

1 **BridgeDex: Proposed Web GIS Platform for Managing and**
2 **Interrogating Multi-Year and Multi-Scale Bridge Inspection Images**

3 Farid Javadnejad, S.M.ASCE¹; Daniel T. Gillins, Ph.D., M.ASCE²; Christopher C.
4 Higgins, Ph.D., M.ASCE³; and Matthew N. Gillins⁴

5
6 **Abstract:** Current bridge inspectors commonly collect high-definition digital photographs
7 of bridge members and connections at different scales when performing inspections over multiple
8 years. Metric images are advantageous for bridge condition evaluation, locating defects, and
9 quantifying and documenting changes that occur over the time. To organize and leverage multi-
10 scale, multi-year imagery, an approach is proposed and a prototype web-based tool, named
11 *BridgeDex*, is developed within a geographic information system (GIS) framework. Using the
12 approach, the spatial and temporal information for each image are attributed and then linked with
13 other bridge metadata, including inspection notes, design drawings, and possible destructive and
14 nondestructive test results. Over the Internet, users can view the georeferenced imagery across
15 various scales and across different inspection time intervals. The tool is designed to present high-
16 resolution inspection imagery and metadata to users while only requiring a web browser and an

¹ Graduate Research Assistant, School of Civil & Construction Engineering, Oregon State University, 101 Kearney Hall, Corvallis, OR 97331. Email: fjnjead@lifetime.oregonstate.edu

² Geodesist, National Geodetic Survey, National Oceanic & Atmospheric Administration, 1315 East-West Highway, Silver Spring, MD 20910; former Assistant Professor, School of Civil & Construction Engineering, Oregon State University. Email: daniel.gillins@noaa.gov

³ Professor, School of Civil & Construction Engineering, Oregon State University, 101 Kearney Hall, Corvallis, OR 97331. Email: chris.higgins@oregonstate.edu

⁴ Graduate Research Assistant, School of Civil & Construction Engineering, Oregon State University, 101 Kearney Hall, Corvallis, OR 97331. Email: gillinsm@oregonstate.edu

17 internet connection. This tool synthesizes bridge inspection data in an intuitive way to enhance
18 bridge management and decision and policy making.

19

20 **Author keywords:** Web GIS, Bridge Inspection, Imagery, Inventory, Management

21

22 **Introduction**

23 The United States Department of Transportation, Federal Highway Administration
24 (FHWA) requires states to inspect all federally-aided highway system bridges at least once every
25 two years (AASHTO 2011). The inspections and assessments are performed by certified inspectors
26 in order to identify faults and distress, and assess condition. During an inspection, the inspector is
27 required to report an inventory for a number of items on the bridge, including the materials, age,
28 and geometry. The report also requires condition rating and appraisal of the bridge elements,
29 including the deck, superstructure, substructure, and channel and channel protection (Ryan et al.
30 2006). Biennial bridge inspections produce large volumes of notes, drawings, and images which
31 are commonly stored as hard copies in a file folder and sometimes digitally on a local server.
32 Keeping this data organized and coherent is critical for identifying changes that occur over time,
33 making informed bridge management and maintenance decisions, and providing guidance to
34 policy makers (Higgins et al. 2016).

35 In recent years, imagery and location-based data management tools have been developed
36 to assist with managing highway assets. For example, Balali et al. (2015) introduced a new cost-
37 effective system for transportation inventory management. This system utilizes computer vision
38 techniques to extract and store the location and type of traffic signs from *Google Street View*
39 (Google Inc. 2017) imagery. Golparvar-Fard et al. (2015) presented a method to use image-based

40 reconstruction techniques for transportation asset management. The 2-D frames extracted from
41 video footage of a highway was processed using structure from motion (SfM) to generate a 3-D
42 point cloud of the highway.

43 Similar approaches could be implemented for managing location-based data resulting from
44 bridge inspections, such as by integrating inspection reports with high-fidelity, geolocated
45 inspection images collected over multiple years. These approaches could be leveraged within a
46 Geographic Information System (GIS), which is commonly used today to store the geolocation of
47 bridges and other relevant information (She et al. 1999). Karlaftis et al. (2005) introduced a web-
48 GIS tool for managing and manipulating the National Bridge Inventory (NBI). This tool allows
49 users to locate the bridge on a map, and it provides methods for managing, storing, and querying
50 the bridge at a national or state level. Another tool named, *Web-based GIS Integration (Bridge-*
51 *WGI)* incorporates NBI and remote sensing data for interactive display and analytical visualization
52 of bridge information. This system contains visual databases, bridge inspection data, LiDAR data,
53 and aerial images of the bridge (Chen et al. 2012; Wang et al. 2009).

54 Despite these recent developments, these GIS tools do not provide intuitive methods for
55 documenting or viewing the location of potential structural defects identified by inspection at a
56 bridge scale, which is critical for evaluating the change in condition of the bridge. To provide
57 location-based management methods, McGuire et al. (2016) presented the *Bridge Information*
58 *Modeling for Inspection and Evaluation Method (BIEM)*, a tool that uses 3-D parametric models
59 to visualize the bridge and document the location of structural defects. However, the *BIEM* is not
60 designed for handling a time-series of high-fidelity inspection photographs taken of bridge
61 elements.

62 Accordingly, this paper proposes a new tool, named *BridgeDex*, to organize and
63 georeference high-resolution imagery collected over years of inspection of bridges within a web
64 GIS. The date, spatial location, and imagery taken over years of inspections are first attributed and
65 rectified. Knowing the location where the image was captured on the bridge allows the transformed
66 and scaled image to be geo-referenced in the GIS. Afterwards, the imagery, bridge inspection
67 reports, and bridge drawings are uploaded to an online database. Over the web, a user can
68 download the reports and drawings and can view, pan, and zoom in and out on a time-series of
69 imagery that is cross referenced to all relevant metadata.

70 The tool is mainly designed for the management of multi-scale bridge inspection images,
71 including the close-up, high-resolution images collected during multi-year bridge inspections. The
72 proposed approach is novel because it allows managing and interrogating time- and location-aware
73 images for damage documentation at a bridge scale together with bridge inspection reports and
74 metadata. This paper presents the architecture for this tool, lists the required data, and demonstrates
75 the steps necessary for data collection, preparation, and publication. In addition, the Graphical
76 User Interface is described, required development steps are given, and the capabilities of
77 *BridgeDex* are detailed. As an example of the capabilities of the tool, data for a very large bridge
78 named “The Bridge of the Gods” in Oregon is presented.

79

80 **Background**

81

82 ***Bridge Inspection***

83 Bridge inspections can be divided into two categories: (1) initial/routine inspections, and
84 (2) in-depth inspections. Initial and routine inspections are most commonly performed visually

85 and are useful for deciding whether or not additional, more in-depth inspections are required (Koch
86 et al. 2015). While visual inspection is the most common technique of data collection for bridge
87 inventory and appraisal (Moore et al. 2001), in-depth inspections may be required for fracture-
88 critical bridges or bridges with visual defects. In-depth inspections typically require scraping,
89 probing or some other type of physical investigation (AASHTO 2011).

90 There are a variety of methods available for inspecting a bridge and assessing its condition.
91 Initial and routine inspections are commonly conducted quickly and generally require limited
92 equipment or access. However, in-depth inspections require the inspector to be within arm's reach
93 of the structure (AASHTO 2011). To access the bridge, inspectors make use of ladders, temporary
94 scaffolding, snoopers vehicles located alongside or on the bridge deck and in some cases by
95 climbing equipment. When in close proximity to the bridge, the inspector examines each member
96 and connection in detail and provides a rating that establishes the condition of the elements. Often,
97 the inspector will take close-up photographs of bridge elements, especially of any parts of the
98 bridge of concern. For instance, detailed photographs might be taken of bolts and gusset plates,
99 cracks or signs of distress, evidence of rust or decay, and more. The photographs are useful for
100 documenting the condition of the bridge element, and the data is then synthesized into a bridge
101 inspection report for submission to the FHWA (Ryan et al. 2006).

102 Today, digital cameras are a common tool, and a large volume of photographs are collected
103 per bridge. The volume of digital photographs per bridge could grow significantly as other remote
104 sensing technologies continue to emerge. For example, some research is underway on using digital
105 imagery from an Unmanned Aircraft System (UAS) for remote inspection of bridges. UAS are
106 being increasingly used for a wide range of mapping, monitoring and inspection applications
107 (Colomina and Molina 2014; Javadnejad and Gillins 2016; Pajares 2015; Turner et al. 2015; Wood

108 et al. 2017). Ellenberg et al. (2016) and Eschmann et al. (2013) have shown that cracks and defects
109 can be visually detected from UAS-sourced high-resolution images. UAS-based imaging was
110 identified as an alternative data-collection platform if inspections using trucks, bucket trucks, or
111 under-bridge inspection vehicles are prohibitive. UAS are favorable for bridges with elements that
112 are difficult or dangerous for the inspector to physically access, especially for remote, safe, and
113 visual bridge inspection (Gillins et al. 2016; Khan et al. 2015; Vaghefi et al. 2012). New tools
114 must continue to be developed for managing the growing number of images collected by remote
115 sensing techniques per bridge.

