

User Manual and Listing of Taku A Three-Dimensional, Time-Dependent Flow Model for Glaciers

Bryan R. Pearce
Liaqat Ali Khan
Peter S. Sucusy
Vijay G. Panchang

ORIGINAL COPY
Sea Grant Depository

Maine/New Hampshire Sea Grant College Program
with the University of Maine Center for Marine Studies
and Department of Civil Engineering

Copyright 1989
Sea Grant College Program
University of Maine
Orono, Maine

TR-MSG-89-2
11/89 300

Published by the Sea Grant College Program at the
University of Maine under grant NA89-AA-D-SG020
from the National Sea Grant College Program,
National Oceanic and Atmospheric Administration,
U.S. Department of Commerce, and with support
from the University of Maine's Center for Marine
Studies and Department of Civil Engineering.

LOAN COPY ONLY

1

User Manual and Listing of

TAKU

**A Three-Dimensional, Time-Dependent
Flow Model for Glaciers**

**CIRCULATING COPY
Sea Grant Depository**

by

**Bryan R. Pearce
Liaqat Ali Khan
Peter S. Sucsy
Vijay G. Panchang**

August 1989

**Department of Civil Engineering
University of Maine
Orono, ME**

04469

**NATIONAL SEA GRANT DEPOSITORY
PELL LIBRARY BUILDING
URI, NARRAGANSETT BAY CAMPUS
NARRAGANSETT, RI 02882**

TABLE OF CONTENTS

	Page
I. Introduction	3
II. Description of the Program	5
III. EXEC, Input/ Output Files	6
IV. User Defined Input Variables	8
A. Parameter Statements	8
B. Namelist Data Set	8
V. Model Output Variables	10
VI. Auxiliary Plotting Routines	11
A. Velocity Field	12
B. 3-D Topography	13
C. Contours	14
VII. Reference	14
VIII. Appendices	15
A. Listing of the TAKU	15
B. Input Data File of the Taku	63
C. Listing of VECTOR	80
D. Input Data file of VECTOR	85

I. INTRODUCTION

The TAKU is a time-dependent, numerical model for the simulation of the flow characteristics of glaciers. The model is three-dimensional in the sense that it computes the vertical variations of the horizontal velocity components. It is assumed that the glacial ice can be treated as a highly viscous Newtonian fluid. The model solves the depth integrated two-dimensional unsteady continuity equation, together with the Navier-Stoke's equations in the x- and y-directions.

The details of the model are been described in "A Numerical Flow Model of the Taku Glacier, Alaska", by Pearce et al.(1989). The equation number cited in this report refers to Chapter-2 of that report.

Figure-1 shows the grid set-up for a hypothetical glacier. Note the additional layer of cells surrounding the glacier. The length and the width of the glacier are two grids less than the grid set-up of the model. The bed and the surface elevations in any cell outside the glacier domain are set equal to zero, unless the glacier is expected to advance in the cell over that simulation period. The surface elevation in the cell in which the glacier is expected to advance in the simulations is set equal to the bed elevation. It should be noted that the bed elevation in any cell inside the glacier domain can not be zero. If actual bed elevation is zero, then a small positive/negative number should be assigned to the grid.

This manual describes the model, the EXEC file used for executing the FORTRAN program, the input/ output files, the user specified input variables, the output variables, a listing of the model and the auxiliary plotting routines.

The research was supported in part by the University of Maine Center for Marine Studies, by the Maine Sea Grant College Program (Grant No. NA86AA-D-SG047), and by the University of Maine Department of Civil Engineering.

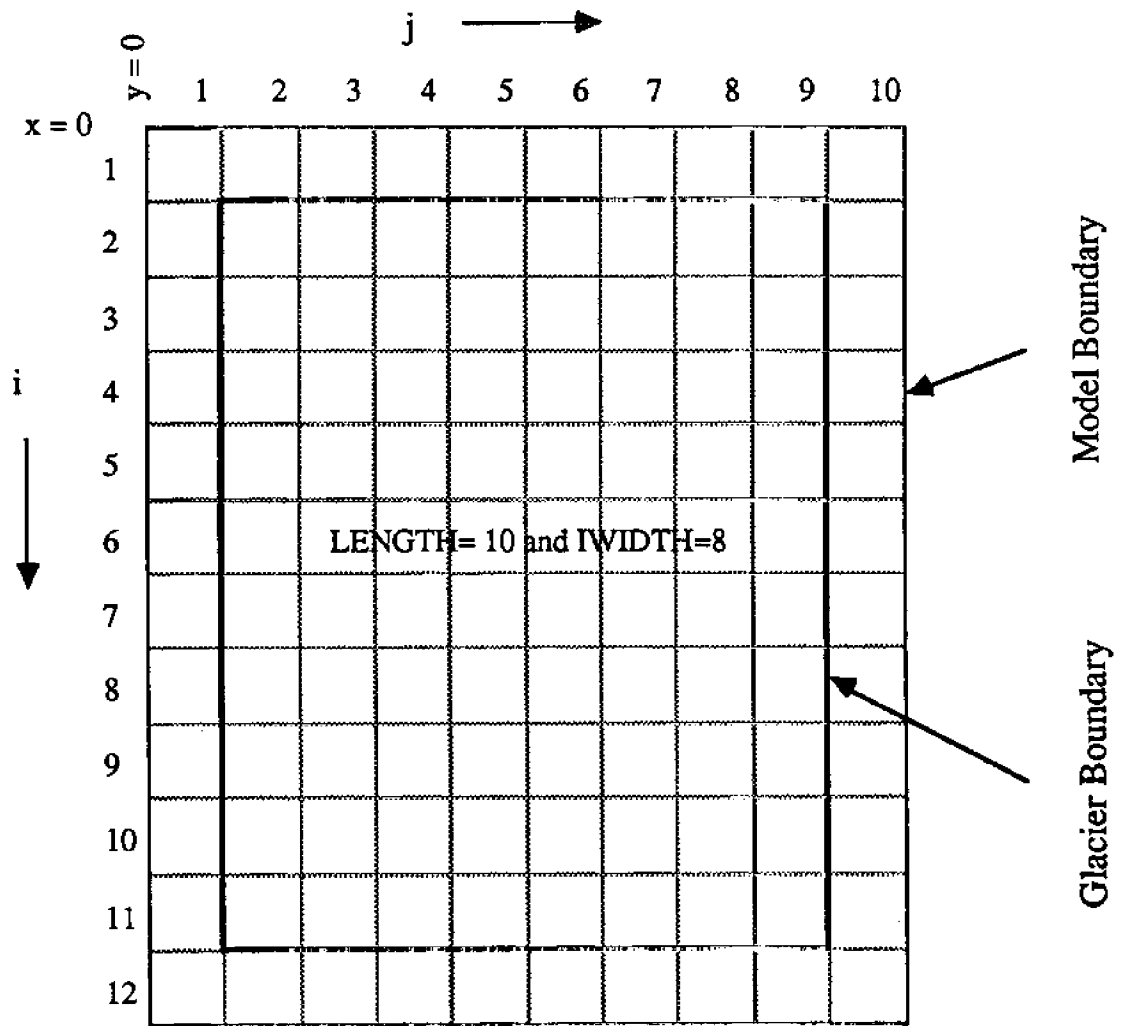


Fig. 1: Grid Setup of the Model

II. DESCRIPTION OF THE COMPUTER PROGRAM

The model consists of a main program (PROGRAM TAKU), fourteen Subroutines and a Function Subroutine. These are as follows:

<u>Module Name</u>	<u>Function of the Module</u>
PROGRAM TAKU	...This is the main program, mainly controlling the sequence of the computations by calling subroutines.
INPUT	...Subroutine for reading all user defined input data from data file [TAKU DATA]. This subroutine also performs some preliminary computations.
INITIL	...Subroutine for the initialization of variables, and reading data for "hot start", if desired.
FILTER	...This subroutine filters the bed topography, friction coefficients, and accumulation/ablation rates specified at the computational cell. This is done only once at the beginning the the computations.
ACALC	...Determines the slip angle at the bed, using the relationship given by equation(2.23c). The Newton-Rapson method is used for the solution of the transcendental equation.
GALIN1	...Evaluates the integrals S1(J), S2(I,J), and S3(J), defined by equations(2.29a), (2.29b) and (2.29c). These integrals are evaluated analytically.
GALIN2	...Evaluates the integrals S4(I,J), S5(I,J), and S6(I,J), defined by equations(2.29d), (2.29e) and (2.29f). These integrals are evaluated by Gaussian Quadrature.
GALIN3	...Evaluates the integrals S8(I,J), S9(I,J), and S10(I,J), defined by equations(2.29h), (2.29i) and (2.29j), by Gaussian Quadrature.
XMOM	...Evaluates the coefficients α_x , β_x and γ_x in

	equation(2.35a) and solves the transformed x-momentum equation by an explicit finite difference scheme.
YMOM	...Evaluates the coefficients α_y , β_y and γ_y in equation(2.35b) and solves the transformed y-momentum equation by an explicit finite difference scheme.
CONTIN	...This subroutine solved the continuity equation [equation 3.36] explicitly.
MOVEIN	...Applies the moving boundary condition at the terminus [equations (2.10), (2.11) and (2.12)].
CLIMATE	...Determines the altitudinal shift of the equilibrium line, and the distribution of ablation rates below the equilibrium line.
VELOB	...Computes the bed velocity based on equation(2.22).
VELOC	...Computes the vertical distribution of velocity at selected, equally spaced, intervals. This routine also determines the mean velocity of flow.
OUTPUT	...This subroutine is used for printing/storing output of the model. This subroutine is also called by the main program for storing output for "hot start".

Subroutines INITIL and OUTPUT have ENTRY Points, defined as INIT and OUPT respectively, and are used for reading/ storing data for "hot start".

III. EXEC, INPUT/ OUTPUT FILES

The listing of the EXEC file used for running the model is as follows:


```

GLOBAL TXTLIB VSF2FORT CMSLIB
FI 1 DISK TAKU DATA D (LRECL 80 BLOCK 80 RECFM F DSORG DA
FI 2 DISK HOTST DATA D (RECFM VS LRECL 32000 BLOCK 32004
FI 3 TERMINAL
FI 11 DISK TEMPA DATA D (LRECL 132 BLOCK 132 RECFM F DSORG DA
FI 12 DISK TEMPB DATA D (LRECL 132 BLOCK 132 RECFM F DSORG DA
FI 13 DISK TEMPC DATA D (LRECL 132 BLOCK 132 RECFM F DSORG DA
FI 14 DISK TEMPD DATA D (LRECL 80 BLOCK 80 RECFM F DSORG DA
FI 15 DISK TEMPE DATA D (LRECL 80 BLOCK 80 RECFM F DSORG DA
LOAD TAKU (START

```

The TAKU DATA is the only user defined input file. The HOTST DATA is generated by the model at time specified by the user [details discussed later] and is used as input file if "hot start" of the model is desired.

The output files stores the following information:

TEMPA.DATA	..Temporal variation of surface elevations at selected locations.
TEMPB.DATA	..Temporal variation of surface velocities at selected locations
TEMPC.DATA	..Vertical variation of velocity at selected location
TEMPD.DATA	..Spatial distributions of the following parameters: <ul style="list-style-type: none"> i. Change of surface elevation over the glacier ii. Surface, bed velocities and the ratio of bed to surface velocity. iii. Bed shear stress.
TEMPE.DATA	...Temporal variations of volume of the glacier, accumulation and ablation areas.

The temporal variations of surface elevations and surface velocities are stored at ten year intervals, while the output for vertical velocity profiles, change in surface elevation, spatial distributions of surface and bed velocities, and their ratio, and bed shear stress are stored every hundred years.

IV. USER DEFINED INPUT VARIABLES

A. Parameter Statements

The variables in the Parameter Statements are:

1. JP Number of cosine terms to be used in constructing the vertical variation of velocity [equation 2.22].
2. KP Number of levels [$\sigma= 0$ to 2 , equation 2.14] at which vertical velocity is to be computed.
3. LENGTH Number of grid elements in the x-direction.
4. IWIDTH Number of grid elements in the y-direction.

B. Namelist

The model input is defined in five namelists. These are as follows:

1. LOGCL

HOTST= .T., if "hot start" is desired [input file HOTST DATA must exist],
 .F., if otherwise.

FTTOM=.T., if input data for surface and bed elevations are in FPS units,
 .F., if these data are in SI units.

HVISC =.T., if horizontal viscosity is to be included in the computations,
 .F., if otherwise.

VFRICT=.T., if the friction coefficient is assumed function of bed elevation ,
 =.F., if the friction coefficient to be used at each cell is as specified in
 the input file [TAKU DATA].

MOVE =.T., if moving boundary condition is to be used at the terminus of the glacier,
 =.F., if no-flow boundary condition is to be used at the terminus.
CLIMET=.T., if global warming of the atmosphere is to be included in the computations,
 =.F., if otherwise.
PRT =.T., if print of the input data is desired on the screen,
 =.F., if otherwise.

If **CLIMET** is set to .T., then **HOTST** should be set to .F., as the present version of the model does not store the data necessary for "hot start" with climatic warming.

2. SYSTEM

H(I,J)	= bed topography of the glacier (ft or m).
ETA(I,J)	= initial surface topography of the glacier (ft or m).
SOS(I,J)	= source (accumulation) and sink (ablation) (m/year).
FMAX	= maximum value of the friction coefficient (m/day).
FMIN	= minimum value of the friction coefficient (m/day).
FRICT(I,J)	= friction coefficient (m/day).
NV	= vertical viscosity of ice (m^2/s).
NH	= horizontal viscosity of ice (m^2/s).
RHO	= density of ice (km/m^3).

The actual values of the friction coefficients, used in the model, are **FMAX** ($\times 10^6$), **FMIN** ($\times 10^6$), and **FRICT** ($\times 10^6$). For numerical stability of the model, $NH \leq NV$.

3. CNTRL

START	= computational step when the model starts printing/ storing the output.
PHOTST	= a "dummy " variable.
POUTPT	= a "dummy" variable.
NHOTST	= time step when "hot start" data is to be stored.

4. MODPAR

DELT	= time step in days.
DELX	=distance step in the x-direction(km).
DELY	=distance step in the y-direction (km).
NFIN	=time step over which the simulation is to be performed.
UPAI	=interval for updating the integrals.

5. METEO

HEQL	=initial altitude of the equilibrium line(m).
DELC	=change in accumulation rate (kg/m^2).
GRADC	=altitudinal gradient of accumulation rate ($\text{kg}/\text{m}^2\text{-m}$).
GRADT	=altitudinal gradient of temperature ($^{\circ}\text{C}/\text{m}$).
ALFA1	=bulk heat transfer coefficient ($\text{J m}^2 \text{d}^{-1} \text{ }^{\circ}\text{C}$).
ALFA2	=radiative coefficient($\text{J m}^2 \text{d}^{-1} \text{ }^{\circ}\text{C}$).
TDEL	=rate of increase in temperature ($^{\circ}\text{C}$ every 10 years).
SMIN	=ablation rate at and below the mean sea level(m/year).

V. MODEL OUTPUT VARIABLES

The subroutine OUTPUT is exclusively used for printing and storing the model output.

The variables stored in the output files are as follows:

NETA(I,J)	=elevation of the glacier surface (m).
VV(K,I,J)	=resultant velocity [$=\sqrt{(u^2 + v^2)}$], K= KP is the surface velocity, K= 1 is the bed velocity, while velocity at intermediate levels can be obtained by setting K to any value between 1 and KP (m/day).
SIGMA	=variable defined by equation(2.14).
HT(I,J)	=change in surface elevation over the simulation period(m).
HTMAX	=maximum value of HT(m).
HTMIN	=minimum value of HT(m).
TW(I,J)	=bed shear stress (kN/m ²).
TWMAX	=maximum value of TW (kN/m ²).
TWMIN	=minimum value of TW (kN/m ²).
VSMAX	=maximum value of surface velocity (m/day).
VSMIN	=minimum value of surface velocity (m/day).
VBMAX	=maximum value of bed velocity (m/day).
VBMIN	=minimum value of bed velocity (m/day).
VR(I,J)	=ratio of bed velocity to surface velocity.
VRMAX	=maximum value of VR.
VRMIN	=minimum value of VR.
VOL	=volume of the glacier (km ³).
ACC	=accumulation area (km ²).
ABL	=ablation area (km ²).
SPO	=total accumulation (x10 ⁶ m ² /year).
SNE	=total ablation (x10 ⁶ m ² /year).
HEQL	=elevation of the equilibrium line (m).

VI. AUXILIARY PLOTTING ROUTINES

Beside CRICKET GRAPH, for making x-y plots, three additional plotting routines are used. These are:

A. VELOCITY FIELD

The velocity field in the glacier is plotted by VECTOR FORTRAN. The EXEC file used for obtaining the plot on the computer screen is as follows:

```
/* HELLO */
'GLOBAL TXTLIB VSF2FORT CMSLIB TEK1073 CALCOMP'
'FI 1 DISK VECTOR DATA D (LRECL 80 BLOCK 80 RECFM F DSORG DA'
'FI 2 DISK HOTST DATA D (RECFM VS LRECL 32000 BLOCK 32004'
'LOAD VECTOR (START'
```

The user defined variables, in the input VECTOR DATA file, are as follows:

GRID	=T., if grid setup is to be plotted, =F., if otherwise.
PLTSIZ	= plot size in inches.
DELX	=grid size in the x-direction in km.
DELY	=grid size in the y-direction in km.
IWMAX	=maximum value of grid number in the y-direction for the plot.
LMAX	=maximum value of grid number in the x-direction for the plot.
IWMIN	=minimum value of grid number in the y-direction for the plot.
LMIN	=minimum value of grid number in the x-direction for the plot.
TIME	=the time corresponding to the plotting data, in year.
SLEVEL	=any value between 0 and 2, =2.0, for surface velocity plot, =0.0, for bed velocity plot.

Other information necessary for the plot is obtained from the HOTST DATA generated by the TAKU.

To use this routine it is necessary to shear ACADEMIC 491 to access CALCOMP plotting routines. Note that by erasing "TEK1073", the plot can be send to CALCOMP plotter.

A listing this routine is provided in the appendix.

B. 3-D TOPOGRAPHY

Three-dimensional plots of the bed and the surface topography of the glacier can be obtained by using PROC G3D of SAS GRAPH. The following routine, called PLT3D SAS, will plot the topography on the computer screen.

```
GOPTIONS DEVICE=TEK4105 TRANTAB=GTABCMS
GPROTOCOL=GSAS7171 NOTEXT82;
CMS FI PLT DISK PLT DATA D1 (RECFM F LRECL 80 BLOCK 80;
DATA;
INFILE PLT;
INPUT X Y Z @@;
PROC G3D;
PLOT Y*X=Z/ ROTATE= 30, 45, 60;
TITLE 'SURFACE TOPOGRAPHY OF THE TAKU GLACIER';
```

The input data file is PLT DATA. The variables X and Y are the distance in the x and y-directions respectively, while Z is either surface or bed topography. The values of these variables should be stored consecutively in the PLT DATA file. Any data (elevation) outside the model domain should be set to any arbitrary value, preferably to zero. The routine will successively plot the topography at three different angles (30°, 45° and 60°).

Note that by replacing "TEK4105" by "CAL5500" the plots can be send to CALCOMP plotter. It is necessary to have 2 MB of working memory and access SAS disk.

C. CONTOURS

The contour plots of the bed, surface topography or the mass balance of the glacier can be obtained by using PROC GCONTOUR of SAS GRAPH. The following routine, called PLTC SAS, will plot the contours on the computer screen.

```
GOPTIONS DEVICE=TEK4105 TRANTAB=GTABCMS
GPROTOCOL=GSAS7171 NOTEXT82;
CMS FI PLT   DISK PLT   DATA D1 (RECFM F LRECL 80 BLOCK 80;
DATA;
INFILE   PLT;
INPUT Y X Z @@;
PROC GCONTOUR;
PLOT Y*X=Z/LEVELS= 200,400,600,800,1000,1200,1400,1600,1800;
TITLE 'SURFACE TOPOGRAPHY OF THE TAKU GLACIER';
```

The input data file is PLT DATA. The variables X and Y are the distance in the x and y-directions respectively, while Z is the elevation of surface/ bed or mass balance. The values of these variables should be stored consecutively in the PLT DATA file. Any data (elevation) outside the model domain should be set arbitrarily to very high or low value (outside the range of the input data). The contour levels to be plotted by the routine are 200, 400, 600, 800, 1000, 1200, 1400, 1600 and 1800.

Note that by replacing "TEK4105" by "CAL5500" the plots can be send to CALCOMP plotter. It is necessary to have 2 MB of working memory and access SAS disk.

REFERENCE

Pearce, B.R., et al.,1989, A Numerical Flow Model of the Taku Glacier, Alaska,
Tech. Rept., Department of Civil Engineering, University of Maine, Orono,
Maine, U.S.A.

APPENDIX-A: LISTING OF TAKU FORTRAN

```

PROGRAM TAKU
*****
*
*   TAKU: A THREE-DIMENSIONAL, TIME-DEPENDENT FLOW MODEL
*   OF THE TAKU GLACIER, ALASKA
*
*   APRIL 1989.
*
*****
*
*   DEVELOPED BY:   LIAQAT ALI KHAN
*                   BRYAN R. PEARCE
*
*   DATE:   JULY, 1989.
*
*   NOTES:
*   1. THE DESCRIPTION OF THE MODEL CAN BE FOUND IN
*       PEARCE ET AL. (1989).
*   2. THE LIST OF INPUT AND OUTPUT VARIABLES ARE LISTED IN
*       THE 'USERS MANUAL' BY PEARCE ET AL. (1989)
*   3. THIS MODEL IS BASED ON THE HYDRODYNAMIC MODEL: 'TIDE',
*       SUCSY AND PEARCE (1986)
*****
*
*
*   PARAMETER (JP=1, KP=21, LENGTH=54, IWIDTH=33)
*   PARAMETER (LENP1=LENGTH+1, IWIDP1=IWIDTH+1, LPLS=LENGTH+2,
*   &          IWPLS=IWIDTH+2)
*
*   REAL   NV, NH, NC, ND, NETA
*   REAL   INTG1, INTG2, INTG3, INTG4, INTG5, INTG6, INTG7
*   LOGICAL FTTOM, HOTST, HVISC, VFRICT, MOVE, CLIMET
*
*   DIMENSION HI (LPLS, IWPLS), SSS (LPLS, IWPLS)
*   COMMON/ BLK1/ H (LPLS, IWPLS), FRICT (LPLS, IWPLS), NV, NH, RHO
*   COMMON/ BLK2/ DELT, DELX, DELY, UPAI, START, PHOTST, POUTPT,
*   &          ISTRT, NFIN, NHOTST
*   COMMON/ BLK3/ FTTOM, HOTST, HVISC, VFRICT, MOVE, CLIMET
*   COMMON/ BLK4/ C (JP, LENP1, IWIDTH), NC (JP, LENP1, IWIDTH),
*   &          D (JP, LENGTH, IWIDP1), ND (JP, LENGTH, IWIDP1)
*   COMMON/ BLK5/ ETA (LPLS, IWPLS), NETA (LPLS, IWPLS), SOS (LPLS, IWPLS)
*   COMMON/ BLK6/ A (JP, LPLS, IWPLS), CONTI (JP, LPLS, IWPLS)
*   COMMON/ BLK7/ INTG1 (JP, LPLS, IWPLS), INTG2 (JP, JP, LPLS, IWPLS),
*   &          INTG3 (JP, LPLS, IWPLS), INTG4 (JP, JP, LPLS, IWPLS),
*   &          INTG5 (JP, JP, LPLS, IWPLS), INTG6 (JP, JP, LPLS, IWPLS),
*   &          INTG7 (JP, JP, LPLS, IWPLS)
*   COMMON/ BLK8/ IGRID (LPLS, IWPLS), XI (4), W (4)
*   COMMON/ BLK10/ QIF (LPLS, IWPLS), QIB (LPLS, IWPLS),
*   &          QJF (LPLS, IWPLS), QJB (LPLS, IWPLS)
*   COMMON/ BLK11/ HEQL, DELC, GRADC, GRADT, ALFA1, ALFA2, TDEL, SMIN
*
*
*   PI=3.14159
*   CNT=1.0
*   TIMEST=0.0

```

```

TAK00010
TAK00020
TAK00030
TAK00040
TAK00050
TAK00060
TAK00070
TAK00080
TAK00090
TAK00100
TAK00110
TAK00120
TAK00130
TAK00140
TAK00150
TAK00160
TAK00170
TAK00180
TAK00190
TAK00200
TAK00210
TAK00220
TAK00230
TAK00240
TAK00250
TAK00260
TAK00270
TAK00280
TAK00290
TAK00300
TAK00310
TAK00320
TAK00330
TAK00340
TAK00350
TAK00360
TAK00370
TAK00380
TAK00390
TAK00400
TAK00410
TAK00420
TAK00430
TAK00440
TAK00450
TAK00460
TAK00470
TAK00480
TAK00490
TAK00500
TAK00510
TAK00520
TAK00530
TAK00540

```

```

*
*****.....READ INPUT DATA
*
      CALL INPUT
*
      PHOTST=PHOTST/DELT
      POUTPT=POUTPT/DELT
*
*****..... INITIALIZES AND SETS COUNTERS
*
      CALL INITIL(HI,SSS)
*
*****.....DETERMINE GRIDS INSIDE MODEL DOMAIN
*
      IF (MOVE) THEN
        DO 101 I=1,LPLS
          DO 101 J=1,IWPLS
            IF (H(I,J).EQ.0.0) THEN
              IGRID(I,J)=1
            ELSE IF (ABS(ETA(I,J)-H(I,J)).LE.1.0) THEN
              IGRID(I,J)=2
            ELSE
              IGRID(I,J)=0
            ENDIF
101      CONTINUE
        ELSE
          DO 102 I=1,LPLS
            DO 102 J=1,IWPLS
              IF (ABS(ETA(I,J)-H(I,J)).LE.1.0) THEN
                IGRID(I,J)=1
              ELSE
                IGRID(I,J)=0
              ENDIF
102      CONTINUE
        ENDIF
*
*****.....FILTER INPUT DATA IF NECESSARY
*
      IF (.NOT.HOTST) THEN
        CALL FILTER(H,IGRID)
        CALL FILTER(ETA,IGRID)
        CALL FILTER(SOS,IGRID)
        CALL FILTER(FRICT,IGRID)
      ENDIF
*
*
*****.....READ INITIAL VALUES FOR HOT START
*
      IF (HOTST) THEN
        CALL INIT(HI,SSS)
      ENDIF
*
*****.....CALCULATION OF CONSTANT FACTORS ***
*
      DTDX=DELT/DELX
      DTDY=DELT/DELY
      DXDY=DELX*DELY
      NFINAL=FLOAT(NFIN)*DELT
*
      WRITE(3,1001)
1001  FORMAT(' ',T10,'BEGIN EXECUTION.....')

