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# MODELING THE APALACHICOLA SYSTEM



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A Hydrodynamic and Water guality Model With a Hydrodynamic and Water }uality Atlas of Apalachicola Bay Project No. R/EM-13

By

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#### 1. INTRODUCTION

The present report discusses the establishment of a numerical model of the Apalachicola system consisting of the River, its tributaries and the biologically highly productive Apalachicola Hay. Much of the material has been published elsewhere in the form of reports (e.g., Graham, DeCosta, and Christensen, 1978), scientific papers (e.g., Christensen, 1979, Graham and Christensen, 1978) and bulletins of a more general nature (e.g., Hill and Graham, 1980).

The present report should therefore be considered as a review of the progress made with special emphasis on the final results that are presented in the form of an atlas depicting the hydrodynamics and pollutant migration in the Apalachicola 6ay during an "average" year taking tidal flushing as well as wind and river flow into consideration. This atlas will allow the reader to determine water velocity, orientation of water velocity, water quality corresponding to any known water quality in the river, and salinity of the bay waters. The atlas is attached to the present report. as Appendix A. The complete verified numerical model is attached as Appendix S on computer tape.

#### 1.1 Logistics of Model Approach

Man's development of drainage basins draining to estuarine waters will always have an impact on the quality of these waters and therefore also on the biological system of the estuary in question. In the case of Apalachicola Bay this has clearly been demonstrated by Livingston (Livingston et al., 1981). A further impact on the economy depending on the estuarine biosystem and the ocean biosystem its supports must therefore be expected and should be considered by the responsible developer.

Such a consideration is certainly justified when it is recalled that our estuarine systems are among the most productive areas as far as biomass is concerned. Figure 1.1 shows a comparison of biomass production in ton per acre per year for typical areas. It should be noted that the estuarine production is two to four times that of our best agricultural land areas



Figure 1.1. Comparison of Biomass Production Rates. (Source: Teal and Teal, 1969).

that, by the way, only can sustain their high production rates by extensive use of fossil fuel based fertilizers.

It is therefore recommended that the impact of development is evaluated and that the results of the evaluation is fed back to the developers or developing agencies to insure optimum utilization of our coastal resources,

Figure 1.2 is a flow chart showing the logistics of optimum land utilization by use of computer models. It is noted how the development's impact on the riverine system is evaluated by a predictive model and the output from this model serves as input to the estuarine model. The output from the estuarine model will again provide information enough in the form of water velocities, pollutant concentrations and salinities to enable the marine biologist to evaluate the impact on the estuary's biosystem. From these the economists may draw their conclusions as to the impact on the region's economical system which will serve as a foundation for further action in the political system providing the feedback to the planners and developers. A slighly more detailed flow chart is given in Figure 1.3.



Figure 1.2. Logistics of Model Approach.



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**The** utilization of computer models in this scheme is of course quite obvious **since** physical models or full scale experimentation would be economically unrealistic **if** not completely impossible.

Since this work deals **with** large areas of **land and sea.it is logical to** utilize satellite imagery as input to the models **and** for verification of the **results obtained by the models. This** is **indicated in Figure 1.2. Input** from the LANDSAT system is **suggested in the river** model. For instance **the LANDSAT images** will **give information** about **the** present utilization of the land by colors as shown in **the** example of Figure 1.4 **indicating how the** drainage **basin** is **used** for **silviculture in the neighborhood of Apalachicola** Bay.



Figure 1.4. Computer Enhanced LANDSAT Image of Area North of Apalachicola Bay Showing Silvicultural Activities. August 19, 1976.

In Figure 1.4 white indicates sand or urban development while the color green shows marsh, swamp or natural forest. Purple areas are clearcut forest that has been harvested within one year of the date of the image. Orange is showing revegetated forest areas.

LANDSAT images enhanced for color (quality) of surface waters are used for verification by pattern recognition of water quality as discussed later in this report and by Graham, Hill and Christensen (1978).



Figure 1.5. LANDSAT Image of Apalachicola Bay Computer Enhanced for Water Quality. Outgoing Tide.

Verification data are of course also obtained by direct observation of velocities and salinities in the bay.

#### 1.2 The Apalachicola Basin/Estuary System

The Apalachicola Basin and Estuary system was selected for the modeling effort described in this report because of its relative simp1icity as far as pollution and pollution sources go. Pollution of the river and bay waters is at the present time generally limited to a lowering of the pH probably caused by clearcutting of areas around East Bay. This phenomenon has been extensively studied and recorded by Livingston (Livingston, 1981) during the Iast decade. Information relating the increased acidity of the waters to the silvicultural activities is scarce and has not been available to the writers.

Although the model developed and verified in this report is specifically dealing with the Apalachicola system it should be emphasized that the general methodology applied may be used in other river-bay systems.

As shown in Figure 1.6 the water entering the Apalachicola Bay may originate as far away as from the Atlanta, Georgia, region from where it enters the Apalachicola River primarily through the Chattahoochee and Flint rivers. Briefly, the basin is about  $50,500$  km<sup>2</sup> in area and the Apalachicola River proper is considered to begin at the Florida line and flows about 170 km to the Gulf of Mexico. The river has been improved by the U.S. Army Corps of Engineers to Bainbridge, Georgia, and a large reservoir has been established at the Florida line.

The Apalachicola River has very good hydrologic data. The mean yearly hydrograph for the decade 1967 through 1976 is shown in Figure 1.7. The yearly average discharge is about 700  $m^3 s^{-1}$ . This is a substantial

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Figure 1.6. The Apalachicola River/Bay System with Tributaries.

discharge. However, compared to the rate of tidal exchange of waters in the bay it is very small. The river is therefore having only a limited influence on the hydrodynamics of the Apalachicola Bay.

Apalachicola Bay, shown in Figure 1.8, is a barrier island-contained estuary on the Florida Panhandle. It is geomorphically typical of such systems, but is significant because of the importance of its waters to marine life (Livingston, 1981). At present, it suffers relatively low levels of point-source pollution.

The bay is about 550 Km<sup>2</sup> in area, depending upon where the boundaries are drawn. Mean depth is about 2 meters and is everywhere less than 3 meters except in West Pass. As expected the system is dominated by the





Figure 1.7. Mean Year'ly Hydrograph for Apalachicola River for 1961 - 1976.

Apalachicola River whose mean annual discharge is about 700  $m^3/s$ . The mean tidal range at Apalachicola is 0.40 m. The tidal prism is thus 220 million  $m^3$  on the average and the mean residence time per river water about 17 days,

In general the bay is shallow, well -mixed and prone to being winddriven. Little else is known about its hydrography. It is quite remarkable that the entire literature on the hydrography of one of the largest estuaries on the Gulf Coast can be easily read in about fifteen minutes. Most of the hydrographic data has been collected by biologists and is not readily useful for engineering or oceanographic purposes, nor has it been

interpreted in a physically rigorous manner. Figure 1.8 shows the major points of hydraulic interest in the modeling effort. These are, beginning at the east side and proceeding in a clockwise manner, East Pass between St. George Island and Dog Island, Sikes Cut penetrating St. George Island, West Pass between Sand Island and St. Vincent Island, Indian Pass between St. Vincent Island and the Florida Panhandle, the Apalachicola River entering the bay north of the city af Apalachicola, and East Bay receiving much of the runoff from the land areas used for silviculture in Franklin County.

The following Figures 1.9 through 1.21 are aeria1 photos of these points taken from the flight path in Figure 1.8 at the locations marked A through M.

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Flight Path Used When Figures 1.9 Through 1.21 Were Taken Figure 1.8. The Apalachicola Bay.



Figure 1.9. Apalachicola Bay. VIEN A: East Pass Seen from South. Left: St. George Island. Right: Dog Island.



Figure 1.10. Apalachicola Bay. VIEW B: St. George Island at Rattlesnak Cove and Goose Island Seen from South.



Figure 1.11. Apalachicola Bay, VIEW C. St. George Island at Causeway Seen rrom Sout



Figure 1.12. Apalachicola Bay. VIEW 0. St. George Island betwee Causeway and Sike Cut Seen from **South.**



Figure 1.13. Apalachicola Bay. VIEW E. Sikes Cut Seen from the Nexican Gulf.



Figure 1.14. Apalachicola Bay. VIEW F. Nest Pass Seen from Southwest. Left: St. Vincent Island. Right: St. George Islan Sand Is1andj.



Figure 1.15. Apalachicola Bay. VIEW G. Indian Pass Seen from Southwest.<br>Right: St. Vincent Island.



Figure 1.16. Apalachicola Bay. VIEW H. Indian Pass Seen from Southwest.<br>Left: St. Vincent Island.

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Figure 1.17. Apalachicola Bay. VIER I. North Shore of Bay at Green Point Seen from Northwe



Figure 1.18. Apalachicola Bay. VIEW J. The Apalachicola River Entering Bay at City of Apalachicola (Right) Seen from Northwest John Gorrie Memorial Bridge.



Figure 1.19. Apalachicola Bay. VIEW K. East Bay Seen from Southeast.



Figure 1.20. Apalachicola Bay. VIEW L. St. George Island Causeway Seen from North.



Figure 1.21. Apalachicola Bay. VIEW M. East Pass Seen from West. Left: Dog Island. Right: St. George Is1and.

# 1.3 Classification of Apalachicola Bay

Estuaries are often classifed- according to the degree and manner in which they are stratified. Stratification is a function of river flow, tidal prism, volume, depth-wide ratio, density difference, hydraulic roughness and so forth. Classification schemes have been proposed (Pritchard, 1970, 1973) which are based on several dimensionless parameters:

$$
\frac{P}{TQ}, \frac{P_2 - P_1}{2}, \frac{D}{L}, \frac{R}{D}
$$
 (1.1)

where

- $T =$  tidal period (12.42 hr) P = tidal prism
- 
- $Q =$  river discharge
- $p_1$ ,  $p_2$  = characteristic extreme densities
	- L = estuary length
	- $D = average$  estuary depth
	- $R = tidal range$

If  $\rho_{\textsf{1}}^{\textsf{}}$  corresponds to s (salinity) = 0 and  $\rho_{\textsf{2}}^{\textsf{}}$  to s = 32% (ocean value) and R is (almost) constant, then any classification scheme must be a function of at least 2 parameters - one expressing inertial mixing ability and the other reflecting geometry. For a given estuary, geometry and hydraulic characteristics are fixed so a classification scheme is primarily based on

$$
\frac{P}{TQ} \tag{1.2}
$$

and, since T is also fixed, it can be seen to be a simple function of retention time providing the estuary depth is not greatly dependent upon river discharge.

The foregoing analysis has not considered wind shear, which is a very important mixing mechanism for small  $D/L$ .

Considering the above and Pritchard's estuarine classification scheme shown in Figure 1.22 the Apalachicola Bay may be characterized as a width dominant estuary controlled by tidal currents originating from astronomical as well as wind tides. It is **a** type D estuary.

# 1.4 The Apalachicola Bay N<u>umerical Model and Atlas of Hydrodynamic</u> <u>ang water uuai</u>

Since the Apalachicola Bay is only slightly influenced by the river discharge as far as the bay's hydrodynamics goes it was decided to use the mean yearly hydrograph for Apalachicola River shown in Figure 1.7 as river model input to the hydrodynamic estuarine model.

Water velocities, their orientation and water surface elevations are modeled by use of the Wang-Connor CAFE-1 model (Wang and Connor, 1975). This is a vertically integrated finite element model.



Figure 1.22. Pritchard's Estuarine Classification Scheme. Pritchard  $(1970, 1973)$ .

Water quality is modeled by use of the Wang-Connor DISPER-1 model (Wang and Connor, 1975) and the output from the CAFE-1 model. DISPER-1 is also a finite element model.

Since very 'little is known about the present and future water quality of the river an arbitrary pollution concentration of 100 units have been used in the quality model. This, together with a fairly simple formula for conversion of the computer printout will allow the user of the reported results to compute the water quality at any location and time in the bay corresponding to any pollutant concentration in the river. At the present time the quality model is limited to conservative pollutants. However, later introduction of decay and generation terms in the governing equation will allow extention to nonconservative substances.

The final results are given for the 12 months of the typical year during which average tides, winds and river flow are presumed to prevail. The conditions are given for the typical tidal cycle for each month. Yelocity, net velocity as well as water quality corresponding to river concentration 100 are given. Conditions are given for time increments equal to one-eighth of a tidal cycle beginning at low tide. Thus each month will be represented by 8 velocity maps, I net velocity map, and 8 water quality maps. The total of these 204 maps makes up the atlas given at the end of this report,

#### 2. SELECTION OF MODELS

A short discussion of the selection of the model is given in this chapter. For a more complete discussion the reader is referred to an earlier report to Sea Grant (Graham, DeCosta and Christensen, 1978).

#### 2.1 Criteria for Selection

The primary criterion for selection of any model must of course be their ability to accurately reflect existing and projected behavior in the water body of interest. The basic characteristics of behavior of Apalachicola Bay are described briefly in Section 1 of this report and in more detail by Graham, DeCosta and Christensen (1978). It was concluded that a two-dimensional vertically, averaged numerical model was appropriate for Apalachicola Hay due to its generally well-mixed body of water. It is likely that Apa'Iachicola 8ay would represent the case in Florida where this assumption is most marginal, so that application to most other Florida estuaries wou1d be justified.

It was felt that a real-time hydrodynamic capability was required to properly simulate transient velocities and quality in the bay, since tidal flow dominates and stormwater inflow is transient by definition. Since many of the concentration terms (of the form  $\overline{u^i c^r}$ ) in the equations are nonlinear, it is not justified to use tidally-average net-flow models.

A primary goal was to reduce the sub-grid scale eddy diffusivity so that the quality model will be as predictive as possible.

While the real-time 2-D hydrodynamic and dispersion models are definitely state-of-the-art, 3-D and multi-layer models are not (in the author's opinion). While promising results are being made with 2-layer and multi-layer models, they must still be considered to be in a development

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phase at least in terms of the capabilities of most potential users in Florida. Data requirements for loading a mul tilayer model are formidable, so the likelihood of re1iable applications is even further removed.

To summarize, the selection criteria used were:

- 1) model must be a least two-dimensional
- 2) model must simulate transient conditions
- 3) model must be sophisticated, yet readily available, proven, and tested
- 4! model must be nonproprietary, or documented to the extent that it is effectively nonproprietary
- 5! model must be "state-of-the-art", but past the research phase
- 6) model must be able to be run by users with reasonable proficiency
- 7! model must be able to be run at a reasonable cost
- 8) model must be flexible, not site-specific, in its applicabi1ity
- 9) model must be compatible with a water quality package
- 10) model must be able to simulate conditions typical of the Apalachicola, and most other Florida estuaries, viz.:
	- a) shallow
	- b) influenced by freshwater inflow, tides and wind.

