For a sample 200 of 10-time points, this corresponds to a total sample size of 36 (27 abundance samples and nine 201 diet proportion samples). All data and code used for these analyses are provided on the Dryad 202 Digital Repository (doi:10.5061/dryad.5q136q2). 203

Empirical study: the functional response of humpback whales

We used the abundance and integrated models to understand the impact of humpback whales on 205 their prey populations in the western Gulf of Alaska. These migratory baleen whales play a ma-206 jor role in structuring this ecosystem through predation (Witteveen et al., 2006, 2012; Wright 207 et al., 2015). Our dataset consisted of annual humpback abundances and the relative abun-208 dances of their zooplankton and fish prey estimated from past surveys (Wynne & Witteveen, 200 2015; Witteveen et al., 2015). We also estimated the proportional contributions of these major 210 food sources to the diets of whales each year using the IsotopeR stable isotope mixing model 211 (Hopkins & Ferguson, 2012). In particular, we used carbon $({}^{13}C/{}^{12}C)$ and nitrogen $({}^{15}N/{}^{14}N)$ 212 stable isotope ratios (expressed as δ^{13} C and δ^{15} N) from individual whales (n=114), fish (n=211), 213

and zooplankton (n=36) to estimate dietary parameters. We then estimated consumption rates of humpback whales using both the standard abundance model and the integrated model and compared the results.

Wynne & Witteveen (2015) estimated whale abundances from photographs of individual 217 whales taken during annual vessel surveys from 2004, 2005, 2007, and 2012-2014. We used the 218 estimated abundances from the eastern portion of the study area because the relative densities 219 of zooplankton and fish were also collected in this region during vessel surveys using acoustic 220 volume backscatter; the relative frequency response was used to estimate relative zooplankton 221 and fish densities (Wynne & Witteveen, 2015; Witteveen et al., 2015). These densities, de-222 scribed here as population indices, are proportional to the total relative abundance of each prey 223 population. 224

We estimated the proportional assimilated diets of humpback whales using carbon $({}^{13}C/{}^{12}C)$ 225 and nitrogen ($^{15}N/^{14}N$) stable isotope ratios (expressed as $\delta^{13}C$ and $\delta^{15}N$) derived from 119 skin 226 samples (114 individuals) collected from adults (n = 80), juveniles (n = 4), and whales of un-227 known age (but not calves that were dependent on their mothers; n = 35). Skin samples of 228 whales were collected using a pneumatic-dart system from June through September between 229 2004-2014 (Wright et al., 2015). We also used stable isotope values for fish (capelin, Mal-230 *lotus villosus*: n = 84; Pacific herring, *Clupea pallasii*: n = 85; Alaska pollock, *Theragra* 231 chalcogramma: n = 42) collected during vessel surveys in 2012 in areas with the highest 232 acoustic backscatter densities. Sampling was done using a mid-water trawl net with 22 mm 233 mesh cod-end liner (following Witteveen et al., 2012). Zooplankton were also collected using 234 a 75 cm diameter twin-ring net (500/1000 μ mesh) and separated into taxonomic groups though 235 not identified to species (e.g., euphausiids and copepods) (euphausiids: n = 14; copepods: 236 n = 22) as reported in Witteveen & Wynne (2016). 237

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We added stable isotope discrimination factors (small offsets of stable isotope values be-

tween dietary sources and animal tissues) to the isotope values of each sampled food. In particular, we added the mean discrimination factors for skin of fin whales that fed on krill (Δ^{13} C = 1.3 ± 0.4; Δ^{15} N = 2.8 ± 0.3; (Borrell *et al.*, 2012)) to the stable isotope values of sampled zooplankton, and discrimination factors for killer whale (*Orcinus orca*) and bottlenose dolphin (*Tursiops truncates*) that fed on fish diets (Δ^{13} C = 2.4; Δ^{15} N = 3.2, (Caut *et al.*, 2011)) to the stable isotope values of fish sampled in this study.