```

```

TAK00550
TAK00560
TAK00570
TAK00580
TAK00590
TAK00600
TAK00610
TAK00620
TAK00630
TAK00640
TAK00650
TAK00660
TAK00670
TAK00680
TAK00690
TAK00700
TAK00710
TAK00720
TAK00730
TAK00740
TAK00750
TAK00760
TAK00770
TAK00780
TAK00790
TAK00800
TAK00810
TAK00820
TAK00830
TAK00840
TAK00850
TAK00860
TAK00870
TAK00880
TAK00890
TAK00900
TAK00910
TAK00920
TAK00930
TAK00940
TAK00950
TAK00960
TAK00970
TAK00980
TAK00990
TAK01000
TAK01010
TAK01020
TAK01030
TAK01040
TAK01050
TAK01060
TAK01070
TAK01080
TAK01090
TAK01100
TAK01110
TAK01120
TAK01130
TAK01140
TAK01150

```

```

*
*****.....SOLVE FOR THE AI'S ***
*
      CALL ACALC
*
*****.....STORE FREQUENTLY USED NUMBERS
*
      DO 103 K=1,IWPLS
        DO 103 L=1,LPLS
          IF(IGRID(L,K).NE.0) THEN
            DO 104 J=1,JP
              IF(A(J,L,K).LT.0.00001) THEN
                CONTI(J,L,K)=1.0
              ELSE
                CONTI(J,L,K)= SIN(A(J,L,K))/A(J,L,K)
              ENDIF
104          CONTINUE
            ELSE
              DO 105 J=1,JP
                CONTI(J,L,K)=0.0
105          CONTINUE
            ENDIF
103    CONTINUE
*
*****.....ALL INTEGRALS BASED ON AI'S
*
      CALL GALIN1
      IF(HVISC) THEN
        CALL GALIN2
        CALL GALIN3
      ENDIF
*
      UPAI=UPAI/(DELT)
      IF(HOTST) THEN
        ISTRT=ISTRT+1
      ELSE
        ISTRT=1
      ENDIF
*
*****.....THE TIME LOOP.....
*
      WRITE(3,1002)
1002  FORMAT(' ',T10,'BEGIN TIME LOOP.....')
*
      DO 900 J=ISTRT,NFIN
        TIME=DELT*CNT
        ISCRN=MOD(J,1 )
        IF(ISCRN.EQ.0) WRITE(3,1003) J
1003  FORMAT(' ',T5,'J=',2X,I15)
*
*****.....UPDATE AI'S AT SELECTED TIME INTERVAL
*
      CALL ACALC
      DO 201 K=1,IWPLS
        DO 201 L=1,LPLS
          IF(IGRID(L,K).NE.0) GOTO 201
        DO 202 I=1,JP
          IF(A(I,L,K).LT.0.00001) THEN

```

```

TAK01160
TAK01170
TAK01180
TAK01190
TAK01200
TAK01210
TAK01220
TAK01230
TAK01240
TAK01250
TAK01260
TAK01270
TAK01280
TAK01290
TAK01300
TAK01310
TAK01320
TAK01330
TAK01340
TAK01350
TAK01360
TAK01370
TAK01380
TAK01390
TAK01400
TAK01410
TAK01420
TAK01430
TAK01440
TAK01450
TAK01460
TAK01470
TAK01480
TAK01490
TAK01500
TAK01510
TAK01520
TAK01530
TAK01540
TAK01550
TAK01560
TAK01570
TAK01580
TAK01590
TAK01600
TAK01610
TAK01620
TAK01630
TAK01640
TAK01650
TAK01660
TAK01670
TAK01680
TAK01690
TAK01700
TAK01710
TAK01720
TAK01730
TAK01740
TAK01750
TAK01760

```

```

CONTI(I,L,K)=1.0
ELSE
CONTI(I,L,K)= SIN(A(I,L,K))/A(I,L,K)
ENDIF
202 CONTINUE
201 CONTINUE
*
*****.....UPDATE THE INTEGRALS
*
CALL GALIN1
IF(HVISC) THEN
CALL GALIN2
CALL GALIN3
ENDIF
*
*****.....SOLVE MOMENTUM EQUATIONS
*
CALL XMOM
CALL YMOM
*
*****.....SMOOTH C & D AND SAVE C & D
*
DO 204 K=1,JP
DO 205 N=1,IWIDTH
DO 205 I=1,LENP1
IF(IGRID(I+1,N+1).EQ.0.AND.IGRID(I,N+1).EQ.0) THEN
CX=(NC(K,I+1,N)+3.0*NC(K,I,N)+NC(K,I-1,N))/5.0
ELSE IF(IGRID(I+1,N+1).EQ.0) THEN
CX=(NC(K,I+1,N)+3.0*NC(K,I,N))/4.0
ELSE IF(IGRID(I-1,N).EQ.0) THEN
CX=(3.0*NC(K,I,N)+NC(K,I-1,N))/4.0
ELSE
CX=NC(K,I,N)
ENDIF
IG1=IGRID(I,N+2)
IG2=IGRID(I+1,N+2)
IG3=IGRID(I,N)
IG4=IGRID(I+1,N)
IF(IG1.EQ.0.AND.IG2.EQ.0.AND.
IG3.EQ.0.AND.IG4.EQ.0) THEN
CY=(NC(K,I,N+1)+3.0*NC(K,I,N)+NC(K,I,N-1))/5.0
ELSE IF(IG1.EQ.0.AND.IG2.EQ.0) THEN
CY=(NC(K,I,N+1)+3.0*NC(K,I,N))/4.0
ELSE IF(IG3.EQ.0.AND.IG4.EQ.0) THEN
CY=(3.0*NC(K,I,N)+NC(K,I,N-1))/4.0
ELSE
CY=NC(K,I,N)
ENDIF
C(K,I,N)=0.5*(CX+CY)
205 CONTINUE
*
DO 206 N=1,IWIDP1
DO 206 I=1,LENGTH
IF(IGRID(I+1,N+1).EQ.0.AND.IGRID(I+1,N).EQ.0) THEN
DY=(ND(K,I,N+1)+3.0*ND(K,I,N)+ND(K,I,N-1))/5.0
ELSE IF(IGRID(I+1,N+1).EQ.0) THEN
DY=(ND(K,I,N+1)+3.0*ND(K,I,N))/4.0
ELSE IF(IGRID(I+1,N).EQ.0) THEN
DY=(3.0*ND(K,I,N)+ND(K,I-1,N))/4.0
ELSE
DY=ND(K,I,N)

```

TAK01770
TAK01780
TAK01790
TAK01800
TAK01810
TAK01820
TAK01830
TAK01840
TAK01850
TAK01860
TAK01870
TAK01880
TAK01890
TAK01900
TAK01910
TAK01920
TAK01930
TAK01940
TAK01950
TAK01960
TAK01970
TAK01980
TAK01990
TAK02000
TAK02010
TAK02020
TAK02030
TAK02040
TAK02050
TAK02060
TAK02070
TAK02080
TAK02090
TAK02100
TAK02110
TAK02120
TAK02130
TAK02140
TAK02150
TAK02160
TAK02170
TAK02180
TAK02190
TAK02200
TAK02210
TAK02220
TAK02230
TAK02240
TAK02250
TAK02260
TAK02270
TAK02280
TAK02290
TAK02300
TAK02310
TAK02320
TAK02330
TAK02340
TAK02350
TAK02360
TAK02370

```

ENDIF
IG1=IGRID(I,N)
IG2=IGRID(I,N+1)
IG3=IGRID(I+2,N)
IG4=IGRID(I+2,N+1)
IF (IG1.EQ.0.AND.IG2.EQ.0.AND.
&      IG3.EQ.0.AND.IG4.EQ.0) THEN
    DX=(ND(K,I+1,N)+3.0*ND(K,I,N)+ND(K,I-1,N))/5.0
ELSE IF (IG1.EQ.0.AND.IG2.EQ.0) THEN
    DX=(ND(K,I-1,N)+3.0*ND(K,I,N))/4.0
ELSE IF (IG3.EQ.0.AND.IG4.EQ.0) THEN
    DX=(3.0*ND(K,I,N)+ND(K,I+1,N))/4.0
ELSE
    DX=ND(K,I,N)
ENDIF
D(K,I,N)=0.5*(DX+DY)
206      CONTINUE
204      CONTINUE
*
*****.....CHANGE ABLATION RATE FOR CLIMATIC WARMING
*
IF (CLIMET) THEN
    ICALL=MOD(J,60)
    IF (ICALL.EQ.0) THEN
        CALL CLIMATE(SSS)
    ENDIF
ENDIF
*
*****.....SOLVE CONTINUITY EQUATION
*
CALL CONTIN(DTDX,DTDY,SSS)
*
*****.....SAVE ETA VALUES
*
DO 208 I=1,LPLS
    DO 208 N=1,IWPLS
        ETA(I,N)=NETA(I,N)
208      CONTINUE
*
*****.....CHECK TO RETREAT IF ICE IS TOO THIN
*
DO 209 M=1,LPLS
    DO 209 N=1,IWPLS
        IF (IGRID(M,N).EQ.0) THEN
            EDIFF=NETA(M,N)-H(M,N)
            IF (ABS(EDIFF).LE.5.0) THEN
                IF (I.LE.40) THEN
                    WRITE(3,*) '** SURFACE FALLS BELOW BED LEVEL**',J
                    WRITE(3,*) 'M,N,H,E:',M,N,H(M,N),NETA(M,N)
                ENDIF
                IGRID(M,N)=2
                ETA(M,N)=H(M,N)
                NETA(M,N)=H(M,N)
            ENDIF
        ENDIF
    ENDIF
*
    IF (IGRID(M,N).EQ.2) THEN
        IF (SSS(M,N).GT.0.0) THEN
            ETA(M,N)=ETA(M,N)+SSS(M,N)
            NETA(M,N)=NETA(M,N)+SSS(M,N)
            EDIFF=NETA(M,N)-H(M,N)

```

TAK02380
TAK02390
TAK02400
TAK02410
TAK02420
TAK02430
TAK02440
TAK02450
TAK02460
TAK02470
TAK02480
TAK02490
TAK02500
TAK02510
TAK02520
TAK02530
TAK02540
TAK02550
TAK02560
TAK02570
TAK02580
TAK02590
TAK02600
TAK02610
TAK02620
TAK02630
TAK02640
TAK02650
TAK02660
TAK02670
TAK02680
TAK02690
TAK02700
TAK02710
TAK02720
TAK02730
TAK02740
TAK02750
TAK02760
TAK02770
TAK02780
TAK02790
TAK02800
TAK02810
TAK02820
TAK02830
TAK02840
TAK02850
TAK02860
TAK02870
TAK02880
TAK02890
TAK02900
TAK02910
TAK02920
TAK02930
TAK02940
TAK02950
TAK02960
TAK02970
TAK02980

IF(EDIFF.GE. 5.5) THEN	TAK02990
IGRID(M,N)=0	TAK03000
ENDIF	TAK03010
ENDIF	TAK03020
209 CONTINUE	TAK03030
*	TAK03040
*****.....ADVANCE OF RETREAT OF GLACIER	TAK03050
*	TAK03060
IF(MOVE) THEN	TAK03070
CALL MOVEIN(J,SSS,DXDY)	TAK03080
ENDIF	TAK03090
*	TAK03100
*****.....WRITE OUTPUT AT SELECTED TIME INTERVAL	TAK03110
*	TAK03120
CNT=CNT+1.0	TAK03130
IF(TIME.LT.START) GOTO 900	TAK03140
ICALL=MOD(J,120)	TAK03150
IF(ICALL.EQ.0) THEN	TAK03160
CALL OUTPUT(J,HI,SSS,HEQL)	TAK03170
ENDIF	TAK03180
*	TAK03190
*****.....WRITE OUTPUT FOR HOT START	TAK03200
*	TAK03210
IF(J.EQ.NHOTST.OR.J.EQ.NFIN) THEN	TAK03220
CALL OUP(T,J,HI,SSS)	TAK03230
ENDIF	TAK03240
900 CONTINUE	TAK03250
WRITE(3,1005)	TAK03260
1005 FORMAT(' ',T10,'END TIME LOOP.....')	TAK03270
*	TAK03280
STOP	TAK03290
END	TAK03300
	TAK03310

```

SUBROUTINE INPUT
*****
*
*   READS INPUT DATA AND MAKES NECESSARY CONVERSIONS
*
*****
PARAMETER (JP=1,KP=21,LENGTH=54,IWIDTH=33)
PARAMETER (LENP1=LENGTH+1,IWIDP1=IWIDTH+1,LPLS=LENGTH+2,
&          IWPLS=IWIDTH+2)
CHARACTER*1 T/Z05/
REAL   NV,NH,NC,ND,NETA
REAL   INTG1,INTG2,INTG3,INTG4,INTG5,INTG6,INTG7
LOGICAL FTTOM,HOTST,HVISC,VFRICT,MOVE,CLIMET,PRT
DIMENSION HH(LPLS,IWPLS)
COMMON/ BLK1/ H(LPLS,IWPLS),FRICT(LPLS,IWPLS),NV,NH,RHO
COMMON/ BLK2/ DELT,DELX,DELY,UPAI,START,PHOTST,POUTPT,
&          ISTRT,NFIN,NHOTST
COMMON/ BLK3/ FTTOM,HOTST,HVISC,VFRICT,MOVE,CLIMET
COMMON/ BLK5/ ETA(LPLS,IWPLS),NETA(LPLS,IWPLS),SOS(LPLS,IWPLS)
COMMON/ BLK6/ A(JP,LPLS,IWPLS),CONTI(JP,LPLS,IWPLS)
COMMON/ BLK8/ IGRID(LPLS,IWPLS),XI(4),W(4)
COMMON/ BLK11/ HEQL,DELC,GRADC,GRADT,ALFA1,ALFA2,TDEL,SMIN
DATA FACT/3.17097E-8/
NAMelist /LOGCL/HOTST,FTTOM,HVISC,VFRICT,MOVE,CLIMET,PRT
NAMelist /SYSTEM/H,ETA,SOS,FMAX,FMIN,FRICT,NV,NH,RHO
NAMelist /CNTRL/START,PHOTST,POUTPT,NHOTST
NAMelist /MODPAR/DELT,DELX,DELY,NFIN,UPAI
NAMelist /METEO/ HEQL,DELC,GRADC,GRADT,ALFA1,ALFA2,TDEL,SMIN
*****.....READ AND ECHO INPUT DATA
*
*   WRITE(3,2001)
2001  FORMAT(' ',T10,'READING INITIAL INPUT DATA.....')
*
*   READ(1,LOGCL)
IF(PRT) THEN
  WRITE(3,LOGCL)
ENDIF
*
*   READ(1,SYSTEM)
IF(PRT) THEN
  WRITE(3,SYSTEM)
ENDIF
*
*   READ(1,CNTRL)
IF(PRT) THEN
  WRITE(3,CNTRL)
ENDIF
*
*   READ(1,MODPAR)
IF(PRT) THEN
  WRITE(3,MODPAR)

```

```

TAK03320
TAK03330
TAK03340
TAK03350
TAK03360
TAK03370
TAK03380
TAK03390
TAK03400
TAK03410
TAK03420
TAK03430
TAK03440
TAK03450
TAK03460
TAK03470
TAK03480
TAK03490
TAK03500
TAK03510
TAK03520
TAK03530
TAK03540
TAK03550
TAK03560
TAK03570
TAK03580
TAK03590
TAK03600
TAK03610
TAK03620
TAK03630
TAK03640
TAK03650
TAK03660
TAK03670
TAK03680
TAK03690
TAK03700
TAK03710
TAK03720
TAK03730
TAK03740
TAK03750
TAK03760
TAK03770
TAK03780
TAK03790
TAK03800
TAK03810
TAK03820
TAK03830
TAK03840
TAK03850
TAK03860
TAK03870
TAK03880
TAK03890
TAK03900

```

```

      ENDIF
*
      IF (CLIMET) THEN
        READ (1, METEO)
      ENDIF
      IF (PRT) THEN
        WRITE (3, METEO)
      ENDIF
*
      DELT=86400.0*DELT
      START=86400.0*START
      DELX=1000.0*DELX
      DELY=1000.0*DELY
*
*
*****.....CONVERT ELEVATIONS TO METER FROM FEET
*
      IF (FTTOM) THEN
        DO 102 I=1, LPLS
          DO 102 J=1, IWPLS
            H(I, J)=0.3048*H(I, J)
            ETA(I, J)=0.3048*ETA(I, J)
102      CONTINUE
      ENDIF
*
***.....CONVERT PPT. FROM MM/YR TO M/S
*
      SMIN=FACT*SMIN*DELT
      DO 103 I=1, LPLS
        DO 103 J=1, IWPLS
          SOS(I, J)=FACT*SOS(I, J)*DELT
103      CONTINUE
*
*
      IF (VFRIC) THEN
        HMAX=-9999.0
        HMIN=+9999.0
        DO 104 I=1, LPLS
          DO 104 J=1, IWPLS
            HMAX=AMAX1(HMAX, H(I, J))
            HMIN=AMIN1(HMIN, H(I, J))
104      CONTINUE
          HDIF=HMAX-HMIN
          HDIF=1.0/HDIF
          FDIF=FMAX-FMIN
          DO 105 J=1, IWPLS
            DO 105 I=1, LPLS
              FRIC(I, J)=FMIN+(H(I, J)-HMIN)*FDIF*HDIF
105      CONTINUE
          ENDIF
          DO 106 I=1, LPLS
            DO 106 J=1, IWPLS
              FRIC(I, J)=FRIC(I, J)*1.0E06
106      CONTINUE
*
      RETURN
      END

```

```

TAK03910
TAK03920
TAK03930
TAK03940
TAK03950
TAK03960
TAK03970
TAK03980
TAK03990
TAK04000
TAK04010
TAK04020
TAK04030
TAK04040
TAK04050
TAK04060
TAK04070
TAK04080
TAK04090
TAK04100
TAK04110
TAK04120
TAK04130
TAK04140
TAK04150
TAK04160
TAK04170
TAK04180
TAK04190
TAK04200
TAK04210
TAK04220
TAK04230
TAK04240
TAK04250
TAK04260
TAK04270
TAK04280
TAK04290
TAK04300
TAK04310
TAK04320
TAK04330
TAK04340
TAK04350
TAK04360
TAK04370
TAK04380
TAK04440
TAK04450
TAK04460
TAK04470
TAK04480
TAK04490
TAK04500
TAK04510
TAK04520

```



```

SUBROUTINE INITIL(HI,SSS)
*****
*
*   INITIALIZES AND SETS COUNTERS FOR MODEL RUN
*
*****
*
*   PARAMETER (JP=1,KP=21,LENGTH=54,IWIDTH=33)
*   PARAMETER (LENP1=LENGTH+1,IWIDP1=IWIDTH+1,LPLS=LENGTH+2,
&             IWPLS=IWIDTH+2)
*
*   REAL    NV,NH,NC,ND,NETA
*   REAL    INTG1,INTG2,INTG3,INTG4,INTG5,INTG6,INTG7
*   LOGICAL  FTTOM,HOTST,HVISC,VFRICT,MOVE
*
*   DIMENSION HI(LPLS,IWPLS),SSS(LPLS,IWPLS)
*   COMMON/ BLK2/ DELT,DELX,DELY,UPAI,START,PHOTST,POUTPT,
&           ISTRT,NFIN,NHOTST
*   COMMON/ BLK3/ FTTOM,HOTST,HVISC,VFRICT,MOVE
*   COMMON/ BLK4/ C(JP,LENP1,IWIDTH),NC(JP,LENP1,IWIDTH),
&           D(JP,LENGTH,IWIDP1),ND(JP,LENGTH,IWIDP1)
*   COMMON/ BLK5/ ETA(LPLS,IWPLS),NETA(LPLS,IWPLS),SOS(LPLS,IWPLS),
&           H(LPLS,IWPLS)
*   COMMON/ BLK6/ A(JP,LPLS,IWPLS),CONTI(JP,LPLS,IWPLS)
*   COMMON/ BLK7/ INTG1(JP,LPLS,IWPLS),INTG2(JP,JP,LPLS,IWPLS),
&           INTG3(JP,LPLS,IWPLS),INTG4(JP,JP,LPLS,IWPLS),
&           INTG5(JP,JP,LPLS,IWPLS),INTG6(JP,JP,LPLS,IWPLS),
&           INTG7(JP,JP,LPLS,IWPLS)
*   COMMON/ BLK8/ IGRID(LPLS,IWPLS),XI(4),W(4)
*   COMMON/ BLK9/ VX(KP,LPLS,IWPLS),VY(KP,LPLS,IWPLS),
&           VV(KP,LPLS,IWPLS),VM(LPLS,IWPLS),DELSIG
*   COMMON/ BLK10/ QIF(LPLS,IWPLS),QIB(LPLS,IWPLS),
&           QJF(LPLS,IWPLS),QJB(LPLS,IWPLS)
*
*
*
*   PI=3.1415927
*
*****.....INITIALIZE C'S AND D'S
*
DO 102 J=1,JP
  DO 103 K=1,LENP1
    DO 103 L=1,IWIDTH
      C(J,K,L)=0.0
      NC(J,K,L)=0.0
103    CONTINUE
  DO 104 K=1,LENGTH
    DO 104 L=1,IWIDP1
      D(J,K,L)=0.0
      ND(J,K,L)=0.0
104    CONTINUE
102  CONTINUE
*
*****..... INITIALIZATION OF AI'S
*
DO 106 K=1,LPLS
  DO 106 L=1,IWPLS