#### 2,2 Models Considered

Earlier reports and papers describe the several models considered for application to Apalachicola Bay according to the criteria in Section 2.1. The strategy was to select a model for the hydrodynamics first.

After this model was chosen, a compatible water quality model could he selected.

Among models considered were the following, wi th more detail given by Graham (1977), Graham, DeCosta and Christensen (1978), and Graham, Daniels and Christensen (1979).

- $1.1$ Hydroscience Estuary Model (Hydroscience, 1977).
- 2. Dynamic Estuary Model (also forms the receiving water model, RECEIV, for the EPA Storm Water Management Model (SWMM) - (Feigner and Harris, 1970)). See also Huber et al. (1975).
- 3. Leendertse Finite-Difference Model (Leendertse, 1967).
- 4. Masch Gulf Coast Model (Masch et al., 1969).
- 5. M. I.T. Finite Element Models

CAFE-1 for hydrodynamics (Wang and Connor (1975), Pagenkopf et al. (1976))

DISPER-1 for water quality (Leimkuhler, et al. (1975), and Pagenkopf et al.  $(1976)$ )

A number of other models were considered and discarded at an early stage, especially those with no real time tidal characteristics (which is also true of model 1 above). Extensive reviews are provided elsewhere and will not be repeated here.

#### 2.3 Models Selected

Based on a review of available models, coupled with the criteria presented in Section 2.1, it was decided that one package, the CAFE-l, DISPER-1 system developed at M.I.T. (also for Sea Grant) seemed overwhelmingly superior. In addition to technical and verification advantages, it was deemed important to select this finite element model for several reasons:

1) it provides more flexibility in discretizing the spatial net,

- 2) nodes can be placed at known measurement stations,
- 3) finite element models were recommended by Dr. Frank Masch, formerly of WRE, **and** Dr. **John** Wang of **the** University of hami, **both** recognized experts in the field,
- 4) Wang and Connor's (1975) finite element model has recently been applied by Swakon and Wang (1977) to **Biscayne Bay** with good **resuIts,**
- and 5) tapes and advice are available from Dr. Wang at the University of Miami.

## 3. SPECIFIC FEATURES OF MODELS USED

In the following, only sufficientmodel detail will be presented to enable understanding model features and limitations. More detail can be found in the basic references and in earlier Sea Grant reports on this work. (See, for example, Graham, Daniels and Christensen, 1979).

## 3.1 The CAFE-1 Model

# 3.1.1 General Description

The CAFE-1 (standing for 1-layer Circulation Analysis by Finite Elements) model was developed and tested by M.I.T. (Wang and Conner, 1975). It has the following general properties:

- 1) Real time, i.e., describing velocities and depths through the tidal cycle.
- 2) Finite-element formulation.
- 3) Implicit time stepping.
- 4) One-layer, i.e., it is vertically integrated.

The model differs from other popular ones based on the Leendertse finite-difference format in that a finite element computation scheme is used. This computational scheme is more complicated, but has two very si gni fi cant advantages:

- 1) The elements can be of different size.
- 2) The elements can assume almost any configuration, providing a triangular network is used.

Thus, the finite element grid can very closely approximate the geometrical boundaries of the body of water being modeled, while a finite difference scheme must approximate the boundary as the edges of squares.

Since the finite element grid sizes can be of arbitrary size (usually finite difference meshes are of one size), the grid can be made finer in narrow enclosed areas as well as in areas of interest. Conversely, the grid size can be made more coarse in 1 arge open areas, and in areas outside of the region of interest. The advantage of having finer resolution only in the region of interest is that computing costs, which are proportional to number of elements, are reduced. The advantage of closely approximating the boundary geometry in a hydrodynamic model is also quite important for obvious reasons. Since pressure terms dominate, and these are easy to measure and/or obtain from published data, for instance from tide tables, and since the results are not greatly sensitive to reasonable value choices of bottom roughness (Manning's  $n$ ) and internal stress coefficients it follows that a very good approximation to the circulation can be computed with very little (and inexpensively acquired) input data. Since verification and calibration of numerical models can be quite expensive, one which is intrinsically quite accurate can reduce total modeling costs substantially by minimizing the empirical modification requirements.

During the study period, several grids were utilized to model Apalachicola Bay. Each was generally characterized by finer grid higher resolution) in the East and West Bayou areas and in the East Bay region, with moderate refinement in the Sikes Cut area and coarser grid elsewhere. Other specialized grids could easily be developed to study other features in the bay, although experience has shown that each new grid has special problems in model stability and convergence to be overcome. These problems will be discussed in more detail later.

Inputs to CAFE-1 include

1) a grid, which requires nodes and elements to be defined

2) depths at each node

- 3) boundary orientations
- 4! wave amplitude, phase and/or flux at boundaries
- 5) latitude
- 6) wind speed and direction
- 7) Manning roughness
- 8) internal stress operator controlled

These are relatively easy to come by, at least for the United States. Outputs include

- 1) unit discharge vectors and/or velocities
- 2) heights above mean low water

for every node point for every timestep. In this case, the unit discharge values  $(q_x$  and  $q_y$  and a height were output for each node for a tidal cycle of 744 minutes.

about \$25.00 on the University's IBM 3033 System for simulation of four tidal cycles. For preliminary purposes the water level was initially set to zero and the model run until a periodic steady state was achieved (by 3 tidal cycles). The output data for a steady tidal cycle were then written on a disk. The data on the disk could then be manipulated and/or called for graphical display, or used as input to the dispersion model DISPER-l. For sinusoidal tides, repeating over each cycle, and use of a single cycle called from memory to drive DISPER-1 result in considerable savings. The CAFE-1 program results presented later for the gridwith 281 nodes and 439 elements, shown in Figure 3.1, typically took about 450 seconds CPU time at a cost of

The CAFE-1 model, as mentioned, was originally developed at the R.M. Parsons Laboratory at M.I.T. It has been applied to



Figure 3.1. Finite Element Grid System of Apalachicola Bay Used in this Study.

- 1) Massachusetts Bay (Briggs and Madsen, 1973); (Christodoulou et al.,  $1974$ ); (Connor et al.,  $1973$ ); and (Parker and Pearce, 1975!.
- 2) Narragansett Bay (Connor and Wang, 1974); (Swanson and Spaulding, undated).
- 3) Great Bay, N.H. (Cellikol and Reichard, 1976); (Swanson et al., 1977}.
- 4) Mareton Bay, Australia (Steele et al., 1977).
- 5) Biscayne Bay, Florida (Sengupta et al., 1978); (Swakon and Wang, 1977).
- 6! Lake Pontchartrain done at Louisiana State Uni versi ty.

A'Il of the known successful applications appear to have been made by M.I.T. trained personnel, with the exceptions of the Lake Pontchartrain study and this University of Florida study.

These latter two studies, therefore, reflect the degree to which the models are available to the public. Both LSU and VF personnel have been able to run the programs, but it was concurred in private communications that the package is, as yet, somewhat underdocumented for most users. In some instances, the lack of documentation merely forces the user to better understand the model before using it. In some cases, however, required units or other items are unclearly specified and can cause considerable confusion. In any event, current model use requires personnel knowledge in both hydrodynamics and computer programming. Based, again, on a comparison of respective progress at I SU and UF, it appears that a training period of 6 to 8 months full time is necessary before satisfactory results and progress can be obtained with this model package. This is not

inherently unreasonable, but it should underline the necessity of establishing continuity in terms of personnel capability.

An excellent outline of model properties and capabilities at a lay level, including potential user applications, is given in an M.I.T. Marine Industry Advisory Services Opportunity Brief.

The models are currently avai lable from the Parsons Laboratory, Department of Civil Engineering at N. I.T., and from Dr. John Wang, Department of Ocean Engineering at the University of Miami. Users manuals are also available from M.I.T. Acquisition costs for both models (CAFE and DISPER), (not debugged) were about \$70.00. This reasonably covers cost in 1978 dol1ars.

The tape containing the CAFE-1 and DISPER-1 models modified for the Apalachicola Bay is available from the kydrau'Iic Laboratory, University of Florida. A copy of this tape is attached as Appendix B to this report in its original copy submitted to the Florida Sea Grant.

#### 3.1.2 Equations for CAFE-1

Wang and Connor (1975) present the most complete derivation of the equations. In the process of equation development, averaging over time (to remove turbulence terms) and space (to reduce the equations to two dimensions) occurs. Such averaging always introduces additional coefficients into the equations and changes the meaning of many terms. For example, dispersion coefficients will include effects of depth averaging as well as turbulent diffusion. Graham, Daniels, and Christensen (1979) follow the outline of Swakon and Wang (1977) to present the basic equations. Several variables must be introduced, including vertically integrated discharges per unit width  $(\mathsf{q}_{\mathsf{x}}^{\phantom{\dag}}$  and  $\mathsf{q}_{\mathsf{y}}^{\phantom{\dag}})$  in the two coordinate directions (x and y) and surface displacement above mean low water, n.
The total depth, H, is then given by

$$
H = \int_{-h}^{h} dz = h + n \tag{3.1}
$$

in which

**z =** vertical coordinate

 $h =$  depth at mean low water  $(MLW)$ 

Conservation of mass: The basic equations can be written as follows:

$$
\frac{\partial H}{\partial t} + \frac{\partial q_x}{\partial x} + \frac{\partial q_y}{\partial y} = q_I
$$
 (3.2)

Conservation of momentum in x-direction:

$$
\frac{\partial q_x}{\partial t} + \frac{\partial (uq_x)}{\partial x} + \frac{\partial (uq_y)}{\partial y} - fq_y
$$
  
+ 
$$
\frac{1}{\rho} \left[ \frac{\partial}{\partial x} \int_{-h}^{h} p dz - p^5 \frac{\partial H}{\partial x} - p^b \frac{\partial h}{\partial x} \right]
$$
  
- 
$$
\frac{\partial}{\partial x} (F_{xx}) - \frac{\partial}{\partial y} (F_{xy}) + \frac{r^5 - r^b}{\rho} - \overline{M}_x = 0
$$
 (3.3)

Conservation of momentum in y-direction:

$$
\frac{\partial q_y}{\partial t} + \frac{\partial (vq_x)}{\partial x} + \frac{\partial (vq_y)}{\partial y} + fq_x
$$
  
+  $\frac{1}{\rho} \left[ \frac{\partial}{\partial y} \int_{-g}^{\eta} p dz - p^5 \frac{\partial H}{\partial y} - p^b \frac{\partial H}{\partial y} \right]$   
-  $\frac{\partial}{\partial y} (F_{xy}) - \frac{\partial}{\partial y} (F_{yy}) + \frac{\tau^5 - \tau^b}{\rho} - \overline{M}_y = 0$  (3.4)

in which  $f =$  Coriolis parameter = 2  $\cdot$   $\omega_{parth}$   $\cdot$  sin 29° corresponding to the latitude of Apalachicola Bay  $p = pressure$  $p^5 = a$ atmospheric pressur  $p^b$  = bottom pressure  $\tau^5$  = surface stres  $\tau^b$  = bottom stress  $p =$  local density of water in the bay  $q_T$  = volume addition rate  $t = time$  $u = q_v/H =$  local mean velocity in x-direction  $(3.5)$  $(3.6)$ q<sub>y</sub>/H = local mean velocity in y-direct  $x, y =$  Cartesian coordinates (horizontal) internal specific stress terms (stress/density F<sub>xy</sub>,F<sub>yy</sub> = internal specific stress terms (stress/o<br>sometimes termed "turbulent eddy viscos" coeffi cients"  $\overline{M}_{x}$ , $\overline{M}_{y}$  = momentum addition per unit horizontal area A Bouissinesq approximation is used in the pressure terms, viz:

$$
\frac{\partial}{\partial x} \int_{-h}^{h} p dz - p^5 \frac{\partial n}{\partial x} p^b \frac{\partial h}{\partial x} \sim \rho_0 qH \frac{\partial n}{\partial x} + H \frac{\partial p^5}{\partial x}
$$
  
+  $\frac{1}{2} qH^2 \frac{\partial \Delta p}{\partial x}$  (3.7)

Here in the x-direction. A simi1ar equation is derived for the y-direction.

$$
\rho(x,y,t) = \rho_0 + \Delta \rho(x,y,t) \tag{3.8}
$$

with the usual definitions. For practical purposes the effect of the atmospheric pressure usually induces a 1 cm change in

sea level; this may not be readily justified. The reason for doing so is simply that these data are not available. Since most estuaries are small in scale compared to weather systems, only a constant error resu1ts. If the MLW is assumed to be a flat arbitrary datum (which, again, for practical purposes is a necessary assumption in most cases), then no detectable error results.

The term  $\frac{1}{2}$  g H<sup>2</sup>  $\frac{\partial \Delta p}{\partial x}$  is also often ignored. Based on the premise that most passive pollutants do not change the density field. An exception, of course is salinity.

The internal stress coefficients, can be written as

$$
F_{ij} = \frac{E_{ij}}{(2\delta_{ij})} \left( \frac{\partial q_i}{\partial x_j} + \frac{\partial q_j}{\partial x_i} \right)
$$
 (3.9)

where E<sub>ij</sub> are the turbulent eddy viscosity coefficients, which can be manipulated. In practice, the terms E<sub>ij</sub> serve several functions, includin

- 1) Expressing "true" turbulent eddy viscosity (assuming the validity of a mixing length analogy).
- 2) "Internalize" Reynolds stress terms lost in averaging over the depth.
- 3) "Internalize" horizontal Reynolds stress terms of such scale that the grid cannot resolve them.
- 4) Expressing true molecular viscosity. This component is of course of negligible importance at these scales.
- 5) An adjustment coefficient to calibrate the model.
- 6) Help stabilize the model.

Addition of the  $\mathsf{F}_{\mathbf{i}\,\mathbf{j}}$  terms essentially adds some elegance to the model. Leendertse's (1967) 2-D finite-difference model neglected these terms. They were included by Wang and Connor (1975) because

"We feel that the inclusion of  $\vdash_{\dagger \mathbf{j}}$  has several attract properties. It a1lows for internal friction and thereby energy dissipation, provided  $E_{i,j}$  is positive; it does represent actual physical processes (although not accurately and it is particularly suitable for damping short wave noise generated by numerical methods."