We used IsotopeR (Ferguson & Hopkins, 2013) to estimate the isotopic mixing space and 245 the proportional diets (fish and zooplankton) of whales each year. We ran 3 MCMC chains with 246 a burn-in of 10^3 draws followed by 10^4 draws from the posterior. We checked graphical and 247 other diagnostic output for evidence of convergence. We reported the mean, 1 SD, median, and 248 95% credible interval for each marginal posterior density distribution (i.e., proportional dietary 249 contribution) for each major food source (Dryad Digital Repository DOI here upon acceptance). 250 Stable isotope mixing models are used to measure the proportional contributions of di-251 gestible biomass from each prey item to consumers (Phillips, 2012), whereas population dy-252 namics are often defined in terms of abundances. To get the proportional diet on the same 253 scale as the per-capita consumption, we converted the per-capita consumption rate from a mea-254 sure of consumed prey individuals to a measure of consumed biomass. First, we calculated 255 the consumed biomass of each prey item by multiplying the total number of consumed prey 256 (C) between observations $\left(C = \int_{t}^{t+1} e^{-\lambda(1-x)} f(P(x), N_1(x), N_2(x)) dx\right)$ by the average prey 257 biomass (b). We then corrected the number consumed by the digestibility (D) to get the con-258 sumed biomass of each prey item $D \cdot b \cdot C$. Prey digestion of zooplankton was assumed to 259 be 93%, consistent with minke whales (Balaenoptera acutorostrata) (Martensson et al., 1994), 260 and 100% for fish, as measured in some species of dolphin (Sekiguchi & Best, 1997). 261

262 Parameter estimation

We used both the abundance and integrated data models to estimate the consumption of prey 263 by humpback whales. We used n-step predictions (where n is the number of years between 264 observations) because annual data were not available for the whole study period. We used 1-265 step predictions in 2005, 2013, and 2014; a 2-step prediction for 2007; and a 5-step prediction 266 for 2012. We fit the type I functional response defined in system 2 to the abundances and as-267 sumed that predicted populations followed a lognormal distribution. To incorporate the known 268 uncertainty in estimated whale, fish, and zooplankton densities, we used a Bayesian model. All 269 estimation was done in JAGS (Plummer, 2012) and code and data to reproduce the analysis are 270 available on the Dryad Digital Repository (doi:10.5061/dryad.5q136q2). 27

In the integrated model, we incorporated isotopic turnover of humpback whales using equation 3. Past work has suggested that equilibration of stable isotopes from food into whale skin can take anywhere from 7 days (Witteveen *et al.*, 2011; Todd *et al.*, 1997) to 2 months (Hicks *et al.*, 1985). We assumed that these turnover times were equal to the half-life $(\ln(2)/\lambda)$ of the tissue and ran our models with both $\lambda = 7/365$ and $\lambda = 60/365$.

Results

Simulation study

²⁷⁹ Under all simulation conditions, integrated models performed better than abundance models ²⁸⁰ at selecting the generating model (Figure 2). The ability to choose the generating model was ²⁸¹ dependent on the sample size, process variance, and generating model. As expected, we found ²⁸² that higher variation in the data tended to reduce the ability to detect the generating model, ²⁸³ whereas larger sample sizes increased capacity to select the generating model. An interest-

ing exception to this pattern was the poor performance of the abundance model with type II 284 functional response under low sample size and process variance. In this case model selection 285 performed worse than more variable scenarios because there was not enough variation in the 286 data to observe fluctuations in the functional response. When the generating model was the type I functional response, there was little difference between the data models with the gener-288 ating model selected over 96% of the time for all simulation conditions (Figure 2a). When the 289 generating model was the type II functional response, there was a large difference between the 290 data models' ability to select the generating model. For example, in a sample of 10-time points 29 with low process variance the abundance data model selected the generating model 26% of the 292 time while the integrated data model selected the generating model 80% of the time (Figure 2b). 293 As the sample size increased, the performance differential of the data models decreased. 294

We report results of estimator bias under the type II functional response and high process 295 variance (Figure 3). We note that the other simulation conditions led to similar conclusions, 296 though performance differences decreased with lower process variance. We found that estima-297 tor bias was less for the integrated data model than the abundance data model with the same 298 number of time points sampled (Figure 3) except for a couple of cases discussed below. The 299 estimates of the half-saturation coefficient for prey 1 (h_1) and both of the consumption rates 300 (c_1, c_2) improved the most under the integrated model. Interesting h_2 did not improve with 301 the integrated model even though we saw improvements in h_1 and c_2 . We also detected im-302 provements in a number parameters that were not directly related to predator diet (e.g., r_1 , s_1 , 303 Figure 3), even though the integrated model did not contain any direct information about these 304 parameters. These improvements occur because well-estimated functional response parameters 305 allow for the identification of other population parameters. 306