```

TAK04530
TAK04540
TAK04550
TAK04560
TAK04570
TAK04580
TAK04590
TAK04600
TAK04610
TAK04620
TAK04630
TAK04640
TAK04650
TAK04660
TAK04670
TAK04680
TAK04690
TAK04700
TAK04710
TAK04720
TAK04730
TAK04740
TAK04750
TAK04760
TAK04770
TAK04780
TAK04790
TAK04800
TAK04810
TAK04820
TAK04830
TAK04840
TAK04850
TAK04860
TAK04870
TAK04880
TAK04890
TAK04900
TAK04910
TAK04920
TAK04930
TAK04940
TAK04950
TAK04960
TAK04970
TAK04980
TAK04990
TAK05000
TAK05010
TAK05020
TAK05030
TAK05040
TAK05050
TAK05060
TAK05070
TAK05080
TAK05090
TAK05100
TAK05110

```

DO 107 J=1,JP
A(J,K,L)=FLOAT(J-1)*PI+0.5*PI
107 CONTINUE
106 CONTINUE
*
*****.....INITIALIZE NETA
*
DO 108 I=1,LPLS
DO 108 J=1,IWPLS
NETA(I,J)=ETA(I,J)
108 CONTINUE
*
*****.....INITIALIZE INTEGRALS
*
DO 109 I=1,LPLS
DO 109 J=1,IWPLS
DO 109 K=1,JP
INTG1(K,I,J)=0.0
INTG3(K,I,J)=0.0
DO 109 L=1,JP
INTG2(L,J,I,J)=0.0
INTG4(L,J,I,J)=0.0
INTG5(L,J,I,J)=0.0
INTG6(L,J,I,J)=0.0
INTG7(L,J,I,J)=0.0
109 CONTINUE
*
*****.....INITIALIZE INFLOW/OUTFLOW VALUES
*
DO 110 I=1,LPLS
DO 110 J=1,IWPLS
QIF(I,J)=0.0
QIB(I,J)=0.0
QJF(I,J)=0.0
QJB(I,J)=0.0
110 CONTINUE
*
DO 111 I=1,LPLS
DO 111 J=1,IWPLS
HI(I,J)=ETA(I,J)
SSS(I,J)=SOS(I,J)
111 CONTINUE
*
*****.....INITIALIZE VELOCITY
*
DELSIG=2.0/(KP-1)
DO 112 I=1,LPLS
DO 112 J=1,IWPLS
VM(I,J)=0.0
DO 112 K=1,KP
VX(K,I,J)=0.0
VY(K,I,J)=0.0
VV(K,I,J)=0.0
112 CONTINUE
*
*****.....SET LOCATION & WEIGHTS OF GAUSSIAN QUADRATURE
*
XI(1)=-0.8611363116
XI(2)=-0.3399810436
XI(3)=-XI(2)
XI(4)=-XI(1)

```

TAK05120
TAK05130
TAK05140
TAK05150
TAK05160
TAK05170
TAK05180
TAK05190
TAK05200
TAK05210
TAK05220
TAK05230
TAK05240
TAK05250
TAK05260
TAK05270
TAK05280
TAK05290
TAK05300
TAK05310
TAK05320
TAK05330
TAK05340
TAK05350
TAK05360
TAK05370
TAK05380
TAK05390
TAK05400
TAK05410
TAK05420
TAK05430
TAK05440
TAK05450
TAK05460
TAK05470
TAK05480
TAK05490
TAK05500
TAK05510
TAK05520
TAK05530
TAK05540
TAK05550
TAK05560
TAK05570
TAK05580
TAK05590
TAK05600
TAK05610
TAK05620
TAK05630
TAK05640
TAK05650
TAK05660
TAK05670
TAK05680
TAK05690
TAK05700
TAK05710
TAK05720

```

*
      W(1)=0.3478548451
      W(2)=0.6521451549
      W(3)=W(2)
      W(4)=W(1)
*
      RETURN
*
*****.....READ INITIAL CONDITION FOR HOT START
*
      ENTRY INIT(HI,SSS)
*
      WRITE(3,2001)
2001  FORMAT(' ',T10,'READING HOT START DATA.....')
      READ(2) ISTRT
      READ(2) IGRID
      READ(2) A
      READ(2) ETA
      READ(2) NETA
      READ(2) C
      READ(2) NC
      READ(2) D
      READ(2) ND
      READ(2) SSS
      READ(2) FRICT
      READ(2) QIF
      READ(2) QIB
      READ(2) QJF
      READ(2) QJB
*
      RETURN
      END

```

```

TAK05730
TAK05740
TAK05750
TAK05760
TAK05770
TAK05780
TAK05790
TAK05800
TAK05810
TAK05820
TAK05830
TAK05840
TAK05850
TAK05860
TAK05870
TAK05880
TAK05890
TAK05900
TAK05910
TAK05920
TAK05930
TAK05940
TAK05950
TAK05960
TAK05970
TAK05980
TAK05990
TAK06000
TAK06010
TAK06020
TAK06030
TAK06040

```

```

SUBROUTINE FILTER(XP,IG)
*****
*
*           FILTERS INPUT DATA IF NECESSARY
*
*****
*
*
PARAMETER (LENGTH=54,IWIDTH=33)
PARAMETER (LENP1=LENGTH+1,IWIDP1=IWIDTH+1,LPLS=LENGTH+2,
        & IWPLS=IWIDTH+2)
DIMENSION XP(LPLS,IWPLS),IG(LPLS,IWPLS),YP(LPLS,IWPLS)
*
*
DO 101 J=1,IWPLS
  DO 101 I=1,LPLS
    YP(I,J)=XP(I,J)
101 CONTINUE
    DO 102 I=1,LPLS
      DO 102 J=1,IWPLS
        IF (IG(I,J).EQ.0) THEN
          IF (IG(I-1,J).EQ.0.AND.IG(I+1,J).EQ.0) THEN
            FX=0.25*(YP(I-1,J)+2.0*YP(I,J)+YP(I+1,J))
          ELSE IF (IG(I-1,J).EQ.0) THEN
            FX=0.33*(YP(I-1,J)+2.0*YP(I,J))
          ELSE IF (IG(I+1,J).EQ.0) THEN
            FX=0.33*(2.0*YP(I,J)+YP(I+1,J))
          ELSE
            FX=YP(I,J)
          ENDIF
        ELSE
          IF (IG(I,J-1).EQ.0.AND.IG(I,J+1).EQ.0) THEN
            FY=0.25*(YP(I,J-1)+2.0*YP(I,J)+YP(I,J+1))
          ELSE IF (IG(I,J-1).EQ.0) THEN
            FY=0.33*(YP(I,J-1)+2.0*YP(I,J))
          ELSE IF (IG(I,J+1).EQ.0) THEN
            FY=0.33*(2.0*YP(I,J)+YP(I,J+1))
          ELSE
            FY=YP(I,J)
          ENDIF
          XP(I,J)=0.5*(FX+FY)
        ENDIF
      ENDIF
    CONTINUE
102 RETURN
END

```

TAK06050
TAK06060
TAK06070
TAK06080
TAK06090
TAK06100
TAK06110
TAK06120
TAK06130
TAK06140
TAK06150
TAK06160
TAK06170
TAK06180
TAK06190
TAK06200
TAK06210
TAK06220
TAK06230
TAK06240
TAK06250
TAK06260
TAK06270
TAK06280
TAK06290
TAK06300
TAK06310
TAK06320
TAK06330
TAK06340
TAK06350
TAK06360
TAK06370
TAK06380
TAK06390
TAK06400
TAK06410
TAK06420
TAK06430
TAK06440
TAK06450
TAK06460
TAK06470
TAK06480
TAK06490

```

SUBROUTINE ACALC
*****
*
*          CALCULATES VALUES OF A(I) 'S
*
*****
*
*          PARAMETER (JP=1, KP=21, LENGTH=54, IWIDTH=33)
*          PARAMETER (LENP1=LENGTH+1, IWIDP1=IWIDTH+1, LPLS=LENGTH+2,
&          IWPLS=IWIDTH+2)
*
*          REAL    NV, NH, NC, ND, NETA
*          LOGICAL FLAG
*
*          COMMON/ BLK1/ H(LPLS, IWPLS), FRICT(LPLS, IWPLS), NV, NH, RHO
*          COMMON/ BLK5/ ETA(LPLS, IWPLS), NETA(LPLS, IWPLS), SOS(LPLS, IWPLS)
*          COMMON/ BLK6/ A(JP, LPLS, IWPLS), CONTI(JP, LPLS, IWPLS)
*          COMMON/ BLK8/ IGRID(LPLS, IWPLS), XI(4), W(4)
*
*          DATA  PI/    3.1515927/
*
*          DO 101 M=1, LPLS
*             DO 101 N=1, IWPLS
*                IF (IGRID(M, N) .NE. 0) GOTO 101
*                IF (FRICT(M, N) .EQ. 0.0) THEN
*                   GOTO 501
*                ELSE
*                   IF (FRICT(M, N) .EQ. -999.0) THEN
*                      GOTO 502
*                   ENDIF
*                ENDIF
*                CB=FRICT(M, N)
*                DP= NETA(M, N) -H(M, N)
*                DPCB=DP*CB
*                C=DPCB/NV
*                IF (C.LT.0.0001) GOTO 501
*                IF (C.GT.250.0) GOTO 502
*
*          *****.....NEWTON-RAPSON ITERATION
*
*             DO 102 J=1, JP
*                SOL=((FLOAT(J)-1.0)*PI)+PI/8.0
*                FLAG=.TRUE.
503          AO=C/SOL
*                A(J, M, N) = (ATAN(AO) + (FLOAT(J-1))*PI)
*                DIFF= ABS(A(J, M, N) - SOL)
*                IF (DIFF.LT.0.01) FLAG=.FALSE.
*                SOL=A(J, M, N)
*                IF (FLAG) GOTO 503
102          CONTINUE
*             GOTO 101
501          DO 104 J=1, JP
*                A(J, M, N) = FLOAT(J-1)*PI
104          CONTINUE
*             GOTO 101
TAKO6500
TAKO6510
TAKO6520
TAKO6530
TAKO6540
TAKO6550
TAKO6560
TAKO6570
TAKO6580
TAKO6590
TAKO6600
TAKO6610
TAKO6620
TAKO6630
TAKO6640
TAKO6650
TAKO6660
TAKO6670
TAKO6680
TAKO6690
TAKO6700
TAKO6710
TAKO6720
TAKO6730
TAKO6740
TAKO6750
TAKO6760
TAKO6770
TAKO6780
TAKO6790
TAKO6800
TAKO6810
TAKO6820
TAKO6830
TAKO6840
TAKO6850
TAKO6860
TAKO6870
TAKO6880
TAKO6890
TAKO6900
TAKO6910
TAKO6920
TAKO6930
TAKO6940
TAKO6950
TAKO6960
TAKO6970
TAKO6980
TAKO6990
TAKO7000
TAKO7010
TAKO7020
TAKO7030
TAKO7040
TAKO7050
TAKO7060
TAKO7070

```

```
502          DO 105 J=1, JP                      TAK07080
          A(J,M,N)=FLOAT(J-1)*PI+PI*0.5        TAK07090
105          CONTINUE                            TAK07100
101          CONTINUE                            TAK07110
*                                                TAK07120
          RETURN                                TAK07130
          END                                  TAK07140
```

```

SUBROUTINE GALINI
*****
*
*           EVALUATES 1, 2 AND 3 INTEGRALS
*
*****
*
*   PARAMETER (JP=1,KP=21,LENGTH=54,IWIDTH=33)
*   PARAMETER (LENP1=LENGTH+1,IWIDP1=IWIDTH+1,LPLS=LENGTH+2,
*             & IWPLS=IWIDTH+2)
*
*   REAL   NV,NH,NC,ND,NETA
*   REAL   INTG1,INTG2,INTG3,INTG4,INTG5,INTG6,INTG7
*
*   COMMON/ BLK6/ A(JP,LPLS,IWPLS),CONTI(JP,LPLS,IWPLS)
*   COMMON/ BLK7/ INTG1(JP,LPLS,IWPLS),INTG2(JP,JP,LPLS,IWPLS),
*             & INTG3(JP,LPLS,IWPLS),INTG4(JP,JP,LPLS,IWPLS),
*             & INTG5(JP,JP,LPLS,IWPLS),INTG6(JP,JP,LPLS,IWPLS),
*             & INTG7(JP,JP,LPLS,IWPLS)
*   COMMON/ BLK8/ IGRID(LPLS,IWPLS),XI(4),W(4)
*
*
*
*****.....FIRST INTEGRAL
*
DO 101 I=1,LPLS
  DO 101 J=1,IWPLS
    IF(IGRID(I,J).NE.0) GOTO 101
    DO 102 K=1,JP
      IF(A(K,I,J).EQ.0.) THEN
        INTG1(K,I,J)=2.0
      ELSE
        INTG1(K,I,J)=1.0+ SIN(2.0*A(K,I,J))/(2.0*A(K,I,J))
      ENDIF
    102 CONTINUE
  101 CONTINUE
*
*****.....SECOND INTEGRAL
*
DO 104 M=1,LPLS
  DO 104 N=1,IWPLS
    IF(IGRID(M,N).NE.0) GOTO 104
    DO 105 I=1,JP
      IF(A(I,M,N).EQ.0.) THEN
        DO 106 J=1,JP
          INTG2(I,J,M,N)=0.0
        106 CONTINUE
          GOTO 502
        ENDIF
        DO 105 J=1,JP
          F1=0.0
          SI=0.5*A(I,M,N)
          SJ=0.5*A(J,M,N)
          DO 107 L=1,4
            X=(1.0+XI(L))
            T1=SI*(2.0-X)
            T2=SJ*(2.0-X)
            XNUB=X* SIN(T1)* COS(T2)*SI
            F1=F1+XNUB*W(L)
          107 CONTINUE
        105 CONTINUE
      ENDIF
    104 CONTINUE
  104 CONTINUE
*

```

TAKO7150
TAKO7160
* TAKO7170
* TAKO7180
* TAKO7190
* TAKO7200
* TAKO7210
* TAKO7220
* TAKO7230
* TAKO7240
* TAKO7250
* TAKO7260
* TAKO7270
* TAKO7280
* TAKO7290
* TAKO7300
* TAKO7310
* TAKO7320
* TAKO7330
* TAKO7340
* TAKO7350
* TAKO7360
* TAKO7370
* TAKO7380
* TAKO7390
* TAKO7400
* TAKO7410
* TAKO7420
* TAKO7430
* TAKO7440
* TAKO7450
* TAKO7460
* TAKO7470
* TAKO7480
* TAKO7490
* TAKO7500
* TAKO7510
* TAKO7520
* TAKO7530
* TAKO7540
* TAKO7550
* TAKO7560
* TAKO7570
* TAKO7580
* TAKO7590
* TAKO7600
* TAKO7610
* TAKO7620
* TAKO7630
* TAKO7640
* TAKO7650
* TAKO7660
* TAKO7670
* TAKO7680
* TAKO7690
* TAKO7700
* TAKO7710
* TAKO7720
* TAKO7730
* TAKO7740
* TAKO7750

```

                                INTG2(I, J, M, N) = F1
105                                CONTINUE
502                                CONTINUE
104                                CONTINUE
*
*****.....THIRD INTEGRAL
*
      DO 109 I=1, LPLS
        DO 109 J=1, IWPLS
          IF (IGRID(I, J) .NE. 0) GOTO 109
          DO 110 K=1, JP
            IF (A(K, I, J) .EQ. 0.) THEN
              INTG3(K, I, J) = 2.0
            ELSE
              INTG3(K, I, J) = 2.0 * SIN(A(K, I, J)) / (A(K, I, J))
            ENDIF
          ENDIF
        DO 110 K=1, JP
          CONTINUE
        DO 109 J=1, IWPLS
          CONTINUE
        DO 109 I=1, LPLS
          CONTINUE
110                                CONTINUE
109                                CONTINUE
*
      RETURN
      END
                                TAK07760
                                TAK07770
                                TAK07780
                                TAK07790
                                TAK07800
                                TAK07810
                                TAK07820
                                TAK07830
                                TAK07840
                                TAK07850
                                TAK07860
                                TAK07870
                                TAK07880
                                TAK07890
                                TAK07900
                                TAK07910
                                TAK07920
                                TAK07930
                                TAK07940
                                TAK07950
                                TAK07960
```



```

SUBROUTINE GALIN2
*****
*
*          EVALUATES INTEGRALS S4, S5, AND S6
*
*****
*
*          PARAMETER (JP=1, KP=21, LENGTH=54, IWIDTH=33)
*          PARAMETER (LENP1=LENGTH+1, IWIDP1=IWIDT+1, LPLS=LENGTH+2,
&                    IWPLS=IWIDT+2)
*
*          REAL    NV, NH, NC, ND, NETA
*          REAL    INTG1, INTG2, INTG3, INTG4, INTG5, INTG6, INTG7
*          LOGICAL  FTTOM, HOTST, HVISC, VFRICT, MOVE
*
*          COMMON/ BLK1/ H(LPLS, IWPLS), FRICT(LPLS, IWPLS), NV, NH, RHO
*          COMMON/ BLK2/ DELT, DELX, DELY, UPAI, START, PROTST, POUTPT,
&                    ISTRT, NFIN, NHOTST
*          COMMON/ BLK3/ FTTOM, HOTST, HVISC, VFRICT, MOVE
*          COMMON/ BLK4/ C(JP, LENP1, IWIDT), NC(JP, LENP1, IWIDT),
&                    D(JP, LENGTH, IWIDP1), ND(JP, LENGTH, IWIDP1)
*          COMMON/ BLK5/ ETA(LPLS, IWPLS), NETA(LPLS, IWPLS), SOS(LPLS, IWPLS)
*          COMMON/ BLK6/ A(JP, LPLS, IWPLS), CONTI(JP, LPLS, IWPLS)
*          COMMON/ BLK7/ INTG1(JP, LPLS, IWPLS), INTG2(JP, JP, LPLS, IWPLS),
&                    INTG3(JP, LPLS, IWPLS), INTG4(JP, JP, LPLS, IWPLS),
&                    INTG5(JP, JP, LPLS, IWPLS), INTG6(JP, JP, LPLS, IWPLS),
&                    INTG7(JP, JP, LPLS, IWPLS)
*          COMMON/ BLK8/ IGRID(LPLS, IWPLS), XI(4), W(4)
*
*
*          DO 101 M=2, LPLS-1
*          DO 101 N=2, IWPLS-1
*
*          IF(IGRID(M,N).NE.0) GOTO 101
*
*****.....COMPUTE DIFFERENTIALS IN X-DIRECTION
*
*          IF(IGRID(M+1,N).EQ.0.AND.IGRID(M-1,N).EQ.0) THEN
*          DHDX=(H(M+1,N)-H(M-1,N))/(2.0*DELX)
*          DEDX=(NETA(M+1,N)-NETA(M-1,N))/(2.0*DELX)
*          DDFX=NETA(M+1,N)-H(M+1,N)
*          DDMX=NETA(M,N)-H(M,N)
*          DDBX=NETA(M-1,N)-H(M-1,N)
*          DDX=(DDFX+5.0*DDMX+DDBX)/7.0
*          ELSE IF(IGRID(M+1,N).EQ.0) THEN
*          DHDX=(H(M+1,N)-H(M,N))/DELX
*          DEDX=(NETA(M+1,N)-NETA(M,N))/DELX
*          DDFX=NETA(M+1,N)-H(M+1,N)
*          DDMX=NETA(M,N)-H(M,N)
*          DDX=(DDFX+5.0*DDMX)/6.0
*          ELSE IF(IGRID(M-1,N).EQ.0) THEN
*          DHDX=(H(M,N)-H(M-1,N))/DELX
*          DEDX=(NETA(M,N)-NETA(M-1,N))/DELX
*          DDMX=NETA(M,N)-H(M,N)
*          DDBX=NETA(M-1,N)-H(M-1,N)
*          DDX=(5.0*DDMX+DDBX)/6.0
*          ELSE
*          DHDX=0.0
*          DEDX=0.0

```

TAK07970
TAK07980
TAK07990
TAK08000
TAK08010
TAK08020
TAK08030
TAK08040
TAK08050
TAK08060
TAK08070
TAK08080
TAK08090
TAK08100
TAK08110
TAK08120
TAK08130
TAK08140
TAK08150
TAK08160
TAK08170
TAK08180
TAK08190
TAK08200
TAK08210
TAK08220
TAK08230
TAK08240
TAK08250
TAK08260
TAK08270
TAK08280
TAK08290
TAK08300
TAK08310
TAK08320
TAK08330
TAK08340
TAK08350
TAK08360
TAK08370
TAK08380
TAK08390
TAK08400
TAK08410
TAK08420
TAK08430
TAK08440
TAK08450
TAK08460
TAK08470
TAK08480
TAK08490
TAK08500
TAK08510
TAK08520
TAK08530
TAK08540
TAK08550
TAK08560
TAK08570

```

      DDX =NETA (M, N) -H (M, N)
ENDIF
*
*****.....COMPUTE DIFFERENTIALS IN Y-DIRECTION
*
      IF (IGRID (M, N+1) .EQ. 0 .AND. IGRID (M, N-1) .EQ. 0) THEN
      DHDY=(H (M, N+1) -H (M, N-1)) / (2.0*DELY)
      DEDY=(NETA (M, N+1) -NETA (M, N-1)) / (2.0*DELY)
      DDFY=NETA (M, N+1) -H (M, N+1)
      DDMY=NETA (M, N) -H (M, N)
      DDBY=NETA (M, N-1) -H (M, N-1)
      DDY = (DDFY+5.0*DDMY+DDBY) / 7.0
      ELSE IF (IGRID (M, N+1) .EQ. 0) THEN
      DHDY=(H (M, N+1) -H (M, N)) / DELY
      DEDY=(NETA (M, N+1) -NETA (M, N)) / DELY
      DDFY=NETA (M, N+1) -H (M, N+1)
      DDMY=NETA (M, N) -H (M, N)
      DDY = (DDFY+5.0*DDMY) / 6.0
      ELSE IF (IGRID (M, N-1) .EQ. 0) THEN
      DHDY=(H (M, N) -H (M, N-1)) / DELY
      DEDY=(NETA (M, N) -NETA (M, N-1)) / DELY
      DDMY=NETA (M, N) -H (M, N)
      DDBY=NETA (M, N-1) -H (M, N-1)
      DDY = (5.0*DDMY+DDBY) / 6.0
      ELSE
      DHDY=0.0
      DEDY=0.0
      DDY =NETA (M, N) -H (M, N)
      ENDIF
      DD=(DDX+DDY) / 2.0
*
*****.....EVALUATE THE INTEGRALS
*
      DO 102 I=1, JP
      DO 105 J=1, JP
      F1=0.0
      F2=0.0
      F3=0.0
      SI=0.5*A (I, M, N)
      SJ=0.5*A (J, M, N)
      DO 104 L=1, 4
      X=(1.0+XI (L))
      T1=SI*(2.0-X)
      T2=SJ*(2.0-X)
      XNUB=(SI) * SIN(T1) * COS(T1) * COS(T2)
      X1=((2.0-X) *DHDX-X*DEDX) /DD
      Y1=((2.0-X) *DHDY-X*DEDY) /DD
      F1=F1+(( COS(T1) * COS(T2)) **2) *W(L)
      F2=F2+X1*XNUB*W(L)
      F3=F3+Y1*XNUB*W(L)
104      CONTINUE
      INTG4 (I, J, M, N) =F1
      INTG5 (I, J, M, N) =F2
      INTG6 (I, J, M, N) =F3
105      CONTINUE
102      CONTINUE
101      CONTINUE
      RETURN
      END

