

1 **Can autocorrelated recruitment be estimated using integrated assessment**
2 **models and how does it affect population forecasts?**

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18

19 **Abstract**

20 The addition of juveniles to marine populations (termed “recruitment”) is highly variable due to
21 variability in the survival of fish through larval and juvenile stages. Recruitment estimates are
22 often large or small for several years in a row (termed “autocorrelated” recruitment).
23 Autocorrelated recruitment can be due to numerous factors, but typically is attributed to multi-year
24 environmental drivers affecting early life survival rates. Estimating the magnitude of recruitment
25 autocorrelation within a stock assessment model and examinations on its effect on the quality of
26 forecasts of spawning biomass within stock assessments is uncommon. We used a simulation
27 experiment to evaluate the estimability of autocorrelation within a stock assessment model over a
28 range of levels of autocorrelation in recruitment deviations. The precision and accuracy of
29 estimated autocorrelation, and the ability of an integrated age-structured stock assessment
30 framework to forecast the true dynamics of the system, were compared for scenarios where the
31 autocorrelation parameter within the assessment was fixed at zero, fixed at its true value, internally
32 estimated within the integrated model, or input as a fixed value determined using an external
33 estimation procedure that computed the sample autocorrelation of estimated recruitment
34 deviations. Internal estimates of autocorrelation were biased toward extreme values (i.e., towards
35 1.0 when true autocorrelation was positive and -1.0 when true autocorrelation was negative).
36 Estimates of autocorrelation obtained from the external estimation procedure were nearly
37 unbiased. Forecast performance was poor (i.e., true biomass outside the predictive interval for the
38 forecasted biomass) when autocorrelation was ignored, but was non-zero in the simulation.
39 Applying the external estimation procedure generally improved forecast performance by
40 decreasing forecast error and improving forecast interval coverage. However, estimates of
41 autocorrelation were shown to degrade when fewer than 40 years of recruitment estimates were
42 available.

43

44 **Keywords:** autocorrelated recruitment; integrated stock assessment model; statistical catch at age;
45 rebuilding plan; population forecast

46 **1. Introduction**

47 Under the United States Magnuson-Stevens Fishery Conservation and Management Act (United
48 States Public Law 104-297), all stocks included in United States Fishery Management Plans must
49 have target and limit reference points and forecasts of the level of catch (annual catch limit) that
50 will prevent overfishing. Protocols for calculating annual catch limits in a way that will prevent
51 overfishing with a specified probability have been developed (Shertzer et al., 2008), but are
52 dependent on the quality of forecast precision. Further, all overfished stocks must have a
53 rebuilding plan. Rebuilding plans involve specifying management measures to rebuild the stock
54 to a biomass associated with maximum sustainable yield (β_{MSY}) within 10 years (or, if rebuilding
55 within 10 years is impossible, then one generation time plus the median time for rebuilding in the
56 absence of fishing). Legally, rebuilding plans must be more likely than not to succeed, i.e., be
57 based upon a probabilistic forecast of future population dynamics given the agreed level of fishing
58 that implies recovery with $\geq 50\%$ probability.

59 Stock assessment models represent the link between collected data and scientific advice in
60 fisheries management. Assessments are expected to use fits to historical data and prescribed
61 harvest policies to forecast future stock abundance and catch levels. These predicted “Acceptable
62 Biological Catches” must account for scientific uncertainty and ensure $\leq 50\%$ probability that
63 overfishing will occur (Methot et al., 2013). Variability in recent recruitment to the stock is a
64 major contribution to this scientific uncertainty. As the United States National Marine Fisheries
65 Service (NMFS) works to reduce the number of overfished stocks, projection success is being
66 examined more critically, and the accuracy of probabilistic forecasts in rebuilding plans is
67 receiving increased research attention (Neubauer et al., 2013; NRC, 2013).

68 Reference points and rebuilding forecasts are often estimated using a stock assessment model
69 that treats fluctuations in recruitment as a random process around a prediction derived from a
70 presumed relationship between spawning biomass and recruits (Clark, 1993; Methot and Wetzel,
71 2013). Stock assessments are increasingly conducted using “integrated” population dynamics
72 models that typically incorporate many data types, including samples of compositional data from
73 fisheries and surveys, indices of abundance, and information regarding total fishery harvests
74 (Maunder and Punt, 2013). These data are combined to estimate values for population productivity
75 (parameters in the stock-recruitment relationship) and status (spawning biomass in each year
76 relative to reference points). Probabilistic forecasts of future population dynamics can then be
77 made given assumed fishing mortality rates.