Note that no explicit stability criteria have yet been developed for CAFE-1, at least as reported by Wang and Connor (1975), so inclusion of a damping term for high-frequency noise is very useful. In comparison, explicit stability criteria are known for a finite-difference grid of constant element size.

The model does not seem particularly sensitive to values of  $F_{\text{ij}}$  as noted by Connor and Wang (1975). A comparison of E<sub>ij</sub> values will be presented shortly. A significant test to determine whether a numerical model application is credible and predictive lies in the values given the "adjustment coefficients", such as E<sub>ij</sub> and n (Manning roughness coefficient in CAFE-1, and the dispersion coefficient D<sub>ij</sub> in DISPER-1. If these coefficients have values which are reasonable in relation to values used in analytic hydrodynamic approximations (taking the grid size into consideration), then some confidence can be placed in the predictability of the model. If extraordinary values of "adjustment coefficients" have to be used to match the model output to measured data, then the application is likely unique (or incorrect). This comparison may be a more valid "bottom line" test than a comparison of model output to measured data.

Note that the gradient terms  $(aq_i/\partial x_i, \ldots)$  in Equation (3.9) are approximated by finite values on the grid, and error results if the grid is non-zero in size. The values of F<sub>ij</sub> and E<sub>ij</sub> are therefore functions of the 1ocal grid scale as well as hydrodynamics.

The bottom stress terms in Equations  $(3.3)$  and  $(3.4)$  use the generally accepted quadratic approximation:

$$
\tau_{x_i}^b = C_f \rho_0 (q_{x_i}^2 + q_{x_j}^2)^{1/2} \frac{q_{x_i}}{H^2}
$$
 (3.10)

in which

$$
C_f = \frac{n^2q}{n^{1/3}}
$$
 (3.11)

n = Manning's "n"

and  $q =$  acceleration due to gravity.

Therefore,

$$
\tau_{x_{\hat{1}}}^{b} \sim \frac{1}{H^{7/3}}
$$
 (3.12)

For shallow estuaries then, significant improvement in the output quality is achieved by computing the velocities using instantaneous values of total depth, since the tidal range is a significant proportion of total depth. Note that Manning's "n" is another "adjustment coefficient". Reasonable values are well known however, and lie in the range 0.020 to 0.040. [Most values of n have been computed for rivers. However, some study is required to find appropriate values for flow over oyster bars and shelllittered bottoms.]

The wind stress term  $\tau^{\text{S}}/p$  warrants qualitative discussion. Recent oceanographic studies have indicated that wind is a far more important energy input source to estuaries then had heretofore been surmised Weisberg, 1976). Most Florida estuaries can be considered to be wind dominated. Work at the University of Florida in coastal canals indicates wind is much more influential in flushing than tidal action (see Morris, Walton, and Christensen, 1978). Tidal measurements by Hydraulic Lab personnel show that wind-set up can be up to about 3 times the tidal range.

The wind stress term in CAFE-1 is of the accepted quadratic form:

$$
\tau^{S} = \rho_{air} C_{D} U_{10}^{2}
$$
 (3.13)

where

 $p_{\text{air}}$  = air density  $\texttt{C}_{\textsf{D}}$  = a dimensionless drag coefficie  $U_{10}$  = air velocity at 10 meters above water surface,  $in m s<sup>-1</sup>$ 

The form given for  $C_{\text{D}}$  is

$$
C_{D} = (1.1 + 0.0536 U_{10}) \times 10^{-3}
$$
 (3.14)

This is based essentially on empirical data. Oiscussion of development and validity of Equation (3.14) and (3.15) is given by Briggs and Madsen (1973). Properly setting the boundaries may be a problem when there is a significant wind setup. This usually requires an independent study of setup properties. One approach is to run the model with no tide and adjust the boundaries so a smooth setup is established and then superpose tides on the MLW level. Alternatively, real-time wind and tidal data can be input.

Final forms of Equations  $(3.2)$  to  $(3.4)$  are developed by inserting these approximations:

Conservation of mass:

$$
\frac{\partial H}{\partial t} + \frac{\partial q_x}{\partial x} + \frac{\partial q_y}{\partial y} = 0
$$
 (3.15)

Conservation of momentum in x-direction:

$$
\frac{9q_x}{3t} + \frac{9(q_x^2/H)}{9x} + \frac{9(q_xq_y/H)}{dy} - fq_y
$$
  
+ g H  $\frac{9n}{9x} + \frac{H}{p} \frac{9p^5}{9x} + \frac{qH^2}{2p} \frac{9\Delta p}{9x}$ 

$$
+\frac{\rho_{\text{air}}}{\rho_0} \quad C_{\text{D}} \quad |U_{10}| \quad U_{10x} - C_{\text{f}} \quad (q_x^2 + q_y^2)^{1/2} \frac{q_x}{H^2}
$$
  

$$
-\frac{\partial F_{XX}}{\partial x} - \frac{\partial F_{YX}}{\partial x} - M_x = 0
$$
 (3.16)

Conservation of momentum in y-direction:

$$
\frac{\partial q_y}{\partial t} + \frac{\partial (q_x q_y / H)}{\partial x} + \frac{\partial (q_y^2 / H)}{\partial y} + f q_x
$$
  
+  $q H \frac{\partial \eta}{\partial y} + \frac{H}{\rho} \frac{\partial \rho^5}{\partial y} + \frac{\partial H^2}{\partial \rho} \frac{\partial \Delta \rho}{\partial y}$   
+  $\frac{\partial \sin \theta}{\partial \rho} C_D |U_{10}| |U_{10y} - C_f (q_x^2 + q_y^2)^{1/2} \frac{q_y}{H^2}$   
-  $\frac{\partial F_{xy}}{\partial x} - \frac{\partial F_{yy}}{\partial y} - \overline{M}_y = 0$  (3.17)

Numerical approximation procedures used in CAFE-1 will not be discussed in detail here. For details see Wang and Connor (1975).

# 3.1.3 Turbulent Eddy Viscosity Coefficient E<sub>i</sub>

this reason a separate section is devoted to this parameter here. Model validity and predictability therefore hinge on the credibility of the values assigned to F<sub>ij</sub>. A brief literature review was made to determine what reasonable values might be. It has been shown that  $F_{\bf i\bf j}$  is a function both of the velocity field and characteristics of the numerical solution grid. The eddy viscosity coefficient  $E_{i,j}$  is the major variable parameter by which the engineer can adjust the model results to fit a data set. For

A "rough" formula for estimating E<sub>xx</sub> is given by Wang and Connor (1975), as

$$
E_{ij} \sim \alpha g \frac{\hat{n}}{\hat{u}_i} \Delta \ell_j
$$
 (3.18)

where

 $\lambda$ 

$$
\alpha \approx 0.1 \text{ to } 0.01
$$
\n
$$
g = 9.31 \text{ m s}^{-2}
$$
\n
$$
\hat{n} = \text{expected tidal range}
$$
\n
$$
\hat{u} = \text{expected velocity}
$$
\n
$$
\Delta \ell = \text{characteristic grid length}
$$
\n(3.19)

For  $\alpha \leq 0.02$  the only effect of this term is to dampen short wave noise.

Note that  $\hat{u}_i$ ,  $\ell_i$ , E<sub>ii</sub> refer to components in direction i. A better approximation for the velocity field contribution might be the difference in characteristic velocities across  $\Delta \ell_4$ .

Few authors have provided any insight into the rational for choosing the eddy viscosity coefficient values they have used. Some sample values are produced in Table 3.1. Since grid sizes varied so greatly in different applications, a nondimensionalized value,  $E_{ij}^*$ , defined by

$$
E_{ij}^* = \frac{E_{ij} \Delta t}{\Delta \ell_i^2} \tag{3.20}
$$

is introduced as more appropriate for comparison. It can be seen in the table that values for this parameter range from .0025 to .002, with credible values being in the range .001 to .05 (depending on the value of  $\alpha$  used). As noted by Wang and Connor (1975), ideally E<sub>ii</sub> should be minimized with  $\alpha$ having a highest practical value for damping of about 0.02. High values af E $\boldsymbol{\ddot{\mathfrak e}}_{\mathbf 1}^*$  indicate the modeler may have forced stability on the system, although many other factors may also be important in such cases.





For the Apalachicola grid some reasonable estimates are, for the smallest element, with low velocities

$$
\alpha = 0.02
$$
  
\n
$$
g = 9.81 \text{ m s}^{-2}
$$
  
\n
$$
\hat{n} \sim 1 \text{ m}
$$
  
\n
$$
\hat{u} \sim 0.1 \text{ m s}^{-1}
$$
  
\n
$$
\Delta \ell_{i} \sim 350 \text{ m at least}
$$
  
\n
$$
E_{ii} \approx (0.02) (34335) = 686.7 \text{ m}^{2} \text{s}^{-1}
$$

and

$$
\frac{E_{\text{ij}} \Delta t}{\Delta z_1^2} = \frac{686.7 \cdot 60}{350} = 0.33
$$

For the largest elements, with highest velocities,

$$
\hat{u} \sim 0.5 \text{ m s}^{-1}
$$
\n
$$
\Delta \ell_{i} \sim 3000 \text{ m}
$$
\n
$$
E_{ii} = (0.02) (58860) = 1177 \text{ m}^{2} \text{s}^{-1}
$$

and

$$
\frac{E_{11} \Delta t}{\Delta \ell_1^2} = \frac{1177 \cdot 60}{3000^2} = 0.0078
$$

In fact, values of  $E_{xx} = E_{yy} = 40 \text{ m}^2 \text{s}^{-1}$  and  $E_{xy} = 2 - \text{ m}^2 \text{s}^{-1}$  were selected for subsequent model runs to minimize impact of this parameter and assure a search to define the important physical variables in the system. Values of  $E_{\hat{i}i}$  for these values of  $E_{\hat{i}i}$  are

1) smallest of elements

$$
E_{ii}^* = .02
$$

2) largest elements

$$
E_{\mathbf{i}\mathbf{i}}^* = .0002
$$

In general the personnel on this project preferred grid manipulation to increasing E<sub>ii</sub> as a means to achieve stability in CAFE-1. The decision was made to use the lowest appropriate va1ues found in the literature and design a stable grid around these. The procedures used to obtain a stable grid wi11 be discussed in the next section.

# 3.1.4 Applica<u>tion and Debugging of CAFE-1 Model for Apalachi</u>c <u>Bay</u>

Application of the CAFE-1 model to Apalachicola Bay turned out to be a trial and error process which took somewhat longer than anticipated. A finite learning curve exists however, since it is now possible to change the grid in a timespan of 2-3 days, whereas it took about 4 months to get the first successful run.

Apalachicola Bay is complicated by the fact that there are several tidal inlets and several river inflow locations. The app1ication was further complicated by the fact that the dispersion model required good resolution of East Bay and East and Hest Bayous. This required an extreme range of element sizes, which tends to make the model unstab1e.

Finding a stable grid is something which was found best learned by trail. It becomes intuitive to some degree, and this is a drawback of the model in its current form. An initial "ideal" grid proved to be completely unstable. Then a grid was made in which e1ements were made more equilateral, and element sizes varied slowly. This was gradually modified to the working grid by changing several unstable areas. To accomplish this the graphics routines were found very helpful.

Unlike DISPER-1, CAFE-1 tends to die quite rapidly when an instability occurs. The initiation of the instabilities could be traced by reviewing velocities at all points for time steps leading up to the instability. This

is, however, very inefficient. Therefore, graphics routines for the Gould (essentially the same as CALCOMP) plotter were developed to enable plotting velocity vectors at desired time steps. It was then very easy to see where instabilities occurred. The problem was usually one of the following items:

- 1) improper node or element definition
- 2) total depth less than about 1 dm at low water
- 3) grid changed size too rapidly
- 4) irregular triangle shape
- 5) grid elements too large in zone of rapid velocity change
- 6) too rapid change of depth.

Since instabilities tended to occur sequentially, the procedure usually consisted ot fixing one problem at a time. As the total number of potential instabilities was not known, the process was discouraging at times.

Despite the fact that an implicit time step routine is used in CAFE-1, there appears to be a limit on the time step imposed by stability considerations. This criterion seems to take the form of the Courant-Friedrichs-Lewy (CFL) condition. The two-dimensional form of the Courant number is given by Cunge (1977) as

$$
C_r = \frac{\Delta t}{\Delta x} \sqrt{2gH} \tag{3.21}
$$

In theory, an implicit scheme should be stable for any value of  $C_p$ , even considerably greater than 1, although the accuracy of the solution will generally decrease as C<sub>r</sub> approaches higher values. The theoretica stability of the model is, however, tempered by real physical features. For example, Cunge (1977) discusses the Leendertse (1967) scheme, which is considered a strictly non-dissipative, second-order accuracy scheme. This

means that no numerical damping of wave amplitudes will occur, which is desirable for real waves. However, this also means that discontinuities, perturbations, rough geometry (rapid depth changes, etc.) will create numerical waves which are not damped. Therefore, a theoretical1y stable scheme may become unstable in some applications. It should also be noted that the theoretical stability limits are always obtained by a linear stability analysis of the von Neumann type which can best be considered a guide to stability of the nonlinear equation system.

Considerable numerical experimentation led to the adoption of a practical CFL-type criterion given by

$$
\Delta t \leq 0.7 \Delta x_0 / \sqrt{2g} H_0 \tag{3.22}
$$

for this model in which x<sub>o</sub> and H<sub>o</sub> refer to the grid location giving the critical value for Gt.

It was found-that for all grids thus far used, Equation (3.22) yielded values close to 60 seconds, and a time step of 60 seconds for CAFE-I runs was in fact found acceptable and will be used for all results presented in this report.

#### 3.2 The DISPER-1 Model

The selection of DISPER-1 was rather direct once CAFE-] was selected as the hydrodynamics model. It is 2-D, real-time, finite-element, compatible with CAFE-1, and readily available. Hecause advection dominates dispersion in tidal systems, a real-time model is required. This need is particularly strong given the transient character of stormwater quality and quantity. Availability of real-time capability will be extremely beneficial when any biological, chemical, or other time-dependent constituent changes and interactions are added to the model at a later date.

DISPER-1 is a real-time, 2-D, vertically-averaged finite element model for solution of' the convective-diffusion equation given hydrodynamic inputs from another source (in this case from CAFE-1). The model is described by Christodoulou et al. (1976), Leimkuhler et al. (1975), and in a user's manual by Pagenkopf et al. (1976).