```

TAK08580
 TAK08590
 TAK08600
 TAK08610
 TAK08620
 TAK08630
 TAK08640
 TAK08650
 TAK08660
 TAK08670
 TAK08680
 TAK08690
 TAK08700
 TAK08710
 TAK08720
 TAK08730
 TAK08740
 TAK08750
 TAK08760
 TAK08770
 TAK08780
 TAK08790
 TAK08800
 TAK08810
 TAK08820
 TAK08830
 TAK08840
 TAK08850
 TAK08860
 TAK08870
 TAK08880
 TAK08890
 TAK08900
 TAK08910
 TAK08920
 TAK08930
 TAK08940
 TAK08950
 TAK08960
 TAK08970
 TAK08980
 TAK08990
 TAK09000
 TAK09010
 TAK09020
 TAK09030
 TAK09040
 TAK09050
 TAK09060
 TAK09070
 TAK09080
 TAK09090
 TAK09100
 TAK09110
 TAK09120
 TAK09130
 TAK09140
 TAK09150
 TAK09160

```

SUBROUTINE GALIN3
*****
*
*          EVALUATES SUM OF INTEGRALS 7 TO 10
*
*****
PARAMETER (JP=1,KP=21,LENGTH=54,IWIDTH=33)
PARAMETER (LENP1=LENGTH+1,IWIDP1=IWIDTH+1,LPLS=LENGTH+2,
&          IWPLS=IWIDTH+2)
REAL    NV,NH,NC,ND,NETA
REAL    INTG1,INTG2,INTG3,INTG4,INTG5,INTG6,INTG7
LOGICAL FTTOM,HOTST,HVISC,VFRICT,MOVE
*
COMMON/ BLK1/ H(LPLS,IWPLS),FRICT(LPLS,IWPLS),NV,NH,RHO
COMMON/ BLK2/ DELT,DELX,DELY,UPAI,START,PHOTST,POUTPT,
&          ISTRT,NFIN,NHOTST
COMMON/ BLK3/ FTTOM,HOTST,HVISC,VFRICT,MOVE
COMMON/ BLK5/ ETA(LPLS,IWPLS),NETA(LPLS,IWPLS),SOS(LPLS,IWPLS)
COMMON/ BLK6/ A(JP,LPLS,IWPLS),CONTI(JP,LPLS,IWPLS)
COMMON/ BLK7/ INTG1(JP,LPLS,IWPLS),INTG2(JP,JP,LPLS,IWPLS),
&          INTG3(JP,LPLS,IWPLS),INTG4(JP,JP,LPLS,IWPLS),
&          INTG5(JP,JP,LPLS,IWPLS),INTG6(JP,JP,LPLS,IWPLS),
&          INTG7(JP,JP,LPLS,IWPLS)
COMMON/ BLK8/ IGRID(LPLS,IWPLS),XI(4),W(4)
*
*
*
DO 101 M=2,LPLS-1
DO 101 N=2,IWPLS-1
*
IF(IGRID(M,N).NE.0) GOTO 101
*
*****.....COMPUTE DIFFERENTIALS IN X-DIRECTION
*
IF(IGRID(M+1,N).EQ.0.AND.IGRID(M-1,N).EQ.0) THEN
DHDX=(H(M+1,N)-H(M-1,N))/(2.0*DELX)
DEDX=(NETA(M+1,N)-NETA(M-1,N))/(2.0*DELX)
D2HDX=((H(M+1,N)-H(M,N))+H(M-1,N)-H(M,N))/(DELX**2)
D2EDX=((NETA(M+1,N)-NETA(M,N))+NETA(M-1,N)-NETA(M,N))
&          / (DELX**2)
D2EDX=NETA(M+1,N)-H(M+1,N)
DDMX=NETA(M,N)-H(M,N)
DDBX=NETA(M-1,N)-H(M-1,N)
DDX=(DDFX+5.0*DDMX+DDBX)/7.0
ELSE IF(IGRID(M+1,N).EQ.0) THEN
DHDX=(H(M+1,N)-H(M,N))/DELX
DEDX=(NETA(M+1,N)-NETA(M,N))/DELX
D2HDX=(H(M+1,N)-H(M,N))/(DELX**2)
D2EDX=(NETA(M+1,N)-NETA(M,N))/(DELX**2)
DDFX=NETA(M+1,N)-H(M+1,N)
DDMX=NETA(M,N)-H(M,N)
DDX=(DDFX+5.0*DDMX)/6.0
ELSE IF(IGRID(M-1,N).EQ.0) THEN

```

TAKO9170
TAKO9180
* TAKO9190
* TAKO9200
* TAKO9210
TAKO9220
TAKO9230
* TAKO9240
TAKO9250
TAKO9260
TAKO9270
TAKO9280
TAKO9290
TAKO9300
TAKO9310
TAKO9320
TAKO9330
TAKO9340
TAKO9350
TAKO9360
TAKO9370
TAKO9380
TAKO9390
TAKO9400
TAKO9410
TAKO9420
TAKO9430
TAKO9440
TAKO9450
TAKO9460
TAKO9470
TAKO9480
TAKO9490
TAKO9500
TAKO9510
TAKO9520
TAKO9530
TAKO9540
TAKO9550
TAKO9560
TAKO9570
TAKO9580
TAKO9590
TAKO9600
TAKO9610
TAKO9620
TAKO9630
TAKO9640
TAKO9650
TAKO9660
TAKO9670
TAKO9680
TAKO9690
TAKO9700
TAKO9710
TAKO9720

```

DHDX=(H(M,N)-H(M-1,N))/DELX          TAK09730
DEDX=(NETA(M,N)-NETA(M-1,N))/DELX      TAK09740
D2HDX=(H(M-1,N)-H(M,N))/(DELX**2)     TAK09750
D2EDX=(NETA(M-1,N)-NETA(M,N))/(DELX**2) TAK09760
DDMX=NETA(M,N)-H(M,N)                  TAK09770
DDBX=NETA(M-1,N)-H(M-1,N)              TAK09780
DDX=(5.0*DDMX+DDBX)/6.0                TAK09790
ELSE                                     TAK09800
  DHDX=0.0                              TAK09810
  DEDX=0.0                              TAK09820
  D2HDX=0.0                             TAK09830
  D2EDX=0.0                             TAK09840
  DDX=NETA(M,N)-H(M,N)                  TAK09850
ENDIF                                    TAK09860
*                                       TAK09870
*****.....COMPUTE DIFFERENTIALS IN Y-DIRECTION TAK09880
*                                       TAK09890
IF(IGRID(M,N+1).EQ.0.AND.IGRID(M,N-1).EQ.0) THEN TAK09900
  DHDY=(H(M,N+1)-H(M,N-1))/(2.0*DELY)  TAK09910
  DEDY=(NETA(M,N+1)-NETA(M,N-1))/(2.0*DELY) TAK09920
  D2HDY=((H(M,N+1)-H(M,N))+ (H(M,N-1)-H(M,N)))/(DELY**2) TAK09930
  D2EDY=((NETA(M,N+1)-NETA(M,N))+ (NETA(M,N-1)-NETA(M,N)))/(DELY**2) TAK09940
  DDFY=NETA(M,N+1)-H(M,N+1)            TAK09950
  DDMY=NETA(M,N)-H(M,N)                 TAK09960
  DDBY=NETA(M,N-1)-H(M,N-1)            TAK09970
  DDY=(DDFY+5.0*DDMY+DDBY)/7.0        TAK09980
  ELSE IF(IGRID(M,N+1).EQ.0) THEN      TAK09990
    DHDY=(H(M,N+1)-H(M,N))/DELY        TAK10000
    DEDY=(NETA(M,N+1)-NETA(M,N))/DELY  TAK10010
    D2HDY=(H(M,N+1)-H(M,N))/(DELY**2) TAK10020
    D2EDY=(NETA(M,N+1)-NETA(M,N))/(DELY**2) TAK10030
    DDFY=NETA(M,N+1)-H(M,N+1)          TAK10040
    DDMY=NETA(M,N)-H(M,N)              TAK10050
    DDY=(DDFY+5.0*DDMY)/6.0           TAK10060
  ELSE IF(IGRID(M,N-1).EQ.0) THEN      TAK10070
    DHDY=(H(M,N)-H(M,N-1))/DELY        TAK10080
    DEDY=(NETA(M,N)-NETA(M,N-1))/DELY  TAK10090
    D2HDY=(H(M,N-1)-H(M,N))/(DELY**2) TAK10100
    D2EDY=(NETA(M,N-1)-NETA(M,N))/(DELY**2) TAK10110
    DDMY=NETA(M,N)-H(M,N)              TAK10120
    DDBY=NETA(M,N-1)-H(M,N-1)          TAK10130
    DDY=(5.0*DDMY+DDBY)/6.0           TAK10140
  ELSE                                  TAK10150
    DHDY=0.0                            TAK10160
    DEDY=0.0                            TAK10170
    D2HDY=0.0                           TAK10180
    D2EDY=0.0                           TAK10190
    DDY=NETA(M,N)-H(M,N)                TAK10200
  ENDIF                                 TAK10210
  DD=(DDX+DDY)/2.0                     TAK10220
*                                       TAK10230
*****.....EVALUATE INTEGRALS AND SUM    TAK10240
*                                       TAK10250
DO 102 I=1,JP                           TAK10260
  DO 102 J=1,JP                           TAK10270
    F1=0.0                                TAK10280
    F2=0.0                                TAK10290
    F3=0.0                                TAK10300
    F4=0.0                                TAK10310
    SI=0.5*A(I,M,N)                       TAK10320
  END DO                                  TAK10330

```

	SJ=0.5*A(J,M,N)	TAK10340
	DO 103 L=1,4	TAK10350
	X=(1.0+XI(L))	TAK10360
	T1=SI*(2.0-X)	TAK10370
	T2=SJ*(2.0-X)	TAK10380
	GAMX=((2.0-X)*DHDX-X*DEDX)/DD	TAK10390
	GAMY=((2.0-X)*DHDY-X*DEDY)/DD	TAK10400
	GX=((2.0-X)*D2HDX-X*D2EDX-GAMX*(DHDX+DEDX+1.0))/DD	TAK10410
	GY=((2.0-X)*D2HDY-X*D2EDY-GAMY*(DHDY+DEDY+1.0))/DD	TAK10420
	F1=F1+GX*A(I,M,N)*0.5* SIN(T1)* COS(T2)*W(L)	TAK10430
	F2=F2+(GAMX**2)*(-(A(I,M,N)**2)*0.25)*	TAK10440
	COS(T1)* COS(T2)*W(L)	TAK10450
	F3=F3+GY*A(I,M,N)*0.5* SIN(T1)* COS(T2)*W(L)	TAK10460
	F4=F4+(GAMY**2)*(-(A(I,M,N)**2)*0.25)*	TAK10470
	COS(T1)* COS(T2)*W(L)	TAK10480
103	CONTINUE	TAK10490
	IF(A(I,M,N).EQ.0.) F1=0.0	TAK10500
	IF(A(I,M,N).EQ.0.) F3=0.0	TAK10510
	INTG7(I,J,M,N)=F1+F2+F3+F4	TAK10520
102	CONTINUE	TAK10530
*		TAK10540
101	CONTINUE	TAK10550
	RETURN	TAK10560
	END	TAK10570

```

SUBROUTINE XMOM
*****
*
* SOLVES THE X-MOMENTUM EQUATION
*
*****
PARAMETER (JP=1,KP=21,LENGTH=54,IWIDTH=33)
PARAMETER (LENP1=LENGTH+1,IWIDP1=IWIDTH+1,LPLS=LENGTH+2,
& IWPLS=IWIDTH+2)
*
REAL NV,NH,NC,ND,NETA
REAL INTG1,INTG2,INTG3,INTG4,INTG5,INTG6,INTG7
LOGICAL FTTOM,HOTST,HVISC,VFRIC,MOVE
*
DIMENSION AA(JP),AI1(JP),AI2R(JP),AI2L(JP),AI3(JP),AI5R(JP),
& AI5L(JP),AI6L(JP),AI6R(JP),AI7R(JP),AI7L(JP)
COMMON/ BLK1/ H(LPLS,IWPLS),FRIC(LPLS,IWPLS),NV,NH,RHO
COMMON/ BLK2/ DELT,DELX,DELY,UPAI,START,PHOTST,POUTPT,
& ISTRT,NFIN,NHOTST
COMMON/ BLK3/ FTTOM,HOTST,HVISC,VFRIC,MOVE
COMMON/ BLK4/ C(JP,LENP1,IWIDTH),NC(JP,LENP1,IWIDTH),
& D(JP,LENGTH,IWIDP1),ND(JP,LENGTH,IWIDP1)
COMMON/ BLK5/ ETA(LPLS,IWPLS),NETA(LPLS,IWPLS),SOS(LPLS,IWPLS)
COMMON/ BLK6/ A(JP,LPLS,IWPLS),CONTI(JP,LPLS,IWPLS)
COMMON/ BLK7/ INTG1(JP,LPLS,IWPLS),INTG2(JP,JP,LPLS,IWPLS),
& INTG3(JP,LPLS,IWPLS),INTG4(JP,JP,LPLS,IWPLS),
& INTG5(JP,JP,LPLS,IWPLS),INTG6(JP,JP,LPLS,IWPLS),
& INTG7(JP,JP,LPLS,IWPLS)
COMMON/ BLK8/ IGRID(LPLS,IWPLS),XI(4),W(4)
*
DATA G/ 9.81 /
*
*
*
DO 101 N=1,IWIDTH
  NX=N+1
  DO 101 I=1,LENP1
    IX=I+1
    IF(IGRID(I,NX).EQ.1) GOTO 101
    IF(IGRID(IX,NX).EQ.1) GOTO 101
    IF(IGRID(I,NX).EQ.2.AND.IGRID(IX,NX).EQ.2) GOTO 101
*
*****.....TERMS INVOLVING VERTICAL VISCOSITY
*
IF(IGRID(I,NX).EQ.0.AND.IGRID(IX,NX).EQ.0) THEN
  AVGNX=0.5*(NETA(I,NX)+NETA(IX,NX))
  AVGEX=0.5*(ETA(I,NX)+ETA(IX,NX))
  AVGHX=0.5*(H(I,NX)+H(IX,NX))
  ETAX=(NETA(IX,NX)-NETA(I,NX))/DELX
ELSE IF(IGRID(I,NX).EQ.0) THEN
  AVGNX=NETA(I,NX)
  AVGEX=ETA(I,NX)
  AVGHX=H(I,NX)
  ETAX=(NETA(I,NX)-NETA(I-1,NX))/DELX
ELSE
  AVGNX=NETA(IX,NX)

```

TAK10580
TAK10590
TAK10600
TAK10610
TAK10620
TAK10630
TAK10640
TAK10650
TAK10660
TAK10670
TAK10680
TAK10690
TAK10700
TAK10710
TAK10720
TAK10730
TAK10740
TAK10750
TAK10760
TAK10770
TAK10780
TAK10790
TAK10800
TAK10810
TAK10820
TAK10830
TAK10840
TAK10850
TAK10860
TAK10870
TAK10880
TAK10890
TAK10900
TAK10910
TAK10920
TAK10930
TAK10940
TAK10950
TAK10960
TAK10970
TAK10980
TAK10990
TAK11000
TAK11010
TAK11020
TAK11030
TAK11040
TAK11050
TAK11060
TAK11070
TAK11080
TAK11090
TAK11100
TAK11110
TAK11120
TAK11130
TAK11140
TAK11150

```

      AVGEX= ETA (IX,NX)
      AVGHX= H (IX,NX)
      ETAX = (NETA (IX+1, NX) -NETA (IX, NX)) /DELX
      ENDIF
      AVGD =AVGNX-AVGHX
      ETAT = (AVGNX-AVGEX) /DELT
*
*****.....TERMS INVOLVING HORIZONTAL VISCOSITY
*
      IF (HVIS) THEN
      IF (IGRID (I, NX) .EQ. 0 .AND. IGRID (IX, NX) .EQ. 0) THEN
        DELEX= (NETA (IX, NX) -NETA (I, NX)) /DELX
        DELHX= (H (IX, NX) -H (I, NX)) /DELX
      ELSE IF (IGRID (I, NX) .EQ. 0) THEN
        DELEX= (NETA (I, NX) -NETA (I-1, NX)) /DELX
        DELHX= (H (I, NX) -H (I-1, NX)) /DELX
      ELSE
        DELEX= (NETA (IX+1, NX) -NETA (IX, NX)) /DELX
        DELHX= (H (IX+1, NX) -H (IX, NX)) /DELX
      ENDIF
      DELDX=DELEX-DELHX
*
      IF (IGRID (I, N) .EQ. 0 .AND. IGRID (I, NX+1) .EQ. 0) THEN
        DELE1= (NETA (I, NX+1) -NETA (I, N)) / (2.0*DELY)
        DELH1= (H (I, NX+1) -H (I, N)) / (2.0*DELY)
      ELSE IF (IGRID (I, NX+1) .EQ. 0) THEN
        DELE1= (NETA (I, NX+1) -NETA (I, NX)) /DELY
        DELH1= (H (I, NX+1) -H (I, NX)) /DELY
      ELSE IF (IGRID (I, NX) .EQ. 0) THEN
        DELE1= (NETA (I, NX) -NETA (I, N)) /DELY
        DELH1= (H (I, NX) -H (I, N)) /DELY
      ELSE
        DELE1=0.0
        DELH1=0.0
      ENDIF
*
      IF (IGRID (IX, NX+1) .EQ. 0 .AND. IGRID (IX, N) .EQ. 0) THEN
        DELE2= (NETA (IX, NX+1) -NETA (IX, N)) / (2.0*DELY)
        DELH2= (H (IX, NX+1) -H (IX, N)) / (2.0*DELY)
      ELSE IF (IGRID (IX, NX+1) .EQ. 0) THEN
        DELE2= (NETA (IX, NX+1) -NETA (IX, NX)) /DELY
        DELH2= (H (IX, NX+1) -H (IX, NX)) /DELY
      ELSE IF (IGRID (IX, N) .EQ. 0) THEN
        DELE2= (NETA (IX, NX) -NETA (IX, N)) /DELY
        DELH2= (H (IX, NX) -H (IX, N)) /DELY
      ELSE
        DELE2=0.0
        DELH2=0.0
      ENDIF
      DELEY=0.5*(DELE1+DELE2)
      DELHY=0.5*(DELH1+DELH2)
      DELDY=DELEY-DELHY
*
      IG1=IGRID (I, NX+1)
      IG2=IGRID (IX, NX+1)
      IG3=IGRID (I, N)
      IG4=IGRID (IX, N)
      ENDIF
*
*****.....TERMS INVOLVING VERTICAL VISCOSITY
*

```

TAK11160
 TAK11170
 TAK11180
 TAK11190
 TAK11200
 TAK11210
 TAK11220
 TAK11230
 TAK11240
 TAK11250
 TAK11260
 TAK11270
 TAK11280
 TAK11290
 TAK11300
 TAK11310
 TAK11320
 TAK11330
 TAK11340
 TAK11350
 TAK11360
 TAK11370
 TAK11380
 TAK11390
 TAK11400
 TAK11410
 TAK11420
 TAK11430
 TAK11440
 TAK11450
 TAK11460
 TAK11470
 TAK11480
 TAK11490
 TAK11500
 TAK11510
 TAK11520
 TAK11530
 TAK11540
 TAK11550
 TAK11560
 TAK11570
 TAK11580
 TAK11590
 TAK11600
 TAK11610
 TAK11620
 TAK11630
 TAK11640
 TAK11650
 TAK11660
 TAK11670
 TAK11680
 TAK11690
 TAK11700
 TAK11710
 TAK11720
 TAK11730
 TAK11740
 TAK11750
 TAK11760

```

DO 102 K=1,JP
  AA(K)=0.0
  AI1(K)=0.0
  AI3(K)=0.0
  IF(IGRID(I,NX).EQ.0.AND.IGRID(IX,NX).EQ.0) THEN
    AA(K)=0.5*(A(K,I,NX)+A(K,IX,NX))
    AI1(K)=0.5*(INTG1(K,I,NX)+INTG1(K,IX,NX))
    AI3(K)=0.5*(INTG3(K,I,NX)+INTG3(K,IX,NX))
  ELSE IF(IGRID(I,NX).EQ.0) THEN
    AA(K)=A(K,I,NX)
    AI1(K)=INTG1(K,I,NX)
    AI3(K)=INTG3(K,I,NX)
  ELSE
    AA(K)=A(K,IX,NX)
    AI1(K)=INTG1(K,IX,NX)
    AI3(K)=INTG3(K,IX,NX)
  ENDIF
  *
  AI2L(K)=0.0
  AI2R(K)=0.0
  DO 103 L=1,JP
    IF(IGRID(I,NX).EQ.0.AND.IGRID(IX,NX).EQ.0) THEN
      AI2=0.5*(INTG2(L,K,I,NX)+INTG2(L,K,IX,NX))
    ELSE IF(IGRID(I,NX).EQ.0) THEN
      AI2=INTG2(L,K,I,NX)
    ELSE
      AI2=INTG2(L,K,IX,NX)
    ENDIF
    IF(K.NE.L) THEN
      AI2R(K)=AI2R(K)+C(L,I,N)*AI2
    ELSE
      AI2L(K)=AI2
    ENDIF
  103 CONTINUE
  *
  C11=AI1(K)/DELT
  C12=-ETAT*AI2L(K)/AVGD
  C13=AA(K)**2*NV*AI1(K)/AVGD**2
  *
  C21=-AI1(K)*C(K,I,N)/DELT
  C22=-ETAT*AI2R(K)/AVGD
  C23=G*ETAX*AI3(K)
  *
  *****.....TREMS INVLOVING HORIZONTAL VISCOSITY
  *
  IF(HVISC) THEN
  *
    AI5L(K)=0.0
    AI5R(K)=0.0
    AI6L(K)=0.0
    AI6R(K)=0.0
    AI7L(K)=0.0
    AI7R(K)=0.0
    DO 105 L=1,JP
      IF(IGRID(IX,NX).EQ.0.AND.IGRID(I,NX).EQ.0) THEN
        AI5=0.5*(INTG5(L,K,I,NX)+INTG5(L,K,IX,NX))
        AI6=0.5*(INTG6(L,K,I,NX)+INTG6(L,K,IX,NX))
        AI7=0.5*(INTG7(L,K,I,NX)+INTG7(L,K,IX,NX))
      ELSE IF(IGRID(IX,NX).EQ.0) THEN
        AI5=INTG5(L,K,IX,NX)
        AI6=INTG6(L,K,IX,NX)

```

```

TAK11770
TAK11780
TAK11790
TAK11800
TAK11810
TAK11820
TAK11830
TAK11840
TAK11850
TAK11860
TAK11870
TAK11880
TAK11890
TAK11900
TAK11910
TAK11920
TAK11930
TAK11940
TAK11950
TAK11960
TAK11970
TAK11980
TAK11990
TAK12000
TAK12010
TAK12020
TAK12030
TAK12040
TAK12050
TAK12060
TAK12070
TAK12080
TAK12090
TAK12100
TAK12110
TAK12120
TAK12130
TAK12140
TAK12150
TAK12160
TAK12170
TAK12180
TAK12190
TAK12200
TAK12210
TAK12220
TAK12230
TAK12240
TAK12250
TAK12260
TAK12270
TAK12280
TAK12290
TAK12300
TAK12310
TAK12320
TAK12330
TAK12340
TAK12350
TAK12360
TAK12370

```



```

        AI7= INTG7(L,K,IX,NX)
    ELSE
        AI5= INTG5(L,K,I,NX)
        AI6= INTG6(L,K,I,NX)
        AI7= INTG7(L,K,I,NX)
    ENDIF
    IF(K.NE.L) THEN
        AI5R(K)=AI5R(K)+C(L,I,N)*AI5
        AI6R(K)=AI6R(K)+C(L,I,N)*AI6
        AI7R(K)=AI7R(K)+C(L,I,N)*AI7
    ELSE
        AI5L(K)=AI5
        AI6L(K)=AI6
        AI7L(K)=AI7
    ENDIF
105 CONTINUE
*
    IF(IGRID(I,NX).EQ.0.AND.IGRID(IX,NX).EQ.0) THEN
        CDX2=(C(K,I+1,N)-2.0*C(K,I,N)+C(K,I-1,N))/DELX**2
    ELSE IF(IGRID(I,NX).EQ.0) THEN
        CDX2=(C(K,I-1,N)-C(K,I,N))/DELX**2
    ELSE
        CDX2=(C(K,I+1,N)-C(K,I,N))/DELX**2
    ENDIF
*
    IF(IG1.EQ.0.AND.IG2.EQ.0.AND.
6      IG3.EQ.0.AND.IG4.EQ.0) THEN
        CDY2=(C(K,I,N+1)-2.0*C(K,I,N)+C(K,I,N-1))/DELY**2
    ELSE IF(IG1.EQ.0.AND.IG2.EQ.0) THEN
        CDY2=(C(K,I,N+1)-C(K,I,N))/DELY**2
    ELSE IF(IG3.EQ.0.AND.IG4.EQ.0) THEN
        CDY2=(C(K,I,N-1)-C(K,I,N))/DELY**2
    ELSE
        CDY2=0.0
    ENDIF
*
    C14=-NH*AI7L(K)
    C15= NH*DELDX*AI5L(K)/AVGD
    C16= NH*DELDY*AI6L(K)/AVGD
*
    C24=-NH*AI7R(K)
    C25= NH*DELDX*AI5R(K)/AVGD
    C26= NH*DELDY*AI6R(K)/AVGD
    C27=-NH*(CDX2+CDY2)*AI1(K)
*
    C28=0.0
    DO 112 L=1,JP
        CDX1=(C(L,I+1,N)-C(L,I-1,N))/(2.0*DELX)
        IF(IG1.EQ.0.AND.IG2.EQ.0.AND.
6          IG3.EQ.0.AND.IG4.EQ.0) THEN
            CDY1=(C(L,I,N+1)-C(L,I,N-1))/(2.0*DELY)
        ELSE IF(IG1.EQ.0.AND.IG2.EQ.0) THEN
            CDY1=(C(L,I,N+1)-C(L,I,N))/DELY
        ELSE IF(IG3.EQ.0.AND.IG4.EQ.0) THEN
            CDY1=(C(L,I,N)-C(L,I,N-1))/DELY
        ENDIF
        AI5=0.5*(INTG5(L,K,I,NX)+INTG5(L,K,IX,NX))
        IF(IGRID(I,NX).EQ.0.AND.IGRID(IX,NX).EQ.0) THEN
            AI6=0.5*(INTG5(L,K,I,NX)+INTG5(L,K,IX,NX))
        ELSE IF(IGRID(I,NX).EQ.0) THEN
            AI5= INTG5(L,K,I,NX)