116

117 ***Metric Images***

118 Photogrammetry and computer vision tools are available for determining the scale,
119 orientation, and location of digital imagery captured of a bridge. For only a few photographs of a
120 bridge location, such as a bridge connection, the scale of the features in the image can be
121 determined using an image reference target placed by the inspector. The reference target enables
122 determination of the linear transformation between points in the real world and pixels on the image
123 plane. Higgins and Turan (2013) proposed the placement of a reference target with nine control
124 points. Four of the control points are required to define the transformation matrix, and the
125 remaining, redundant points help estimate measurement errors and reduce the sensitivity of the
126 control point selections. Because the reference target points are known precisely and are mapped
127 to the image pixels, the direct linear transformation is performed that rectifies the image and
128 establishes the pixel scale to real world dimensions. The method generates a two-dimensional
129 transformation based solely on the control point coordinates and thus, camera calibration is not

130 required unless radial distortions are present in the lens. Knowing the position of the reference
131 targets allows the transformed and scaled image to be geo-referenced in the GIS for the bridge.

132 If an image set has been collected systematically with enough overlap, computer vision
133 techniques such as Structure from Motion (SfM) can be used to generate orthomosaics by
134 processing and stitching overlapping images together. Using a set of overlapping images, SfM can
135 recover geometry from a series of un-oriented overlapping images through simultaneous, highly
136 redundant, iterative bundle adjustment procedures. Using the reconstructed geometry, SfM can
137 rectify perspective and generate orthomosaics (Eltner et al. 2016; Furukawa and Ponce 2010;
138 Snavely et al. 2006). There are a number of commercial software packages that are capable of
139 SfM-based image stitching, e.g., *Agisoft* (2016) and *Pix4D* (2016). SfM is a particularly popular
140 technique for stitching and processing imagery collected with a UAS. SfM processing results in
141 an orthomosaic at an arbitrary scale. Applying the real world scale on the SfM-derived
142 orthomosaics can be done by (1) providing the 3-D coordinate values of distinguishable objects
143 (i.e., center of pins) or targets with known coordinate values (georeferencing), (2) adding known
144 distances between objects (scaling), or (3) by assigning camera position and orientation (direct
145 geo-referencing) (Eltner et al. 2016).

146

147 **Web GIS**

148 The term web GIS is used for any GIS that utilizes web technologies to communicate
149 between its components. A web GIS has many advantages, such as it: enables access for a large
150 number of users over the web, has an independent platform, can be easily updated and maintained,
151 does not require the user to install software or download updates, and is composed of simple
152 scripting and coding (Fu and Sun 2011; Sharifi-Mood et al. 2016). The basic components of a web

153 GIS is shown in Fig. 1. The GIS server is a critical component of the web GIS that provides spatial
154 analysis services for web services, e.g., the *ArcGIS® Server* (Esri 2016a). A user will be able to
155 view the data and any updates by accessing a web page that has a unique URL (Uniform Resource
156 Locator).

157 The source code for most web pages is HTML (Hypertext Markup Language). The
158 Cascading Style Sheets (CSS) are used to improve the appearance, style and layout of pages coded
159 in HTML (Duckett 2011; Fu and Sun 2011). The Scripting language are often used to make the
160 web pages dynamic and interactive. Large applications often require lengthy amounts of coding,
161 which can be addressed by using object-oriented programming. Templates or blueprints that are
162 used to regenerate objects are called classes. Classes are stored in the components of the system
163 called modules (Eckel 2006). Application programming interfaces (APIs) can call modules and
164 implement their classes in the application. *ArcGIS JavaScript API* (Esri 2016b), *Google Maps API*
165 (Google Inc. 2016) and *Leaflet API* (Agafonkin 2016) are some common APIs for developments
166 of interactive web mapping applications.

167

168 **Proposed Methodology**

169

170 *BridgeDex* is proposed as a web GIS tool that allows access and management of bridge
171 images, inventory data, plans, inspection reports, and other relevant metadata. Fig. 2 shows the
172 overview of proposed collection, preparation, architecture, and graphical user interface (GUI) and
173 the software requirements are discussed with greater details in following sections.

174

175 **Data Collection**

176 *BridgeDex* was developed to manage bridge inspection data, including digital photographs,
177 reports, and drawings. Special emphasis was placed on managing the location- and time-aware
178 series of close-up imagery collected of a bridge during inspection.

179

180 ***Database Preparation***

181 The collected images can be single images (Fig. 3b) or a mosaic of images. If a set of
182 images is collected systematically, that is usually done by deploying a UAS, further processing of
183 the image set is needed to generate an orthomosaic. The orthomosaics have spatial resolution
184 comparable to the original images used in processing, so they can provide high-resolution data for
185 visual inspection. For example, Fig. 3a shows a schematic UAS flight plan for capturing the
186 overlapping images, which is later processed to generate an orthomosaic similar to Fig. 3c. This
187 imagery can be an input to *BridgeDex*.

188 As a first step, the imagery must be georeferenced to the bridge. Fig. 4 shows an example
189 of the use of a total station for determining the coordinates of distinguishable bridge connections.
190 These coordinates can be used for georeferencing an orthomosaic image derived from SfM. On
191 the other hand, scaling and rectification of single images can be performed using an image
192 reference target. This can be done using the *ArcMap's* georeferencing toolbar where linear
193 transformations are determined using the control points in 2-D space (Esri 2016c). The
194 georeferenced images are later used to build a GIS database (Esri 2016d), which is published on a
195 servers and available for online applications.

196

197 ***BridgeDex***

198 Fig. 5 shows the hierarchical structure and components of *BridgeDex*. The base section of
199 the tool is called *BridgeDex-map*, which provides a geographical plan view map of the locations
200 of bridges included in the database. *BridgeDex-map* displays a number of markers that each depicts
201 the geographical location of a bridge. Clicking on the marker opens a pop-up window that shows
202 a description and a portfolio image of the bridge. The information of all the bridges required for
203 generating the pop-up are stored in a spreadsheet file. The pop-up window also provides a
204 hyperlink to the second section of the tool called *BridgeDex-profile* that interacts with the image
205 services and displays them in a map container. *BridgeDex-profile* provides a profile view of the
206 selected bridge and allows interaction with bridge imagery in two different domains: 1) at varying
207 zoom levels, and 2) at different instances of time (inspection intervals). The raster image were
208 stored as tiles in a map service. In addition to image data, it includes hyperlinks to metadata such
209 as design drawings, inspection reports, notes, sketches, past repairs and retrofits associated with
210 the current view.

211 All of the web pages and their components, including scripts, bridge portfolio images, and
212 descriptive data were stored in folders placed on the website. The HTML files contain the code for
213 the structure of the web page, including the headers, text, interactive forms, panels, and map
214 container frame. The CSS files define the layout, style and appearance of the web page contents,
215 and the JS files contain the JavaScript code that make the web pages interactive. In addition to
216 communication with local codes, the HTML file also calls remote library scripts, such as mapping
217 API modules that empower the web spatial capabilities. The *BridgeDex* uses *ArcGIS JavaScript*
218 *API* (Esri 2016b) for enabling GIS tools and geospatial data on a web environment. In *BridgeDex-*
219 *map*, a URL address is allocated to the folder that defines a global web address to the application.

220 Image services are tiles of raster data divided into smaller, more manageable chunks that
221 are ordered in pyramidal scheme. A raster pyramid is a series of raster data of the same area that
222 has been resampled into coarser resolutions or are generated from coarse resolution images. The
223 coarse or fine resolution raster pyramids appear depending on the zoom level. In addition to
224 automatically representing the raster pyramids at different zoom levels (based on the definition
225 given in the image server), the *BridgeDex-profile* also dynamically overlays the close-up images
226 on top of the overview image as the user zooms into a specific portion of the bridge. A reverse
227 action occurs when the user zooms out from the close-up view, and the higher detailed image is
228 removed from the overview image.

229 One important and novel feature of *BridgeDex* is that the user can view higher-resolution
230 imagery by selecting closer zoom levels. In addition, it is also possible to select imagery from
231 different years in order to monitor and detect changes in the bridge with time. Fig. 6 provides an
232 illustration of time-stamped raster data (i.e., t_1, t_2, t_3) at different zoom levels (i.e., L_1, L_2, L_3, L_4)
233 with varying resolution, stored as image tiles. *BridgeDex-profile* uses time-aware image tiles.
234 Similar design can be developed using a raster mosaic dataset, which would add more automated
235 time-series management of the raster data.

236

237 ***Development***

238 The following section describes some important parts of the JavaScript code used in the
239 *BridgeDex* tool. This is meant to present a prototype for managing tempo-spatial bridge images,
240 where images are defined as one image service layer that is dynamically added or removed with
241 respect to the zoom level of the map. The GIS databases can be constructed in *ArcMap* (Esri
242 2016e). Scaling is done either in *ArcMap* or through orthomosaic generation procedure via SfM.

243 The databases are then placed on *ArcGIS Server* and thereby are accessible for the online
244 applications. More details on publishing map services can be found in Esri (2016f).