78 Recent studies illustrate that recruitment for many fishes is non-random over time and includes
79 high and low periods (Hollowed et al., 2001; Szuwalski et al., 2014; Thorson et al., 2014). These
80 periods could be driven by environmental factors acting on recruit survival (Wilderbuer et al.,
81 2002), adult reproductive output (Jørgensen et al., 2006), or both simultaneously (Okamoto et al.,
82 2012; Wooster and Bailey, 1989), or changes in the abundance of predators (Bailey, 2000).
83 Ideally, researchers can identify measureable environmental factors that are correlated with
84 recruitment deviations or regime shifts, and which can be forecast into the future (Haltuch and
85 Punt, 2011). If an environmental factor that helps predict future recruitment can be identified, it
86 can then be used to inform rebuilding forecasts (Holt and Punt, 2009; Punt, 2011) and reference
87 point calculations (Lindgren and Checkley, 2013). If an environmental factor cannot be
88 identified, population forecasts are sometimes calculated for various “states-of-nature”, where
89 each state-of-nature depends upon a hypothetical scenario for expected future recruitment (e.g.,
90 high, average, and low productivity scenarios; Peterman and Anderson, 1999).

91 When correlated measurable environmental factors remain unidentified, the influence of
92 regime shifts can still be accounted for by invoking autocorrelation in future recruitment deviations
93 (i.e., where future recruitment deviations are greater or less than zero for many years in a
94 sequence). Including “autocorrelated recruitment” in the population dynamics model may result
95 in wider forecast intervals (i.e., less precise) compared with the case in which recruitment is
96 assumed to follow a white-noise process. This wider forecast interval may, in some cases, have
97 better statistical coverage (e.g., a 75% forecast interval that contains the true value 75% of the
98 time) than forecasts that do not account for autocorrelation in recruitment. Well-calibrated
99 statistical coverage is a pre-requisite of probabilistic methods used for forecasting and reference
100 point determination (Shertzer et al., 2008).

101 In this study, we explore and evaluate the performance of population forecasts obtained from
102 an integrated, age-structured assessment model when recruitment is autocorrelated. We conduct
103 a simulation experiment using a design involving six plausible levels of autocorrelation in
104 recruitment deviations (ρ) and four alternative configurations for estimating ρ in the assessment
105 model. We explore estimation performance by answering two questions:

- 106 1. How well can the magnitude of autocorrelation be estimated? and
- 107 2. Does accounting for autocorrelation improve the accuracy and predictive coverage of
108 forecasts compared with ignoring autocorrelation in recruitment deviations?

109 We conclude by outlining a practical strategy to test and account for autocorrelated recruitment
110 when generating forecasts in real-world assessment models.

111 2. Methods

112 We conducted a simulation experiment using the Stock Synthesis (SS; based on version 3.24f)
113 assessment software (Methot and Wetzel, 2013), which is widely used in the United States and
114 provides an integrated framework for conducting assessment models for a broad variety of data
115 and biological conditions. The SS software is an age-structured forward-projection single-species
116 stock assessment framework that estimates recruitment along with other parameters related to
117 stock productivity and trends. SS uses the C++ ADMB libraries (Fournier et al., 2012) to calculate
118 uncertainty estimates for parameters of interest (e.g., past and future recruitments) based on the
119 Delta method approximation. Simulations and analyses were accomplished using the *ss3sim*
120 software package (Anderson et al., 2014a, 2014b; available at github.com/kellijohnson/AR-perf-testing)
121 to ensure the results are reproducible.

122 The simulation framework consists of three components: (1) an operating model that generates
123 the true population dynamics; (2) a sampling model that generates data from the operating model;
124 and (3) an estimation method that is applied to the simulated data, where the parameter estimates
125 and derived quantities (i.e., forecasted future population abundances) from the estimation method
126 can be compared with their true values from the operating model. We use a design involving six
127 levels of ρ and four alternative configurations of the estimation method. Additionally, a “less-
128 informative” scenario was simulated and fitted using each estimation method while also estimating
129 stock-recruit steepness to facilitate evaluating performance in a more realistic environment. One
130 hundred simulation replicates were generated for each scenario, where each replicate has a
131 different realization of process (here, recruitment deviations) and observation errors. Each
132 replicate involves simulating population dynamics over 100 years, which we divide into three
133 periods:

- 134 1. “Burn-in period” – Years 1-25 are simulated without any fishing;

- 135 2. “Fishing period” – Years 26-80 include a simulated fishery, with fishing mortality set to
 136 F_{MSY} , and the potential for data from the fishery and a survey, which is used to fit an
 137 assessment model in year 80; and
 138 3. “Forecast period” – Years 81-100 are simulated without fishing, which can be compared
 139 to forecasts based on parameter estimates derived from the estimation method.