We did find some significant issues in the sampling distributions of the diet efficiencies and predator mortality terms (ε_1 , ε_2 , μ). The sampling distribution of these parameters was mul-

timodal (Figure S1), though we found that the primary mode of the sampling distribution did 309 appear to be a reasonable estimator. It is likely that multimodality occurs because these pa-310 rameters are additive functions of the predator population in system 1; therefore, they can be 311 difficult to identify statistically. Approaches to deal with this issue are to place biologically 312 plausible constraints on the range of diet efficiencies or to determine reasonable starting points 313 for parameter values from the literature then use local optimization instead of a global algo-314 rithm. We performed a small set of secondary simulations that indicate reasonable constraints 315 on parameters removes the multimodal behavior and lead to estimates that behave similarly to 316 others in the study. 317

Empirical Study: Trophic dynamics of humpback whales

319 Abundance and proportional diets

Abundance estimates of the humpback whale population ranged from 1665 whales in 2004 to 551 in 2012 (Figure 4), with a coefficient of variation of 0.41 over the course of the study. The population indices for fish and zooplankton were also highly variable with coefficients of variation of 0.69 and 1.08, respectively (Figure 4).

The stable isotope values measured from whale skin, fish, and zooplankton data and sources 324 are illustrated in Figure 1. Using Kruskal–Wallis tests, we found that unlike $\delta^{15}N$ (H = 7.792, 325 df = 5, p = 0.1681), $\delta^{13}C$ values were different among years (H = 49.3747, df = 5, 326 p < 0.005; Figure S1). Interestingly, $\delta^{13}C$ values seemed to decrease in a step-wise fash-327 ion (Figure S2). We also learned that both $\delta^{13}C$ and $\delta^{15}N$ values were lower for zooplankton 328 $(\delta^{13}C: -18.2 \pm 1.0; \delta^{15}N: 11.9 \pm 0.9)$ than fish $(\delta^{13}C: -15.4 \pm 0.9; \delta^{15}N: 15.7 \pm 1.0)$ (Figure 329 1). We used these stable isotope data to estimate the diets of whales through time using Iso-330 topeR and found that the annual mean contribution of fish varied substantially in the diets of 331

³³² whales from 45% in 2004 to 4% in 2014 (Figure 4 inset).

333 Parameter estimation

The abundance data model had 15 observations for a system with six parameters. Incorporating 334 diet data with the integrated data model increased the number of observations by 40% to 20 ob-335 servations. Here, we report estimates assuming that the tissue half-life is 7 days, though we note 336 increasing upper limit on the estimate of turnover 60 days does not alter the point estimates. We 337 estimated the consumption rate of fish (c_{fish}) in our abundance model as $\hat{c}_{\text{fish}} = 5.06 \cdot 10^{-10}$ 338 versus the estimate from the integrated model of $\hat{c}_{\text{fish}} = 3.85 \cdot 10^{-13}$. Both estimates have cred-339 ible intervals that extend to 0 (Figure 5a) and are thus weakly estimable (sensu Ponciano et al., 340 2012), with a flat posterior distribution. The estimates of the consumption rate on zooplankton 341 for the abundance data model estimated $\hat{c}_{\rm zoo} = 1.34 \cdot 10^{-10}$ versus $1.10 \cdot 10^{-6}$ for the inte-342 grated data model. Incorporating the diet estimates in the integrated model led to this parameter 343 becoming estimable (Figure 5b). 344

345 Discussion

We developed a framework to parameterize food web models by integrating proportional diet 346 and population abundance data. The primary advantage of using proportional diet information 347 is that it provides an independent measure of consumption, a quantity that dynamical models 348 have estimated by relying on correlations between populations. The simulation component of 349 our study demonstrated that the integrated approach yields more precise parameter estimates 350 and can better distinguish competing between hypotheses relative to standard abundance mod-351 els. Because the integrated food web model uses more data than conventional methods im-352 proved performance was not surprising; however, we were surprised by the substantial degree 353

of improvement in the integrated models for datasets with low sample size and low process variance
 ance or moderate sample sizes with high process variance (Figure 2). Our empirical example
 highlighted how incorporating diet information can resolve parameters that cannot be precisely
 estimated using abundance data (Figure 5).