### 3.2.1 Equations and Boundary Conditions for DISPER-1

The model solves the classicial convective-diffusion equations: Following Leimkuhler et al. (1976)

$$
\frac{\partial c}{\partial t} + \frac{\partial}{\partial x} (uc) + \frac{\partial}{\partial y} (vc) = -\frac{\partial}{\partial x} \frac{\partial}{x} - \frac{\partial}{\partial y} \zeta_y + P_0 \qquad (3.23)
$$

in which

$$
\zeta_{\chi} = - \rho \text{ H } D_{\chi\chi} \frac{\partial c}{\partial x} - \rho \text{ H } D_{\chi y} \frac{\partial c}{\partial y}
$$
 (3.24)

$$
T_y = - \rho H D_{xy} \frac{\partial C}{\partial x} - \rho H D_{xy} \frac{\partial C}{\partial y}
$$
 (3.25)

$$
c = \rho \overline{c} H \tag{3.26}
$$

 $\Delta\mathbf{r}$  , and  $\Delta\mathbf{r}$  , and  $\Delta\mathbf{r}$ 

where  $\overline{c}$  = average concentration of a constituent

- $H = total$  depth
- $p =$  density of water
- $u, v$  = vertically averaged velocities in x and y directions, respectively
	- $c =$  vertically integrated concentrations
	- P = sources and sinks of mass 0
- D<sub>ii</sub> = dispersion coeffici

Note that Equation  $(3.23)$  expresses conservation of mass of the constituent of interest. Values of u and v came from CAFE-1.

Either a fixed concentration or a fixed mass flux can be specified as a boundary condition. These may be specified on elements or nodes or some combination thereof.

It is important to bear in mind that this is a finite element scheme when loading the boundaries. Linear interpolation functions are used, so if a smooth unit load of 1 kg s<sup>-1</sup> is to be placed across 3 points, then loading will have to be assigned as 0.25 kg s<sup>-1</sup> on each of the outer points and 0.50  $kq s^{-1}$  on the central point of the three. Also, if the grid has a depth of 2 m, then the initial concentration of the above scheme will be 1/2 that for a grid of 1 m depth. This is because the model solves for depthintergrated values, as noted in Equation  $(3.26)$ .

At the present time boundary conditions may vary in DISPER, but only if they are specified explicitly over the tidal cycle or over time. This is inconvenient for many problems (and especially for the determination of salinity) since the solution at the boundary must be specified before it is known. Known applications avoid this problem by assigning a decay value, or by having the source sufficiently weak that complete dilution occurs, so that c is equal to zero at all times at the boundary. Another useful approach is the floating boundary condition developed by Dailey and Harleman (1972) which sets the boundary concentrations at ocean value during flood tide, and specifies that the gradient of the dispersive flux during ebb tide remains constant.

# 3.2.2 Stability and Convergence of DISPER-1

The best work in the area of stability and convergence of DISPER-'I has been done by Christodoulou et al. (1976), and experience at the University of Florida has helped strengthen their findings for application of DISPER-1 to Apa1achicola Bay. In the dispersion model, three factors combine to

change constituent concentrations. These are advection (represented by the velocity,  $u$ ), dispersion (represented by the dispersion coefficient, D<sub>ii</sub>), and decay (represented by the appropriate decay or reaction coeffi cients). It has been found that typical decay terms create slower changes than the other two terms and can generally be neglected in stability analyses. Christodoulou et al. (1976) found that the total effect of advection and dispersion could be represented in defining a "safe" region given by the following inequality.

$$
(1.22 \frac{u \Delta t}{\Delta x})^{2} + (8 \frac{D_{11} \Delta t}{\Delta x^{2}})^{2} < 1
$$
 (3.27)

It should be noted that Equation  $(3.27)$  is based on a theoretical analysis assuming very regular and equilateral triangles and verification has occurred only on moderately irregular grids. For highly irregular grids, the allowable time step may be considerably below that given by Equation  $(3.27)$ . Equation  $(3.27)$  can be converted to

$$
\Delta t \leq [ (1.22 \frac{u}{\Delta x})^{2} + (8 \frac{D_{11}}{\Delta x^{2}})^{2} ]
$$
 (3.28)

As an example, for element sizes of about 400 mm, D<sub>ii</sub> of 100 m<sup>2</sup>s<sup>-1</sup>, and a maximum velocity of about 1.5 m s<sup>-1</sup>, Equation (3.28) yields a value of 147 s. This, too, may need to be further reduced due to other problems. However, in general 1t is true that OISPER-1 is stable at longer time steps than CAFE-l,

Once the models have been made stable for a given grid, then one must turn to the question of accuracy of the solution or convergence to the true solution. No specific criteria have been developed in this regard for CAFE-1, although it is generally believed that a stable solution is

also accurate unless unexplained oscillations persist in any portion of the flow region.

Christodoulou et al. (1976) proposed an accuracy criterion for DISPER-1, given by inequality (3.29)

$$
\Delta x \times \frac{2 \, \mathsf{D}_{\mathbf{i}\,\mathbf{i}}}{\mathsf{u}} \tag{3.29}
$$

Inaccuracies in OISPER-1 exhibit themselves as negative concentrations and as ocillating values of concentrations. For  $D_{i,i}$  = 100  $m^2 s^{-1}$  and a maximum velocity of  $u = 1.5$  m s<sup>-1</sup>, it can be seen that Equation (3.29) yields a very small element size of about 130 m. If in fact such a small element size were chosen, then values of the time increment would be drastically lowered, as shown by Equation (3.29) for DISPER-1 and Equation (3.22) for CAFE-1.

Fortunately, Equation (3.29) applies primarily in areas of high concentration gradients and high concentrations. In regions far from the sources, where concentrations remain lower, a larger length scale may function satisfactorily. It should be realized, however, that the grid size may have to be modified, and hence the time step, to eliminate oscillations and non-negligible negative concentrations.

Several other features may play a role in determining model behavior but have not been cast in any quantitative criterion. A few of interest here will be mentioned. It has been shown that the schematization of the source(s) in DISPER-1 is very important. In one example given by Christodoulou et al. (1976), the criteria given by Equations (3.28) and (3.29) were both met. In two runs, all parameters were the same except that the source was distributed over two elements in one run and over eight elements in the other run. The run with eight elements for the source gave

completely satisfactory results, while those from the other runs exhibited excessive oscil1ation. Therefore sources should be distributed over several elements, but it should be realized that this often means that model predictions very near the source may be less valid.

The element shapes and gradation of element sizes have been observed by Hydraulic Laboratory personnel to be very important also. Elements too different from an equilaterial triangle may cause problems. **In** addition, problems may occur where element sizes change too rapidly. This also includes too rapid a change in depth, even where element sizes and shapes are fairly regular.

A factor **in** stability and accuracy is the initial condi tion chosen for the bay, A common approach used in earlier Apalachicola Bay runs is the so-called cold-start, with zero concentrations, e.g., specified in DISPER-l. The model can, however, be operated in a hot-start mode, where concentrations are specified throughout the grid at time zero. Of course, in either case, the model is run sufficiently long (through several tidal cycles) to remove any bias provided by the assumed initial conditions. However, instabilities or inaccuracies could occur due to the extreme gradient of concentration setup at the onset of model operation. If this occurs, it may be more economical to specify a realistic initial concentration field as opposed to severely restricting element size and time increment.

#### 4. NODEL VERIFICATION

As noted in Section 3, the two rmdels being used have been verified by application to other waterbodies and comoaring results to measured data. Of course, as is always the case, verification may be in the eye of the beholder. In the following, verifications of the models as used in the Apalachicola area will be discussed.

#### 4.1 Verification of CAFE-1

#### 4.1.1 Field Data

Two primary types of data were obtained from the field: (1) tidal information at various points in the bay and (2) water velocity measurements. In addition, the wind velocity was measured several times during the data collection process.

Host of the field data to be discussed in this report were gathered from September 15 through September 26, 1980, and from November 7 through November 9, 1980.

4.1.1.1 Tide Recordings. Tide gages were place at each of the four ocean boundaries: East Pass, Sikes Cut, Hest Pass, and Indian Pass. The tides recorded at these gages were used as input boundary information to the model .

In addition, tide gages were installed at two internal points in the bay (points A and B in Figure 4.1). The recordings from these two tide gates were used as a comparison with the model resuIts. Figure 4.2 shows a tide gage and recorder in place on a private dock at Indian Pass. A sample recording of the tide at East Pass is shown in Figure 4.3.

Additional tidal information was obtained from NOAA.



Figure 4.1. Location of Verification Points in Apalachicola Bay.



Figure 4.2. Tide Gage and Recorder in Place at Indian Pass.

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Figure 4.3. Samp1e Recording **from** Tide Gage at East Pass.

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4.1.1.2 Velocity Measurements. All velocity measurements were taken from a boat using a V "Arkansas" Ott Meter (see Figures 4.4 and 4.5). Logarithmic velocity profiles were assumed, so the velocity readings to be compared with the model output were taken at 36.8X of the total depth from the bottom (which is the location of the spatial mean velocity for a logarithmic velocity profile). Velocities were also recorded at other depths so that velocity profiles could be plotted and the assumption of logarithmic velocity profile checked.

At points C and D (Figure 4.1) measurements were taken at short intervals for periods of about four hours. These values were used as a comparison with the model results. Velocity profiles were also measured at several other points in the bay.

Flow direction was measured with a compass after hoisting the Ott Meter to an elevation where it could be seen (see Figure 4.6). It is assumed that the flow direction is the same at all depths below the water surface.

# 4.1.2 Model Input for Verification Runs

4.1.2.1 Grid Configuration. The finite element grid shown in Figure 3.1 was used for all of the computer runs to be discussed in this report. It contains 281 nodes and 439 elements.

This particular grid was chosen after experimentation with several grids because of its many desirable characteristics. First, the element size is small enough to provide an accurate representation of the bay. Second, most of the triangles are approximately equilateral and there is no rapid change in element size. This is of particular importance because rapid change in element size as well as irregular triangles, tends to produce instabilities which cannot be predicted by quantifiable stability criteria as discussed cartier.



Figure 4.4. Ott Propeller Meter Used for Velocity Measurements in Apalachicola Bay.



Figure 4.5. Ott Propeller Meter Near Water Surface.

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Figure 4.6. Observation of Direction of Water Flow.

The remaining reasons for choosing this grid are related to the cost of running the model. This cost is roughly proportional to the number of elements and inversely proportional to the timestep.

The timestep was chosen to be 60 seconds in accordance with the earlier discussed stability criteria. In addition, the output from CAFE-1 is used as input to a water quality model and 60 seconds is a convenient interval for transferring this information.

4.1.2.2 Turbulent Eddy Viscosity Coefficients. As stated earlier, internal stresses from turbulence and velocity shear are represented in the model in the form of Equation  $(3.9)$ . Since there is no way to actually measure these stresses, the literature review provided reasonable values for the eddy viscosity coefficients. The values currently being used are the following:

$$
E_{XX} = 40.0 \text{ m}^3 \text{s}^{-1}
$$
  
\n
$$
E_{yy} = 40.0 \text{ m}^3 \text{s}^{-1}
$$
  
\n
$$
E_{XY} = 20.0 \text{ m}^2 \text{s}^{-1}
$$

The sensitivity of the model to these coefficients was not known. A single computer run was made with each of these values cut in half. The resultant change in velocities was only about 1-2%. The turbulent eddy viscosity coefficients are parameters that can be easily manipulated by the operator for the purpose of calibrating the model. Therefore, a more detailed study on the effects of making larger changes in these parameters may easily be undertaken if necessary.

4.1.2.3 Manning's n. The first set of computer runs was made with n = O.C45. This value was calculated in accordance with the method proposed by Christensen (1975) from a few scattered velocity profiles obtained in the field. From the velocity profiles that were logarithmic (surprisingly few of them were not), an average of the n values was taken. This average was input **as** a constant value for the entire bay.

Since the first set of runs yielded velocities that were too small, a second set of runs was made with n equal to a constant 0.030 throughout the bay. The result of this change will be discussed in more detail in the next section.

It is also possible to input varying values of Manning's n throughout the bay. Although this is more time consuming than simply supplying a constant value, it is the only way to account for di fferences in bottom friction at various locations. This type of input can be used as a final step in "fine-tuning" the model.

4.1.2.4 River Flow. Although river flow is a physical characteristic of the bay, the exact river discharges are not known for the periods during which data was taken. However, average monthly flows for the Apalachicola River (1961 - 1976) were available from the U.S.G.S. so these values were used (see Table 4.1 and Figure 1.7). Fortunately, errors in the river flow do not significantly affect the overall hydrodynamics of the bay, because the river flow constitutes a very small part of the total amount of water entering the bay. This is illustrated in the following calculation showing the ratio of river flow  $(\overline{Q} = 705 \text{ m}^3 \text{s}^{-1})$  for the Apalachicola River) during a half tidal cycle to a mean tidal prism height of 0.5 m:

Month	Mean Discharge $m^3$ s <sup>-1</sup>	Ratio to Mean Annual Discharge
0	387	.55
N	391	.56
D	617	.88
J	985	1.40
Ē	1131	1.60
$\mathsf{M}$	1209	1.72
A	1082	1.54
M	687	.97
J $\overline{\phantom{a}}$	580	.82
J	505	.71
A	496	.70
S	392	.56
Mean Annual Discharge	705	1.00

Table 4.1. Average Monthly Flows for the Apalachicola River for Period 1961-1976.

These **values correspond to the hydrograph given** in Figure 1.7.

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 $\omega_{\rm{max}}=2\pi$ 

 $\sim$ 

$$
(100\%) - \frac{(705 \text{ m}^3 \text{s}^{-1}) (60 \text{ s min}^{-1}) (60 \text{ min h}^{-1}) (6.21 \text{ h})}{(550 \text{ km}^2) (0.5 \text{ m}) (1,000,000 \text{ m}^2 \text{ km}^{-2})} = 5.7\%
$$

4.1.2.5 Wind Velocity. The model does not provide for the input of time-varying wind velocity, so average velocities were used. For the run used as a comparison with the internal water surface fluctuations:

wind velocity = 2.24  $m s^{-1}$  (5 mph) at 207° clockwise from North For the two runs used as comparisons with water velocities:

wind velocity = 2.24 m s<sup>-1</sup> (5 mph) at 0° clockwise from North

4.1.2.6 Tide Information at Boundaries. The tidal curves at the boundaries are input to the model as a set of amplitudes and times. The model then approximates the tides as a series of sinusoidal curves. It is important that the first half tide curve input to the model is one of increasing water elevation (i.e., from low tide to high tide) since the initial depths in the model are at MLW.