```

TAK12380
 TAK12390
 TAK12400
 TAK12410
 TAK12420
 TAK12430
 TAK12440
 TAK12450
 TAK12460
 TAK12470
 TAK12480
 TAK12490
 TAK12500
 TAK12510
 TAK12520
 TAK12530
 TAK12540
 TAK12550
 TAK12560
 TAK12570
 TAK12580
 TAK12590
 TAK12600
 TAK12610
 TAK12620
 TAK12630
 TAK12640
 TAK12650
 TAK12660
 TAK12670
 TAK12680
 TAK12690
 TAK12700
 TAK12710
 TAK12720
 TAK12730
 TAK12740
 TAK12750
 TAK12760
 TAK12770
 TAK12780
 TAK12790
 TAK12800
 TAK12810
 TAK12820
 TAK12830
 TAK12840
 TAK12850
 TAK12860
 TAK12870
 TAK12880
 TAK12890
 TAK12900
 TAK12910
 TAK12920
 TAK12930
 TAK12940
 TAK12950
 TAK12960
 TAK12970
 TAK12980

```

ELSE
    AI5= INTG5(L,K,I,NX)
ENDIF
C28A=(NH*CDX1)*AI5
C28B=(NH*CDY1)*AI6
C28=C28-2.0*(C28A+C28B)
112 CONTINUE
ELSE
    C14=0.0
    C15=0.0
    C16=0.0
    C24=0.0
    C25=0.0
    C26=0.0
    C27=0.0
    C28=0.0
ENDIF
*
CC1=C11+C12+C13+C14+C15+C16
CC2=C21+C22+C23+C24+C25+C26+C27+C28
IF(ABS(CC2).LT.1.0E-25) CC2=0.0
NC(K,I,N)=-CC2/CC1
102 CONTINUE
101 RETURN
END
TAK12990
TAK13000
TAK13010
TAK13020
TAK13030
TAK13040
TAK13050
TAK13060
TAK13070
TAK13080
TAK13090
TAK13100
TAK13110
TAK13120
TAK13130
TAK13140
TAK13150
TAK13160
TAK13170
TAK13180
TAK13190
TAK13200
TAK13210
TAK13220
TAK13230
TAK13240

```

```

SUBROUTINE YMOM
*****
*
*          SOLVES THE Y-MOMENTUM EQUATION
*
*****
PARAMETER (JP=1, KP=21, LENGTH=54, IWIDTH=33)
PARAMETER (LENP1=LENGTH+1, IWIDP1=IWIDTH+1, LPLS=LENGTH+2,
&          IWPLS=IWIDTH+2)
REAL      NV, NH, NC, ND, NETA
REAL      INTG1, INTG2, INTG3, INTG4, INTG5, INTG6, INTG7
LOGICAL   FTTOM, HOTST, HVISC, VFRICT, MOVE

DIMENSION AA(JP), AI1(JP), AI2R(JP), AI2L(JP), AI3(JP), AI5R(JP),
&          AI5L(JP), AI6L(JP), AI6R(JP), AI7R(JP), AI7L(JP)
COMMON/ BLK1/ H(LPLS, IWPLS), FRICT(LPLS, IWPLS), NV, NH, RHO
COMMON/ BLK2/ DELT, DELX, DELY, UPAI, START, PHOTST, POUTPT,
&          ISTRT, NFIN, NHOTST
COMMON/ BLK3/ FTTOM, HOTST, HVISC, VFRICT, MOVE
COMMON/ BLK4/ C(JP, LENP1, IWIDP1), NC(JP, LENP1, IWIDP1),
&          D(JP, LENGTH, IWIDP1), ND(JP, LENGTH, IWIDP1)
COMMON/ BLK5/ ETA(LPLS, IWPLS), NETA(LPLS, IWPLS), SOS(LPLS, IWPLS)
COMMON/ BLK6/ A(JP, LPLS, IWPLS), CONTI(JP, LPLS, IWPLS)
COMMON/ BLK7/ INTG1(JP, LPLS, IWPLS), INTG2(JP, JP, LPLS, IWPLS),
&          INTG3(JP, LPLS, IWPLS), INTG4(JP, JP, LPLS, IWPLS),
&          INTG5(JP, JP, LPLS, IWPLS), INTG6(JP, JP, LPLS, IWPLS),
&          INTG7(JP, JP, LPLS, IWPLS)
COMMON/ BLK8/ IGRID(LPLS, IWPLS), XI(4), W(4)
DATA      G/ 9.81/

DO 101 N=1, IWIDP1
  NY=N+1
  DO 101 I=1, LENGTH
    IY=I+1

    IF (IGRID(IY, N) .EQ. 1) GOTO 101
    IF (IGRID(IY, NY) .EQ. 1) GOTO 101
    IF (IGRID(IY, N) .EQ. 2 .AND. IGRID(IY, NY) .EQ. 2) GOTO 101

*****.....TERMS INVOLVING VERTICAL VISCOSITY
*
    IF (IGRID(IY, N) .EQ. 0 .AND. IGRID(IY, NY) .EQ. 0) THEN
      AVGNV=0.5*(NETA(IY, NY)+NETA(IY, N))
      AVGEY=0.5*(ETA(IY, NY)+ETA(IY, N))
      AVGHY=0.5*(H(IY, NY)+H(IY, N))
      ETAY=(NETA(IY, NY)-NETA(IY, N))/DELY
    ELSE IF (IGRID(IY, N) .EQ. 0) THEN
      AVGNV= NETA(IY, N)
      AVGEY= ETA(IY, N)
      AVGHY= H(IY, N)
      ETAY=(NETA(IY, N)-NETA(IY, N-1))/DELY
    ELSE
      AVGNV= NETA(IY, NY)
      AVGEY= ETA(IY, NY)

```

TAK13250
TAK13260
TAK13270
TAK13280
TAK13290
TAK13300
TAK13310
TAK13320
TAK13330
TAK13340
TAK13350
TAK13360
TAK13370
TAK13380
TAK13390
TAK13400
TAK13410
TAK13420
TAK13430
TAK13440
TAK13450
TAK13460
TAK13470
TAK13480
TAK13490
TAK13500
TAK13510
TAK13520
TAK13530
TAK13540
TAK13550
TAK13560
TAK13570
TAK13580
TAK13590
TAK13600
TAK13610
TAK13620
TAK13630
TAK13640
TAK13650
TAK13660
TAK13670
TAK13680
TAK13690
TAK13700
TAK13710
TAK13720
TAK13730
TAK13740
TAK13750
TAK13760
TAK13770
TAK13780
TAK13790
TAK13800
TAK13810
TAK13820

```

      AVGHY= H(IY,NY)
      ETAY = (NETA(IY,NY+1)-NETA(IY,NY))/DELY
    ENDIF
    AVGD =AVGNY-AVGHY
    ETAT = (AVGNY-AVGEY)/DELT
*
*****.....TERMS INVLOVING HORIZONTAL VISCOSITY
*
    IF(HVISC) THEN
      IF (IGRID(I,NY).EQ.0.AND.IGRID(IY+1,NY).EQ.0) THEN
        DELE1=(NETA(IY+1,NY)-NETA(I,NY))/(2.0*DELX)
        DELH1=(H(IY+1,NY)-H(I,NY))/(2.0*DELX)
      ELSE IF (IGRID(I,NY).EQ.0) THEN
        DELE1=(NETA(IY,NY)-NETA(I,NY))/DELX
        DELH1=(H(IY,NY)-H(I,NY))/DELX
      ELSE IF (IGRID(IY+1,NY).EQ.0) THEN
        DELE1=(NETA(IY+1,NY)-NETA(IY,NY))/DELX
        DELH1=(H(IY+1,NY)-H(IY,NY))/DELX
      ELSE
        DELE1=0.0
        DELH1=0.0
      ENDIF
*
      IF (IGRID(I,N).EQ.0.AND.IGRID(IY+1,N).EQ.0) THEN
        DELE2=(NETA(IY+1,N)-NETA(I,N))/(2.0*DELX)
        DELH2=(H(IY+1,N)-H(I,N))/(2.0*DELX)
      ELSE IF (IGRID(I,N).EQ.0) THEN
        DELE2=(NETA(IY,N)-NETA(I,N))/DELX
        DELH2=(H(IY,N)-H(I,N))/DELX
      ELSE IF (IGRID(IY+1,N).EQ.0) THEN
        DELE2=(NETA(IY+1,N)-NETA(IY,N))/DELX
        DELH2=(H(IY+1,N)-H(IY,N))/DELX
      ELSE
        DELE2=0.0
        DELH2=0.0
      ENDIF
      DELEX=0.5*(DELE1+DELE2)
      DELHX=0.5*(DELH1+DELH2)
      DELDX=DELEX-DELHX
*
      IF (IGRID(IY,N).EQ.0.AND.IGRID(IY,NY).EQ.0) THEN
        DELEY=(NETA(IY,NY)-NETA(IY,N))/DELY
        DELHY=(H(IY,NY)-H(IY,N))/DELY
      ELSE IF (IGRID(IY,N).EQ.0) THEN
        DELEY=(NETA(IY,N)-NETA(IY,N-1))/DELY
        DELHY=(H(IY,N)-H(IY,N-1))/DELY
      ELSE
        DELEY=(NETA(IY,NY+1)-NETA(IY,NY))/DELY
        DELHY=(H(IY,NY+1)-H(IY,NY))/DELY
      ENDIF
      DELDY=DELEY-DELHY
*
      IG1=IGRID(I,N)
      IG2=IGRID(I,NY)
      IG3=IGRID(IY+1,N)
      IG4=IGRID(IY+1,NY)
*
    ENDIF
*
*****.....TERMS INVOLVING VERTICAL VISCOSITY
*

```

TAK13830
 TAK13840
 TAK13850
 TAK13860
 TAK13870
 TAK13880
 TAK13890
 TAK13900
 TAK13910
 TAK13920
 TAK13930
 TAK13940
 TAK13950
 TAK13960
 TAK13970
 TAK13980
 TAK13990
 TAK14000
 TAK14010
 TAK14020
 TAK14030
 TAK14040
 TAK14050
 TAK14060
 TAK14070
 TAK14080
 TAK14090
 TAK14100
 TAK14110
 TAK14120
 TAK14130
 TAK14140
 TAK14150
 TAK14160
 TAK14170
 TAK14180
 TAK14190
 TAK14200
 TAK14210
 TAK14220
 TAK14230
 TAK14240
 TAK14250
 TAK14260
 TAK14270
 TAK14280
 TAK14290
 TAK14300
 TAK14310
 TAK14320
 TAK14330
 TAK14340
 TAK14350
 TAK14360
 TAK14370
 TAK14380
 TAK14390
 TAK14400
 TAK14410
 TAK14420
 TAK14430

```

DO 102 K=1,JP
  AA(K)=0.0
  AI1(K)=0.0
  AI3(K)=0.0
  IF(IGRID(IY,N).EQ.0.AND.IGRID(IY,NY).EQ.0) THEN
    AA(K)=0.5*(A(K,IY,NY)+A(K,IY,N))
    AI1(K)=0.5*(INTG1(K,IY,NY)+INTG1(K,IY,N))
    AI3(K)=0.5*(INTG3(K,IY,NY)+INTG3(K,IY,N))
  ELSE IF(IGRID(IY,N).EQ.0) THEN
    AA(K)=A(K,IY,N)
    AI1(K)=INTG1(K,IY,N)
    AI3(K)=INTG3(K,IY,N)
  ELSE
    AA(K)=A(K,IY,NY)
    AI1(K)=INTG1(K,IY,NY)
    AI3(K)=INTG3(K,IY,NY)
  ENDIF
  AI2L(K)=0.0
  AI2R(K)=0.0
DO 103 L=1,JP
  IF(IGRID(IY,N).EQ.0.AND.IGRID(IY,NY).EQ.0) THEN
    AI2=0.5*(INTG2(L,K,IY,NY)+INTG2(L,K,IY,N))
  ELSE IF(IGRID(IY,N).EQ.0) THEN
    AI2=INTG2(L,K,IY,N)
  ELSE
    AI2=INTG2(L,K,IY,NY)
  ENDIF
  IF(K.NE.L) THEN
    AI2R(K)=AI2R(K)+D(L,I,N)*AI2
  ELSE
    AI2L(K)=AI2
  ENDIF
103 CONTINUE
  D11=AI1(K)/DELT
  D12=-ETAT*AI2L(K)/AVGD
  D13=AA(K)**2*NV*AI1(K)/AVGD**2
  D21=-AI1(K)*D(K,I,N)/DELT
  D22=-ETAT*AI2R(K)/AVGD
  D23=G*ETAY*AI3(K)
*****.....TREMS INVLOVING HORIZONTAL VISCOSITY
  IF(HVISC) THEN
    AI5L(K)=0.0
    AI5R(K)=0.0
    AI6L(K)=0.0
    AI6R(K)=0.0
    AI7L(K)=0.0
    AI7R(K)=0.0
DO 105 L=1,JP
  IF(IGRID(IY,N).EQ.0.AND.IGRID(IY,NY).EQ.0) THEN
    AI5=0.5*(INTG5(L,K,IY,NY)+INTG5(L,K,IY,N))
    AI6=0.5*(INTG6(L,K,IY,NY)+INTG6(L,K,IY,N))
    AI7=0.5*(INTG7(L,K,IY,NY)+INTG7(L,K,IY,N))
  ELSE IF(IGRID(IY,N).EQ.0.) THEN
    AI5=INTG5(L,K,IY,N)
    AI6=INTG6(L,K,IY,N)

```

```

TAK14440
TAK14450
TAK14460
TAK14470
TAK14480
TAK14490
TAK14500
TAK14510
TAK14520
TAK14530
TAK14540
TAK14550
TAK14560
TAK14570
TAK14580
TAK14590
TAK14600
TAK14610
TAK14620
TAK14630
TAK14640
TAK14650
TAK14660
TAK14670
TAK14680
TAK14690
TAK14700
TAK14710
TAK14720
TAK14730
TAK14740
TAK14750
TAK14760
TAK14770
TAK14780
TAK14790
TAK14800
TAK14810
TAK14820
TAK14830
TAK14840
TAK14850
TAK14860
TAK14870
TAK14880
TAK14890
TAK14900
TAK14910
TAK14920
TAK14930
TAK14940
TAK14950
TAK14960
TAK14970
TAK14980
TAK14990
TAK15000
TAK15010
TAK15020
TAK15030
TAK15040

```

```

        AI7= INTG7(L,K,IY,N)
ELSE
        AI5= INTG5(L,K,IY,NY)
        AI6= INTG6(L,K,IY,NY)
        AI7= INTG7(L,K,IY,NY)
ENDIF
IF(K.NE.L) THEN
        AISR(K)=AISR(K)+D(L,I,N)*AI5
        AI6R(K)=AI6R(K)+D(L,I,N)*AI6
        AI7R(K)=AI7R(K)+D(L,I,N)*AI7
ELSE
        AISL(K)=AI5
        AI6L(K)=AI6
        AI7L(K)=AI7
ENDIF
105 CONTINUE
*
        IF(IG1.EQ.0.AND.IG2.EQ.0.AND.IG3.EQ.0.AND.
        & IG4.EQ.0) THEN
                DDX2=(D(K,I+1,N)-2.0*D(K,I,N)+D(K,I-1,N))/DELX**2
ELSE IF(IG1.EQ.0.AND.IG2.EQ.0) THEN
                DDX2=(-D(K,I,N)+D(K,I-1,N))/DELX**2
ELSE IF(IG3.EQ.0.AND.IG4.EQ.0) THEN
                DDX2=(D(K,I+1,N)-D(K,I,N))/DELX**2
ELSE
                DDX2=0.0
ENDIF
*
        IF(IGRID(IY,NY).EQ.0.AND.IGRID(IY,N).EQ.0) THEN
                DDY2=(D(K,I,N+1)-2.0*D(K,I,N)+D(K,I,N-1))/DELY**2
ELSE IF(IGRID(IY,NY).EQ.0) THEN
                DDY2=(D(K,I,N+1)-D(K,I,N))/DELY**2
ELSE
                DDY2=(-D(K,I,N-1)+D(K,I,N))/DELY**2
ENDIF
*
        D14=-NH*AI7L(K)
        D15= NH*DELDX*AI5L(K)/AVGD
        D16= NH*DELDY*AI6L(K)/AVGD
*
        D24=-NH*AI7R(K)
        D25= NH*DELDX*AI5R(K)/AVGD
        D26= NH*DELDY*AI6R(K)/AVGD
        D27=-NH*(DDX2+DDY2)*AI1(K)
*
        D28=0.0
        DO 112 L=1,JP
                IF(IG1.EQ.0.AND.IG2.EQ.0.AND.
                & IG3.EQ.0.AND.IG4.EQ.0) THEN
                        DDX1=(D(L,I+1,N)-D(L,I-1,N))/(2.0*DELX)
ELSE IF(IG1.EQ.0.AND.IG2.EQ.0) THEN
                        DDX1=(D(L,I,N)-D(L,I-1,N))/DELX
ELSE IF(IG3.EQ.0.AND.IG4.EQ.0) THEN
                        DDX1=(D(L,I+1,N)-D(L,I,N))/DELX
ENDIF
                        DDY1=(D(L,I,N+1)-D(L,I,N-1))/(2.0*DELY)
                IF(IGRID(IY,NY).EQ.0.AND.IGRID(IY,N).EQ.0) THEN
                        AI5=0.5*(INTG5(L,K,IY,NY)+INTG5(L,K,IY,N))
                ELSE IF(IGRID(IY,NY).EQ.0) THEN
                        AI5= INTG5(L,K,IY,NY)
                ELSE

```

```

TAK15050
TAK15060
TAK15070
TAK15080
TAK15090
TAK15100
TAK15110
TAK15120
TAK15130
TAK15140
TAK15150
TAK15160
TAK15170
TAK15180
TAK15190
TAK15200
TAK15210
TAK15220
TAK15230
TAK15240
TAK15250
TAK15260
TAK15270
TAK15280
TAK15290
TAK15300
TAK15310
TAK15320
TAK15330
TAK15340
TAK15350
TAK15360
TAK15370
TAK15380
TAK15390
TAK15400
TAK15410
TAK15420
TAK15430
TAK15440
TAK15450
TAK15460
TAK15470
TAK15480
TAK15490
TAK15500
TAK15510
TAK15520
TAK15530
TAK15540
TAK15550
TAK15560
TAK15570
TAK15580
TAK15590
TAK15600
TAK15610
TAK15620
TAK15630
TAK15640
TAK15650

```

	AI5= INTG5 (L,K,IY,N)	TAK15660
	ENDIF	TAK15670
	AI6=0.5*(INTG6(L,K,IY,NY)+INTG6(L,K,IY,N))	TAK15680
	D28A=(NH*DDX1)*AI5	TAK15690
	D28B=(NH*DDY1)*AI6	TAK15700
	D28=D28-2.0*NH*(DDX1*AI5+DDY1*AI6)	TAK15710
112	CONTINUE	TAK15720
	ELSE	TAK15730
	D14=0.0	TAK15740
	D15=0.0	TAK15750
	D16=0.0	TAK15760
	D24=0.0	TAK15770
	D25=0.0	TAK15780
	D26=0.0	TAK15790
	D27=0.0	TAK15800
	D28=0.0	TAK15810
	ENDIF	TAK15820
*		TAK15830
	DD1=D11+D12+D13+D14+D15+D16	TAK15840
	DD2=D21+D22+D23+D24+D25+D26+D27+D28	TAK15850
	IF (ABS(DD2) .LT. 1.0E-25) DD2=0.0	TAK15860
	ND(K,I,N)=-DD2/DD1	TAK15870
102	CONTINUE	TAK15880
101	CONTINUE	TAK15890
	RETURN	TAK15900
	END	TAK15910

```

SUBROUTINE CONTIN (DTDX, DTDY, SSS)
*****
*
* SOLVES THE CONTINUITY EQUATION
*
*****
*
*
PARAMETER (JP=1, KP=21, LENGTH=54, IWIDTH=33)
PARAMETER (LENP1=LENGTH+1, IWIDP1=IWIDTH+1, LPLS=LENGTH+2,
& IWPLS=IWIDTH+2)
REAL NV, NH, NC, ND, NETA
REAL INTG1, INTG2, INTG3, INTG4, INTG5, INTG6, INTG7
LOGICAL FTTOM, HOTST, HVISC, VFRIC, MOVE
*
DIMENSION SSS (LPLS, IWPLS)
COMMON/ BLK1/ H (LPLS, IWPLS), FRIC (LPLS, IWPLS), NV, NH, RHO
COMMON/ BLK2/ DELT, DELX, DELY, UPAT, START, PHOTST, POUTPT,
& ISTRT, NFIN, NHOTST
COMMON/ BLK3/ FTTOM, HOTST, HVISC, VFRIC, MOVE
COMMON/ BLK4/ C (JP, LENP1, IWIDTH), NC (JP, LENP1, IWIDTH),
& D (JP, LENGTH, IWIDP1), ND (JP, LENGTH, IWIDP1)
COMMON/ BLK5/ ETA (LPLS, IWPLS), NETA (LPLS, IWPLS), SOS (LPLS, IWPLS)
COMMON/ BLK6/ A (JP, LPLS, IWPLS), CONTI (JP, LPLS, IWPLS)
COMMON/ BLK7/ INTG1 (JP, LPLS, IWPLS), INTG2 (JP, JP, LPLS, IWPLS),
& INTG3 (JP, LPLS, IWPLS), INTG4 (JP, JP, LPLS, IWPLS),
& INTG5 (JP, JP, LPLS, IWPLS), INTG6 (JP, JP, LPLS, IWPLS),
& INTG7 (JP, JP, LPLS, IWPLS)
COMMON/ BLK8/ IGRID (LPLS, IWPLS), XI (4), W (4)
DATA ITERS /1 /
*
*
*
DO 101 ITER=1, ITERS
DO 102 N=2, IWPLS-1
DO 102 I=2, LPLS-1
IF (IGRID (I, N) .EQ. 0) THEN
Z1=0.0
Z2=0.0
Z3=0.0
Z4=0.0
SS=SSS (I, N)
*
*****.....COMPUTATIONS IN X-DIRECTION
*
DO 103 K=1, JP
IF (IGRID (I+1, N) .EQ. 0) THEN
SQ1=(CONTI (K, I, N)+CONTI (K, I+1, N))*0.5
ELSE IF (IGRID (I+1, N) .EQ. 2) THEN
SQ1=CONTI (K, I, N)
ELSE
SQ1=0.
ENDIF
IF (IGRID (I-1, N) .EQ. 0) THEN
SQ2=(CONTI (K, I, N)+CONTI (K, I-1, N))*0.5
ELSE IF (IGRID (I-1, N) .EQ. 2) THEN
SQ2=CONTI (K, I, N)
ELSE