Based on the results of our stable isotope analysis, around 25% of the humpback whale diet 358 is composed of fish, though this can vary from over 40% in some years to under 5% in oth-359 ers (Figure 4). Previous diet estimates, calculated using stable isotope mixing models, found a 360 larger proportion of fish in humpback whale diets (Witteveen et al., 2012; Wright, 2014). We 36 attribute this discrepancy to different analytical procedures. For instance, we used skin discrim-362 ination factors for marine mammals that fed on these food sources (fish and krill), rather than 363 those associated with other tissues and foods. We also structured our mixing models differently 364 than past studies by grouping sampled foods into two main food sources whereas Witteveen 365 et al. (2012) estimated the diets of whales using 2-isotope systems and either 5 or 9 sources. 366

Although we applied the best analytical practices available in our analysis of whale diets, 367 several limitations may have influenced the results of our case study. First, our model did not 368 explicitly account for the migratory life history of whales. Stable isotopes from food acquired 369 in the winter breeding ground could be influencing the measurements made in Alaska if the 370 isotopic turnover time is on the long end of the estimated range (between 7 and 60 days). 371 In addition, we did not include any direct interactions between fish and zooplankton due to 372 the constraint imposed by having a small sample size. Finally, our analysis assumed that 373 the isotope values of whale's prey did not significantly vary through time. It is known that 374 the isotope values of fishes can vary considerably from year to year, sometimes as much as 375 up to 2% in Nitrogen and Carbon (Kurle et al., 2011). Accounting for such variation will 376 be a significant step in refining the estimates obtained here. Thus, while we do not consider 377 our models sufficiently sophisticated for making accurate predictions of system dynamics, our 378

analysis showed that integrative food web models do have significant advantages over standard
 abundance approaches.

We focused this study on three-species trophic interactions. When applying integrated food 381 web models to larger food webs, stable isotope methods may be unable to uniquely estimate the dietary proportions of generalist consumers (Hopkins & Kurle, 2016). This nonestimability 383 occurs when the number of sources exceeds the number of isotope tracers commonly used in 384 ecology (²H, ¹⁵O, ¹³C, ¹⁵N, and ³⁴S) by more than one (Phillips & Gregg, 2003). Including 385 informative priors in the mixing model (Chiaradia et al., 2014) or using prey abundance data to 386 weight source estimates (Yeakel et al., 2011) have both been used to circumvent this analytical 387 limitation. Another promising method is to supplement stable isotopes with fatty acid data, 388 a technique that can extend the number of ecological tracers for systems with many dietary 389 sources (Galloway et al., 2015). 390

As a general rule of thumb for designing integrated multispecies studies, we advise sampling 391 both abundance and tissues at a frequency defined by the population with the fastest turnover. 392 This study design will generate datasets with sufficient fluctuations in density that the response 393 to predation can be observed without increasing effort by surveying populations that have not 394 had time to respond to the effects of predation. In cases where the stable isotopes are being 395 collected retroactively, e.g., through museum specimens, we suggest starting with asensitivity 396 analysis of the multispecies abundance model to determine which interactions are the most 397 critical to answering your scientific question. Then place most effort on collecting and analyzing 398 the appropriate tissues to inform those interactions. 399

We believe that integrated food web models show promise for ecologists interested in studying new facets of multispecies dynamics. The ability of ecological tracers to detect differences in consumption at the individual level could lead to new models that explore the impacts of group, or even individual heterogeneity on food web dynamics. For example, integrated data models could be used to explore the heterogeneity of diet over the life history of individuals.
This heterogeneity may play a substantial role in compartmentalizing feeding interactions and
thus buffering the propagating effects of a single population going extinct (Stouffer & Bascompte, 2011) and thus in determining community stability (May, 2001; Ferguson *et al.*, 2012),
though there is currently very little data available to test this hypothesis.

It is difficult to accurately determine the functional response without experiments (e.g., 409 Arditi et al., 1991) or extensive behavioral field studies (e.g., Fryxell et al., 2007; Novak & 410 Wootton, 2008). However, the functional response determines a number of key ecosystem 411 properties such as whether trophic cascades occur and how systems will respond to enrich-412 ment (Arditi & Ginzburg, 2012). Here we show that combining existing data sources using 413 integrated methods is one way forwards for accurately parameterizing complex, empirical food 414 web dynamics. New methods to directly observe ecological interactions may allow ecologists 415 to accurately model the functional response and lead to new insights into the role of predation 416 in food webs. 417

Data accessibility: Data and code for analysis of the humpback whales and their prey is available from Dryad: doi:10.5061/dryad.5q136q2.