245 The main classes required for the application (e.g., “*Map*”, “*OverviewMap*”,
246 “*BasemapGallery*”, “*Scalebar*”, “*ArcGIS@ImageServiceLayer*”, “*ImageServiceParameters*”) are
247 from *Esri* modules (e.g., “*esri*”, “*esri/dijit*”, “*dojo*”, etc.). These classes are used to create different
248 parts of the tool without the need of writing new detailed code. The basic framework for both
249 *BridgeDex-map* and *BridgeDex-profile* is a *Map* class that is defined as a *variable*, constructed
250 inside of the given HTML container. It is possible to specify construction properties, define the
251 center of the map extent, the zoom level, and add an *Esri* basemap.

252 Fig. 7 summarizes the algorithm used for development of *BridgeDex-map*. The *marker* is
253 defined as a picture symbol, with construction properties (e.g., type, height, width, and the URL
254 of the graphics) specified in constructor properties. Each time that the tool is loaded on the web
255 page, the spreadsheet file is parsed, and the marker is rendered in the *map* container based on the
256 latitude and longitude fields. The popup window displays the field information from the
257 spreadsheet when the user clicks on the marker. The popup window loads an image of the bridge
258 by reading the URL address of the image from the spreadsheet, and the window converts the image
259 and its caption into hyperlinks to the *BridgeDex-profile* by reading the URL page address field
260 from the spreadsheet. The hyperlink in the popup window opens the *BridgeDex-profile* tool.

261 Fig. 8 summarizes the algorithm for development of *BridgeDex-profile*. The
262 “*ArcGIS@ImageServiceLayer*” class from the “*esri/layers*” module is used to handle the image
263 service layers. The URL location and the parameters from the image service layer are needed to
264 be specified. In addition, cutoff zoom levels were defined, which were used to dynamically add
265 and remove the image services based on the zoom levels. The next step is to add a default layer to

266 the web GIS map. For example, the default layer can be the overview image of the entire bridge
267 for the first year.

268 If the *map* identifies an “*extent-change*”, the code gets the zoom level from the *map*. By
269 using if statements based on the zoom level, imagery will be added or removed. According to
270 zoom cutoff levels. The *year* variable is a parameter that specifies the year of the imagery. In order
271 to load imagery for a specific time, one of the necessary steps is to read the year selected by the
272 user from the right panel of the GUI. The input from *radio button* is read and parsed to an integer
273 value for the given year. If the user selects a different year all of the imagery will be removed, then
274 new imagery for the selected year will be added according to the year and the zoom level.

275 Typically, the maximum default level of detail (LOD) or zoom level in web GIS is 22;
276 however, this tool must zoom into very close, high-resolution bridge images. Therefore, it is
277 necessary to manually define the scale and resolution of each zoom level to the application. Each
278 zoom level has a level ID, where the top level is 0, resolution value for each pixel unit, and the
279 scale. For example, the level 22 defined for the experimental implementation (discussed later) a
280 scale at 0.245, the resolution at 6.56E-05 in WGS84 Web Mercator (Auxiliary Sphere) units.

281

282 **Software Requirements**

283 *NetBeans IDE 8.0* (Oracle Co. 2016) was used for web development. Most of integrated
284 development environment (IDE) packages or editors, such as *Aptana Studio* (Aptana Inc. 2016),
285 *Visual Studio* (Microsoft Co. 2016), *Sublime Text* (Skinner 2016), *Notepad++* (Ho 2016) would
286 work for this purpose. *ArcGIS 10.2* (Esri 2016e) was used for generating raster databases and
287 publishing online image services. To run *BridgeDex* and access the data requires the user to have
288 only a web browser and an Internet connection.

289

290 **Graphical User Interface (GUI)**

291 The GUI for *BridgeDex* and its tools and capabilities are discussed in this section.

292 *Map View:*

293 A screenshot of the BridgeDex-map is shown in Fig. 9 and its components (numbered in
294 the figure) are described below:

- 295 1. *Zooming and Panning:* The user can navigate through the map by clicking on the zoom in and out
296 buttons or by using a mouse wheel.
- 297 2. *Home Button:* The default view of the map is currently set to the state of Oregon. If the user
298 changes the zoom level or pans the map to a different extent, the zoom level and map extent will
299 return back to this view by clicking the Home Button.
- 300 3. *Basemaps:* By clicking on this icon, a new box will appear that includes a list of available
301 basemaps for display (e.g., Esri Streets, Imagery and Topography, OpenStreetMaps, USGS
302 National Maps etc.). Once the selection is done, the user can close the box by clicking on the base
303 map icon.
- 304 4. *Scalebar:* The scalebar is interactive and provides map scale both in metric and imperial units.
- 305 5. *Overview Map:* This coarser map shows the spatial extent of the view of the main window. The
306 box is located on the lower right corner of the map container. The user can hide the overview map
307 box by clicking on the arrow at the corner of the box.
- 308 6. *Address Locator:* This tool allows searching for a specific location on the map by entering its
309 address. Running this command centers and zooms the view of the main window to the address.
- 310 7. *Marker:* Each marker shows the latitude and longitude of a bridge included in the database.
- 311 8. *Popup Information Window:* The user can access basic information about the bridge via an
312 information window that will appear when clicking on the marker. The information window
313 displays the name of the bridge, the name of the feature that the bridge crosses, the organization

314 that is responsible for maintaining the bridge, and other general information. The window also
315 contains an overall image of the bridge and a hyperlink that takes the user to the BridgeDex-profile
316 tool.

317

318 *Profile View*

319 A screenshot of the BridgeDex-profile is shown in Fig. 10 and its components (numbered
320 in the figure) are described below. The crossbar shown in the figure is the setup of control points
321 that can be used for scaling the image.

322 1. *Zooming and Panning*: Similar to BridgeDex-map, the zoom in or out buttons can be used to
323 navigate the data. Changing the zoom level will load different image service tiles. In addition,
324 image services will be added or removed dynamically based on the zoom level. For example, as
325 the user zooms in, increasingly closer-up, higher-resolution images appear on the screen that are
326 fully referenced to the prior coarser resolution tile.

327 2. *Select Year*: The user can select a year of interest for filtering the imagery. Only image services
328 for a selected year will be shown on the screen that correspond to the current zoom level. The user
329 can change the year at a certain level of zoom, and the raster image for that year at the level of
330 zoom will be displayed. This enables the user to “travel back and forward in time” in order to
331 identify temporal changes that are occurring.

332 3. *Reports*: The user can view available metadata such as an electronic copy of a report by clicking
333 on a hyperlink to download the document. The hyperlinks show text that indicates the year and
334 title of the report. The hyperlinks only show available metadata associated with the current view.

335

336 **Example Dataset**

337 The example dataset for *BridgeDex-map* includes four bridges in state of Oregon (as shown
338 in Fig. 9). Table 1 includes the list of bridges with a simplified example of data in the spreadsheet

339 file. The tool queries the latitude and longitude fields in this table in order to display a marker
340 (i.e., a point) at each bridge on the digital map. The “Image Link” field provides the relative
341 address to the bridge portfolio image of the bridge. Similarly, the “Page Link” field lists the address
342 to the *BridgeDex-profile* web page for the bridge. When the user clicks on the marker, a popup
343 window will appear which displays the attribute information from the spreadsheet file, the
344 overview image, and a hyperlink that will open the profile view of the bridge.

345 Fig. 11 presents overview images in different years at zoom level 24 for the Bridge of the
346 Gods in Oregon that is used as example dataset for *BridgeDex-profile*. The images of the bridge
347 were first georeferenced (rotated and translated) to a geographic coordinate system. The overview
348 image(s) of the entire bridge were first imported in *Esri ArcGIS* software. The overview images
349 were roughly georeferenced to the location of the bridge using the “georeferencing tool” in *ArcGIS*
350 by applying a reasonable scale factor. Afterwards, the closer-up, higher-resolution images of the
351 bridge were imported and georeferenced on top of the overview images. This process was followed
352 for all images, and the time each photo was taken was also tagged for all of the images. Fig. 12
353 displays high-resolution images of a joint at the same bridge captured during different years at
354 zoom level 29, and Fig. 13 shows an example for the dynamic addition and removal of image
355 services to the display based on the level of zoom, from the overview image at zoom level 24 to a
356 close up image at zoom level 35. The images at different scales have reference targets placed in
357 form of crossbars with control points for scaling the images.

358

359 **Conclusions**

360

361 This paper proposed a new web GIS tool to manage and query multi-scale/multi-year
362 bridge inspection images, bridge reports, and other relevant metadata. *BridgeDex* is a web-based
363 tool that provides the user a simple interface for viewing, panning, and zooming in and out of
364 bridge imagery collected over the years as a result of numerous bridge inspections. The tool is
365 meant to provide the user an intuitive, organized method for querying, evaluating, and managing
366 bridge inspection data that is collected over time. Particular emphasis was placed on developing
367 methods for viewing high-resolution, time-aware, close-up images of bridge elements and joints.
368 The graphical organization of data, the ability to zoom in and out of the varying scales of the
369 imagery, and the tools for viewing imagery by clicking backwards and forwards in time makes
370 bridge inspection data inherently more accessible, easier to interpret, and more effective in
371 identifying and quantifying changes that occur over time. Further, the real-scale allows for
372 quantification of changes that are taking place. These features can improve bridge management
373 and decision and policy making.