```

TAK15920
TAK15930
TAK15940
TAK15950
TAK15960
TAK15970
TAK15980
TAK15990
TAK16000
TAK16010
TAK16020
TAK16030
TAK16040
TAK16050
TAK16060
TAK16070
TAK16080
TAK16090
TAK16100
TAK16110
TAK16120
TAK16130
TAK16140
TAK16150
TAK16160
TAK16170
TAK16180
TAK16190
TAK16200
TAK16210
TAK16220
TAK16230
TAK16240
TAK16250
TAK16260
TAK16270
TAK16280
TAK16290
TAK16300
TAK16310
TAK16320
TAK16330
TAK16340
TAK16350
TAK16360
TAK16370
TAK16380
TAK16390
TAK16400
TAK16410
TAK16420
TAK16430
TAK16440
TAK16450
TAK16460
TAK16470
TAK16480
TAK16490
TAK16500


```

                SQ2=0.                                TAK16510
            ENDIF                                    TAK16520
*                                                    TAK16530
*****.....COMPUTATIONS IN Y-DIRECTION            TAK16540
*                                                    TAK16550
            IF (IGRID(I,N+1).EQ.0) THEN            TAK16560
                SQ3=(CONTI(K,I,N)+CONTI(K,I,N+1))*0.5 TAK16570
            ELSE IF (IGRID(I,N+1).EQ.2) THEN        TAK16580
                SQ3=CONTI(K,I,N)                    TAK16590
            ELSE                                      TAK16600
                SQ3=0.                                TAK16610
            ENDIF                                    TAK16620
*                                                    TAK16630
            IF (IGRID(I,N-1).EQ.0) THEN            TAK16640
                SQ4=(CONTI(K,I,N)+CONTI(K,I,N-1))*0.5 TAK16650
            ELSE IF (IGRID(I,N-1).EQ.2) THEN        TAK16660
                SQ4=CONTI(K,I,N)                    TAK16670
            ELSE                                      TAK16680
                SQ4=0.                                TAK16690
            ENDIF                                    TAK16700
*                                                    TAK16710
            Z1=Z1+C(K,I,N-1)*SQ1                    TAK16720
            Z2=Z2+C(K,I-1,N-1)*SQ2                  TAK16730
            Z3=Z3+D(K,I-1,N)*SQ3                    TAK16740
            Z4=Z4+D(K,I-1,N-1)*SQ4                  TAK16750
*                                                    TAK16760
            103 CONTINUE                             TAK16770
*                                                    TAK16780
            IF (IGRID(I+1,N).EQ.0) THEN            TAK16790
                DA=0.5*(NETA(I,N)+ETA(I,N))          TAK16800
                DB=0.5*(NETA(I+1,N)+ETA(I+1,N))      TAK16810
                D1=0.5*(DA-H(I,N)+DB-H(I+1,N))       TAK16820
            ELSE                                      TAK16830
                DA=0.5*(NETA(I,N)+ETA(I,N))          TAK16840
                D1= DA-H(I,N)                          TAK16850
            ENDIF                                    TAK16860
*                                                    TAK16870
            IF (IGRID(I-1,N).EQ.0) THEN            TAK16880
                DA=0.5*(NETA(I,N)+ETA(I,N))          TAK16890
                DB=0.5*(NETA(I-1,N)+ETA(I-1,N))      TAK16900
                D2=0.5*(DA-H(I,N)+DB-H(I-1,N))       TAK16910
            ELSE                                      TAK16920
                DA=0.5*(NETA(I,N)+ETA(I,N))          TAK16930
                D2=DA-H(I,N)                          TAK16940
            ENDIF                                    TAK16950
*                                                    TAK16960
            IF (IGRID(I,N+1).EQ.0) THEN            TAK16970
                DA=0.5*(NETA(I,N)+ETA(I,N))          TAK16980
                DB=0.5*(NETA(I,N+1)+ETA(I,N+1))      TAK16990
                D3=0.5*(DA-H(I,N)+DB-H(I,N+1))       TAK17000
            ELSE                                      TAK17010
                DA=0.5*(NETA(I,N)+ETA(I,N))          TAK17020
                D3=DA-H(I,N)                          TAK17030
            ENDIF                                    TAK17040
*                                                    TAK17050
            IF (IGRID(I,N-1).EQ.0) THEN            TAK17060
                DA=0.5*(NETA(I,N)+ETA(I,N))          TAK17070
                DB=0.5*(NETA(I,N-1)+ETA(I,N-1))      TAK17080
                D4=0.5*(DA-H(I,N)+DB-H(I,N-1))       TAK17090
            ELSE                                      TAK17100
                DA=0.5*(NETA(I,N)+ETA(I,N))          TAK17110

```

```

                                D4=DA-H(I,N)
                                ENDIF
*
                                Z1=Z1*D1
                                Z2=Z2*D2
                                Z3=Z3*D3
                                Z4=Z4*D4
                                NETA(I,N)=ETA(I,N)-DTDY*(Z1-Z2)-DTDY*(Z3-Z4)+SS
                                ENDIF
102                                CONTINUE
101                                RETURN
                                END
                                TAK17120
                                TAK17130
                                TAK17140
                                TAK17150
                                TAK17160
                                TAK17170
                                TAK17180
                                TAK17190
                                TAK17200
                                TAK17210
                                TAK17220
                                TAK17230
                                TAK17240
```

```

          SUBROUTINE MOVEIN(JJ,SSS,DXDY)
*****
*
*   SUBROUTINE DETERMINES THE ADVANCE/RETREAT OF GLACIER
*
*****
*
*   PARAMETER (JP=1, KP=21, LENGTH=54, IWIDTH=33)
*   PARAMETER (LENP1=LENGTH+1, IWIDP1=IWIDTH+1, LPLS=LENGTH+2,
&             IWPLS=IWIDTH+2)
*   REAL  NV, NH, NC, ND, NETA
*   REAL  INTG1, INTG2, INTG3, INTG4, INTG5, INTG6, INTG7
*   LOGICAL  FTTOM, HOTST, HVISC, VFRICT, MOVE
*
*   DIMENSION SSS(LPLS, IWPLS)
*   COMMON/ BLK1/ H(LPLS, IWPLS), FRICT(LPLS, IWPLS), NV, NH, RHO
*   COMMON/ BLK2/ DELT, DELX, DELY, UPAL, START, PHOTST, POUTPT,
&             ISTRT, NFIN, NHOTST
*   COMMON/ BLK3/ FTTOM, HOTST, HVISC, VFRICT, MOVE
*   COMMON/ BLK4/ C(JP, LENP1, IWIDTH), NC(JP, LENP1, IWIDTH),
&             D(JP, LENGTH, IWIDP1), ND(JP, LENGTH, IWIDP1)
*   COMMON/ BLK5/ ETA(LPLS, IWPLS), NETA(LPLS, IWPLS), SOS(LPLS, IWPLS)
*   COMMON/ BLK6/ A(JP, LPLS, IWPLS), CONTI(JP, LPLS, IWPLS)
*   COMMON/ BLK7/ INTG1(JP, LPLS, IWPLS), INTG2(JP, JP, LPLS, IWPLS),
&             INTG3(JP, LPLS, IWPLS), INTG4(JP, JP, LPLS, IWPLS),
&             INTG5(JP, JP, LPLS, IWPLS), INTG6(JP, JP, LPLS, IWPLS),
&             INTG7(JP, JP, LPLS, IWPLS)
*   COMMON/ BLK8/ IGRID(LPLS, IWPLS), XI(4), W(4)
*   COMMON/ BLK10/ QIF(LPLS, IWPLS), QIB(LPLS, IWPLS),
&             QJF(LPLS, IWPLS), QJB(LPLS, IWPLS)
*
*
*
*****.....ADVANCE OR RETREAT IN X-DIRECTION
*
*
*   DO 101 J=2, IWPLS-1
*     DO 101 I=2, LPLS-1
*
*       IF (IGRID(I, J).EQ.2) THEN
*
*         IF (IGRID(I+1, J).EQ.0) THEN
*
*           UU=0.0
*           DO 102 K=1, JP
*             UU=UU+CONTI(K, I+1, J)*NC(K, I, J-1)
102          CONTINUE
*           DEP=NETA(I+1, J)-H(I+1, J)
*           FLOW= UU*DEP*DELY*DELT
*           QIF(I, J)=QIF(I, J)+FLOW
*           VOL=0.5*DEP*DELX*DELY
*           IF(UU.LE.0.0) THEN
*             SSS(I+1, J)=SOS(I+1, J)+ABS(FLOW)/DXDY
*           ELSE
*             SSS(I+1, J)=SOS(I+1, J)-ABS(FLOW)/DXDY
*           ENDIF
*           IF( ABS(QIF(I, J)).GT.VOL) THEN
*             SSS(I+1, J)=SOS(I+1, J)
*             IF(QIF(I, J).GT.0.0) THEN
*               IGRID(I+1, J)=2

```

TAK17250
TAK17260
TAK17270
TAK17280
TAK17290
TAK17300
TAK17310
TAK17320
TAK17330
TAK17340
TAK17350
TAK17360
TAK17370
TAK17380
TAK17390
TAK17400
TAK17410
TAK17420
TAK17430
TAK17440
TAK17450
TAK17460
TAK17470
TAK17480
TAK17490
TAK17500
TAK17510
TAK17520
TAK17530
TAK17540
TAK17550
TAK17560
TAK17570
TAK17580
TAK17590
TAK17600
TAK17610
TAK17620
TAK17630
TAK17640
TAK17650
TAK17660
TAK17670
TAK17680
TAK17690
TAK17700
TAK17710
TAK17720
TAK17730
TAK17740
TAK17750
TAK17760
TAK17770
TAK17780
TAK17790
TAK17800
TAK17810
TAK17820
TAK17830
TAK17840
TAK17850

```

ETA(I+1, J)=H(I+1, J)
NETA(I+1, J)=H(I+1, J)
DO 103 K=1, JP
  A(K, I+1, J)=0.0
  CONTI(K, I+1, J)=0.0
  INTG1(K, I+1, J)=0.0
  INTG3(K, I+1, J)=0.0
  DO 103 L=1, JP
    INTG2(L, K, I+1, J)=0.0
    INTG4(L, K, I+1, J)=0.0
    INTG5(L, K, I+1, J)=0.0
    INTG6(L, K, I+1, J)=0.0
    INTG7(L, K, I+1, J)=0.0
  CONTINUE
ELSE
  IGRID(I, J)=0
  ETA(I, J)=H(I, J)+10.00
  NETA(I, J)=H(I, J)+10.0
  DO 104 K=1, JP
    A(K, I, J)=A(K, I+1, J)
    CONTI(K, I, J)=CONTI(K, I+1, J)
    INTG1(K, I, J)=INTG1(K, I+1, J)
    INTG3(K, I, J)=INTG3(K, I+1, J)
    DO 104 L=1, JP
      INTG2(L, K, I, J)=INTG2(L, K, I+1, J)
      INTG4(L, K, I, J)=INTG4(L, K, I+1, J)
      INTG5(L, K, I, J)=INTG5(L, K, I+1, J)
      INTG6(L, K, I, J)=INTG6(L, K, I+1, J)
      INTG7(L, K, I, J)=INTG7(L, K, I+1, J)
    CONTINUE
  ENDDIF
  QIF(I, J)=0.0
ENDDIF
*
*
ELSE IF(IGRID(I-1, J).EQ.0) THEN
  UU=0.0
  DO 105 K=1, JP
    UU=UU+CONTI(K, I-1, J)*NC(K, I-1, J-1)
  CONTINUE
  DEP=NETA(I-1, J)-H(I-1, J)
  FLOW = UU*DEP*DELY*DELT
  QIB(I, J)=QIB(I, J)+FLOW
  VOL=0.5*DEP*DELX*DELY
  IF(UU.GE.0.0) THEN
    SSS(I-1, J)=SOS(I-1, J)+ABS(FLOW)/DXDY
  ELSE
    SSS(I-1, J)=SOS(I-1, J)-ABS(FLOW)/DXDY
  ENDDIF
  IF(ABS(QIB(I, J)).GT.VOL) THEN
    SSS(I-1, J)=SOS(I-1, J)
    IF(QIB(I, J).GT.0.0) THEN
      IGRID(I, J)=0
      ETA(I, J)=H(I, J)+10.0
      NETA(I, J)=H(I, J)+10.0
      DO 106 K=1, JP
        A(K, I, J)=A(K, I-1, J)
        CONTI(K, I, J)=CONTI(K, I-1, J)
        INTG1(K, I, J)=INTG1(K, I-1, J)
        INTG3(K, I, J)=INTG3(K, I-1, J)
        DO 106 L=1, JP

```

```

TAK17860
TAK17870
TAK17880
TAK17890
TAK17900
TAK17910
TAK17920
TAK17930
TAK17940
TAK17950
TAK17960
TAK17970
TAK17980
TAK17990
TAK18000
TAK18010
TAK18020
TAK18030
TAK18040
TAK18050
TAK18060
TAK18070
TAK18080
TAK18090
TAK18100
TAK18110
TAK18120
TAK18130
TAK18140
TAK18150
TAK18160
TAK18170
TAK18180
TAK18190
TAK18200
TAK18210
TAK18220
TAK18230
TAK18240
TAK18250
TAK18260
TAK18270
TAK18280
TAK18290
TAK18300
TAK18310
TAK18320
TAK18330
TAK18340
TAK18350
TAK18360
TAK18370
TAK18380
TAK18390
TAK18400
TAK18410
TAK18420
TAK18430
TAK18440
TAK18450
TAK18460

```

```

                                INTG2(L,K,I,J)=INTG2(L,K,I-1,J)  TAK18470
                                INTG4(L,K,I,J)=INTG4(L,K,I-1,J)  TAK18480
                                INTG5(L,K,I,J)=INTG5(L,K,I-1,J)  TAK18490
                                INTG6(L,K,I,J)=INTG6(L,K,I-1,J)  TAK18500
                                INTG7(L,K,I,J)=INTG7(L,K,I-1,J)  TAK18510
106      CONTINUE                                                    TAK18520
      ELSE                                                            TAK18530
        IGRID(I-1,J)=2                                              TAK18540
        ETA(I-1,J)=H(I-1,J)                                        TAK18550
        NETA(I-1,J)=H(I-1,J)                                       TAK18560
        DO 107 K=1,JP                                              TAK18570
          A(K,I-1,J)=0.0                                           TAK18580
          CONTI(K,I-1,J)=0.0                                       TAK18590
          INTG1(K,I-1,J)=0.0                                       TAK18600
          INTG3(K,I-1,J)=0.0                                       TAK18610
          DO 107 L=1,JP                                           TAK18620
            INTG2(L,K,I-1,J)=0.0                                     TAK18630
            INTG4(L,K,I-1,J)=0.0                                     TAK18640
            INTG5(L,K,I-1,J)=0.0                                     TAK18650
            INTG6(L,K,I-1,J)=0.0                                     TAK18660
            INTG7(L,K,I-1,J)=0.0                                     TAK18670
107      CONTINUE                                                    TAK18680
        ENDIF                                                       TAK18690
        QIB(I,J)=0.0                                               TAK18700
      ENDIF                                                         TAK18710
*                                                                    TAK18720
*                                                                    TAK18730
*                                                                    TAK18740
*                                                                    TAK18750
*                                                                    TAK18760
101      CONTINUE                                                    TAK18770
*                                                                    TAK18780
*                                                                    TAK18790
*****.....ADVANCE IN Y-DIRECTION                                  TAK18800
*                                                                    TAK18810
*                                                                    TAK18820
      DO 201 J=2,IWPLS-1                                           TAK18830
        DO 201 I=2,LPLS-1                                          TAK18840
*                                                                    TAK18850
          IF(IGRID(I,J).EQ.2) THEN                                  TAK18860
*                                                                    TAK18870
            IF(IGRID(I,J+1).EQ.0) THEN                              TAK18880
*                                                                    TAK18890
              VV=0.0                                               TAK18900
              DO 202 K=1,JP                                         TAK18910
                VV=VV+CONTI(K,I,J+1)*ND(K,I-1,J)                TAK18920
202      CONTINUE                                                    TAK18930
              DEP=NETA(I,J+1)-H(I,J+1)                             TAK18940
              FLOW = VV*DEP*DELX*DELT                              TAK18950
              QJF(I,J)=QJF(I,J)+FLOW                               TAK18960
              VOL=0.5*DEP*DELX*DELY                                TAK18970
              IF(VV.LE.C.O) THEN                                     TAK18980
                SSS(I,J+1)=SOS(I,J+1)+ABS(FLOW)/DXDY            TAK18990
              ELSE                                                 TAK19000
                SSS(I,J+1)=SOS(I,J+1)+ABS(FLOW)/DXDY            TAK19010
              ENDIF                                               TAK19020
              IF(ABS(QJF(I,J)).GT.VOL) THEN                         TAK19030
                SSS(I,J+1)=SOS(I,J+1)                             TAK19040
                IF(QJF(I,J).GT.0.0) THEN                           TAK19050
                  IGRID(I,J+1)=2                                   TAK19060
                  ETA(I,J+1)=H(I,J+1)                             TAK19070

```

	NETA(I,J+1)=H(I,J+1)	TAK19080
	DO 203 K=1,JP	TAK19090
	A(K,I,J+1)=0.0	TAK19100
	CONTI(K,I,J+1)=0.0	TAK19110
	INTG1(K,I,J+1)=0.0	TAK19120
	INTG3(K,I,J+1)=0.0	TAK19130
	DO 203 L=1,JP	TAK19140
	INTG2(L,K,I,J+1)=0.0	TAK19150
	INTG4(L,K,I,J+1)=0.0	TAK19160
	INTG5(L,K,I,J+1)=0.0	TAK19170
	INTG6(L,K,I,J+1)=0.0	TAK19180
	INTG7(L,K,I,J+1)=0.0	TAK19190
203	CONTINUE	TAK19200
	ELSE	TAK19210
	IGRID(I,J)=0	TAK19220
	ETA(I,J)=H(I,J)+10.0	TAK19230
	NETA(I,J)=H(I,J)+10.0	TAK19240
	DO 204 K=1,JP	TAK19250
	A(K,I,J)=A(K,I,J+1)	TAK19260
	CONTI(K,I,J)=CONTI(K,I,J+1)	TAK19270
	INTG1(K,I,J)=INTG1(K,I,J+1)	TAK19280
	INTG3(K,I,J)=INTG3(K,I,J+1)	TAK19290
	DO 204 L=1,JP	TAK19300
	INTG2(L,K,I,J)=INTG2(L,K,I,J+1)	TAK19310
	INTG4(L,K,I,J)=INTG4(L,K,I,J+1)	TAK19320
	INTG5(L,K,I,J)=INTG5(L,K,I,J+1)	TAK19330
	INTG6(L,K,I,J)=INTG6(L,K,I,J+1)	TAK19340
	INTG7(L,K,I,J)=INTG7(L,K,I,J+1)	TAK19350
204	CONTINUE	TAK19360
	ENDIF	TAK19370
	QIF(I,J)=0.0	TAK19380
	ENDIF	TAK19390
*		TAK19400
*	ELSE IF(IGRID(I,J-1).EQ.0) THEN	TAK19410
		TAK19420
	VV=0.0	TAK19430
	DO 205 K=1,JP	TAK19440
	VV=VV+CONTI(K,I,J-1)*ND(K,I-1,J-1)	TAK19450
205	CONTINUE	TAK19460
	DEP=NETA(I,J-1)-H(I,J-1)	TAK19470
	FLOW = VV*DEP*DELX*DELT	TAK19480
	QJB(I,J)=QJB(I,J)+FLOW	TAK19490
	VOL=0.5*DEP*DELX*DELY	TAK19500
	IF(VV.GE.0.0) THEN	TAK19510
	SSS(I,J-1)=SOS(I,J-1)+ABS(FLOW)/DXDY	TAK19520
	ELSE	TAK19530
	SSS(I,J-1)=SOS(I,J-1)-ABS(FLOW)/DXDY	TAK19540
	ENDIF	TAK19550
	IF(ABS(QJB(I,J)).GT.VOL) THEN	TAK19560
	SSS(I,J-1)=SOS(I,J-1)	TAK19570
	IF(QJB(I,J).GT.0.0) THEN	TAK19580
	IGRID(I,J)=0	TAK19590
	ETA(I,J)=H(I,J)+10.0	TAK19600
	NETA(I,J)=H(I,J)+10.0	TAK19610
	DO 206 K=1,JP	TAK19620
	A(K,I,J)=A(K,I,J-1)	TAK19630
	CONTI(K,I,J)=CONTI(K,I,J-1)	TAK19640
	INTG1(K,I,J)=INTG1(K,I,J-1)	TAK19650
	INTG3(K,I,J)=INTG3(K,I,J-1)	TAK19660
	DO 206 L=1,JP	TAK19670
	INTG2(L,K,I,J)=INTG2(L,K,I,J-1)	TAK19680

		INTG4(L,K,I,J)=INTG4(L,K,I,J-1)	TAK19690
		INTG5(L,K,I,J)=INTG5(L,K,I,J-1)	TAK19700
		INTG6(L,K,I,J)=INTG6(L,K,I,J-1)	TAK19710
		INTG7(L,K,I,J)=INTG7(L,K,I,J-1)	TAK19720
206		CONTINUE	TAK19730
		ELSE	TAK19740
		IGRID(I,J-1)=2	TAK19750
		ETA(I,J-1)=H(I,J-1)	TAK19760
		NETA(I,J-1)=H(I,J-1)	TAK19770
		DO 207 K=1,JP	TAK19780
		A(K,I,J-1)=0.0	TAK19790
		CONTI(K,I,J-1)=0.0	TAK19800
		INTG1(K,I,J-1)=0.0	TAK19810
		INTG3(K,I,J-1)=0.0	TAK19820
		DO 207 L=1,JP	TAK19830
		INTG2(L,K,I,J-1)=0.0	TAK19840
		INTG4(L,K,I,J-1)=0.0	TAK19850
		INTG5(L,K,I,J-1)=0.0	TAK19860
		INTG6(L,K,I,J-1)=0.0	TAK19870
		INTG7(L,K,I,J-1)=0.0	TAK19880
207		CONTINUE	TAK19890
		ENDIF	TAK19900
		QIF(I,J)=0.0	TAK19910
		ENDIF	TAK19920
*			TAK19930
		ENDIF	TAK19940
*			TAK19950
		ENDIF	TAK19960
*			TAK19970
201		CONTINUE	TAK19980
*			TAK19990
*			TAK20000
		RETURN	TAK20010
		END	TAK20020

```

SUBROUTINE CLIMATE(SSS)
*****
*
*   COMPUTES THE CHANGE IN ABLATION RATE BELOW THE
*   EQUILIBRIUM LINE
*
*****
*
*   PARAMETER (JP=1,KP=21,LENGTH=54,IWIDTH=33)
*   PARAMETER (LENP1=LENGTH+1,IWIDP1=IWIDTH+1,LPLS=LENGTH+2,
*   &          IWPLS=IWIDTH+2)
*   REAL  NV,NH,NC,ND,NETA,LHEAT
*   REAL  INTG1,INTG2,INTG3,INTG4,INTG5,INTG6,INTG7
*   LOGICAL FTTOM,HOTST,HVISC,VFRIC,MOVE
*
*   DIMENSION SSS(LPLS,IWPLS)
*   COMMON/ BLK1/ H(LPLS,IWPLS),FRIC(LPLS,IWPLS),NV,NH,RHO
*   COMMON/ BLK4/ C(JP,LENP1,IWIDTH),NC(JP,LENP1,IWIDTH),
*   &          D(JP,LENGTH,IWIDP1),ND(JP,LENGTH,IWIDP1)
*   COMMON/ BLK5/ ETA(LPLS,IWPLS),NETA(LPLS,IWPLS),SOS(LPLS,IWPLS)
*   COMMON/ BLK8/ IGRID(LPLS,IWPLS),XI(4),W(4)
*   COMMON/ BLK11/ HEQL,DELCL,GRADC,GRADT,ALFA1,ALFA2,TDEL,SMIN
*
*   DATA LHEAT/3.35E05/
*
*****.....DETERMINE CHANGE IN THE ELEVATION OF EL
*
      Z=HEQL
      HEQL1=HEQL
      DAY=193.6 -2.646E-01*Z +4.351E-04*Z**2 -4.472E-07*Z**3
      DAY=DAY+2.142E-10*Z**4 -3.946E-14*Z**5
      COEF=DAY*(ALFA1+ALFA2)/LHEAT
      SUMT=-DELCL+COEF*TDEL
      SUMB=GRADC-COEF*GRADT
      HDEL=SUMT/SUMB
      HEQL=HEQL+HDEL
*
*****.....DETERMINE ABLATION BELOW EQL.
*
      DO 101 J=1,IWIDTH
      DO 101 I=1,LPLS
      SP=SSS(I,J)
      IF (NETA(I,J).LE.HEQL.AND.NETA(I,J).GE.HEQL1) THEN
      DIF=HEQL-NETA(I,J)
      SSS(I,J)=DIF*SMIN/HEQL
      IF (SP.LT.SSS(I,J)) THEN
      SSS(I,J)=SP
      ENDIF
      ENDIF
      IF (NETA(I,J).LE.HEQL1.AND.NETA(I,J).GT.0.0) THEN
      DIF1=(HEQL1-NETA(I,J))/HEQL1
      DIF2=(HEQL-NETA(I,J))/HEQL
      SSS(I,J)=SSS(I,J)+(DIF2-DIF1)*SMIN
      IF (SP.LT.SSS(I,J)) THEN

```

```

TAK20030
TAK20040
TAK20050
TAK20060
TAK20070
TAK20080
TAK20090
TAK20100
TAK20110
TAK20120
TAK20130
TAK20140
TAK20150
TAK20160
TAK20170
TAK20180
TAK20190
TAK20200
TAK20210
TAK20220
TAK20230
TAK20240
TAK20250
TAK20260
TAK20270
TAK20280
TAK20290
TAK20300
TAK20310
TAK20320
TAK20330
TAK20340
TAK20350
TAK20360
TAK20370
TAK20380
TAK20390
TAK20400
TAK20410
TAK20420
TAK20430
TAK20440
TAK20450
TAK20460
TAK20470
TAK20480
TAK20490
TAK20500
TAK20510
TAK20520
TAK20530
TAK20540
TAK20550
TAK20560
TAK20570
TAK20580