Authors' contributions: JMF and JBH conceived the study; JMF led the analysis and wrote the first draft of the manuscript. JBH contributed substantial revisions and performed the stable isotope analysis. BHW provided data and feedback on the manuscript.

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Data accessibility: Data available from the Dryad Digital Repository (link available upon
 acceptance).

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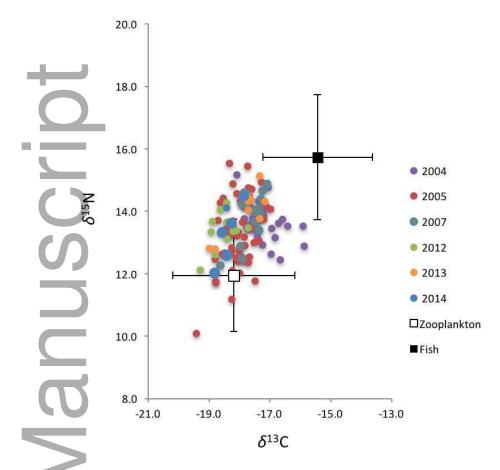


Figure 1: Isotope values ($\delta^{13}C$, $\delta^{15}N$) derived from the skin of humpback whales and their prey (corrected for isotopic discrimination). Each color denotes a different sampling year and error bars denote 2 standard deviations.

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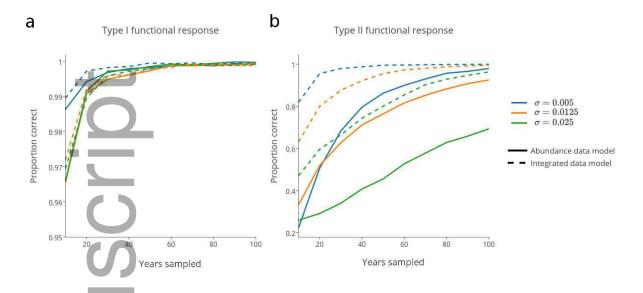


Figure 2: Proportion of correct functional response selections made using BIC for each data model (solid lines for abundance data model, dashed lines for integrated data models). The x-axis is given in terms of the number of sample points used for the estimation, where samples occur yearly. In panel **a** the generating model is a type I functional response and panel **b** is for when the generating model is a type II functional response.

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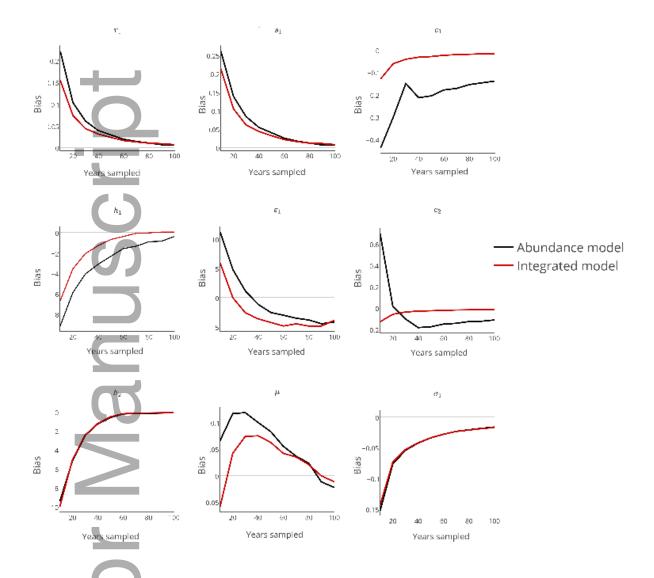


Figure 3: Estimator bias under a type II functional response with high process variance. Parameters ε_2 , σ_2 , and σ_p are not reported as their behavior is similar to ε_1 and σ_1 . Bias is given in terms of the difference between the log parameter values, the x-axis is given in terms of the number of sample points used for the estimation, where samples occur yearly.