140 2.1 Operating model

141 The operating model represents a cod-like life history based on biological parameters estimated
 142 from the stock assessment for North Sea cod (*Gadus morhua*; Deroba et al., 2015) with some
 143 simplifications facilitating interpretation of the results (Table 1). Simplifications include: one
 144 fishery and one survey, combined sexes, and selectivity parameters based on the maturity ogive.

145 We used the steepness-parameterization of the Beverton-Holt stock-recruit function:

$$146 \quad r_t = \frac{4hr_0b_t}{b_0(1-h)+b_t(5h-1)} e^{\varepsilon_t - \sigma_r^2/2}, \quad (1)$$

147 where r_t and b_t are the estimates of recruitment output and spawning biomass, respectively, in year
 148 t , h , and r_0 are estimated parameters representing steepness (the strength of recruitment
 149 compensation) and average recruitment at unfished spawning biomass b_0 . The recruitment
 150 deviation ε_t is calculated as:

$$151 \quad \varepsilon_t = \rho\varepsilon_{t-1} + \delta_t\sqrt{1 - \rho^2}, \quad (2)$$

152 where δ_t is a normally distributed coefficient representing recruitment variability after accounting
 153 for the stock recruit relationship:

$$154 \quad \delta_t \sim N(0, \sigma_r^2), \quad (3)$$

155 where σ_r^2 is the marginal variance of recruitment deviations and ρ is the magnitude of
 156 autocorrelation in recruitment. Eq. 1 includes the term $e^{\varepsilon_t - \sigma_r^2/2}$, which has an average value of
 157 1.0. This term is included to ensure that r_0 is equal to mean (not median) recruitment given
 158 unfished spawning biomass.

159 Each replicate of the operating model involved simulating true dynamics over 100 years, where
 160 recruitment is variable each year, but the same across scenarios for a given iteration (i.e., the values
 161 of δ_t for the first replicate of the $\rho = 0.0$ scenario were the same as for the first replicate of the $\rho =$
 162 0.9 scenario, see Fig. 1). Years 1 through 25 had no fishing and are included to ensure that the
 163 population age-structure in year 25 had plausible deviations away from its expectation in an
 164 unfished state. In years 26-80, fully-selected fishing mortality, F , was fixed at the value that
 165 produced MSY . Fishery selectivity was logistic, based on fish length, and was identical to the
 166 maturity ogive. Survey selectivity was similar, except that the length at which 50% of individuals
 167 were selected by the survey was specified as 80% of the length at which 50% of individuals were
 168 mature to ensure that the survey sampled younger fish than were caught in the fishery.

169 We simulated data for six scenarios that differed in the value of autocorrelation used to
 170 generate recruitment: -0.25, 0, 0.25, 0.5, 0.75, and 0.9. Included levels of ρ are centered
 171 approximately around estimates from recent meta-analyses (Mueter et al., 2007; Thorson et al.,
 172 2014). An autocorrelation level of 0.5 and a marginal log-standard deviation of recruitment of 0.6
 173 (0.2 higher than all other scenarios) was used for a “less-information” scenario.

174 **2.2 Sampling model**

175 Annual catch was reported without error from the start of the fishery (year 26) to the year of the
 176 assessment (year 80). Fishery and survey age-composition data were simulated every year for
 177 years 26-80, and were drawn from a multinomial distribution with an annual sample size of 100.
 178 The survey was simulated every year providing an index of relative abundance for years 26-80,
 179 and the abundance index was drawn from a lognormal distribution with log-standard deviation of
 180 0.1 and log-mean equal to logarithm of stock biomass available to the survey in that year. Data
 181 are relatively informative to focus the results on the effects of autocorrelated recruitment
 182 deviations when estimation is theoretically possible. Data collection for the “less-information”
 183 scenario started in year 41 and the log-standard deviation of the index of abundance was 0.25.