```



```
          SSS(I,J)=SP
        ENDIF
      ENDIF
101     CONTINUE
*
      RETURN
      END
```

```
TAK20590
TAK20600
TAK20610
TAK20620
TAK20630
TAK20640
TAK20650
```

```

      FUNCTION VELOB(M,N)
*****
*
*   CALCULATES BOTTOM VELOCITY FOR QUADRATIC FRICTION
*
*****
*
      PARAMETER (JP=1,KP=21,LENGTH=54,IWIDTH=33)
      PARAMETER (LENP1=LENGTH+1,IWIDP1=IWIDTH+1,LPLS=LENGTH+2,
&              IWPLS=IWIDTH+2)
      REAL      NC,ND
      COMMON/ BLK4/ C(JP,LENP1,IWIDTH),NC(JP,LENP1,IWIDTH),
&              D(JP,LENGTH,IWIDP1),ND(JP,LENGTH,IWIDP1)
      COMMON/ BLK6/ A(JP,LPLS,IWPLS),CONTI(JP,LPLS,IWPLS)
*
*
      MM=M
      NN=N
      IF(M.EQ.1) MM=M+1
      IF(M.EQ.LPLS) MM=M-1
      IF(N.EQ.1) NN=N+1
      IF(N.EQ.IWPLS) NN=N-1
*
      SIGMA=0.
      U=0.
      V=0.
      DO 101 I=1,JP
          C1=(C(I,MM,NN-1)+C(I,MM-1,NN-1))*0.5
          D1=(D(I,MM-1,NN)+D(I,MM-1,NN-1))*0.5
          TRIG= COS(A(I,MM,NN))*(2.0-SIGMA)*0.5
          U=U+C1*TRIG
          V=V+D1*TRIG
101  CONTINUE
      VELOB= SQRT(U*U+V*V)
*
      RETURN
      END
TAK20660
TAK20670
TAK20680
TAK20690
TAK20700
TAK20710
TAK20720
TAK20730
TAK20740
TAK20750
TAK20760
TAK20770
TAK20780
TAK20790
TAK20800
TAK20810
TAK20820
TAK20830
TAK20840
TAK20850
TAK20860
TAK20870
TAK20880
TAK20890
TAK20900
TAK20910
TAK20920
TAK20930
TAK20940
TAK20950
TAK20960
TAK20970
TAK20980
TAK20990
TAK21000
TAK21010
TAK21020

```

```

SUBROUTINE VELOC
*****
*
*          COMPUTES VERTICAL VELOCITY PROFILE
*
*****
PARAMETER (JP=1,KP=21,LENGTH=54,IWIDTH=33)
PARAMETER (LENP1=LENGTH+1,IWIDP1=IWIDTH+1,LPLS=LENGTH+2,
&          IWPLS=IWIDTH+2)
*
REAL      NC,ND,NETA
*
COMMON/ BLK1/ H(LPLS,IWPLS),FRICT(LPLS,IWPLS),NV,NH,RHO
COMMON/ BLK4/ C(JP,LENP1,IWIDTH),NC(JP,LENP1,IWIDTH),
&          D(JP,LENGTH,IWIDP1),ND(JP,LENGTH,IWIDP1)
COMMON/ BLK5/ ETA(LPLS,IWPLS),NETA(LPLS,IWPLS),SOS(LPLS,IWPLS)
COMMON/ BLK6/ A(JP,LPLS,IWPLS),AR1(JP),AR2(JP),AA(JP),
&          AI1(JP),AI3(JP),CONTI(JP,LPLS,IWPLS)
COMMON/ BLK8/ IGRID(LPLS,IWPLS),XI(4),W(4)
COMMON/ BLK9/ VX(KP,LPLS,IWPLS),VY(KP,LPLS,IWPLS),
&          VV(KP,LPLS,IWPLS),VM(LPLS,IWPLS),DELSIG
DATA FACT /86400.0 /
*
*
DO 100 I=1,LPLS
DO 100 J=1,IWPLS
DO 100 K=1,JP
VX(K,I,J)=0.0
VY(K,I,J)=0.0
VV(K,I,J)=0.0
VM(I,J)=0.0
100 CONTINUE

DO 101 I=2,LPLS-1
DO 101 J=2,IWPLS-1
IF (IGRID(I,J).NE.0) GOTO 101
*
*****.....COMPUTE X-VELOCITY COMPONENT
*
SIGMA=0.0
DO 102 L=1,KP
VSUM=0.0
DO 103 K=1,JP
AVGC=0.5*(NC(K,I-1,J-1)+NC(K,I,J-1))
TRIG=0.5*A(K,I,J)*(2.0-SIGMA)
TRIG= COS (TRIG)
VSUM=VSUM+AVGC*TRIG
103 CONTINUE
VX(L,I,J)=FACT*VSUM
SIGMA=SIGMA+DELSIG
102 CONTINUE
*
*****..... COMPUTE Y-VELOCITY COMPONENT
*
SIGMA=0.0
DO 104 L=1,KP
VSUM=0.0
DO 105 K=1,JP
AVGD=0.5*(ND(K,I-1,J-1)+ND(K,I-1,J))

```

```

TAK21030
TAK21040
TAK21050
TAK21060
TAK21070
TAK21080
TAK21090
TAK21100
TAK21110
TAK21120
TAK21130
TAK21140
TAK21150
TAK21160
TAK21170
TAK21180
TAK21190
TAK21200
TAK21210
TAK21220
TAK21230
TAK21240
TAK21250
TAK21260
TAK21270
TAK21280
TAK21290
TAK21300
TAK21310
TAK21320
TAK21330
TAK21340
TAK21350
TAK21360
TAK21370
TAK21380
TAK21390
TAK21400
TAK21410
TAK21420
TAK21430
TAK21440
TAK21450
TAK21460
TAK21470
TAK21480
TAK21490
TAK21500
TAK21510
TAK21520
TAK21530
TAK21540
TAK21550
TAK21560
TAK21570
TAK21580
TAK21590
TAK21600
TAK21610
TAK21620
TAK21630

```

```

          TRIG=0.5*A(K,I,J)*(2.0-SIGMA)
          TRIG= COS (TRIG)
          VSUM=VSUM+AVGD*TRIG
105      CONTINUE
          VY(L,I,J)=FACT*VSUM
          SIGMA=SIGMA+DELSIG
104      CONTINUE
*
*****.....COMPUTE RESULTANT VELOCITY
*
          DO 106 L=1,KP
            VV(L,I,J)=0.0
            IF ( ABS (VX(L,I,J)) .LE.1.0E-25) THEN
              VX(L,I,J)=0.0
            ENDIF
            IF ( ABS (VY(L,I,J)) .LE.1.0E-25) THEN
              VY(L,I,J)=0.0
            ENDIF
            VV(L,I,J)= SQRT (VX(L,I,J)**2+VY(L,I,J)**2)
106      CONTINUE
*
*****.....COMPUTE MEAN VELOCITY
*
          VSUM=0.0
          DO 107 K=1,JP
            AVGC=0.5*(NC(K,I-1,J-1)+NC(K,I,J-1))
            IF (A(K,I,J) .NE.0.0) THEN
              VSUM=VSUM+AVGC*CONTI(K,I,J)
            ELSE
              VSUM=VSUM+AVGC
            ENDIF
107      CONTINUE
          VMX=VSUM
*
          VSUM=0.0
          DO 108 K=1,JP
            AVGD=0.5*(ND(K,I-1,J-1)+NC(K,I,J+1))
            IF (A(K,I,J) .NE.0.0) THEN
              VSUM=VSUM+AVGD*CONTI(K,I,J)
            ELSE
              VSUM=VSUM+AVGD
            ENDIF
108      CONTINUE
          VMY=VSUM
*
          IF ( ABS (VMX) .LE.1.0E-25) THEN
            VMX=0.0
          ENDIF
          IF ( ABS (VMY) .LE.1.0E-25) THEN
            VMY=0.0
          ENDIF
          VM(I,J)=FACT* SQRT (VMX*VMX+VMY*VMY)
*
101      CONTINUE
*
          RETURN
          END

```

TAK21640
 TAK21650
 TAK21660
 TAK21670
 TAK21680
 TAK21690
 TAK21700
 TAK21710
 TAK21720
 TAK21730
 TAK21740
 TAK21750
 TAK21760
 TAK21770
 TAK21780
 TAK21790
 TAK21800
 TAK21810
 TAK21820
 TAK21830
 TAK21840
 TAK21850
 TAK21860
 TAK21870
 TAK21880
 TAK21890
 TAK21900
 TAK21910
 TAK21920
 TAK21930
 TAK21940
 TAK21950
 TAK21960
 TAK21970
 TAK21980
 TAK21990
 TAK22000
 TAK22010
 TAK22020
 TAK22030
 TAK22040
 TAK22050
 TAK22060
 TAK22070
 TAK22080
 TAK22090
 TAK22100
 TAK22110
 TAK22120
 TAK22130
 TAK22140
 TAK22150
 TAK22160
 TAK22170
 TAK22180
 TAK22190
 TAK22200

```

SUBROUTINE OUTPUT(JJJ,HI,SSS,HEQL)
*****
*
*          PRINT AND STORE COMPUTED OUTPUTS
*
*****
PARAMETER (JP=1,KP=21,LENGTH=54,IWIDTH=33)
PARAMETER (LENP1=LENGTH+1,IWIDP1=IWIDTH+1,LPLS=LENGTH+2,
&          IWPLS=IWIDTH+2)
*
CHARACTER*1 T /Z05/
REAL    NV,NH,NC,ND,NETA
REAL    INTG1,INTG2,INTG3,INTG4,INTG5,INTG6,INTG7
LOGICAL  FTTOM,HOTST,HVISC,VFRIC,MOVE
*
DIMENSION HI(LPLS,IWPLS),SSS(LPLS,IWPLS)
DIMENSION HT(LPLS,IWPLS),VR(LPLS,IWPLS),TW(LPLS,IWPLS)
COMMON/ BLK1/ H(LPLS,IWPLS),FRIC(LPLS,IWPLS),NV,NH,RHO
COMMON/ BLK2/ DELT,DELX,DELY,UPAI,START,PHOTST,POUTPT,
&          ISTRT,NFIN,NHOTST
COMMON/ BLK3/ FTTOM,HOTST,HVISC,VFRIC,MOVE
COMMON/ BLK4/ C(JP,LENP1,IWIDTH),NC(JP,LENP1,IWIDTH),
&          D(JP,LENGTH,IWIDP1),ND(JP,LENGTH,IWIDP1)
COMMON/ BLK5/ ETA(LPLS,IWPLS),NETA(LPLS,IWPLS),SOS(LPLS,IWPLS)
COMMON/ BLK6/ A(JP,LPLS,IWPLS),CONTI(JP,LPLS,IWPLS)
COMMON/ BLK7/ INTG1(JP,LPLS,IWPLS),INTG2(JP,JP,LPLS,IWPLS),
&          INTG3(JP,LPLS,IWPLS),INTG4(JP,JP,LPLS,IWPLS),
&          INTG5(JP,JP,LPLS,IWPLS),INTG6(JP,JP,LPLS,IWPLS),
&          INTG7(JP,JP,LPLS,IWPLS)
COMMON/ BLK8/ IGRID(LPLS,IWPLS),XI(4),W(4)
COMMON/ BLK9/ VX(KP,LPLS,IWPLS),VY(KP,LPLS,IWPLS),
&          VV(KP,LPLS,IWPLS),VM(LPLS,IWPLS),DELSIG
COMMON/ BLK10/ QIF(LPLS,IWPLS),QIB(LPLS,IWPLS),
&          QJF(LPLS,IWPLS),QJB(LPLS,IWPLS)
*
DATA ISKIP      / 240 /
DATA ROW        / 900.0/
DATA FACT       / 3.17097E-8/
*
*
*****.....PRINT SURFACE ELEVATION ON THE SCREEN
*
      WRITE(3,1001)      NETA(9,23),NETA(23,12),NETA(21,20),
&          NETA(28,20),NETA(34,20),NETA(30,26),NETA(37,26),
&          NETA(45,29)
1001  FORMAT(1X,8(F9.2))
*
*
*****.....COMPUTE VELOCITY
*
      CALL VELOC
*
*****.....PRINT SURFACE ELEVATION AT SELECTED LOCATIONS
*
      WRITE(11,1002) JJJ,T,NETA(9,23),T,NETA(23,12),T,NETA(21,20),
&          T,NETA(28,20),T,NETA(34,20),T,NETA(30,26),T,NETA(37,26),
&          T,NETA(45,29)
1002  FORMAT(1X,I5,8(A1,F9.2))
*

```

```

TAK22210
TAK22220
TAK22230
TAK22240
TAK22250
TAK22260
TAK22270
TAK22280
TAK22290
TAK22300
TAK22310
TAK22320
TAK22330
TAK22340
TAK22350
TAK22360
TAK22370
TAK22380
TAK22390
TAK22400
TAK22410
TAK22420
TAK22430
TAK22440
TAK22450
TAK22460
TAK22470
TAK22480
TAK22490
TAK22500
TAK22510
TAK22520
TAK22530
TAK22540
TAK22550
TAK22560
TAK22570
TAK22580
TAK22590
TAK22600
TAK22610
TAK22620
TAK22630
TAK22640
TAK22650
TAK22660
TAK22670
TAK22680
TAK22690
TAK22700
TAK22710
TAK22720
TAK22730
TAK22740
TAK22750
TAK22760
TAK22770
TAK22780
TAK22790
TAK22800
TAK22810

```

```

*
*****.....PRINT SURFACE VELOCITY AT SELECTED LOCATIONS
*
          WRITE(12,1003) JJJ,T,VV(KP,9,23),T,VV(KP,23,12),T,
          &          VV(KP,21,20),T,VV(KP,28,20),T,VV(KP,34,20),T,
          &          VV(KP,30,26),T,VV(KP,37,26),T,VV(KP,45,29)
1003  FORMAT(1X,I5,8(A1,F9.5))
*
*
*****.....COMPUTE AND PRINT DIFFERENT PARAMETERS OF THE GLACIER
*
          VOL=0.0
          ACC=0.0
          ABL=0.0
          SPO=0.0
          SNE=0.0
          DO 101 I=1,LPLS
            DO 101 J=1,IWPLS
              IF(IGRID(I,J).EQ.0) THEN
                DIF=NETA(I,J)-H(I,J)
                VOL=VOL+DIF
                IF(SSS(I,J).GT.0.0) THEN
                  ACC=ACC+1.0
                  SPO=SPO+SSS(I,J)
                ELSE
                  ABL=ABL+1.0
                  SNE=SNE+SSS(I,J)
                ENDIF
              ENDIF
            ENDIF
101  CONTINUE
          VOL=0.001*VOL
          SPO=SPO/(FACT*DELT)
          SNE=SNE/(FACT*DELT)
          WRITE(15,1004) VOL,T,ACC,T,ABL,T,SPO,T,SNE,T,HEQL
1004  FORMAT(1X,6(F10.2,A1))
*
*
          KK=JJJ/ISKIP
          IF((KK*ISKIP-JJJ).EQ.0) THEN
*
*****.....VERTICAL VELOCITY AT SELECTED LOCATIONS
*
          SIGMA=0.0
          DO 102 K=1,KP
            WRITE(13,1005) SIGMA,T,VV(K,9,23),T,VV(K,23,12),T,
            &          VV(K,21,20),T,VV(K,28,20),T,VV(K,34,20),T,
            &          VV(K,30,26),T,VV(K,37,26),T,VV(K,45,29)
1005  FORMAT(1X,9(F8.5,A1))
          SIGMA=SIGMA+DELSIG
102  CONTINUE
*
*
*****.....DETERMINE AND PRINT FLOW PARAMETERS OF THE GLACIER
*
          HTMAX=-99999.0
          HTMIN=+99999.0
          TWMAX=-99999.0
          TWMIN=+99999.0
          VRMAX=-99999.0
          VRMIN=+99999.0
          VSMAX=-99999.0

```

TAK22820
TAK22830
TAK22840
TAK22850
TAK22860
TAK22870
TAK22880
TAK22890
TAK22900
TAK22910
TAK22920
TAK22930
TAK22940
TAK22950
TAK22960
TAK22970
TAK22980
TAK22990
TAK23000
TAK23010
TAK23020
TAK23030
TAK23040
TAK23050
TAK23060
TAK23070
TAK23080
TAK23090
TAK23100
TAK23110
TAK23120
TAK23130
TAK23140
TAK23150
TAK23160
TAK23170
TAK23180
TAK23190
TAK23200
TAK23210
TAK23220
TAK23230
TAK23240
TAK23250
TAK23260
TAK23270
TAK23280
TAK23290
TAK23300
TAK23310
TAK23320
TAK23330
TAK23340
TAK23350
TAK23360
TAK23370
TAK23380
TAK23390
TAK23400
TAK23410
TAK23420

```

VSMIN=+99999.0
VBMAX=-99999.0
VBMIN=+999.0
DO 103 J=1, IWPLS
  DO 103 I=1, LPLS
    IF (IGRID(I, J) .EQ. 0) THEN
      HT(I, J) = NETA(I, J) - HI(I, J)
      VR(I, J) = VV(1, I, J) / VV(KP, I, J)
      TW(I, J) = FRICT(I, J) * ROW * VV(1, I, J)
      TW(I, J) = 1.1574E-8 * TW(I, J)
      HTMAX = AMAX1(HTMAX, HT(I, J))
      HTMIN = AMIN1(HTMIN, HT(I, J))
      TWMAX = AMAX1(TWMAX, TW(I, J))
      TWMIN = AMIN1(TWMIN, TW(I, J))
      VRMAX = AMAX1(VRMAX, VR(I, J))
      VRMIN = AMIN1(VRMIN, VR(I, J))
      VSMAX = AMAX1(VSMAX, VV(KP, I, J))
      VSMIN = AMIN1(VSMIN, VV(KP, I, J))
      VBMAX = AMAX1(VBMAX, VV(1, I, J))
      VBMIN = AMIN1(VBMIN, VV(1, I, J))
    ENDIF
103 CONTINUE
*
  WRITE(14, *) 'HTMAX & HTMIN: ', HTMAX, HTMIN
  DO 104 J=1, IWPLS
    WRITE(14, 1006) (HT(I, J), I=1, LPLS)
1006   FORMAT((9F7.2))
104 CONTINUE
  WRITE(14, *) 'TWMAX & TWMIN: ', TWMAX, TWMIN
  DO 105 J=1, IWPLS
    WRITE(14, 1006) (TW(I, J), I=1, LPLS)
105 CONTINUE
  WRITE(14, *) 'VRMAX & VRMIN: ', VRMAX, VRMIN
  DO 106 J=1, IWPLS
    WRITE(14, 1006) (VR(I, J), I=1, LPLS)
106 CONTINUE
  WRITE(14, *) 'VSMAX & VSMIN: ', VSMAX, VSMIN
  DO 107 J=1, IWPLS
    WRITE(14, 1006) (VV(KP, I, J), I=1, LPLS)
107 CONTINUE
  WRITE(14, *) 'VBMAX & VBMIN: ', VBMAX, VBMIN
  DO 108 J=1, IWPLS
    WRITE(14, 1006) (VV(1, I, J), I=1, LPLS)
108 CONTINUE
*
  REWIND(14)
  ENDIF
*
  RETURN
*
*****.....WRITE OUTPUT FOR HOT START
*
  ENTRY OUP(T(JJJ, HI, SSS))
*
  WRITE(3, 2001) JJJ
2001  FORMAT(' ', T10, 'WRITING HOT START DATA....', I5 )
  REWIND(2)
  WRITE(2) NHOTST
  WRITE(2) IGRID
  WRITE(2) A
  WRITE(2) ETA

```

TAK23430
TAK23440
TAK23450
TAK23460
TAK23470
TAK23480
TAK23490
TAK23500
TAK23510
TAK23520
TAK23530
TAK23540
TAK23550
TAK23560
TAK23570
TAK23580
TAK23590
TAK23600
TAK23610
TAK23620
TAK23630
TAK23640
TAK23650
TAK23660
TAK23670
TAK23680
TAK23690
TAK23700
TAK23710
TAK23720
TAK23730
TAK23740
TAK23750
TAK23760
TAK23770
TAK23780
TAK23790
TAK23800
TAK23810
TAK23820
TAK23830
TAK23840
TAK23850
TAK23860
TAK23870
TAK23880
TAK23890
TAK23900
TAK23910
TAK23920
TAK23930
TAK23940
TAK23950
TAK23960
TAK23970
TAK23980
TAK23990
TAK24000
TAK24010
TAK24020
TAK24030

WRITE(2) NETA	TAK24040
WRITE(2) C	TAK24050
WRITE(2) NC	TAK24060
WRITE(2) D	TAK24070
WRITE(2) ND	TAK24080
WRITE(2) SSS	TAK24090
WRITE(2) FRICT	TAK24100
WRITE(2) QIF	TAK24110
WRITE(2) QIB	TAK24120
WRITE(2) QJF	TAK24130
WRITE(2) QJB	TAK24140
	TAK24150
	TAK24160
	TAK24170
RETURN	
END	

0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1330.0,	1250.0,	1220.0,	1230.0,	1260.0,	1270.0,	1290.0,	1300.0,
0.0,	1300.0,	1350.0,	1380.0,	1400.0,	1450.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	1400.0,	1240.0,	1215.0,	1220.0,	1260.0,	1270.0,	1280.0,
1290.0,	1290.0,	1300.0,	1320.0,	1330.0,	1350.0,	1360.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1300.0,	1225.0,	1220.0,	1210.0,	1230.0,	1260.0,	1270.0,	1280.0,
1290.0,	1290.0,	1300.0,	1310.0,	1320.0,	1340.0,	1350.0,	1350.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1300.0,	1220.0,	1190.0,	1190.0,	1190.0,	1220.0,	1240.0,	1260.0,
1280.0,	1290.0,	1310.0,	1320.0,	1340.0,	1340.0,	1350.0,	1350.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1300.0,	1180.0,	1170.0,	1160.0,	1170.0,	1210.0,	0.0,	1330.0,
1300.0,	1300.0,	1320.0,	1340.0,	1400.0,	1440.0,	1550.0,	1350.0,	1350.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	1300.0,	1220.0,	1230.0,	1210.0,
1190.0,	1180.0,	1160.0,	1130.0,	1120.0,	1120.0,	1130.0,	0.0,	1400.0,
1370.0,	1380.0,	0.0,	0.0,	0.0,	0.0,	1400.0,	1400.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
1170.0,	1130.0,	1110.0,	1090.0,	1070.0,	1050.0,	1090.0,	1250.0,	1280.0,
1320.0,	1320.0,	1320.0,	1300.0,	1290.0,	1280.0,	1280.0,	0.0,	1240.0,
1280.0,	1230.0,	1220.0,	1220.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
1100.0,	1060.0,	1020.0,	970.0,	940.0,	930.0,	940.0,	960.0,	990.0,
1010.0,	1020.0,	1040.0,	1040.0,	1050.0,	1070.0,	1090.0,	0.0,	1120.0,
1090.0,	1070.0,	1030.0,	980.0,	990.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	1220.0,	1180.0,	1130.0,
1090.0,	1060.0,	1030.0,	980.0,	950.0,	910.0,	890.0,	890.0,	900.0,
910.0,	920.0,	940.0,	980.0,	1060.0,	1140.0,	0.0,	1080.0,	1010.0,
1050.0,	970.0,	960.0,	970.0,	990.0,	0.0,	0.0,	0.0,	0.0,