Complete tidal information at all boundaries was available for the run used as a comparison with the internal water surface fluctuations. However, for the two runs used as comparisons with the water velocities, only partial boundary data was available. (Tide gages were only set-up at East Pass and Indian River Pass when the velocity data were gathered.) Correction factors for both amplitude and time lag were established from the complete set of curves and used to estimate the tidal curves at West Pass and Sikes Cut for the remaining runs from the information at East Pass.

4.1.2.7 Depths at MLM. The depths input at each node were obtained from a Navigational Chart published by NOAA. The depths input at West Pass

and Sikes Cut are slightly lower than the actual values, because the latter causes instabilities in the model with the 60 second time step. Using a time step small enough to permit the input of actual depths would make the cost of running the model prohibitive. To compensate for the smaller depths, larger than actual widths were input so that the cross-sectional area of the outlets remained the same.

# 4.1.3 Comparison of Model Results with Field Data

Figures 4.7 and 4.8 show field measurements and model results for the water surface fluctuations at two points, 8 and A,in the bay. Computer results are shown for  $n = 0.045$  and  $n = 0.030$ . At point B, both computer runs are extremely close to the range and phase lag of the actual curve. The change in Manning's n produced only about a 5 percent change in the tidal range and almost no difference in the phase lag. This is important to note, since the same change induced a much larger difference in velocities. The difference between the range of the computer run with n = 0.030 and the actual measured range is only about 7 percent.

At point A, there is almost exact correlation between the range of the n = 0.030 computer run and the range of the recorded curve. However, there appears to be a slight phase lag difference between the two (about 10 percent).

Similar correlations between measured and computed velocity and velocity orientation are obtained with the model. Figure 4.9 shows the comparison at point C as an example. Observed and computed values of the vertically averaged velocities at points A through B show similar satisfactory agreement. The predicted model velocities are often lower than the observed velocities. However, Wang (1978) reports that a comparison of current velocities measured by portable current



Figure 4.7. Water Surface Elevation vs Time at Point B in Apalachicola Bay.



Water Surface Elevation vs Time at Point A in Apalachicola Bay. Figure 4.8.





meters from boats with those measured by recording current meters mounted on fixed structures showed that the former tend to be inflated due to wave motion. Hence, the agreement between observed and model predicted velocities may be even better than the observations indicate.

# 4.1.4 Comparison with Wang's Verification

Figures 4.10 and 4.11 show field and preliminary model results obtained by Wang (1978) using the CAFE-1 model at Biscayne Bay. Wang considers his resu1ts to be good for an initial computer run with no adjustments. All of the results for Apa1achicola Bay discussed in the previous section fa11 well within the errors illustrated in the two figures. Therefore, it may be assumed that CAFE-1 correctIy predicts the principal physical processes in Apa1achicola Bay. However, further refinement is still possible as more detailed data in specific areas are obtained.

## 4.1.5 Further Calibration

Because of the large change in ve1ocities occurring when n was decreased from  $0.045$  to  $0.030$ , it was estimated that further decreasing n to 0.015 would cause the model to output velocities of magnitudes approximately equal to those measured in the field. However, use of n = 0.015 results stability problems, presumably because the larger velocities produced violated the stability criterion. Since the instabilities occurred early in the run (about halfway through the first tidal cycle), it is possible that the velocities causing the stability problems are produced only as a result of the "cold-start" i.e., all initia1 velocities and water surface elevations set equal to zero). Assuming that the steadystate velocities are sma11er in magnitude than these initial velocities, it may be possible to eliminate the instabilities by inputting initial



Figure 4.10. Surface Displacement Verification by Wang for a Model of Biscayne Bay Using CAFE-1 (Wang, 1978b).



Figure 4.ll. Hodograph Comparison by Wang for a Model of Biscayne Bay Using Cafe-1 (Wang, 1978b).
va1ues for the velocities and water-surface elevations. These values can be estimated by using the model output from past runs. Although it will take some time to input these values initially, this change will probably decrease computer cost because **less** computer time will be required for the model to reach a steady-state. The model is currently being run for three to five tidal cycles before the final information is output).

#### 4.2 Verification of DISPER-1

The verification of a transport model can take many forms. Fie1d data can be obtained for releases ot a dye or other tracer from the river mouth or other sources. In an estuary of this size, the problems with such measurements can be simply too great in terms of time and manpower. A reasonable alternative is to model some naturally occurring substance which can be monitored by point samples through the bay, rather than following a tracer cloud. The best choice is salinity. While large amounts of salinity data exist on the bay, unfortunately concurrent tidal and velocity are data rarely available. Therefore, additional data was obtained for this study.

#### 4.2.1 Field Data for Quality Verification

The specific set of salinity data to be treated here was taken in September, 1980, by a field crew from the Hydrau1ic Laboratory at the University of Florida and analyzed in Gainesville. The data are reported in Table 4.2.

A review **of** the data **in** Table 4.2 indicates both spatial and temporaI variation of salinity; see, for example, the values at East Pass at two different times. Notice also some apparent small anomalies in the data which evidently reflect measurement error, symptomatic of difficulties of sampling in such an environment. It is also interesting that samples 22 to 26 at East Pass are inverted from that expected, indicating possible

Sample No.	Approximate Location	Salinity ppt	Date, Time of Sample
1	Apalachicola River Mouth	1.6 <sup>5</sup>	$9 - 18 - 80, 1010$
$\overline{c}$	Apalachicola River Mouth	21.2	9-18-80, 1010
3	Center of Bay	$30.4^{3}$	9-18-80, 1100
4	Center of Bay	30.0	9-18-80, 1100
5	Center of Bay	31.6	9-18-80, 1100
6	Center of Bay	28.8	$9 - 18 - 80$ , 1100
$\overline{I}$	Center of Bay	$31.2^{D}$	9-18-80, 1100
8	West Pass	$33.2^5$	9-18-80, 1630
9	West Pass	34.0	$9 - 18 - 80$ , 1630
10	West Pass	29.2	9-18-80, 1630
11	West Pass	33.8	$9 - 18 - 80$ , 1630
12	West Pass	$32.4^{b}$	9-18-80, 1630
13	Sikes Cut	$29.8^5$	9-18-80, 1730
14	Sikes Cut	30.0	9-18-80, 1730
15	Sikes Cut	31.8	9-18-80, 1730
16	Sikes Cut	32.0	9-18-80, 1730
17	Sikes Cut	$33.0^{b}$	9-18-80, 1730
18	East Pass	$35.0^{5}$	9-19-80, 1140
19	East Pass	35.0	9-19-80, 1140
20	East Pass	34.4	9-19-80, 1140
21	East Pass	$34.8^{b}$	9-19-80, 1140
22	East Pass	$36.8^{D}$	9-26-80, 1500
23	East Pass	35.8	$9 - 26 - 80$ , 1500
24	East Pass	38.2	9-26-80, 1500
25	East Pass	44.3	$9 - 26 - 80$ , 1500
26	East Pass	$43.5^{5}$	$9 - 26 - 80, 1500$
27	New River	28.7	$9-26-80, 1600$
28	South Span-Causeway	$34.9^{5}$	$9 - 26 - 80$ , 1820

Table 4.2. Salini ties in Apalachicola Bay, September 1980. Observed by Hydraulic Laboratory, University of Florida.

s = surface

b = bottom

Table 4.2 - continued.



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L.

 $\blacksquare$ 

s = surfa

b = botto

upwelling or local disturbances. This sort of variability should be recalled when assessing model agreement with the data. It should further be noted that the model, being two-dimensional, yields a depth-averaged concentration value.

#### 4.2.2 Model Input for Verification Runs

Due to the time span in salinity measurements, typical tides and winds for that period were specified for a CAFE run to form hydrodynamic input to DISPER. While this of course may lead to some inadequacies in the simulation, it was perceived as a good test, for uncertainity in these model parameters often exists. The 439 element, 281 node general grid shown in Fi gure 3.1 was used again for the simulation. Salini ties of 36 ppt. were specified at the external passes and inlets, with 10 ppt and 5 ppt at appropriate elements for the river mouth. River flow was taken at 337  $m^3 s^{-1}$ during this period, based on USGS records.

Some oscillations of concentrations were observed in the early simulation. As noted earlier, both the spatial increment,  $\Delta x$ , and the time increment,  $\Delta t$ , bear on this problem. Changing  $\Delta x$  means a change in the grid, locating critical areas and then refining the grid there.

Oscillations in the results caused some experimentation with the dispersion coefficient,  $D_{ij}$ , resulting in specifying input values which typically yield maximum values of  $D_{i,j}$  of 150-300  $m^2 s^{-1}$  in the bay.

These values are within the range of reported values for estuaries. Further accuracy considerations resulted in selection of a time step,  $\Delta t$ , of 60 seconds. These steps were chosen first in the verification process as they represent reasonable options for the typical user.

#### 4.2.3 Results of DISPER-1 Verification Runs

Results of one verification run are shown in Figure 4.12. Values shown in the elements are salinities in parts per thousand. It can be seen by comparison with Tab1e 4.2 that there is reasonable agreement with measured, values in the East and West Pass regions, in St. Vincent Sound, and in the East Bay - East Point region where the freshwater input from the Apalachicola River is so important. There are, however, some regions where values are too low, especiaIly near the causeway island and slightly east of that region.

There are several possible explanations for these low values in the regions noted. First, it should be observed that the figures shows a synoptic view of the bay, i.e., at a single time, while the observations in Table 4.2 were taken over a range of times and therefore occur at different parts of the tidal cycle. What is more important, however, is the fact that measurements spanned such a long time that varying wind, tides, and other conditions can significantly influence bay behavior. The run pictured here is based on a constant wind speed and direction. In addition, no attempts have been made to fine-tune CAFE results by varying Nanning's n across the bay and other such steps which might help resolve some localized errors.

It appears that verification is easier against data taken synoptically,. such as in enhanced LANDSAT photographs. Comparison of predicted and observed shapes and extents of plumes, i.e., pattern recognition, can provide a good assessment of model performance. Graham, Hill and Christensen (1978) and Hill and Graham (1980) reported on use of such data for this verification.

In conclusion, it can be stated that an attempt at model verification with no fine-tuning yielded acceptable results over much of the bay.

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However, some changes in element arrangement would be necessary to remove some locally low values near the causeway island.

#### 4.3 Satellite Verification of DISPER-1

Use of LANDSAT imagery computer enhanced for surface water color may be utilized for verification of the DISPER-1 model, since surface water color and water quality (e.g., acidity expressed by  $pH$ ) may be related. Since the satellite images only reveal what is going on in the upper inches of the water column, it may be difficult to let the images relate to the vertically averaged water quality. However, the general pattern of the dispersion of a pollutant at the surface may be observed and compared to the print-out of the DISPER-1 model. Assuming a well-mixed bay, the surface water quality shouId indeed be indicative of the vertica1ly average quality parameter.

Verification by such pattern recognition from LANDSAT images has given surprisingly good results.

Figure 4.13 shows an example of the color enhanced pictures used. Note the red colored water in East Bay and at Carrabelle. This color indicates low pH water. The pattern shown in Figure 4.13 is in almost perfect agreement with computer printouts. The plume at Sikes Cut is also noteworthy. Also this phenomenon may be reproduced by the model.



Figure 4.13. Computer Enhanced LANDSAT Image Showing Water Quality Patterns in Apalachico'la Bay.

5. THE ATLAS, SELECTION OF CONDITIONS FOR A TYPICAL YEAR

To illustrate more clearly behavior in the bay, model solutions demonstrating variation through a typical year were sought. The objective is to provide an overview of possible behavior, with the expectation that specific problems will still require running the model for conditions appropriate to those problems. The material generated for the average year is presented in the form of an atlas at the end of this report.

There are several sets of physical parameters to be selected to provide a view of bay behavior. Major ones include the following:

- 1) Tides amplitude and phase lag.
- 2! River f'lows.
- 3) Wind speed and direction.
- 4) Source location and loading.

To provide a reasonable view of expected bay behavior and yet keep the size of this report reasonable, it was decided to produce runs for each month, or twelve in all. Therefore, parameter values selected should be expected to represent monthly average values.

5.1 River Flows

The average monthly river flows shown in Table 4.1 were used for the CAFE-1 simulations.

#### 5.2 Tides

Tidal data was obtained from the National Ocean Survey for the fiveyear period from 1975-1980. Tide tables and the tidal data discussed in Section 4.1.1.1 were used to estimate expected tidal height variations from points of measured values to other boundary points and time (phase) lag between tidal peaks.

The tide at Apalachicala is considered diurnal, in that two highs or two lows may occur on the same day with different amplitudes. This is clearly indicated in Figure 4.3. There are difficulties and uncertainities associated with selecting a "typical" tide pattern for each month of the form in Figure 4.3. In addition, the runs of interest, and many problems of practical interest, occur over several tidal cycles. This tends to average out the influence of tidal amplitude variation. Therefore, given the objective of providing an overview of bay behavior, it was decided to simply use mean tidal amplitudes to drive the model, with a respecting sinusoidal tide specified. This should reproduce the general structure well, although there may be sma11 local differences at individual times within a tidal cycle.

A review of the tidal data fram 1975-1980 showed mean tidal ranges at the Apalachicola gage rather close to one faot far all months. The lowest value obtained was 0.86 ft and the highest 1.10 ft. No consistent trend appeared by month, at least for the five years reviewed. It was therefare decided to simply use a single value of 1.0 ft (or a tidal amplitude of 0.50 ft =  $0.155$  m). Review of tide tables and UF measured data then led to the tides at the bay boundaries, as shown in Table **5.1.**



Table 5.1. Tidal Amplitudes and Phase Lags for Model Runs.

Again, these values are taken as typical and should not be interpreted as representing any specific case.

## 5. 3 Winds

Wind is an extremely important factor in bay behavior. Wind data from 1975 through early 1981 was obtained from the Apa1achicola office of the National Weather Service in the form of monthly surmaries of Local Climatological Data, with wind speed and direction reported at three-hour intervals, as well as daily and monthly average speeds and directions. A review of the data led to selection of the mont1y average wind values shown in Table 5.2.

Location	Wind Speed, mi/hr	Wind direction, deg. from N <sup>a</sup>
January	8.4	030
February	8.2	073
March	8.4	186
April	7.9	192
May	7.4	182
June	7.0	197
July	$6.3^{\circ}$	217
August	6.1	130
September	6.7	110
October	7.15	063
November	7.3	078
December	7.4	045

Table 5.2. Monthly Average Values of Wind Speed and Direction Used in Model Runs.

a: For example, 090 is a wind from the East, 180 from the South, etc.