184 **2.3 Estimation method**

185 An age-structured stock assessment model was fit to each simulated data set, using data generated
 186 during the “fishing period” (see Table 1 for a list of estimated parameters). Each estimation
 187 method provides forecasts of population abundance during years 81 to 100, and estimates
 188 recruitment deviations for years 1-100. For clarity of communication, we refer to recruitment
 189 deviations during the three periods:

- 190 1. Recruitment deviations for years 1-25: These recruitment deviations occur prior to the
 191 collection of any data, and are estimated so that the estimated age-structure in the first year with
 192 data (typically year 26) has plausible deviations away from the unfished age-distribution;
- 193 2. Recruitment deviations for years 26-80: These recruitment deviations occur during years with
 194 available data, and are generally estimated with some precision;
- 195 3. Recruitment deviations for years 81-100: These recruitment deviations occur during the
 196 forecast period, and ensure that dynamics during this period include a plausible magnitude of
 197 recruitment variation.

198 All estimation methods are provided no data during the forecast period (years 81-100), so
 199 recruitment deviations for years 81-100 are estimated at their expected value (i.e., zero when $\rho = 0$,
 200 or decaying towards zero from the value of the estimated recruitment deviation in year 80 when ρ
 201 $\neq 0$).

202 The estimation method is similar to the operating model, except it also includes annually
 203 varying bias-correction for estimated recruitment:

$$204 \quad r_t = \frac{4hr_0b_t}{b_0(1-h)+b_t(5h-1)} e^{\varepsilon_t - \gamma_t \sigma_r^2 / 2}, \quad (4)$$

205 where Eq. 4 replaces Eq. 1 from the operating model, and γ_t is the fraction of bias-correction
 206 included for each year. The bias-correction term $e^{-\gamma_t \sigma_r^2 / 2}$ is included to ensure that r_0 is equal to
 207 mean (not median) recruitment given unfished spawning biomass. The corresponding negative
 208 log-likelihood computation is:

$$209 \quad -\log(\mathcal{L}_t) = \begin{cases} \gamma_t \log(\sigma_r \sqrt{1 - \rho^2}) + \frac{\varepsilon_t^2}{(1 - \rho^2) \sigma_r^2} & \text{if } t = t_{first} \\ \gamma_t \log(\sigma_r \sqrt{1 - \rho^2}) + \frac{(\varepsilon_t - \varepsilon_{t-1})^2}{(1 - \rho^2) \sigma_r^2} & \text{if } t > t_{first}, \end{cases} \quad (5)$$

210 where this equation uses the conditional standard deviation, $\sigma_r \sqrt{1 - \rho^2}$, as the standard deviation
 211 for each recruitment deviation, such that the input standard deviation parameter, σ_r , corresponds
 212 to the standard deviation across the entire time series and t_{first} refers to the first year that
 213 recruitment deviations are estimated. This calculation is identical to the negative log-likelihood

214 for a normal distribution except that it ignores the additional constant of integration, $\log(2\pi)$, and
215 multiplies the conditional standard deviation by the bias-correction term, γ_t . Exploratory analysis
216 suggested that scaling the log of the conditional standard deviation by the bias-correction factor
217 leads to improved estimates of recruitment variability σ_r . However, we note that it is necessary to
218 remove γ_t from Eq. 5 when conducting mixed-effects estimation (Thorson et al., 2015b), and that
219 an alternative bias-corrected estimator is possible using mixed-effects methods without including
220 an explicit bias-correction term in the likelihood computation (Thorson and Kristensen, 2016).
221 However, we use Eqs. 4-5 here, following standard practice in penalized likelihood models and
222 SS.

223 We implement bias-correction for each simulation replicate following the approach in Methot
224 and Taylor (2011) of:

- 225 1. Run the model once to identify maximum likelihood estimates and standard errors for all
226 parameters including ε_t ;
- 227 2. Calculate standard error estimates, $\widehat{SE}(\varepsilon_t)$, and estimate the bias-correction for each year, $\hat{\gamma}_t =$
228 $1 - \widehat{SE}(\varepsilon_t)^2 / \sigma_r^2$
- 229 3. Fit a five-parameter bias-correction “ramp” (Methot and Taylor, 2011) to the annual bias
230 correction estimates, $\hat{\gamma}_t$;
- 231 4. Use predictions of bias-correction, γ_t , for each year in Eq. 1, and re-run the estimation method
232 to identify maximum likelihood estimates and standard errors for all parameters.