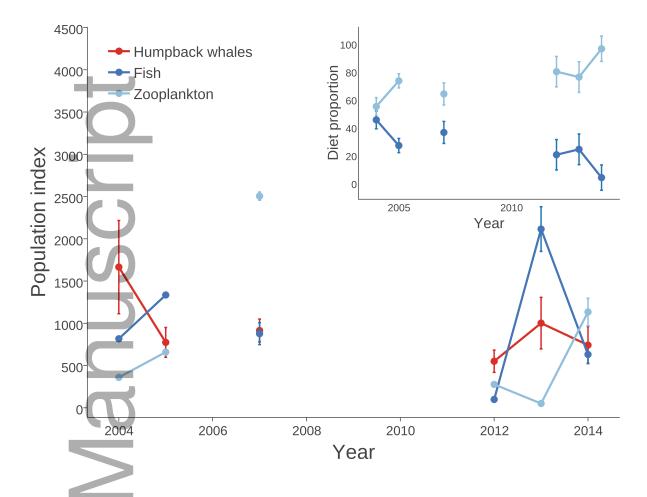


Figure 4: Estimated abundances of humpback whales and their prey from 2004 to 2014. Points denote mean population index estimates, error bars are one standard error from the mean. Proportional diets of whales (inset) are estimated using stable isotopes, thus, are expressed in terms of assimilated biomass. Each point in the inset gives the posterior mean diet estimate and error bars are one posterior standard deviation from the mean.

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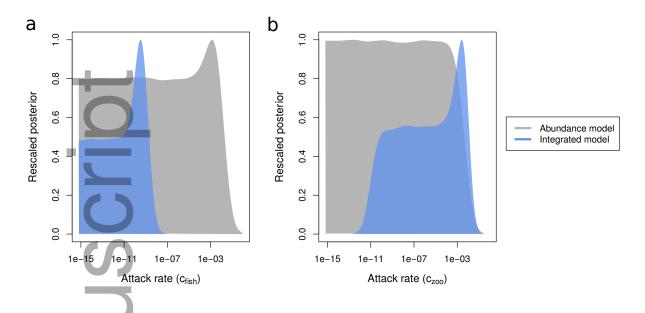


Figure 5: Posterior distribution of interaction rates between humpback whales and their prey. Abundance model in grey, integrated model in blue. Posteriors are rescaled for comparability.