0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,							
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	1230.0,	1250.0,	1250.0,
0.0,	1240.0,	1065.0,	980.0,	940.0,	900.0,	870.0,	860.0,	870.0,
900.0,	920.0,	1000.0,	0.0,	1110.0,	1110.0,	0.0,	1000.0,	940.0,
910.0,	900.0,	950.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,							
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	1380.0,	1380.0,	0.0,
0.0,	1040.0,	1020.0,	980.0,	930.0,	900.0,	860.0,	850.0,	850.0,
860.0,	860.0,	890.0,	920.0,	0.0,	1000.0,	900.0,	870.0,	880.0,
900.0,	970.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,							
0.0,	1660.0,	1650.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1700.0,	1600.0,	1540.0,	1500.0,	1460.0,	1390.0,	1400.0,	1400.0,
1170.0,	1140.0,	1060.0,	1010.0,	970.0,	950.0,	830.0,	800.0,	760.0,
740.0,	730.0,	770.0,	0.0,	930.0,	960.0,	950.0,	950.0,	1050.0,
1080.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,							
0.0,	1610.0,	1600.0,	1550.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1690.0,	1560.0,	1680.0,	0.0,	1470.0,	1360.0,	1270.0,	1220.0,
1110.0,	1080.0,	1050.0,	1030.0,	1080.0,	0.0,	960.0,	890.0,	770.0,
740.0,	710.0,	700.0,	780.0,	800.0,	850.0,	910.0,	970.0,	990.0,
1020.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,							
0.0,	0.0,	1760.0,	1620.0,	1610.0,	1700.0,	1720.0,	0.0,	0.0,
1550.0,	1530.0,	1500.0,	1470.0,	1450.0,	1400.0,	1360.0,	1210.0,	1150.0,
1110.0,	1080.0,	1140.0,	0.0,	0.0,	1040.0,	1000.0,	1060.0,	900.0,
820.0,	730.0,	700.0,	700.0,	720.0,	740.0,	850.0,	890.0,	900.0,
900.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,							
0.0,	0.0,	0.0,	1690.0,	1600.0,	1660.0,	1640.0,	1580.0,	1560.0,
1540.0,	1520.0,	1500.0,	1420.0,	1340.0,	1310.0,	1330.0,	1190.0,	1150.0,
1110.0,	1100.0,	1200.0,	0.0,	0.0,	1020.0,	1040.0,	0.0,	880.0,
830.0,	800.0,	700.0,	650.0,	690.0,	730.0,	860.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,							
0.0,	0.0,	0.0,	1590.0,	1550.0,	1560.0,	1540.0,	1530.0,	1520.0,
1550.0,	1500.0,	1450.0,	1420.0,	1340.0,	1310.0,	1330.0,	1200.0,	1210.0,
1270.0,	1260.0,	1270.0,	1300.0,	1220.0,	1100.0,	1060.0,	0.0,	850.0,
0.0,	750.0,	700.0,	600.0,	550.0,	530.0,	560.0,	540.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,							
0.0,	0.0,	0.0,	0.0,	1530.0,	1530.0,	1520.0,	1590.0,	1660.0,
1670.0,	1600.0,	1630.0,	1680.0,	1520.0,	1390.0,	1360.0,	0.0,	0.0,
0.0,	1350.0,	1420.0,	1420.0,	1380.0,	1275.0,	1340.0,	0.0,	0.0,
0.0,	0.0,	700.0,	600.0,	530.0,	520.0,	500.0,	480.0,	470.0,
450.0,	500.0,	435.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,							
0.0,	0.0,	0.0,	0.0,	0.0,	1600.0,	1600.0,	1650.0,	1770.0,
1830.0,	1610.0,	1600.0,	1630.0,	1650.0,	0.0,	1390.0,	1370.0,	1230.0,
0.0,	1220.0,	1250.0,	1260.0,	1280.0,	1280.0,	1120.0,	1100.0,	1070.0,

0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,							
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1500.0,	1430.0,	1440.0,	1450.0,	1470.0,	1470.0,	1500.0,	1520.0,
0.0,	1510.0,	1520.0,	1540.0,	1560.0,	1580.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
1500.0,	1510.0,	1520.0,	1540.0,	1560.0,	1580.0,	1600.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1470.0,	1410.0,	1370.0,	1370.0,	1380.0,	1410.0,	1460.0,	1490.0,
1500.0,	1515.0,	1530.0,	1550.0,	1560.0,	1560.0,	1580.0,	1600.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1440.0,	1400.0,	1360.0,	1350.0,	1360.0,	1390.0,	1410.0,	1450.0,
1475.0,	1490.0,	1520.0,	1540.0,	1550.0,	1560.0,	1570.0,	1590.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1440.0,	1380.0,	1330.0,	1320.0,	1340.0,	1370.0,	0.0,	1520.0,
1480.0,	1500.0,	1530.0,	1550.0,	1560.0,	1580.0,	1650.0,	1590.0,	1600.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	1410.0,	1390.0,	1360.0,	1350.0,
1350.0,	1360.0,	1350.0,	1310.0,	1280.0,	1280.0,	1300.0,	0.0,	1510.0,
1480.0,	1520.0,	0.0,	0.0,	0.0,	0.0,	1530.0,	1550.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
1320.0,	1300.0,	1280.0,	1260.0,	1220.0,	1230.0,	1280.0,	1400.0,	1440.0,
1450.0,	1450.0,	1450.0,	1430.0,	1430.0,	1420.0,	1420.0,	0.0,	1380.0,
1410.0,	1390.0,	1380.0,	1380.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
1270.0,	1250.0,	1230.0,	1200.0,	1170.0,	1170.0,	1170.0,	1170.0,	1190.0,
1190.0,	1190.0,	1200.0,	1200.0,	1220.0,	1240.0,	1260.0,	0.0,	1290.0,
1240.0,	1220.0,	1200.0,	1180.0,	1190.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	1380.0,	1320.0,	1280.0,
1280.0,	1270.0,	1270.0,	1220.0,	1200.0,	1170.0,	1130.0,	1140.0,	1140.0,

1140.0,	1150.0,	1170.0,	1190.0,	1240.0,	1300.0,	0.0,	1250.0,	1200.0,
1240.0,	1180.0,	1170.0,	1180.0,	1190.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	1380.0,	1350.0,	1350.0,
0.0,	1350.0,	1275.0,	1220.0,	1180.0,	1150.0,	1120.0,	1120.0,	1120.0,
1140.0,	1170.0,	1200.0,	0.0,	1280.0,	1280.0,	0.0,	1170.0,	1140.0,
1120.0,	1120.0,	1180.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	1550.0,	1550.0,	0.0,
0.0,	1280.0,	1270.0,	1230.0,	1200.0,	1150.0,	1120.0,	1100.0,	1100.0,
1100.0,	1080.0,	1110.0,	1130.0,	0.0,	1160.0,	1110.0,	1090.0,	1100.0,
1130.0,	1200.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1850.0,	1840.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1850.0,	1825.0,	1750.0,	1700.0,	1650.0,	1560.0,	1530.0,	1530.0,
1400.0,	1360.0,	1280.0,	1240.0,	1200.0,	1180.0,	1220.0,	1090.0,	1070.0,
1060.0,	1050.0,	1060.0,	0.0,	1150.0,	1060.0,	1080.0,	1090.0,	1130.0,
1150.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1830.0,	1810.0,	1780.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1840.0,	1790.0,	1840.0,	0.0,	1660.0,	1560.0,	1480.0,	1420.0,
1350.0,	1330.0,	1310.0,	1270.0,	1270.0,	0.0,	1160.0,	1130.0,	1070.0,
1060.0,	1050.0,	1040.0,	1040.0,	1030.0,	1050.0,	1090.0,	1120.0,	1130.0,
1140.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	1900.0,	1830.0,	1820.0,	1870.0,	1860.0,	0.0,	0.0,
1780.0,	1760.0,	1700.0,	1680.0,	1650.0,	1600.0,	1530.0,	1400.0,	1380.0,
1340.0,	1330.0,	1330.0,	0.0,	0.0,	1220.0,	1190.0,	1160.0,	1100.0,
1070.0,	1050.0,	1020.0,	1000.0,	1000.0,	1000.0,	1040.0,	1060.0,	1070.0,
1080.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	1870.0,	1810.0,	1850.0,	1840.0,	1800.0,	1780.0,
1760.0,	1720.0,	1680.0,	1630.0,	1570.0,	1540.0,	1490.0,	1400.0,	1380.0,
1350.0,	1340.0,	1390.0,	0.0,	0.0,	1220.0,	1220.0,	0.0,	1090.0,
1050.0,	1040.0,	1020.0,	980.0,	980.0,	980.0,	1000.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	1830.0,	1790.0,	1790.0,	1780.0,	1770.0,	1760.0,
1740.0,	1720.0,	1670.0,	1630.0,	1570.0,	1540.0,	1490.0,	1420.0,	1410.0,
1440.0,	1420.0,	1420.0,	1435.0,	1440.0,	1300.0,	1280.0,	0.0,	1040.0,
0.0,	1000.0,	980.0,	960.0,	930.0,	920.0,	890.0,	860.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	1790.0,	1780.0,	1780.0,	1820.0,	1860.0,
1880.0,	1810.0,	1850.0,	1870.0,	1725.0,	1550.0,	1480.0,	0.0,	0.0,
0.0,	1480.0,	1460.0,	1475.0,	1480.0,	1425.0,	1460.0,	0.0,	0.0,
0.0,	0.0,	960.0,	940.0,	930.0,	900.0,	880.0,	860.0,	840.0,
800.0,	770.0,	745.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	1800.0,	1800.0,	1830.0,	1900.0,

1950.0,	1840.0,	1830.0,	1850.0,	1870.0,	0.0,	1540.0,	1530.0,	1460.0,
0.0,	1450.0,	1450.0,	1450.0,	1460.0,	1460.0,	1350.0,	1340.0,	1240.0,
1000.0,	970.0,	950.0,	940.0,	920.0,	900.0,	880.0,	860.0,	820.0,
780.0,	740.0,	720.0,	700.0,	680.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	1900.0,	1860.0,	1890.0,	0.0,	0.0,	1540.0,	1420.0,
1420.0,	1380.0,	1350.0,	1300.0,	1230.0,	1230.0,	1240.0,	1270.0,	1165.0,
1010.0,	970.0,	950.0,	930.0,	900.0,	880.0,	860.0,	850.0,	820.0,
780.0,	740.0,	720.0,	700.0,	660.0,	650.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	1620.0,	1560.0,	1560.0,	0.0,	1450.0,	1410.0,	1370.0,
1350.0,	1340.0,	1290.0,	1250.0,	1220.0,	1200.0,	1180.0,	1170.0,	1150.0,
1150.0,	1000.0,	960.0,	950.0,	920.0,	900.0,	880.0,	870.0,	840.0,
800.0,	740.0,	700.0,	660.0,	620.0,	575.0,	535.0,	480.0,	420.0,
380.0,	330.0,	-20.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	1540.0,	1510.0,	1480.0,	1450.0,	1430.0,	1400.0,	1360.0,
1340.0,	1330.0,	1280.0,	1230.0,	1210.0,	1190.0,	1150.0,	1120.0,	1090.0,
1060.0,	1020.0,	1000.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	610.0,	600.0,	550.0,	490.0,	440.0,	410.0,
380.0,	350.0,	-20.0,	-30.0,	-20.0,	-27.0,	-34.0,	-41.0,	-27.0,
-13.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	1530.0,	1490.0,	1480.0,	1450.0,	1430.0,	1410.0,	1410.0,
0.0,	1370.0,	1280.0,	1240.0,	1220.0,	1220.0,	1160.0,	1120.0,	1090.0,
1060.0,	1030.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	-0.0,
0.0,	0.0,	0.0,	580.0,	550.0,	500.0,	460.0,	440.0,	420.0,
370.0,	330.0,	-20.0,	-20.0,	-20.0,	-30.0,	-37.0,	-44.0,	-51.0,
-36.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	1530.0,	1480.0,	1450.0,	1440.0,	1530.0,
1530.0,	1410.0,	1360.0,	1350.0,	0.0,	1270.0,	1185.0,	1130.0,	1100.0,
1070.0,	1040.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	530.0,	480.0,	450.0,	430.0,	420.0,
380.0,	275.0,	-20.0,	-20.0,	-20.0,	-20.0,	-10.0,	-1.0,	10.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	1530.0,	1480.0,	1480.0,	1510.0,
1510.0,	1500.0,	1380.0,	0.0,	0.0,	1220.0,	1170.0,	1170.0,	1120.0,
1100.0,	1100.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	-30.0,	-20.0,	-20.0,	-27.0,	-34.0,	-41.0,	-48.0,
-55.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1520.0,	1430.0,	1370.0,	1370.0,	1220.0,	1200.0,	1165.0,	1140.0,
1110.0,	1120.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	-30.0,	-20.0,	-27.0,	-34.0,	-41.0,	-53.0,	-55.0,
-62.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	1400.0,	1390.0,	1180.0,	1180.0,	0.0,	0.0,	1150.0,	1120.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,	0.0,
0.0,	0.0,	30.0,	-20.0,	-30.0,	-20.0,	10.0,	20.0,	0.0,


```

0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 75.0, 75.0, 75.0, 75.0, 0.0, 0.0, 75.0, 75.0,
0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 0.0, 75.0, 75.0, 75.0, 75.0, 75.0, 75.0, 0.0,
0.0, 0.0,
0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 75.0, 75.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 0.0, 75.0, 75.0, 75.0, 75.0, 75.0, 75.0, 0.0,
0.0, 0.0,
0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
0.0, 0.0,
NV =
14000000000.000,
NH =
1200000000000.0,
RHO =
1000.,
&CNTRL START = 000.0,
PHOTST= 200.,
POUTPT=10.,
NHOTST=1500,
&MODPAR DELT =30.0
DELX =1.0,
DELY =1.0,
NFIN =-2400,
UPAI =100.0,
&METEO HEQL =925.0,
DELC =0.0,
GRADC =1.84,
GRADT =-0.0055,
ALFA1 =1820000,
ALFA2 =362000,
TDEL =-0.125,
SMIN =-15.0,
&END
&END
&END
&END
&END

```

APPENDIX-C: LISTING OF VECTOR FORTRAN

```

PROGRAM VECTOR
*****
*
*   PROGRAM FOR PLOTING VELOCITY FILED IN A GLACIER
*
*****
*
*   PARAMETER (JP=1, LENGTH=54, IWIDTH=33, LENP1=LENGTH+1,
&             IWIDP1=IWIDTH+1, LPLS=LENGTH+2, IWPLS=IWIDTH+2)
*
*   LOGICAL GRID
*
*   COMMON/BLK1/ ETA(LPLS, IWPLS), IGRID(LPLS, IWPLS)
*   COMMON/BLK2/ A(JP, LPLS, IWPLS), C(JP, LENP1, IWIDTH),
&             D(JP, LENGTH, IWIDP1)
*   COMMON/BLK3/ DELX, DELY, TIME, XMAX, YMAX, IWMAX, LMAX, IWMIN,
&             LMIN, SLEVEL
*
*   NAMELIST /MODPAR/ GRID, PLTSIZ, DELX, DELY, IWMAX, LMAX, IWMIN, LMIN,
&             SLEVEL, TIME
*
*
*   READ(1, MODPAR)
*   WRITE(*, MODPAR)
*   READ(2) ISTRT
*   READ(2) IGRID
*   READ(2) A
*   READ(2) ETA
*   READ(2) C
*   READ(2) C
*   READ(2) D
*   READ(2) D
*
*
*   DO 101 I=1, LPLS
*     DO 101 J=1, IWPLS
*       IF (IGRID(I, J).EQ.2) THEN
*         IGRID(I, J)=1
*       ENDIF
101  CONTINUE
*
*
*   XMAX=FLOAT(LMAX)*DELX
*   YMAX=FLOAT(IWMAX)*DELY
*   CALL DEVICE('CAL5500')
*   CALL HEADER('LIAQAT', 10)
*   FACT=PLTSIZ/XMAX
*   CALL PLOTS(0, 0, 14)
*   CALL FACTOR(FACT)
*   CALL PLOT(0.0, 0.0, -3)
*
*
*   IF (GRID) THEN
*     CALL MESH
*   ELSE
*     CALL BORDER

```

```

VEC00010
VEC00020
VEC00030
VEC00040
VEC00050
VEC00060
VEC00070
VEC00080
VEC00090
VEC00100
VEC00110
VEC00120
VEC00130
VEC00140
VEC00150
VEC00160
VEC00170
VEC00180
VEC00190
VEC00200
VEC00210
VEC00220
VEC00230
VEC00240
VEC00250
VEC00260
VEC00270
VEC00280
VEC00290
VEC00300
VEC00310
VEC00320
VEC00330
VEC00340
VEC00350
VEC00360
VEC00370
VEC00380
VEC00390
VEC00400
VEC00410
VEC00420
VEC00430
VEC00440
VEC00450
VEC00460
VEC00470
VEC00480
VEC00490
VEC00500
VEC00510
VEC00520
VEC00530
VEC00540
VEC00550

```

CALL VELO	VEC00560
ENDIF	VEC00570
*	VEC00580
999 CONTINUE	VEC00590
*	VEC00600
CALL PLOT(0.0,0.0,999)	VEC00610
*	VEC00620
STOP	VEC00630
END	VEC00640
	VEC00650
SUBROUTINE MESH	VEC00660
*****	VEC00670
*	VEC00680
* GENERATES GRID FOR THE VELOCITY VECTORS	VEC00690
*	VEC00700
*****	VEC00710
*	VEC00720
PARAMETER (JP=1, LENGTH=54, IWIDTH=33, LENP1=LENGTH+1,	VEC00730
& IWIDP1=IWIDTH+1, LPLS=LENGTH+2, IWPLS=IWIDTH+2)	VEC00740
*	VEC00750
*	VEC00760
COMMON/BLK1/ ETA(LPLS, IWPLS), IGRID(LPLS, IWPLS)	VEC00770
COMMON/BLK3/ DELX, DELY, TIME, XMAX, YMAX, IWMAX, LMAX, IWMIN,	VEC00780
& LMIN, SLEVEL	VEC00790
*	VEC00800
*	VEC00810
SLEN=DELX	VEC00820
ANGLE=0.0	VEC00830
SN=4.0	VEC00840
DO 10 J=1, IWMAX-1	VEC00850
JJ=J-1	VEC00860
NN=J+1	VEC00870
YP=FLOAT(JJ)*SLEN	VEC00880
DO 10 I=1, LENGTH	VEC00890
MM=I+1	VEC00900
IF(IGRID(MM, NN).EQ.1) GO TO 10	VEC00910
II=I-1	VEC00920
XP=FLOAT(II)*SLEN	VEC00930
CALL POLY(XP, YP, SLEN, SN, ANGLE)	VEC00940
10 CONTINUE	VEC00950
*	VEC00960
RETURN	VEC00970
END	VEC00980
SUBROUTINE BORDER	VEC00990
*****	VEC01000
*	VEC01010
* PLOTS THE BOUNDARY OF THE MODEL DOMAIN	VEC01020
*	VEC01030
*****	VEC01040
*	VEC01050
PARAMETER (JP=1, LENGTH=54, IWIDTH=33, LENP1=LENGTH+1,	VEC01060
& IWIDP1=IWIDTH+1, LPLS=LENGTH+2, IWPLS=IWIDTH+2)	VEC01070
*	VEC01080
COMMON/BLK1/ ETA(LPLS, IWPLS), IGRID(LPLS, IWPLS)	VEC01090
COMMON/BLK3/ DELX, DELY, TIME, XMAX, YMAX, IWMAX, LMAX, IWMIN,	VEC01100


```

JJ=J-1
U1=0.0
U2=0.0
V1=0.0
V2=0.0
DO 300 K=1, JP
  IF (SLEVEL.EQ.-1) THEN
    IF (A(K, I, J).LT.0.00001) THEN
      TRIG=1.0
    ELSE
      TRIG=(SIN(A(K, I, J)))/(A(K, I, J))
    ENDIF
  ELSE
    TRIG=COS(A(K, I, J))*(2.0-SIGMA)*0.5
  ENDIF
  U1=U1+C(K, II, JJ)*TRIG
  U2=U2+C(K, I, JJ)*TRIG
  V1=V1+D(K, II, JJ)*TRIG
  V2=V2+D(K, II, J)*TRIG
300 CONTINUE
  U=86400*(U1+U2)*0.5
  V=86400*(V1+V2)*0.5
  XMAG(II, JJ)=(U**2+V**2)**0.5
  IF (U.EQ.0.0.AND.V.EQ.0.0) THEN
    DIR(II, JJ)=0.0
    GO TO 100
  ENDIF
  DIR(II, JJ)=ATAN2(V, U)
100 CONTINUE
*
VMAX=0.0
DO 20 I=1, LENGTH
  DO 20 J=1, IWIDTH
    IF (XMAG(I, J).GT.VMAX) VMAX=XMAG(I, J)
20 CONTINUE
VMAX=1.0
FUDGE=DELX/VMAX
DO 600 I=1, LENGTH
  DO 600 J=1, IWIDTH
    XMAG(I, J)=XMAG(I, J)*FUDGE
600 CONTINUE
*
ID=0
DO 10 J=IWMIN, IWMAX
  ID=ID+1
  JJ=J-1
  YPAGE=(FLOAT(ID-1)*DELY+DELY*0.5)
  IC=0
  DO 10 I=LMIN, LMAX
    IC=IC+1
    II=I-1
    XPAGE=(FLOAT(IC-1)*DELX+DELX*0.5)
    IF (IGRID(I, J).EQ.1) GO TO 10
    AHLEN=XMAG(II, JJ)
    XTIP=AHLEN*COS(DIR(II, JJ))+XPAGE
    YTIP=AHLEN*SIN(DIR(II, JJ))+YPAGE
    AHLEN=AHLEN*0.2
    CALL AROHD(XPAGE, YPAGE, XTIP, YTIP, AHLEN, 0.0, 11)
10 CONTINUE
*
CALL PLOT(0.0, , 3)

```

VEC01670
 VEC01680
 VEC01690
 VEC01700
 VEC01710
 VEC01720
 VEC01730
 VEC01740
 VEC01750
 VEC01760
 VEC01770
 VEC01780
 VEC01790
 VEC01800
 VEC01810
 VEC01820
 VEC01830
 VEC01840
 VEC01850
 VEC01860
 VEC01870
 VEC01880
 VEC01890
 VEC01900
 VEC01910
 VEC01920
 VEC01930
 VEC01940
 VEC01950
 VEC01960
 VEC01970
 VEC01980
 VEC01990
 VEC02000
 VEC02010
 VEC02020
 VEC02030
 VEC02040
 VEC02050
 VEC02060
 VEC02070
 VEC02080
 VEC02090
 VEC02100
 VEC02110
 VEC02120
 VEC02130
 VEC02140
 VEC02150
 VEC02160
 VEC02170
 VEC02180
 VEC02190
 VEC02200
 VEC02210
 VEC02220
 VEC02230
 VEC02240
 VEC02250
 VEC02260
 VEC02270

```

XPAGE=7.0*DELX
YPAGE=5.0*DELY
YM= 0.10*YL
HEI=0.6*DELX
CALL SYMBOL(XPAGE,YPAGE,HEI,'TIME(YEARS): ',90.0,13)
YPAGE=YPAGE+7.5*DELY
CALL NUMBER(XPAGE,YPAGE,HEI,TIME,90.0,0)
XP=8.0*DELX
YP=5.0*DELY
CALL SYMBOL(XP,YP,HEI,'SCALE(M/DAY): ',90.0,13)
OMAG=0.01
YP=13.0*DELY
XTIP=8.0*DELX
YTIP=YP+VMAX*FUDGE
AHLEN=VMAX*0.15
CALL AROHD(XP,YP,XTIP,YTIP,AHLEN,0.0,11)
XP= 9.0*DELX
YP= 12.5*DELY
CALL NUMBER(XP,YP,HEI,VMAX,90.0,1)
XM=XL-10.0*DELX
YM=4.0*DELY
CALL SYMBOL(XM,YM,HEI,'VELOCITY FIELD OF THE TAKU GLACIER',
&          90.0,34)
XM=XM+2.0*DELX
YM=YM+5.0*DELY
IF(SLEVEL.EQ.2.0) THEN
    CALL SYMBOL(XM,YM,HEI,' S',          ',
&          90.0,24)
ELSE IF(SLEVEL.EQ.0.0) THEN
    CALL SYMBOL(XM,YM,HEI,' B',          ',
&          90.0,24)
ENDIF
*
RETURN
END

```

VEC02280
 VEC02290
 VEC02300
 VEC02310
 VEC02320
 VEC02330
 VEC02340
 VEC02350
 VEC02360
 VEC02370
 VEC02380
 VEC02390
 VEC02400
 VEC02410
 VEC02420
 VEC02430
 VEC02440
 VEC02450
 VEC02460
 VEC02470
 VEC02480
 VEC02490
 VEC02500
 VEC02510
 VEC02520
 VEC02530
 VEC02540
 VEC02550
 VEC02560
 VEC02570
 VEC02580
 VEC02590
 VEC02600
 VEC02610
 VEC02620

APPENDIX-D: INPUT DATA FILE OF VECTOR FORTRAN

```
&MODPAR  GRID  =.F.,  
          PLTSIZ= 8.0,  
          DELX  =1.0,  
          DELY  =1.0,  
          IWMAX =35,  
          LMAX  =56,  
          IWMIN =1,  
          LMIN  =1,  
          TIME  =200.0,  
          SLEVEL=2.0,      &END
```