Yariation in wind speed shown in Table 5.2 seems less significant than direction. Note the tendency of the wind to be from slightly west of south during March-July, but more like easterly to northeasterly during the rest of the year.

#### 5.4 Generated Results

The model CAFE-1 is run with the grid shown in Figure 4,7 for each of the twelve months, utilizing river flows from Table 4.1, tidal information from Table 5.1 (the same for all months), and the wind data from Table 5.2. The results will be presented as views of the velocity field throughout a tidal cycle and the net velocity field over a cycle. Output from CAFE-1 runs for each of the twelve months will then be used to drive a DISPER-1 run representing a continuous discharge concentration of 100 units (ppm, eg.) in the river water.

The results from the conservative pollutant can be scaled directly to salinity by assuming an average salinity at the river mouth af 7.5 ppt (typical) with 36 ppt at the ocean boundary. Then any reported concentration can be converted to salinity by

 $s = 36 - 0.285$  c  $(5.1)$ in which  $c =$  concentration projected by model **s =** salinity in ppt

Full results are presented in the attached Atlas in 204 maps depicting hydrodynamics as well as water quality during the "average" year.

#### 6. DETERMINATION OF POLLUTANT CONCENTRATION (AND SALINITY) AT AN ARBITRARY LOCATION FOR OTHER RIVER CONCENTRATIONS AND OCEAN CONCENTRATIONS

The computer prepared maps, given in the atlas showing the distribution of conservative pollutant concentrations c in the Apalachicola Bay, are based on the river concentration  $c_R = 100$  (e.g., ppm) and the ocean (Gulf of Mexico) concentration c<sub>o</sub> = 0.

Pollutant concentrations,  $c_1$ , corresponding to other river and ocean concentrations may be found from these maps by use of a simple conversion formula to be established in the following.

Since the c distribution, shown in the maps and schematically in the upper part of Figure 6.1, is a solution to the differential equations governing the migration of conservative pollutants in the Apalachicola Bay, it is easily proven that the concentration  $c_1$  given by the linear expression

$$
c_1 = a c + b \tag{6.1}
$$

also must be a solution. In Equation  $(6.1)$  a and b are constants.

A special case of Equation  $(6.1)$  is

$$
c_1 = c \frac{c_R - c_0}{100} + c_0 \tag{6.2}
$$

in which  $c_R$  and  $c_o$  are arbitrary pollutant concentrations in the river and ocean, respecti vely.

This equation satisfies the boundary conditions

 $c_1$  = c for  $c_R$  = 100 and  $c_0$  = 0 corresponding to the original c-mapping,



Figure 6.l. Schematic Maps Showing Boundary Conditions Used in Concentration Conversion Formulas.

k,

$$
c_1 = c_0 \text{ for } c = 0
$$
  

$$
c_1 = c_0 \text{ for } c_R = c_0
$$
  
and 
$$
c_1 = c_R \text{ for } c_0 = 100
$$

Equation  $(6.2)$  will therefore give the pollutant concentration at any point where  $c$ , based on  $c_R$  = 100 and  $c_o$  = 0, is known when the river and ocean pollutant levels are known. The maps presented in the attached atlas will therefore, when combined with Equation (6.2), yield the vertical average of the pollutant concentration at any location in the bay and at any time during the tidal cycle for any values of c<sub>R</sub> and c<sub>o</sub>.

In the same way the maps may be used to predict the salinity at any point and at any time during the average tidal cycle.

The equation

$$
s = (1 - \frac{c}{100}) s_0 \tag{6.3}
$$

in which s = the salinity at  $(x,y)$  at time t and  $s_0$  = salinity of the Gulf of Mexico waters is of the same form as Equation  $(6.1)$ . s is therefore a solution to the equations governing the water quality of the bay. Since it furthermore satisfies the boundary conditions

$$
s = 0 \text{ for } c = 100
$$
  
and 
$$
s = s_0 \text{ for } c = 0
$$

it must represent the bay's salinity distribution. These boundary conditions are indicated in the lower part of Figure 6.1.

#### 7. ACKNOWLEDGEMENTS

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#### 8. LIST OF SYMBOLS

in the text and in the following list of symbols. The symbols used in this report are defined where they first appear

- $a =$  dimensionless constant
- $b = dimensionless constant$
- c = vertically averaged pollutant concentration at point  $(x,y)$ , at time t corresponding to  $\mathsf{c}_\mathsf{R}$  = 100. Note in Secton 3  $\mathsf{c}$ stands for the vertically integrated concentration while the vertically averaged concentration there is denoted  $\bar{c}$
- $c_{\overline{1}}$  = vertically averaged pollutant concentration at point (x,y at time t corresponding to  $c_{R}$   $\overline{\dagger}$  100
- $c_{\rm o}$  = vertically averaged pollutant concentration in Gulf of  $\sim$ Mexico and entrances to the bay
- $_{\mathsf{R}}$  = pollutant concentration of river water entering the bay
- $\mathsf{C}_\mathsf{f}$  = dimensionless friction coeffic
- $D = average$  estuary depth
- $D_{ij}$  = dispersion coefficient

D $_{\mathsf{xx}}$ , $\mathsf{D}_{\mathsf{xy}}$ , $\mathsf{D}_{\mathsf{yy}}$  = dispersion coefficie

\* = dimensionless turbulent eddy viscosity coefficie<br>ii

<sub>ij</sub> = turbulent eddy viscosity coefficie

f = Coriolis paramete

F<sub>xx</sub>,F<sub>xy</sub>,F<sub>yy</sub> = internal specific stress terms (stress/densit<sub>)</sub>

 $q = 9.806$  m s<sup>-2</sup> = acceleration due to gravity

- $h =$  water depth below mean low water (MLW) at point  $(x,y)$
- $H = h + \eta$  = total depth at point  $(x,y)$  at time t
- H $_{\sf a}$  = refer to grid location giving critical  $\Delta {\sf t}$  valu
	- $k = Nikuradse's equivalent sand roughness$
	- $L =$  estuary length

 $M_{\chi}$ , $M_{\chi}$  = momentum addition per unit horizontal area

n = Manning's n = k<sup>l/b</sup>/(8.25<sub>y</sub>g) (metric  $p = pressure$  $p^b$  = pressure at the bottom  $p^5$  = pressure at the water surface  $P = t$ idal prism  $R = tidal$  range s = salinity at point  $(x,y)$  at time t s<sub>o</sub> = salinity in Gulf of Mexico at entrances to the bay  $t = time$  $T =$  tidal period =  $12.42$  hr  $\hat{\mathsf{u}}$  = expected veloci U  $(u,v)$  = vertically averaged velocity components in the x- and ydirection, respectively, at point (x,y) at time t  $U_{10}$  = air velocity at 10 m above the water surface in m s<sup>-1</sup>  $x, y$  = horizontal Cartesian coordinates  $z =$  vertical coordinate Greek Letters  $\alpha$  = dimensionless coefficient  $\Delta \ell$  = characteristic grid length  $\Delta t$  = time increment  $\Delta \mathsf{x}_{_{\mathbf{O}}}$  = refer to grid location giving critical  $\Delta \mathsf{t}$  - value  $\eta$  = elevation of water surface above mean low water (MLW)  $P_{\overline{0}}$  = sources and sinks of mass  $q_x,q_y$  = discharge per unit width in x- and y-direction, respectively  $\mathsf{q}_{\mathrm{I}}$  = volume addition rat  $Q =$  river discharge

 $\hat{\eta}$  = expected tidal range

 $\rho$  = density of water  $\rho_{\text{air}}$  = density of air  $\rho_{0}$  = reference value of  $\rho$  $\rho_1, \rho_2$  = characteristic extreme densities <sup>D</sup> = bottom shear stre  $\tau^S$  = surface shear stress earth <sup>=</sup> angular velocity of earth = 2π/(24 • 3600)

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## APPENDIX A

A

HYDRODYNAMIC

**AND** 

## WATER QUALITY

# **ATLAS**

of

### THE APALACHICOLA BAY SYSTEM Franklin County, Florida

Prepared Under Sea Grant

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Contract No. R/EM-13

by

Hydraulic Laboratory<br>Department of Civil Engineering<br>University of Florida<br>Gainesville, Florida

December 1981

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#### FOREWORD

This somewhat unconventional atlas is intended to give the reader detailed information about velocity conditions, pollutant concentrations and salinity in the Apalachicola Bay System during an average year taking typical astronomical tides, wind intensities and river flow into consideration.

It covers the entire bay from Dog Island and East Pass in the East to St. Vincent Island and West Pass in the West and is based on the CAFE and DISPER finite element models applied to a grid system consisting of 489 elements and 281 nodes representing this bay area. The models have been verified by direct observations of salinities and velocities in the bay and by pattern recognition in LANDSAT pictures computer enhanced to show ocean and bay water quality by colors.

The Apalachicola Bay may be classified as a tide dominated we11 mixed estuarine system with only sporadic and unsignificantly small areas of stratification. Consequently, the river flow is of minor importance to the hydrodynamics of the bay. A hydrograph representing the monthly discharges averaged from 1971 to 1976 has therefore been used in the model to represent rates of freshwater flow into the bay.

While the river discharge is of minor importance to the hydrodynamics of the bay the same can not be said for pollutants brought into the bay by the river. This influence must be and is modeled in detail and the results are presented in such a way that the influence of any numerical value of the river water's pollutant concentration may be evaluated at any location in the system. As represented in this atlas the water quality predictions are limited to conservative po11utants, however, the numerical

model may be extended to consider nonconservative substances transported by the water .

The atlas shows conditions during a typical tidal cycle representing each of the twelve months of the year. Each month's events are shown on seventeen individual sheets. The first eight show the distribution of the vertically averaged water velocities and their circulation during that tidal cycle in eight time increments of equal lengths beginning at low tide. These eight sheets are marked by the name of the month and number 1 through 8.

The ninth sheet, marked by name of the month and 9, represents the velocities from the first eight sheets averaged over the tidal cycle. In other words this is the net vertically averaged water velocity.

The remaining eight sheets, marked by the name of the month and numbers 10 through 17, are reserved for water quality. They show the distribution of the vertically averaged pollutant concentration c at the same times during the tidal cycle the vertically averaged horizontal velocities are given in sheets No. 1 through 8. The shown concentrations c are based on a concentration  $c_R$  of the same pollutant in the river discharge equal to 100 (e.g., ppm) and c<sub>o</sub> = 0 pollutant concentration at all inlet: to the bay from the Mexican Gulf. Simple formulas for the calculation of c-values corresponding to other  $c_R$ - and  $c_\alpha$ -values and for determination of the vertically averaged salinity s from the salinity s<sub>o</sub> at the inlets to the bay are given on the individual water quality sheets.

While this atlas will answer most questions concerning velocities, their orientation, pollutant concentrations and salinities it is limited inasmuch as it is prepared for average conditions during the year. Data corresponding to extreme conditions such as tropical storms or periodic excessive pollutant loads must be generated separately by use of the detailed computer model. This model is stored on tape and attached to this report.

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## **JUNE**



JUN 9:

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Net values of vertically averaged ve1ocities. Time averaged over one tidal cycle.

JUN 10 through JUN 17: Vertically averaged polluta concentration corresponding to river concentration  $c_{\bf p}$  = 100 and

concentration  $c_{\text{o}}$  = 0 at all inle

to bay. Concentrations given at time increments equal to one eighth of the tidal period beginning at 1ow tide.



























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## JULY

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time increments equal to one eighth of the tidal period beginning at low ti de.

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## AUGUST





































## SEPTEMBER



river concentration  $\mathsf{c}_\mathsf{R}$  = 100 and concentration c<sub>o</sub> = 0 at all inle to bay. Concentrations given at time increments equal to one eighth of the tidal period beginning at low tid




























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APPENDIX B

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A MAGNETIC TAPE QF THE COMPUTER PROGRAMS USED FOR THIS REPORT ALONG WITH EXPLANATIONS AND INSTRUCTIONS COMPRISE APPENDIX B

The tape contains FORTRAN programs constituting the hydrodynamic features model, the dispersion model and a plotting routine. The Hydraulics Laboratory used the following parameters to create the tape.



A map of the tape follows.

Files 1, 2, 3, and 4 contain programs needed to prepare the data for use in the hydrodynamic features model. Files 5, 6, 7, and 8 represent the hydrodynamic features model, and files 9, 10, and 11 contain the dispersion model. File 12 comprises a Gould 5100 Electrostatic Plotter routine which can plot grid and element geometry, water surface elevation, velocity vectors and concentrations. The program files are a size convenient for storage in interactive terminal files.

The Hydraulics Laboratory user's instructions and sample job control used by the Hydraulics Laboratory for the two models and the plotting program on the University of Florida's Amdahl 470 V/6-II under OS MVS/SE and JES2/NJE system control also follow.

#### USER'S MANUAL FOR CNEE

SOURCE: Massachusetts Institute of Technology Report No. 200

The program is designed to run without overlays. All arrays have object time dimensions and thus only the actual dimensions in the main program need to be changed. The variables used to determine the correct dimensions must be specified in main program. They are:



The dimensions should be assigned as follows:

DIMENSION TITLE(20), TEXT1(2,2), TEXT2(2,2), TEXT3(2,2),

ICON(MAXEL, 3), A(MAXEL, 3), B(MAXEL, 3), AREA(MAXEL), NEUM(MAXEL),  $\mathbf{I}$ 

2 HEXT (MAKNOD), NINT (MAKNOD), XORD (MAXNOD), VORD (MAKNOD), DEPTH (MAXNOD), NBC (MAXNOD),

- 3 SYSMH (MAXNOD, MAXBWH), SYSMQ (2\*MLYNOD, MAXBWQ),
- 4 H(MAXNOD), Q(2\*MAXNOD), HPREV(MANNOD), QPREV(2\*MAXNOD),
- 5 SYSFH (MAXNOD), SYSFQ (2\*MAXNOD),
- SYSEMH(2\*MAXHBN, MAXBWH), SYSBMQ(2\*MAXQBN, MAXBWQ), NHN(MAXHBN), 6. NON(MAXQBN)MNVN(10),
- 7 [REQUAREBN], ALAG (EAXHBN), QB (SEXQBN), QUANG (EAXQBN), TAUWX (MAXNOD), TAUWY (MANNOD),
- 8 PSPLUS (MAXNOD), CF (MAXEL), EDEX (MAXEL), EDEY (MAXEL), NILM (MAXEL), NEN (3\*MAXBEL).
- 9 EDXY(MAXEL), HTC(MAXHBN, MAXHTC), IPNT(MAXHBN), NFLUX(30), FLUX(30), VS (MAXRBN)
- DIMENSION ETA (MAKNOD), U (MAXNOD), V (MAXNOD), ETAPRV (MAXNOD), DELRO (MAXNOD),
- 1 NHEN(3), ICONL(3, MAXL), NMETP3(3), ICON3(3, MAXO), DISCHS(MAXO), CBDIS(4)

For special tidal and wind forcing the and routines STETAB and WINDS can be modified.