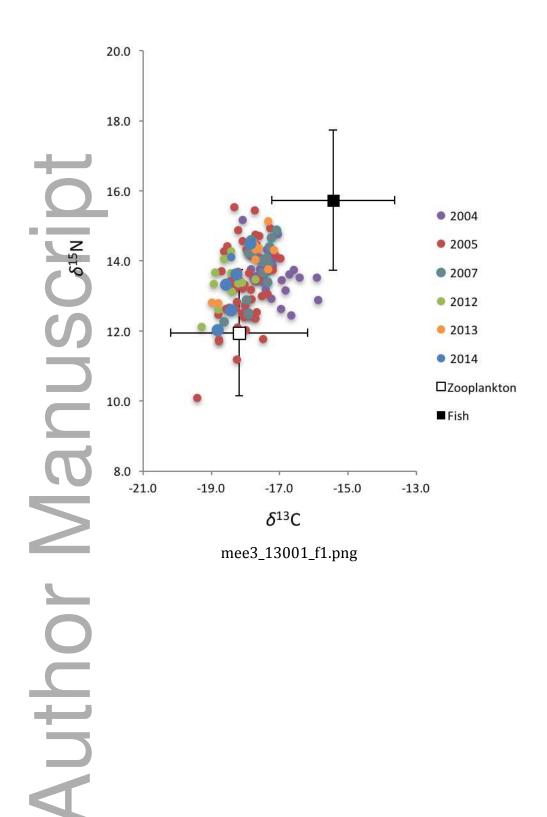


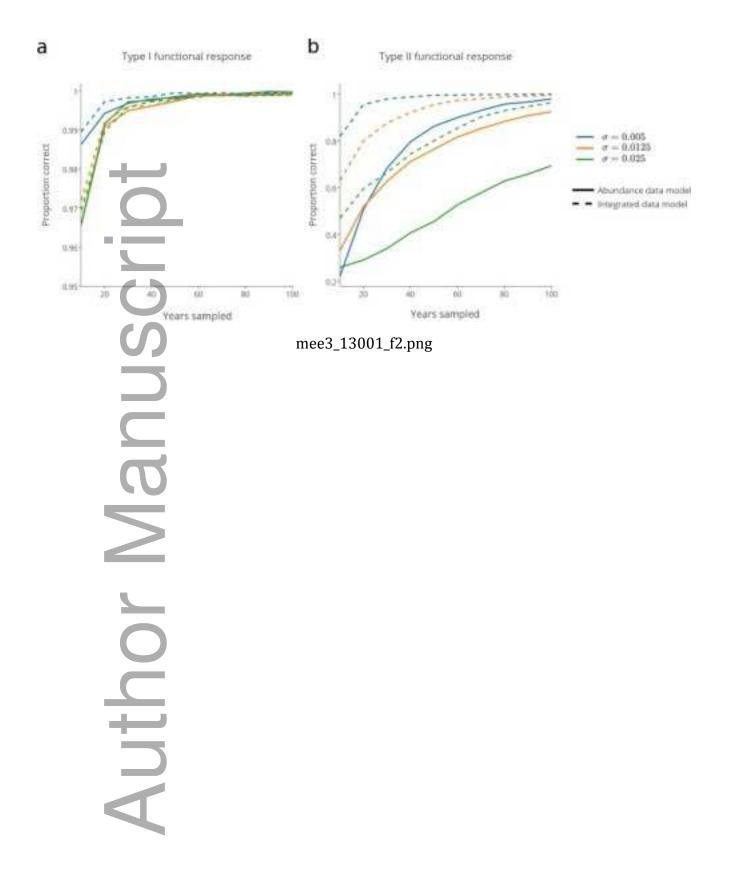
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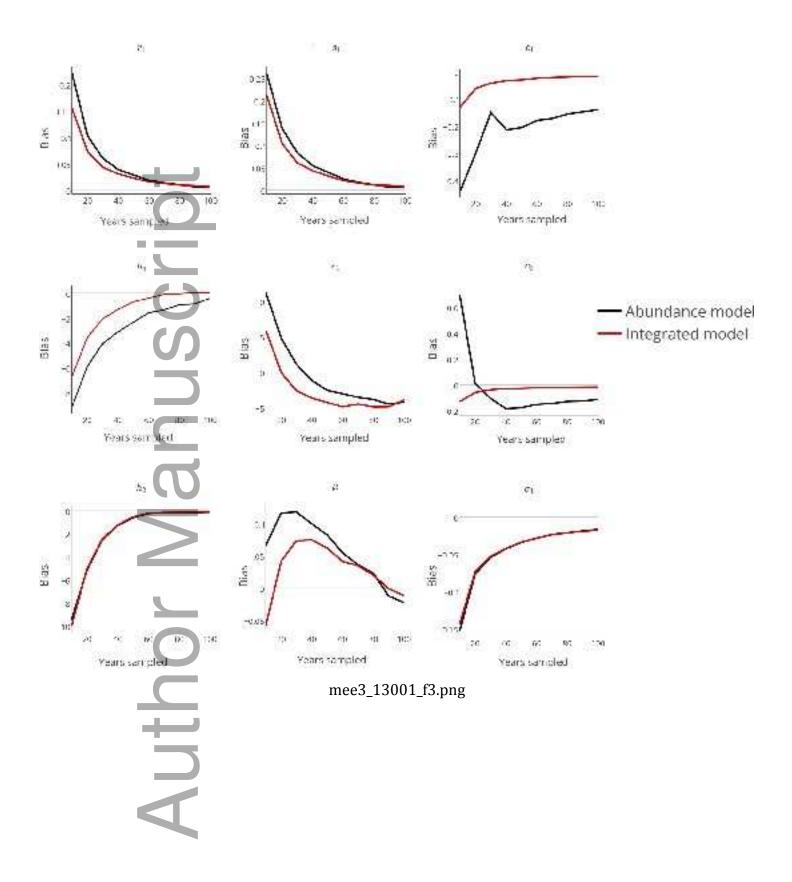
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Table 1: Parameters used for simulations.

Parameter	symbol	value
conversion efficiency		
type I and II response	$\varepsilon_1, \varepsilon_2$	0.6, 0.6
consumption rate		
type I response	c_1, c_2	0.0002, 0.00024
type II response	c_1, c_2	0.001, 0.003
half-saturation coefficient		
type II response	h_1, h_2	5, 5
predator mortality rate	μ	0.1
prey growth rate	r_1, r_2	1.8, 1.8
strength of prey density dependence	s_1, s_2	0.001, 0.001
process error		
type I and II response	$\sigma_P, \sigma_1, \sigma_2$	varied







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