233 This bias-correction algorithm can be derived under the assumption that recruitment deviations are
234 a random effect (Thorson and Kristensen, 2016). For estimation methods with $\rho \neq 0$, the bias
235 correction γ_t is sometimes greater than 0.0 during the forecast period, particularly for larger levels
236 of recruitment autocorrelation. Bias-correction is included during the forecast period because
237 recruitment deviations at the end of the fishing period (e.g., year 80) will inform recruitment
238 deviations during the forecast period (e.g., year 81) whenever $\rho \neq 0$. The delta-method is used
239 for calculating uncertainty in population abundance during the forecast period. Therefore, forecast
240 period abundance has a standard error that includes uncertainty about future recruitment
241 deviations, and this uncertainty is a function of the level of recruitment autocorrelation.
242

243 **2.3.1 Estimation method configurations**

244 The following four estimation methods were investigated for each level of ρ :

- 245 1. “True” – an estimation method where the autocorrelation parameter was fixed at the level used
246 to generate the recruitment deviations in the operating model. This estimation method is not
247 plausible for any real-world assessment (given that the true value of ρ will never be known),
248 but is included as a reference case to demonstrate model performance if the extent of
249 autocorrelation were known exactly.
- 250 2. “Zero” – an estimation method where $\rho=0$. This estimation method represents the most
251 common assumption in stock assessment models to date.
- 252 3. “Internal” – an estimation method where ρ is estimated as a fixed effect in SS. This scenario
253 will likely result in biased estimates of ρ , given that SS implements “penalized likelihood”
254 estimation rather than true “mixed-effect” estimation (Thorson and Minto, 2015). Previous
255 research demonstrates that penalized likelihood estimation results in negative bias when
256 estimating the variation in the recruitment deviations (σ_r , Thorson et al., 2014). The bias
257 correction approach developed by Methot and Taylor (2011) is an empirical attempt to
258 overcome this negative bias. However, its performance when estimating the magnitude of ρ
259 has not been previously explored.

260 4. “External” – an estimation method where ρ is estimated externally to SS. This involves
261 extracting estimates of recruitment deviations from the “Zero” estimation method, and then
262 estimating the first-order autocorrelation of these estimates using the `acf` function in R (R
263 Core Development Team, 2015). This level of autocorrelation is then set as a fixed value in
264 SS and the bias-correction parameters are updated, and then SS is run again. This estimation
265 method will likely have different estimation performance than the “Internal” estimation
266 method, given that sample- and population-level estimates are often different in maximum
267 likelihood estimates of mixed-effects models (Breslow and Clayton, 1993).

268 In each scenario, the marginal log-standard deviation of recruitment σ_r was fixed at the true value
269 (Table 1). Steepness was estimated in the “less-information” scenario using a beta prior (mean =
270 0.65, sd = 0.147) and fixed at the true value for all other scenarios.

271 For each estimation method, we specified that fishing mortality was zero during the forecast
272 period, and this matches the operating model, which has no fishing during the forecast period.
273 Given that fishing rate is correctly specified during the forecast period, any bias or imprecision in
274 population abundance during the forecast period arises either from (1) bias and imprecision of
275 estimated parameters during the fishing period or (2) the impact of mis-specifying ρ during the
276 forecast period. The correct input sample size for multinomial composition samples ($N_{input} = 100$)
277 were specified in each estimation method (i.e., the estimation method had correct weighting for
278 age-composition sampling data). Convergence of the estimation method was determined using the
279 maximum gradient of the objective function, where models with a maximum gradient of less than
280 0.01 and a positive definite Hessian matrix were assumed to have converged. Models that failed
281 to converge were removed from the analysis, and exploratory analysis confirms that results (not
282 shown) are qualitatively similar when changing the gradient threshold used to identify model
283 convergence.

284

285 2.3.2 Evaluating model performance

286 Estimation performance was evaluated using three performance statistics:

- 287 1. relative error, $RE = (\hat{\theta} - \theta)/\theta$, where $\hat{\theta}$ and θ are estimated and true parameter values,
288 respectively and a well-performing estimation method will have a relative error close to zero
289 for all simulation replicates;
- 290 2. average absolute relative error, $AARE = (\sum_{i=1}^{n_{reps}} \sum_{t=t_{min}}^{t_{max}} |RE_{i,t}|)/N$, where $RE_{i,t}$ is the relative
291 error in spawning biomass, n_{reps} is the number of simulation replicates, t_{min} and t_{max} are years
292 over which AARE is calculated (e.g., $t_{min}=26$ and $t_{max}=80$ when summarizing performance
293 during the “fishing period”), and N is the total number of observations (i.e., years and
294 replicates); and
- 295 3. yearly forecast interval coverage, defined as the proportion of simulation replicates where the
296 forecast interval contains the true value from the operating model. A well-calibrated model
297 will have approximately nominal forecast interval coverage, i.e., a 50% forecast interval will
298 contain the true value in 50% of simulation replicates.