374 *BridgeDex* has two main parts: 1) *BridgeDex-map*, which is a web GIS tool that provides
375 a plan view of the locations of bridges that are included in the database, and 2) *BridgeDex-profile*
376 that is a profile view of each bridge that allows the user to navigate through large volumes of
377 bridge images collected at different physical scales and at different times. The user is also provided
378 links to a library of scanned bridge inventory metadata such as inspection notes, nondestructive
379 test results, structural drawings, etc.

380 This paper presented the architecture for the tool, listed the required data, and demonstrated
381 the steps necessary for preparing and publishing the required data. Example data for The Bridge
382 of the Gods was developed and implemented in the database. Georeferenced raster photos of the

383 bridge were published as image service layers on an *ArcGIS Server* and were used in the
384 application. An explanation of the GUI and the capabilities of the tool was also given.

385

386 **Future Recommendations**

387

388 *BridgeDex* was designed for enhancing the management and interrogation of bridge
389 inspection images and inventory data. Several items could be added to enhance *BridgeDex*:

- 390 1. As the number of bridges increase in the database, it may become difficult for the user
391 to find particular bridges in *BridgeDex-map*. A tool could be developed that allows the
392 user to search, sort, and filter the bridges in the database based on bridge attributes in
393 the CSV file.
- 394 2. The current design only shows one profile view of each bridge. It is proposed that
395 additional map panels be generated to *BridgeDex-profile* so that each panel can show
396 slices of the bridge from the upstream to the downstream sides of the bridge
397 superstructure with an associated plan view sub-map that can show the user where
398 through the bridge the present view is located.
- 399 3. In addition to providing time-aware images of both profile views of the bridge,
400 additional panels or pages could be developed to display imagery collected above or
401 beneath the bridge in map view. Aerial orthomosaic collected over time can provide
402 another tool for monitoring the bridge.
- 403 4. One of the limitations of the current development is how it handles time. Based on the
404 current design, each image is defined as one image service layer that is dynamically
405 added or removed with respect to the zoom level of the map. It is recommended to use

406 sliders instead of radio buttons in the future, and to develop web-based code that can
407 use a raster mosaic database capable of handling time-series data in multiple
408 dimensions instead of using a separate raster layer for each image.

409 5. In most cases, the close-up, higher definition images were taken for a small portion of
410 the bridge. For example, often the imagery was limited to the areas that were identified
411 by the inspector to be important, such as at a few connectors or along a problematic
412 structural member. One idea is to add markers on the bridge portfolio image that allows
413 users to quickly identify the areas on the bridge that contain higher resolution images
414 when zoomed out. The current development lacks such highlighting markers.

415

416 **Acknowledgements**

417

418 The funding for the research and development of *BridgeDex* was provided by
419 transportation pooled fund program by Federal Highway Administration, Oregon Department of
420 Transportation, Caltrans, Idaho Transportation Department, New York Department of
421 Transportation, North Carolina Department of Transportation, Texas Department of
422 Transportation, and Wisconsin Department of Transportation (Higgins et al. 2016). The authors
423 would like to thank Dr. Michael Olsen (OSU) for providing insights that helped in the development
424 of *BridgeDex*, and Dr. Chris Parrish and Chase Simpson (OSU) for assisting with collecting the
425 UAS imagery presented in this paper. The findings and conclusions are those of the authors and
426 may not represent the views of those acknowledged. We also thanks two anonymous reviewers for
427 their valuable comments and suggestions on improving the quality of this paper.

428

429 **References**

- 430 AASHTO. (2011). *The Manual for Bridge Evaluation*. American Association of State Highway
431 Transportation Officials (AASHTO), Washington, D.C.
- 432 Agafonkin, V. (2016). “Leaflet.” Kiev, Ukraine.
- 433 Agisoft. (2016). “PhotoScan Professional.” Agisoft LLC, St. Petersburg, Russia.
- 434 Aptana Inc. (2016). “Aptana Studio.” San Mateo, CA.
- 435 Balali, V., Ashouri Rad, A., and Golparvar-Fard, M. (2015). “Detection, classification, and
436 mapping of U.S. traffic signs using google street view images for roadway inventory
437 management.” *Visualization in Engineering*, Visualization in Engineering, 3(1), 15.
- 438 Chen, S.-E., Bian, H., Tong, Y., Stein, J., and Stein, A. (2012). *Integrated Remote Sensing and*
439 *Visualization (IRSV) System for Transportation Infrastructure Operations and Management:*
440 *Phase Two, Volume Four: Web-Based Bridge Information Analytical Visualization.*
441 Washington, DC.
- 442 Colomina, I., and Molina, P. (2014). “Unmanned aerial systems for photogrammetry and remote
443 sensing: A review.” *ISPRS Journal of Photogrammetry and Remote Sensing*, 92, 79–97.
- 444 Duckett, J. (2011). *HTML & CSS: design and build websites*. John Wiley & Sons, Inc.,
445 Indianapolis, IN.
- 446 Eckel, B. (2006). *Thinking in Java*. Pearson Education, Inc., Upper Saddle River, NJ.
- 447 Ellenberg, A., Kontsos, A., Moon, F., and Bartoli, I. (2016). “Bridge related damage quantification
448 using unmanned aerial vehicle imagery.” *Structural Control and Health Monitoring*, 23(9),
449 1168–1179.
- 450 Eltner, A., Kaiser, A., Castillo, C., Rock, G., Neugirg, F., and Abellán, A. (2016). “Image-based
451 surface reconstruction in geomorphometry – merits, limits and developments.” *Earth Surface*
452 *Dynamics*, 4(2), 359–389.
- 453 Eschmann, C., Kuo, C.-M., Kuo, C.-H., and Boller, C. (2013). “High-resolution multisensor
454 infrastructure inspection with Unmanned Aircraft Systems.” *ISPRS - International Archives*
455 *of the Photogrammetry, Remote Sensing and Spatial Information Sciences*, XL-1/W2, 125–
456 129.
- 457 Esri. (2016a). “ArcGIS Server.” *Web GIS Server*, Esri, Redlands, CA.
- 458 Esri. (2016b). “ArcGIS JavaScript API.” Esri, Redlands, CA.

- 459 Esri. (2016c). “Georeferencing toolbar tools.”
 460 <[http://desktop.arcgis.com/en/arcmap/10.3/manage-data/raster-and-images/georeferencing-
 toolbar-tools.htm](http://desktop.arcgis.com/en/arcmap/10.3/manage-data/raster-and-images/georeferencing-

 461 toolbar-tools.htm)> (Feb. 2, 2017).
- 462 Esri. (2016d). “What is a geodatabase?” <[http://desktop.arcgis.com/en/arcmap/10.3/manage-
 data/geodatabases/what-is-a-geodatabase.htm](http://desktop.arcgis.com/en/arcmap/10.3/manage-

 463 data/geodatabases/what-is-a-geodatabase.htm)> (Feb. 2, 2017).
- 464 Esri. (2016e). “ArcGIS Desktop.” Esri, Redlands, CA.
- 465 Esri. (2016f). “Tutorial: Publishing a map service.” *ArcGIS for Server*,
 466 <[http://server.arcgis.com/en/server/latest/get-started/windows/tutorial-publishing-a-map-
 service.htm](http://server.arcgis.com/en/server/latest/get-started/windows/tutorial-publishing-a-map-

 467 service.htm)> (Oct. 16, 2016).
- 468 Fu, P., and Sun, J. (2011). *Web GIS : principles and applications*. Esri Press, Redlands, CA.
- 469 Furukawa, Y., and Ponce, J. (2010). “Accurate, Dense, and Robust Multiview Stereopsis.” *IEEE
 470 Transactions on Pattern Analysis and Machine Intelligence*, IEEE, 32(8), 1362–1376.
- 471 Gillins, M. N., Gillins, D. T., and Parrish, C. (2016). “Cost-Effective Bridge Safety Inspections
 472 Using Unmanned Aircraft Systems (UAS).” *Geotechnical and Structural Engineering
 473 Congress 2016*, American Society of Civil Engineers, Phoenix, AZ, 1931–1940.
- 474 Golparvar-Fard, M., Balali, V., and de la Garza, J. M. (2015). “Segmentation and Recognition of
 475 Highway Assets Using Image-Based 3D Point Clouds and Semantic Texton Forests.” *Journal
 476 of Computing in Civil Engineering*, 29(1), 04014023.
- 477 Google Inc. (2016). “Maps JavaScript API.” Mountain View, CA.
- 478 Google Inc. (2017). “Google Street View.” <<https://www.google.com/streetview/>> (Feb. 7, 2017).
- 479 Higgins, C. C., Gillins, D. T., Scott, M. H., Todorovic, S., Javadnejad, F., and Varakantham, S.
 480 (2016). “Image processing, analysis, and management tools for gusset plate connections in
 481 steel truss bridges.” Oregon Dept. of Transportation, Salem, OR.
- 482 Higgins, C., and Turan, O. T. (2013). “Imaging Tools for Evaluation of Gusset Plate Connections
 483 in Steel Truss Bridges.” *Journal of Bridge Engineering*, 18(5), 380–387.
- 484 Ho, D. (2016). “Notepad++.”
- 485 Javadnejad, F., and Gillins, D. T. (2016). “Unmanned Aircraft Systems-Based Photogrammetry
 486 for Ground Movement Monitoring.” *Pipelines 2016*, American Society of Civil Engineers,
 487 Reston, VA, 1000–1011.
- 488 Karlaftis, M., Kepaptsoglou, K., and Lambropoulos, S. (2005). “A Web-Supported National
 489 Bridge Inventory Management Tool.” *Public Works Management & Policy*, 9(3), 248–258.