ALTER DIMENSIONS IN SUBROUTINE FORCEQ



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MBAND a maximum over all alerents (1 = 1, 2991) of 1 plus maxidum internal node number of element I minus the minimum internal node number of element 1, where the internal node number, NINT(I), is determined by the ordering during read in: NINT(NEXT(I)) =  $\lambda$ ,  $I = 1$ , NMNP.  $NBC(I)$ node code = 0 internal node = 1 prescribed normal flow  $= 2$  prescribed height = 3 prescribed height and normal flow  $=$  4 prescribed normal and tangential flow ( $\equiv$ 0) = 5 prescribed height and both flows  $= 6$  source/sink node = 7 source/sink node with prescribed normal flow = 8 source/sink node with both flows set to zero  $XORD(I)$  x - coordinate  $y -$ coordinate  $TORD(1)$  $DEFTH(I)$ bottom depth referred to datum (usually MLW). Positive if bottom is below datum, negative if above.  $DUM$ DUM2 dummy variables used to input prescribed values DUM3 according to NBC as described below: DUM4 NBC + E met used  $JUM1 = 01$ ,  $DUM2 = OBM17$ . DUM1 =  $\text{HB}$ , DUM2 =  $\text{MAC}$ DUMI HE, DUMP ALAG, DUMB = QB, DUM4 = QBANG DUM:  $+$  OB, DUM2 = 2ANC  $5$  DUM1 = HE DUM2 = ALAG, DUM3 = OB, DUM4 = QRANG  $6$  DUM1 = FI.UX 7 DUM1 FLUX, DUM2 = QE, DUM3 = QEANG  $9$  DUM $1$  = FLUX where: OB is local x flow OBANG is the angle from x-agis to outward normal at node. The direction of the normal is determined by requiring net flow across adjoining segments to vanish.

```
H as tidal amolitade
                      ALAN is time lug-
                      FLUX is source flux, \pi^3/sec
CARD GROUP 4 Element Data. NMEL Cards, (4710, 4F10.0)
      I = 1, NMEL, 1
      NELM(I) external element number
      ICON (1,1) external node numbers el, e2, e3 in sense from s
      ICON (I, 2)toward y.
      TCON (1, 3)CF(I) bottom friction coefficient, note: if CF(I) > 1, and IF(1) \leq lthen CF(1) - 1. is taken as Mannings
                                          n throughout.
      EDX(1)EDYY(I) \rightarrow eddy viscosities
      EDXY(I)CARD GROUP 5 System Properties. One Card (F10.0, E10.3, 3F10.0)
      ALATT latitude north
      OMEGA – phase velocity of earth's rotation = .72722 x 10<sup>-4</sup> sec<sup>-1</sup>
      GRAVI gravitational acceleration (=9.31 \text{ m/sec}^2)PERIOD period of tide, (not used if EITC = 1)
      DENSTY average density of water
CARD Geoup 6. Integration Parameters. One Card(3910.0, 110, F10.0, 2110)
      STRTIM start time of integration
      ENDTIM end time of integration
      TINC
              time increment
      NØ.
              external node number for which stability is checked
              (0 = zero)bound on height variation at node N3
      BOUND
              parameter to be used for variable time stepping, use
      TGT
              I since this has not yet been implemented
              hard copy output for every NOUT time steps
      NOUT
            max number of half tide curves +1NMHTC
CARD GROUP 7 Land Boundary Data. One Card (8110)
              number of land boundaries
      NMLB
      (MMLBN(I), I = 1, NMLB) number of nodes on each land boundary,
      including first and last
```
Card group 8: Segment connectivity. One Card per Boundary (2014)  $I = 1$ , MMLB (ICONL(I,J),  $J = 1$ , NMLEN(I) external node numbers on boundary in sequential order such that area is to left of direction of advance Card group 9: Ocean Boundary Data. One Card (8110) NSEGMT number of ocean boundaries (NMHNPB (I), I = 1, NSEGMT) number of height nodes on ocean boundary, including first and last Card group 10: Segment Connectivity. One Card per Boundary (2014)  $1 = 1$ . NSEGMT  $(1 \text{COMB}(I,J), J = 1, \text{MMMPB}(I))$  external node numbers on ocean boundary in sequential order such that area is to left of direction of advance Lard group 11: Boundary elements First card (I10) NMBEL number of sides of total boundary Next cards (2014) NBN(I) I = 1, 3\*NMBEL, element and two node numbers corresponding to each side. Card group 12: Wind information. One card (2F10.0) WINDSP Wind speed in [m/sec]. Note: the wind drag coefficient assumes WINDSP is in [m/sec]. WDIRC Wind direction (blowing from!) relative to x-axis in degrees. Card group 13: Mass storage file specifications. The cat? (8110) IUNITQ = File unit number for discharges NRECQ = Number of records in file HUNITQ NSIZEQ = Record size in file IUNITO IPOINT = Record pointer in file IUNITQ (usually = 1) (Ex. DEFINE FILE IUNITO (NGCCO, NSIZEO, U. IPOINT)

ENITH = File unit number for depths  $NRECH$  = Number of records in file IUNITH NSIZEH = Record size in file IUNITH KPOINT = Record pointer in file IUNITQ (usually  $\sim$  1) (Ex. DEFINE FILE IUNITH (NRECH, NSIZEH, U, KPOINT)

## Only if

IHTC = 1 include data for each ocean boundary node in the sequence that the boundary nodes appear in the group 3 cards consisting of 2\*(MMHTC) values. The first two values should be zero. (8F10.0)  $(I = 1, 13958)$ HTC(I,J)  $J = 1, 2\star$ (NMHTC) consist of pairs of amplitude and time.

## $0aly$  if

INPUTH = 2 include data for initial values of heights (  $(NMNP - 1)/8 + 1$ ) cards (8F10.0)  $(ETA(I), I = 1, NMP)$  initial surface elevations, internal in role ordering.

#### Only if

INPUTQ = 2 include data for initial values of flows  $((2*NMP - 1)/8 + 1)$  cards (8F10.0)  $(Q(I), I = 1, 2*NDNP)$  initial flows in pairs of x- and ycomponents. Internal node ordering.

Card group 14: Termination Card. One Card (16I5)

## $IVERS$ : = 0 Instead of fermination card, which will stop the execution, input for a new problem may be inserted (repeat card groups I through II).

User's Manual for DISPER SOURCE: Massachusetts Institute of Technology Report No. 2l8

The following describes the requirements of the 2-D vertically integrated dispersion model, DISPER. The model predicts contaminant concentration at the nodal points of a two dimensional finite element grid representing the solution field given the following information:

- i! **the** geometry of **the** solution field in **the** form of a finite element grid, including the depth of each node.
- ii) direct input, functional relations, or auxiliary program describing the circulation field aver time, dispersion values **and decay coefficients.**
- iii) location, duration, and strength of source and sink nodes, elements or sides.
- **iv! location,** duration, and magnitude at prescribed concentration nodes (boundary conditions).
- v) initial concentrations at each node (initial conditions).

The user may choose whatever units he wants to work with, as long as **they** are **maintained in** all **the input.** Units **of** mass **N!, length L!,** and time (T) are indicated in the input description.

**The user** must asceztain **that rhe** dimensioned **arrays** eze sufficiently large. For this purpose and for transferring arrays to subroutines the following variables must **be** defined:

> MAXNP Maximum number of nodes that can be handled by program. C1, C2, C3, F1, F2, P, XORD, YORD, DEPTH. SYSM, SYSB, NINT, NEXT, U, H, V, COE. P2

- MAXEL Maximum number of elements that can be handled by program, ICON, AREA, A, B, ED, NELM, NILM.
- MAXES Maximum number of element sides with prescribed load, 1B, QS.
- MAXBN Maximum number of nodes with prescribed concentration. CNODE, NB.
- MAXFE Maximum number of element with prescribed load. IPE, PE.
- MAXFN Maximum number of nodes with prescribed load. IPN. PN.
- MAXBW Maximum bandwidth of coefficient. The model will compute the necessary bandwidth for a given problem. See also card group 3. SYSM, SYSS.
- MAXLB Maximum nunber of land boundaries. NLBN. ICONTU

MAXLBN Maximum number of nodes per land boundary. ICONTU

The arrays associated with each variable have been listed. In addition the following array should be dimensioned:

### Q(2\*MAXNP)

All arrays are transferred to subroutine as arguments and need only be dimensioned in the main program. Note, if the above maximum values exceed the values needed for a given problem no changes are necessary.

The following describes the specific input data requirements. Card group 1: Title. One card (18A4)

Card group 2: Parameters and Options. One card (8I10)

- NUMEL Number of elements (not eo excood MAXEL set in main program)
- NUMAP number of nodes (not to exceed MAXNP)
- NBSIDE number of boundary sides with specified flux (not to exceed MAXBS)
- NBNODF. number af noues with specif ied concentration not to exceed MX3N!
- NFLXE number of source/sink elements (not to exceed MAXFE)
- NFLXN **number** of source/sink nodes (not to exceed MAXFN)
- NFLAG  $\{ =0 \}$  constant boundary conditions over time **1 varying** boundary conditions over time

Card group 3: Nodal Information. NUMNP cards (I5, 5X, 3F10.0)  $M = 1$ , NUMNP NEXT(M) external node number

The order in which these values are entered is important. The order must be such **that** the band width of the grid **does** not exceed the **maximum specified value, MAXBW, in the main program. Internal node** numbers are assigned to each node in the order in which they are read in. The band width is calculated as the maximum value of the difference between the highest and lowest internal node numbers for each element. **For** efficiency of storage, this value should be kept small.

> XORD(M) x-coordinate of external node NEXT(M) (L) YORD  $(M)$  y-coord inate of external node NEXT  $(M)$  (L)  $DEFTH(M)$  depth at node  $NENT(M)$ . (L)
Card group 4: Element Data. NUMEL cards (4110)  $I = 1$ , NUMEL N(I) element number (in ascending order)  $ICON(N,1))$ external node numbers of the element given  $ICON(N, 2)$ in sense of x toward y  $ICON(N, 3)$ Card group 5: Land boundaries. One card (8110). **NMLB** number of land boundaries (MLBN(I),  $I = 1$ , NMLB) number of nodes in each boundary For each boundary  $(I = 1, NMLB)$  (2014) ICONTU(J, I) nodes of boundary I in successive order when progressing such that the domain is to the left at the boundary.  $(J = 1, NLSN(I))$ Card group 6: Prescribed loads and concentrations. Only if NBSIDE > 0: Side Boundary Data. NBSIDE cards (2110, F10.5)  $1 = 1$  NBSIDE  $IB(I,1)$  external node numbers at end points of side  $1B(1,2)$  boundary I given so that area of interest is<br>to left of direction of advance inward flux per unit length  $(M - 2T^{-1})$  $QS(I)$ Only if RENGE-G: Node Boundary Data. NBNODE cards (I10, F10.0)  $1 = 1$ , NENODE  $NB(I)$ external node number at which concentration is specified  $CNODE(I)$ specified concentration at external node  $N\overline{B(1)(N/2)}$ Only if NFIXE > 0: Source/sink Elements. NFLXE cards (I10, FULA)  $I = 1$ , NFLXE IPE(I) source/sink external node number  $PE(I)$ specified inflow per unit standard area  $(ML^{-2}T^{-1})$ 

Only if NFLXN > 0: Scott /sink Node. . 187 XN enrds (110, E10.4)  $I = 1$ , NFLXN IPN(I) source/sink external node number PN(I) specified inflow at external node IPN(I)  $(MT^{-1})$ Card group 7: Integration Parameters and Options. One card (2F10.0 F15.0, 5, F10.5, 615) STRTIM start time of integration ENDTIM end time of integration **DT** time increment MAXIT maximum number of allowable iterations (should be 10 in most cases) **TOL** tolerance for convergence (this is the normalized RMS error, .001 used in development work with satisfactory results) hard copy output for every NOUT timesteps NOUT IRUN run identifications number 1 constant uniform velocity field own purposes. = 1 constant dispersion coefficient with uniform IDIS  $\begin{cases} \text{given value} \\ = 2 \text{ variable dispersion coefficient determined in} \end{cases}$ subroutine DISCO IHOT  $\int_{-1}^{\infty} \frac{1}{t^2}$  values of initial concentration to be read in