- 490 Khan, F., Ellenberg, A., Mazzotti, M., Kontsos, A., Moon, F., Pradhan, A., and Bartoli, I. (2015).
 491 “Investigation on Bridge Assessment Using Unmanned Aerial Systems.” *Structures Congress*
 492 *2015*, American Society of Civil Engineers, Reston, VA, 404–413.
- 493 Koch, C., Zhu, Z., German Paal, S., and Brilakis, I. (2015). “Machine Vision Techniques for
 494 Condition Assessment of Civil Infrastructure.” 351–375.
- 495 McGuire, B., Atadero, R., Clevenger, C., and Ozbek, M. (2016). “Bridge Information Modeling
 496 for Inspection and Evaluation.” *Journal of Bridge Engineering*, 21(4), 04015076.
- 497 Microsoft Co. (2016). “Visual Studio.” Redmond, WA.
- 498 Moore, M., Phare, B., Graybeal, B., Rolander, D., and Washer, G. (2001). *Reliability of Visual*
 499 *Inspection for Highway Bridges*. McLean, VA.
- 500 Oracle Co. (2016). “NetBeans IDE.” Redwood City, CA.
- 501 Pajares, G. (2015). “Overview and Current Status of Remote Sensing Applications Based on
 502 Unmanned Aerial Vehicles (UAVs).” *Photogrammetric Engineering & Remote Sensing*,
 503 81(4), 281–330.
- 504 Pix4D. (2016). “Pix4Dmapper Pro.” Lausanne, Switzerland.
- 505 Ryan, T. W., Hartle, R. A., Mann, J. E., and Danovich, L. J. (2006). *Bridge Inspector’s Reference*
 506 *Manual*. Washington, D.C.
- 507 Sharifi-Mood, M., Olsen, M. J., Gillins, D. T., and Javadnejad, F. (2016). “Oregon hazard explorer
 508 for lifelines program (OHELP): A web-based geographic information system tool for
 509 assessing potential Cascadia earthquake hazard.” *Poster session presented at the AGU Fall*
 510 *Meeting 2016*, American Geophysical Union (AGU), San Francisco, CA.
- 511 She, T. H., Aouad, G., and Sarshar, M. (1999). “A Geographic Information System (GIS)-Based
 512 Bridge Management System.” *Computer-Aided Civil and Infrastructure Engineering*, 14(6),
 513 417–427.
- 514 Skinner, J. (2016). “Sublime Text.” Sublime HQ Pty Ltd.
- 515 Snavely, N., Seitz, S. M., and Szeliski, R. (2006). “Photo tourism.” *ACM SIGGRAPH 2006 Papers*
 516 *on - SIGGRAPH ’06*, ACM Press, New York, New York, USA, 835.
- 517 Turner, D., Lucieer, A., and Jong, S. de. (2015). “Time series analysis of landslide dynamics using
 518 an unmanned aerial vehicle (UAV).” *Remote Sensing*.
- 519 Vaghefi, K., Oats, R. C., Harris, D. K., Ahlborn, T. (Tess) M., Brooks, C. N., Endsley, K. A.,
 520 Roussi, C., Shuchman, R., Burns, J. W., and Dobson, R. (2012). “Evaluation of Commercially

- 521 Available Remote Sensors for Highway Bridge Condition Assessment.” *Journal of Bridge*
522 *Engineering*, American Society of Civil Engineers, 17(6), 886–895.
- 523 Wang, X., Dou, W., Chang, R., and Ribarsky, W. (2009). *Integrated Remote Sensing and*
524 *Visualization (IRSV) System for Transportation Infrastructure Operations and Management:*
525 *Phase One, Volume 4, Use of Knowledge Integrated Visual Analytics System in Supporting*
526 *Bridge Management*.
- 527 Wood, R. L., Gillins, D. T., Mohammadi, M. E., Javadnejad, F., Tahami, H., Gillins, M. N., and
528 Liao, Y. (2017). “2015 Gorkha Post-Earthquake Reconnaissance of a Historic Village with
529 Micro Unmanned Aerial Systems.” *16th World Conference on Earthquake (16WCEE)*,
530 Santiago, Chile.

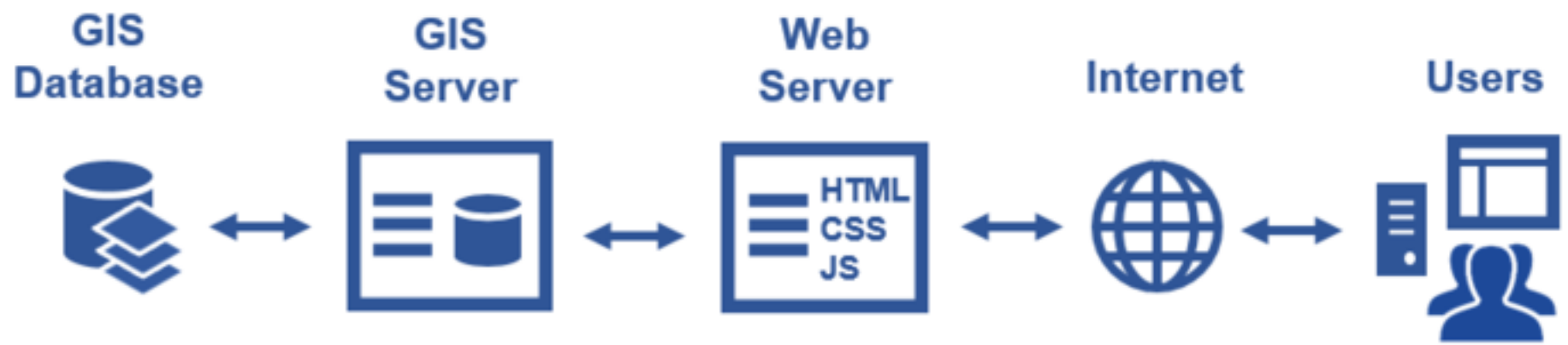
1 Tables

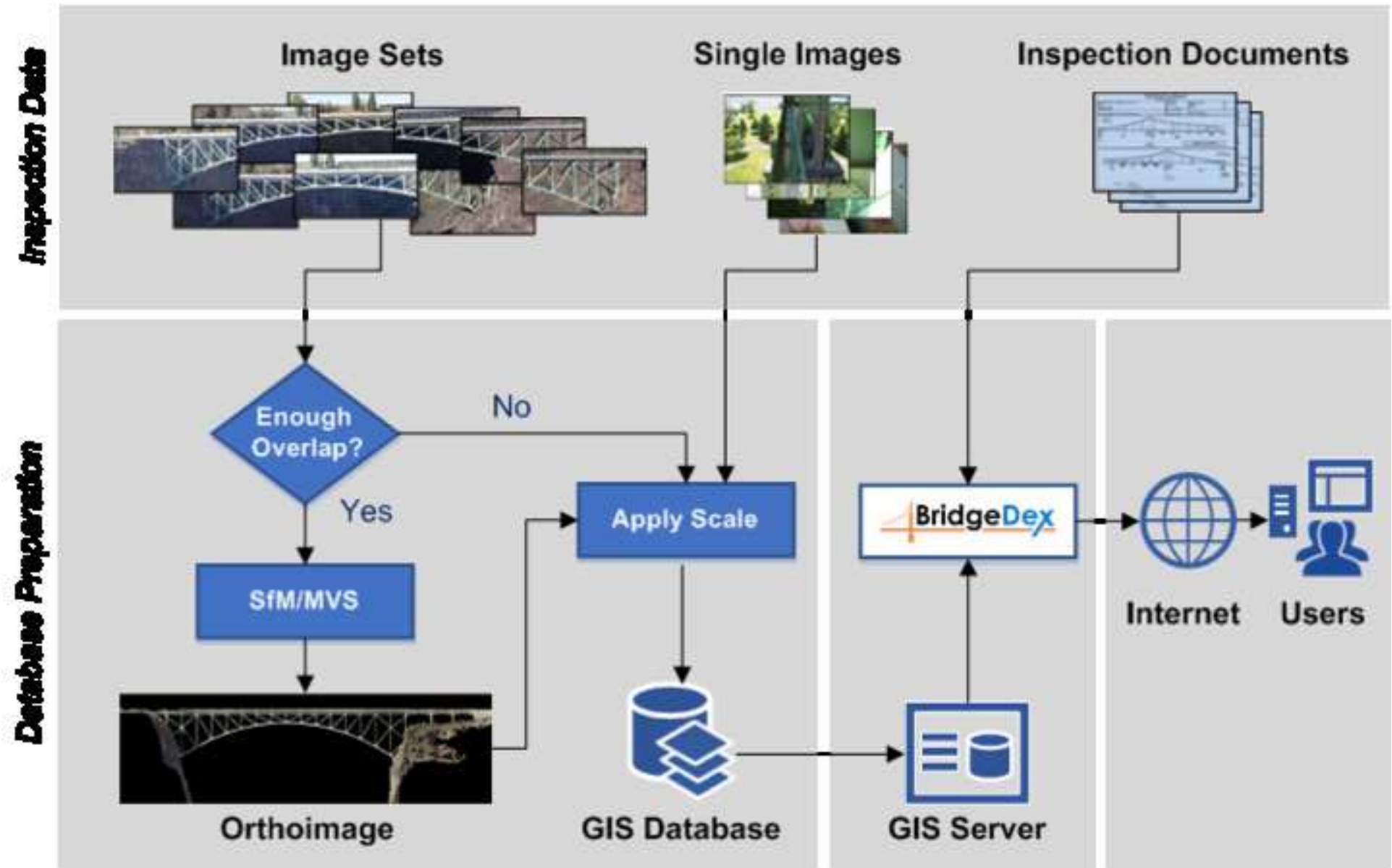
2

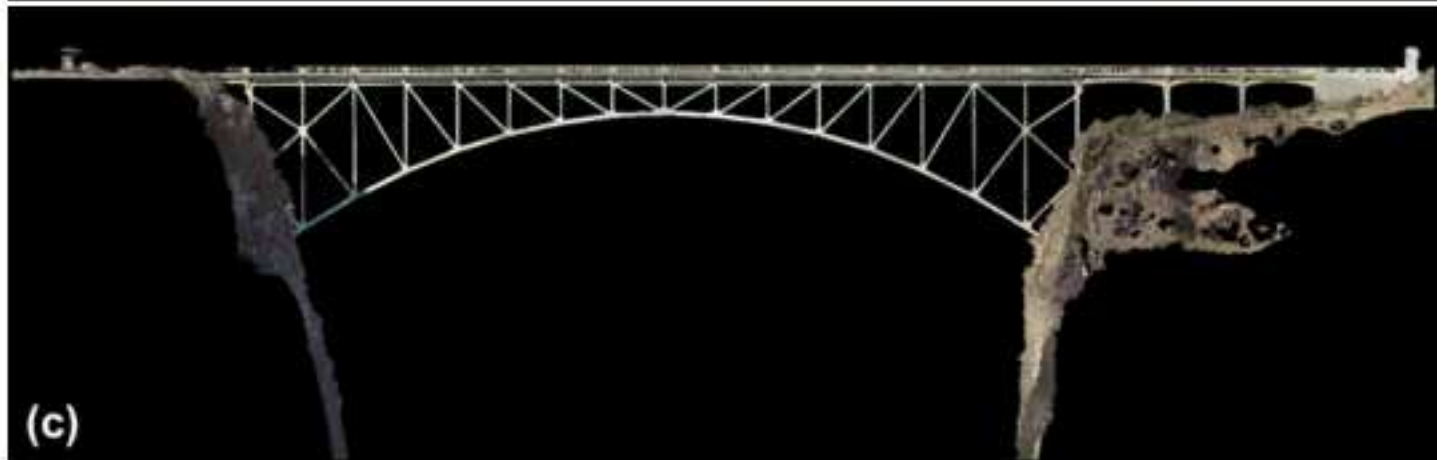
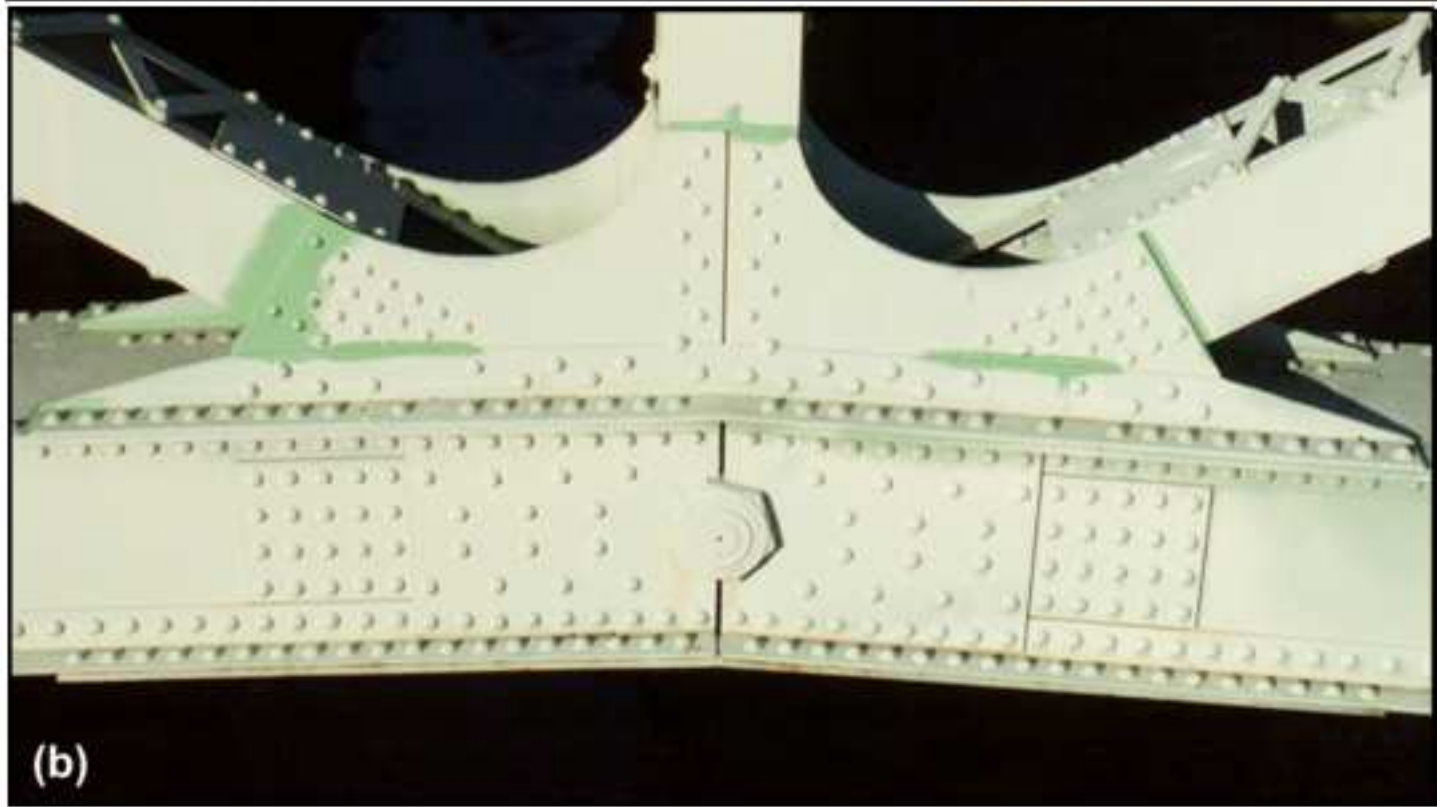
Table 1. Example of a CSV file for storing bridge inventory data

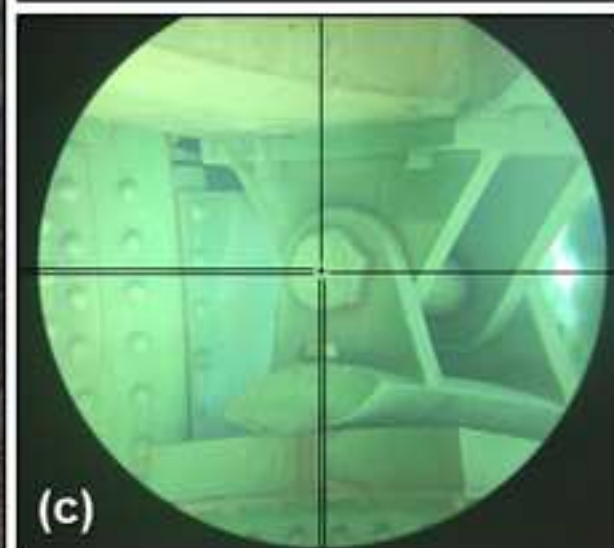
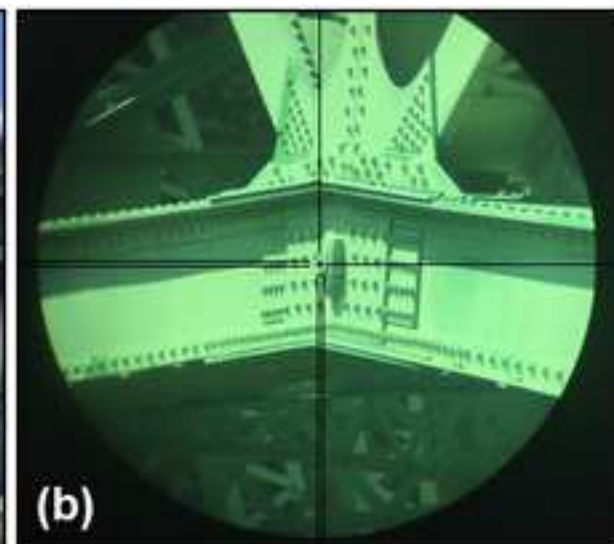
Name	Latitude	Longitude	Cross	Image Link	Page Link
Bridge of the Gods	45.66242	-121.90128	Columbia River	/B01/bridge01.jpg	/B01/bridge01.html
Steel Bridge	45.52778	-122.66778	Willamette River	/B02/bridge02.jpg	/B02/bridge02.html
Yaquina Bay Bridge	44.62207	-124.05636	Yaquina Bay	/B03/bridge03.jpg	/B03/bridge03.html
Astoria - Megler Bridge	46.21725	-123.86291	Columbia River	/B4/bridge04.jpg	/B04/bridge04.html