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```
= 1 values of concentration will be punched
                ICARD<br>= 0 values of concentration will not be
                               punched after last iteration
Card group 8A
Only if IVEL \neq 3 include data for initial values of the velocity, tidal
                  amplitude and tidal velocity angular frequency.
                  One card (4F10.3)
                  VTIME velocity in x direction
                  VTR42 velocity in y direction
Only if IVEL = 2 AMP tidal velocity amplitude
                  OMEG tidal velocity angular frequency
Card group 8B
Only if \text{DIS} = 1: One card (3F10.3, E10.3)
                   DXEYY \Big\{ dispersion coefficients (L^2T^{-1})EXY )
                   WDECAY decay (T^{-1})Card group 80
Only if IDIS = 2: One card (2F10.3, E10.3)
                   CONl longitudinal dispersion constant (L^2r^{-1}):0M2 lateral dispersion constant (L^2T^{-1})PMCAY decay (T^{-1})Card group ti
Only if 160f = 1: \equiv eger (NUMNP/7) cards (7EI1.4)
                    CI(III), ifi - 1, MMMP in'tial concentration
                    vector, in internal numbering order (i.e., the
                    same order in which the nodes are read in)
```
Card group 9: Termination Card (F10.0) STRTIM =  $-1$ . Instead of a termination card, which will stop the execution, input for a new variation of card group 7 may be inserted (repeat Card groups 7 through 7D).

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These programs were written to assist the user in preparing the input data for CAFE. Their use will not only reduce the setup time for a new grid, but will ensure greater accuracy in the results. This set of programs includes:

- BOUNDELM This program computes the boundary element data for CAFE (Card Group 2).
- **QBANG** - Computes values of QBANG for all land boundary nodes  $(in$  Card Group  $3).$
- **NBAND** - Computes internal node numbering for minimum band width.
- Allows user to specify system inflows in units of cubic **QBCOMP** meters per second. QBCGMP will convert these units into those required by CAFE  $(m^2 \text{ sec}^{-1})$ .

### **BOUNDELM**

This program will determine the boundary element data required as input to CAFE. Inputs are: number of nodes, number of elements, element connectivity, and boundary data. The boundary element data are output in a form suitable for input to CAFE.

DIMENSIONING:

 $NMEL = number of elements$ NMNP =  $number$  of nodes #BNDS = number of separate boundary strings, land and water MAX#NODS = mamimum number of nodes on any one boundary #BNDELMS = maximum number of boundary elements #OCNBNDS = number of ocean boundaries

Dimensions should be at least

 $NELM - (NMEL)$ 

 $ICON - (NMEL, 3)$ 

MEMEL =  $(NMNP, 8)$ 

 $NMENT - (NMP)$ 

ICONB - (#BNDS, MAX#NODS)

 $NMSN - (ABNDS)$ 

BNDARY - (#BNDELMS)

BNDELM - (#BNDELMS)

 $BND:01 - (BANDELMS)$ 

BNDNO2 - (#BNDELMS)

NMENO - (#OCNBNDS)

Input Data:

Card Group 1: NMEL, NMRP

 $(m_e \text{ Card } (215))$ 

Card Group 2: Element Conectivity

Same as Card Group 5 in CAFE User's Manual.

 $\sim 100$ 

 $\sim 10^{-11}$ 

 $\sim 10^{-1}$ 

Card Group 3: Boundary Data

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Same as Card Groups 8, 9, 10 and 11 in CAFE User's Manual.

 $\sim 10^{11}$  k  $^{-1}$ 

 $\blacksquare$ 

 $\sim 100$ 

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 $\mathcal{L}^{\text{max}}_{\text{max}}$  .

 $\sim 200$ 

This program will, upon input of the nodal and boundary information from CAFE, compute all values of QBANG and output correctly formatted CAFE node input data with values of NEXT, NBC, X, Y, DEPTH, and QBANG.

# Dimensioning:

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```
NMNP - number of node points
NMLB - number of land boundaries
NMLBN - maximum number of nodes on any land boundary
```
# Inputs:

Card Group 1: 1 Card NMNP ( $\dot{=}$  of node points) (110) Card Group 2: NHNP Cards (215, 3F10.0) (NEXT(I), NBC(NEXT(I)), X(HEXT(I), Y(HEXT(I)), DEPTH(NEXT(I)),  $I = 1$ ,  $NMP$ Card Group 3: Land Boundary Data- (3110) One Card NMLB,  $(NMLBN(I), I = 1, NMLB)$ Card Group 4: Segment Connectivity (2014)

 $(ICONL(I,J), J = 1, NMLBH(I))$ 

### **NBANO**

Upon entering of the number of nodes, the number of elements, the CAFE nodal data, and the element interconnectivity matrix, this program will reorder the nodes in such a way as to provide the lowest possible bandwidth for the element configuration.

Dimensioning:

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Dimension Variables:

NMEL - number of elements

NMNP - number of node points

DIMENION ICON1(NMEL), ICON2(NMEL), ICON3(NMEL), ICON(3\*NMEL), MEMJT(8\*NMNP), JMEM(NMNP), JNT(NMNP), NEWJT(NMNP), JOINT(NMNP),<br>JPD(NMNP), NEXT(NMNP), NBC(NMNP), X(NMNP), Y(NMNP), D(NMNP), DI (NMNOP), D2(NMNP), D3(NMNP), D4(NMNP)

Input Data:

Card Group 1: NMNP, NMEL One Card (215)

 $\mathcal{L}(\mathcal{A})$  , and  $\mathcal{L}(\mathcal{A})$ Card Group 2: Nodal Information

Same as Card Group 3 in CAFE User's Manual

Card Group 3: Element Connectivity

Same as Card Group 4 in CAFE User's Manual

Program Output:

The program will output the nodal information in its reordered form, it will also output the bandwidth of the grid configuration.

## 0500MP

In CAFE, specified inflows to the system are given in units of meters<sup>2</sup>-sec<sup>-1</sup> (velocity x depth). QBCOMP will convert units of meters<sup>3</sup>-sec<sup>-1</sup> (discharge) into the CAFE units. (Note: This program is used most easily in interactive WATFIV, but can be run in batch if desired.)

Dimensioning:

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NMNP - number of node points

NMLB - number of land boundaries

NMLBN - maximum number of nodes on any land boundary

DIMENION NEXT(NMNP), X(NMNP), Y(NMNP), S(NMNP), IS(NMNP), JS(NMNP), ICONL (NMLB, NMLBN), NMLBN (NMLB)

Input Data:

Card Group 1: NMNP One Card (I5)

Card Group 2: Nodal Information

Same as Card Group 3 in CAFE User's Manual.

Card Group 3: Land Boundary Data

Same as Card Group 8 and 9 in CAFE User's Manual.

Card Group 4: NNODES One Card  $(15)$ 

NNODES is the number of nodes for which inflow computation is desired.

Card Group 5: Inflow Data "KODES Cards (15, F10.2)

- a) Node external node number of node for which inflow computation is delined.
- b)  $Q =$  specified inflaw in  $\approx 3\pi s^3$ -sec<sup>-1</sup>.

#### MISCELLANY

Define File Statements - The define file statements in the main program (statement numbers 27, 28, and 32) must be modified to correspond to the directaccess files being read. (For an explanation of the define file statement, see "IBM System 360/370 FORTRAN IV Language, p. 72.) File 10 contains discharge information, File 11 contains heights, and File 12 has concentrations. The number of records, and the length of these records, should be specified as they were in the CAFE or DISPER run which generated the output to be plotted. If problems with reading the direct-access files are encountered, these statements are the first places to check.

Net Velocity Plots - When producing a net velocity plot (IVEL = 2), the "time information" card (Card Group 2c) should be coded:

 $NPLOTS = 2$ 

 $\label{eq:2} \frac{1}{\sqrt{2}}\int_0^1 \frac{dx}{y^2}dx$ 

NTIME(1) = NTIME at which velocity averaging is to start

NTIME $(2)$  = NTIME at which velocity averaging is to stop

When plotting net velocities over one tidal cycle, care must be taken to ensure that NTIME(1) and NTIME(2) define exactly one tidal cycle. Since the magnitude of instantaneious velocities is generally much greater than the magnitude of the net velocities, and since the net velocities are generated by vector addition, omission of even a small part of a tidal cycle will lead to large errors in the plot.

Dimensioning - If dimensioning problems are encountered in one of the subroutines, check the dimension variable initialization in the block data suproutine.

This program will graphically display the outputs generated by CAFE and DISPER. It will:

Plot element geometry with optional element numbering. Plot element grid boundaries. Plot velocity vectors generated by CAFE. Generate and plot net velocities. Plot concentrations generated by DISPER. Plot water surface elevations generated by DISPER.

The nodal coordinates may be any real value; the grid will be drawn properly 'located with respect to a pair of labeled x and y axes. The line thicknesses of the elements, grid boundaries, and velocity vectors are user-specified options. Inputs for velocity, water surface elevation, and concentration are taken from the directaccess files generated by CAFE or DISPER.

NOTE: All references to the CAFE User's Nanua1 refer to Wang's version.

# Dimensionin

# Dimension Yariables:

- NMNP number of node points
- NMEL number of elements
- NMLB number of land boundaries
- NMLBN maximum number of nodes on any land boundar
- NMOB number ot ocean boundari
- NMOBN maximum number of nodes on any ocean boundary
- $NPLOTS number of plots in a time sequence (see card group 2)$

# Dimension Statement: (M/PROG)

DIMENSION NEXT (NMNP), NINT(NMNP), X(NMNP), Y(NMNP), NELM(NMEL),<br>ICON(NMEL, 3), XC(NMEL), YC(NMEL), NMLBN(NMLB), ICONL(NMLB, NMLBN), NMOBN(NMOB), ICONO(NMOB, NMOBN), C(NMNP), ARRAY(NMNP), U(NMNP), V(NMNP),  $H(NMNP), Q(NMNP*2), A(3), TITLE(14), XT(18), YT(18), NTIME(NPLOTS),$  $BS(10)$ ,  $D(NMNP)$ 

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# Program Inputs



2b) BS (10A4) this is another space for entering notes in the title block. This space is useful for recording the data set name(s) of the disk(s being used.

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2c) Time Information (2015)

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NPLOTS,  $(NTIME(I), I = 1, NPLOTS)$ 

Where each NTIME(I) is a fortran direct-access record number for which a plot is desired, and NPLOTS is the number of these.

Card Group 3: Scale Parameters One Card (4F10.2)

- a) GSCALE scale of plot (GSCALE units/inch of plot)
- b) VSCALE scale of velocity vectors
- c) CFACT concentrations to be plotted will be multiplied by this factor to aid in plot interpretation
- d) TSC scale factor for title block. This is useful when producing plots which will be reduced. TSC = 1.0 yields a title block  $4.0" \times 1.6".$  TSC > 1.0 yields a proportionately large title block.

One Card (415) Card Group 4: Lineweights

An explanation of allowable values for the line weight parameters can be found in the Gould Plot Package Programming Manual, Sec. 2.4.

- a) LW1 element geometry
- b) LW2 land boundaries
- $c)$  LW3 ocean boundaries
- d) LW4 velocity vector arrows
- Card Group 5: NMEL, NMNP One Card  $(215)$ 
	- a) NMEL number of elements
	- b) NMNP number of node points

## Card Group 6: Nodal Coordinates

This is the same as "Card Group 3" in the CAFE User's Manual.

# Card Group 7: Element Data

This is the same as "Card Group 4" in the CNFE User's Manual.

Card Group 8: Land Boundary Data

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Card Group 9: Segment Connectivity

Card Group 10: Ocean Boundary Data

Card Group 11: Segment Connectivity

Card Groups 8-11 are identical to Card Groups 7-10 in the CAFE Users 's Manual. If IBOUND = 0, these cards may be omitted.

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//\$CAFE\_JIB(1066,0806,1000,25,0), 'CARIL\_CIRINER', CLASS=1,REGIUM=300K<br>/\*PASSHORD\_\_\_\_\_001,NDHE //\$CAFE JUE(1063,0803,1000,25,0), 'CARUL CORNER', CLASS=1,<br>/\*PASSMORO 001,NDHE<br>/\*ROMITE FRINT LOCAL<br>/\* EXEC FORTXCC, OFTIONS='OFT=2',LPARN='SIZE=500K'<br>//FORT.SYSTH DO \*<br>/\*INCLUDE SSPACES 10040604.3<br>/\*INCLUDE CAFE3 10040604 51  $\mathbf{1}$  $\mathbf{1}$  $\mathbf{1}$ ٥ % 218000 406045<br>AINCLUDE BRIND6 10060806.4<br>AINCLUDE BROELING 10060906.3  $\mathbf{1}$ 200  $11$  $\frac{2.24}{10}$  $\frac{707}{1464}$  ${\bf u}$ 1464 281  $\mathbf{1}$ 1 532 /#INCLIDE HTIDE oC 10060506.2  $\ddot{\mathbf{0}}$ ÷ VCO.FIOT 001 DD SYSOLT=0<br>//CO.FI10F001 DD DSN=UF.00060006.HTCCU.<br>// UNIF=SYSO0.SPACE=(TRK.(53.2).RUSE).<br>// DISP=(.CATLC).DCB=(DSNN=DA)<br>// DISP=(.CATLC).DCB=(DSNN=DA)<br>// UNIF=SYSO0.SPACE=(TRK.(26.2).RUSE).<br>// DISP=(.CATLG).

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//DISPER\_JEB\_(1006,0806,1500,50,0),/fiPHLACHICELA\_BAY/,CLASS=1\_<br>/\*PASSLDRD\_\_\_\_\_\_001,NINE **SUBARUM AND ANNUAL STATE STATE**<br>STREBUTE PRINT LOCAL<br>STREBUTE PRINT LOCAL<br>STREBUTE PRINCE, ON TIONS = 'GPT = 2' //FORT.SYSIN DO W<br>/MINCLUDE DISDING 10060306.2<br>/MINCLUDE DISPERS 10060306.3<br>/MINCLUDE\_DISPER2 10060606.3 **AGU.SYSIN OD #** GRED #6 - CONSTANT RODE CONCENTRATEORS, HEN FORRS 439 281<br>
ATROLLOE RIDES 10060806.3<br>
ATROLLOE RIDES 10060806.4<br>
ATROLLOE DISBND6 10060806.4<br>
ATROLLOE DISBND6 10060806.4<br>
ATROLLOE PORTET 10060806.4<br>
0.0<br>
0.0<br>
0.0<br>
0.0 23 9. O. 0 ٥ 10 0.001 60  $\overline{z}$  $\mathbf{1}$ 3  $\mathbf{1}$ 1500.00 1500.00 0.0E01<br>/\*INCLUDE NOTCONG 10060006.3  $-1.9$ ä, ANSO LEOPEROL DD SYSGIT-4 //GB.FFIGF001 BD DSR=IF A0040804.HTChR,<br>// DISP=(BLD, KEEP)<br>//GB.FFI1F001 BD DSR=IF A0040804.HTChH, 77 DISP=(OLD, KEEP) 

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//CAFERAF JER (1906,0809,10,2.0),/ANN CONNAY/,CLASS=A<br>/\*RASSMORO 001,NIME<br>/\*ROUTE FRINT TCP<br>// EXEC FURTGCG,PLUT=<br>//FORT.SYSPRINT DD DUMYY<br>//FORT.SYSTN DD \*<br>/\*IRCLUDE GRAFFORT<br>//CO.SYSTN DD \*<br>0 1 0 1 0 0 1 1 5800<br>
0 -1 2 0<br>
0 -1 2 0<br>
439 781<br>
41HCLUDE NUDE6 10C6(809.1<br>
ALHCLUDE NUDE6 10C6(809.1<br>
ALHCLUDE EUMBE6 10C6(809.1<br>
AKKCLUDE EUMBE6 10060809.3<br>
AKKCLUDE EUMBE1<br>
AKKCLUDE EUMBE1<br>
AKKCLUDE CURCI<br>
ACCO.FT10F001 DD DSN=UF.  $1 - 91$  $0.6$  $\mathbf{r}$ 

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