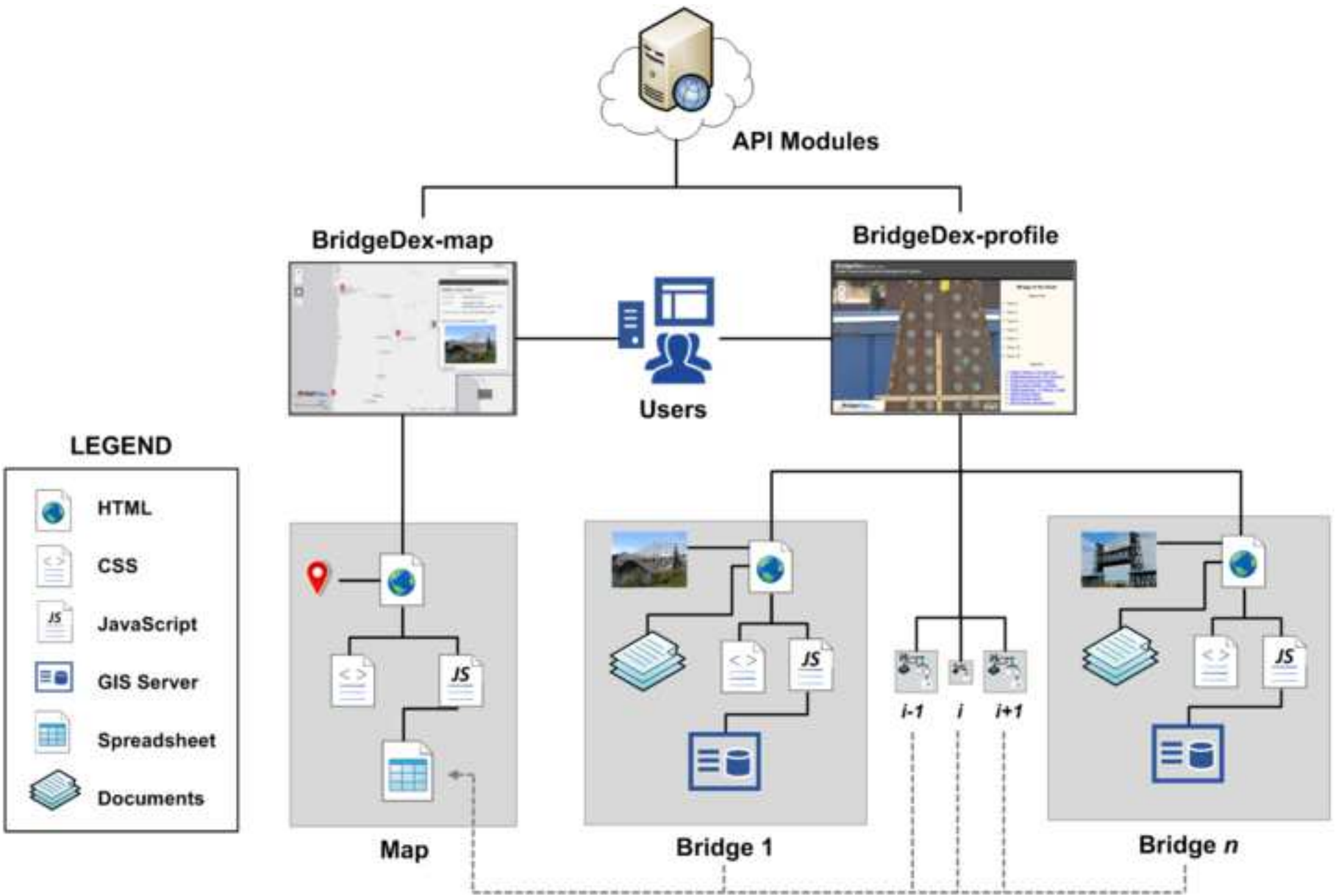
3

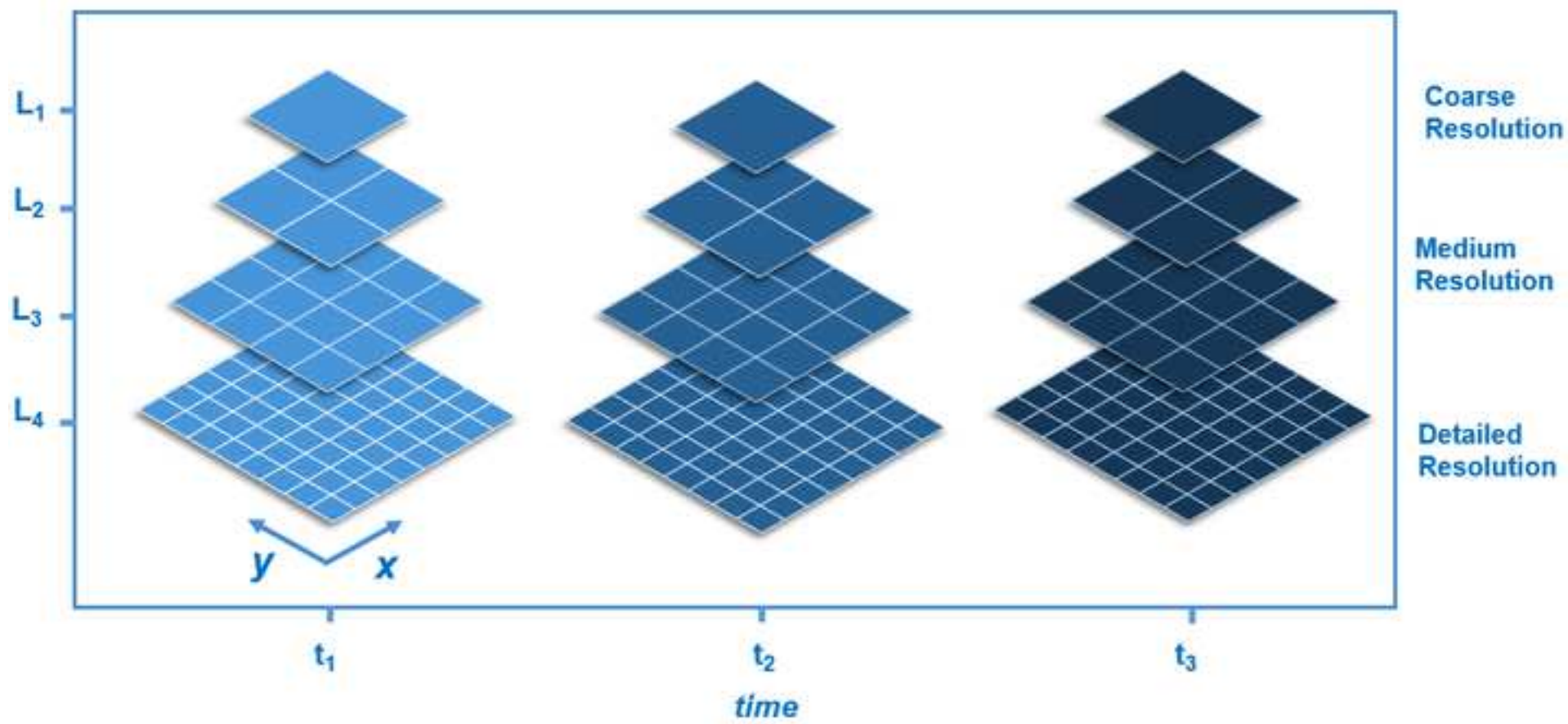












Inputs: CSV file of bridge information
Marker graphic file
Esri classes

Output: Marker displayed at the location of bridges
Popup template being updated upon click

m

- 1 Define *map*
- 2 Define *marker*
- 3 Define *dataLayer* and read CSV file
- 4 Define *renderer* displaying *marker* at the “latitude” and “longitude”
- 5 Set *renderer* to *dataLayer*
- 6 Define *template*
- 7 **click event** on *marker*
 - 8 Assign field information to be displayed from CSV and set to *template*
 - 9 Assign image type media info, read the image address from CSV and
 - 10 Set media info to *template*
 - 11 Set *template* to *dataLayer*
- 12 **end event**
- 13 Add *dataLayer* to *map*

Inputs: URL of image server layers
 Radio-button reading year value
 Esri classes

Output: Display image server relevant to *year* and *level*
 m

```

1  Define LOD {
2      Specify level ID
3      Specify scale
4      Specify resolution }
5  Define map
6  Define level and set a default value
7  Define year and set a default value
8  Define radio-layer
9  for all years
10     for all levels
11         Define image(year, level) as a new image service layer
12         Set the URL to the attribution
13         Set a min and max zoom level range for visualization
14     end for
15 end for
16 Add image (year, level)
17 on level change event
18     Set year = reading form radio-layer
19     Set level = zoom level on map
20     If level is not within min and max of current image
21         Remove image
22         Add image (year, level)
23     end if
24 end event
25 on radio-layer click event
26     Remove image (year, level)
27     Set year = reading form radio-layer
28     Set level = zoom level on map
29     Add image (year, level)
30 end event

```


The screenshot displays the BridgeDex web application interface. The main map shows the Pacific Northwest coastline with several cities labeled: Astoria, Longview, Hillsboro, Gresham, Newberg, Salem, Albany, and Corvallis. A red location pin is placed on the map near Gresham, and another red pin is visible near Astoria. A search bar at the top right contains the text 'Yakima'. A search icon is located to the right of the search bar. A search box is also present at the top right, with an arrow pointing to it from callout 6. A search box is also present at the top right, with an arrow pointing to it from callout 6. A search box is also present at the top right, with an arrow pointing to it from callout 6. A search box is also present at the top right, with an arrow pointing to it from callout 6.

Numbered callouts (1-8) point to various UI elements:

- 1: Zoom in (+) and zoom out (-) buttons.
- 2: Home button.
- 3: Map navigation arrow.
- 4: BridgeDex logo and scale bar (40km/30mi).
- 5: Inset map showing the current location within the state of Washington.
- 6: Search bar.
- 7: Location pin on the map.
- 8: Information panel for the 'Bridge of the Gods'.

The information panel for the 'Bridge of the Gods' includes the following details:

- Bridge of the Gods**
- Crosses:** Columbia River
- Locale:** Cascade Locks, OR/Skamania County, WA
- Maintained:** Port of Cascade Locks
- [Click to load BridgeDex-profile](#)
- 
- [Zoom to](#)

At the bottom of the map, the text 'Esri, HERE | Esri, HERE, DeL' is visible.

BridgeDex (profile view)
Bridge Inspection Inventory Management System

Bridge of the Gods

Select Year

- Year 0
- Year 2
- Year 4
- Year 6
- Year 8
- Year 10
- Year 12

Reports:

- [\(1926\) 3 Sheets of 10 Sheet Set](#)
- [\(1938\) Alterations for 135' Clearance](#)
- [\(1939\) Structural Steel Details](#)
- [\(1940\) Ladder Details - 2 Sheets](#)
- [\(1968\) Redecking - 13 Sheets + odds](#)
- [\(1985\) Bridge Repair](#)
- [\(2013\) Gusset repairs](#)
- [\(2013\) Stringer strengthening](#)

BridgeDex Profile

POWERED BY **esri**





(a)



(b)



(c)



(d)



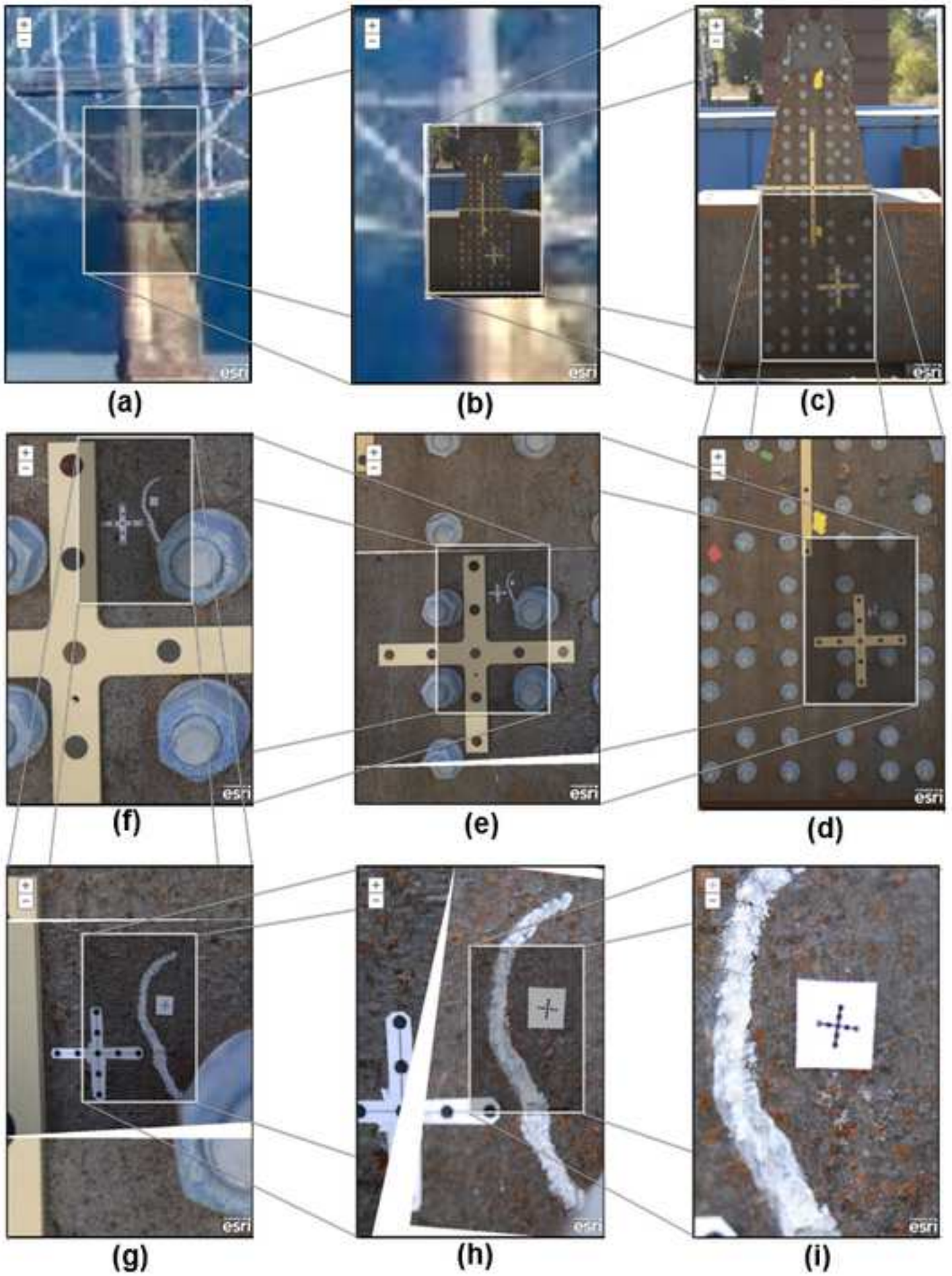
(e)



(f)



(g)



1 **Figures**

2 Fig. 1. Basic components and workflow of a web GIS application.

3 Fig. 2. Overview of the data collection, preparation and proposed *BridgeDex* data
4 management

5 Fig. 3. (a) A schematic representation of overlapping images taken from a UAS and the
6 flight path, (b) an example of a high-resolution image captured from the UAS during a
7 bridge inspection campaign at the Cooked River (High) bridge in Oregon, and (c) a
8 mosaic image produced from processing the overlapping image collection

9 Fig. 4. (a) A total station for surveying the members of the bridge and, (b) and (c)
10 distinguishable bridge connections that were surveyed with the total station for
11 establishing control coordinates for georeferencing the digital imagery

12 Fig. 5. Hierarchical structure of the files and folders of the BridgeDex-Map and
13 BridgeDex-Profile tools

14 Fig. 6. Time-aware tile pyramid representation of images

15 Fig. 7. The algorithm for development of BridgeDex-map

16 Fig. 8. The algorithm for development of BridgeDex-profile

17 Fig. 9. Outline view of BridgeDex-map with various feature tools and their screen
18 location.

19 Fig. 10. The overall design of BridgeDex-profile with the time tools and report
20 hyperlinks. The crossbar is a reference target with the control points.

21 Fig. 11. Example overview images for The Bridge of the Gods in different years: a) year
22 0, b) year 4, c) year 8, and d) year 12

23 Fig. 12. Images of a gusset plate in different years: a) year 0, b) year 2, c) year 4, d) year
24 6, e) year 8, f) year 10, and g) year 12

25 Fig. 13. Bridge inventory images for a gusset plate at different zoom levels: a) 27, b) 28,
26 c) 29, d) 30, e) 31, f) 32, g) 33, h) 34, and i) 35. Image services are represented in coarse
27 or fine resolution tiles. The image services are dynamically added or removed based on
28 the defined zoom levels. The crossbars are reference targets with the control points for
29 scaling the multi-scale images.