299 3. Results

300 3.1 Estimating autocorrelation

301 We first seek to determine whether an integrated assessment model can provide an accurate and
302 precise estimate of ρ . We therefore evaluate estimates produced either when treating ρ as a fixed
303 effect (“Internal”) or when calculating the sample autocorrelation of estimated recruitment
304 deviations (“External”). “Internal” estimation is biased towards extreme values in all scenarios

305 (i.e., towards 1.0 when true autocorrelation is positive and towards -1.0 when true autocorrelation
306 is negative; Fig. 2, top row). “Internal” estimation also has a high proportion of simulation
307 replicates that does not converge when the true autocorrelation is 0.9. In these cases, the estimated
308 autocorrelation approaches the bound at 1.0 and the Hessian matrix is generally not positive
309 definite. By contrast, external estimates of ρ are approximately unbiased for all levels of
310 autocorrelation (Fig. 2, bottom row). “External” estimation also leads to a larger proportion of
311 converged replicates compared to “Internal” estimation. As a sensitivity analysis, we also show
312 “External” estimates of ρ given different quantities of data for estimating recruitment (Fig. 3; i.e.,
313 with fishery compositional data and survey data starting in either year 41 or 56, compared with
314 year 26 by default). This shows that ρ can be estimated reasonably well with as few as 25 years
315 of informative data (Fig. 3, bottom row), although estimates become more precise with increasing
316 years of data. Additionally, “External” estimation was on average less biased than “Internal”
317 estimation for the “less-information” scenario ($\overline{RE} = -0.21$ and 0.42 , respectively).

318 **3.2 Impact of autocorrelation on population forecasts**

319 We next seek to determine the impact of autocorrelated recruitment on population forecasts, and
320 whether estimating and accounting for ρ improves model performance. To do so, we first illustrate
321 the effect of autocorrelated recruitment on estimated spawning biomass for all years (years 1-100)
322 for a single replicate of the simulation experiment (Fig. 4). As expected, fixing autocorrelation at
323 its true value results in a forecast interval that expands rapidly during the forecast period (years
324 81-100) whenever autocorrelation is substantially different from zero. Most notable, the lower
325 confidence bound for forecasts of spawning biomass declines over time when recruitment
326 autocorrelation is 0.9, despite the forecast model correctly assuming that fishing is absent during
327 this period (Fig. 4, top right).

328 These patterns also hold for the average absolute relative error (AARE) in estimates of
329 spawning biomass across replicates (Fig. 5). During the “fishing” period (years 26-80), the AARE
330 in estimates of spawning biomass is generally less than 0.04 for all estimation methods and all
331 levels of true autocorrelation. We therefore conclude that increased recruitment autocorrelation,
332 or mis-specifying recruitment autocorrelation, has relatively little impact on the precision and
333 accuracy of estimates of spawning biomass during the period with information to estimate
334 recruitment deviations, given an otherwise correctly specified model. However, increased
335 autocorrelation leads to a large increase in AARE during the forecast period (years 81-100), such
336 that AARE is 0.20-0.26 when autocorrelation is 0.9. All estimation methods have an AARE of
337 0.1 during the forecast period when recruitment is not autocorrelated, but when ρ is high ($\rho =$
338 0.75 or 0.9) the “True” and “External” methods have lower AARE (0.17 - 0.18 and 0.20 - 0.21) than
339 the “Zero” method (0.19 and 0.26). All estimation methods have a small positive bias in spawning
340 biomass during the forecast period when autocorrelation is 0.75 and even more so when
341 autocorrelation is 0.9 . Exploratory analysis indicates that this bias arises due to the nonlinear
342 stock-recruit function, i.e., because calculating forecasts based on the mean of the stock-recruit
343 function is not identical to the expectation of the forecast due to this nonlinearity.

344 Finally, we illustrate 50% forecast interval coverage for each estimation method, defined as
345 the proportion of simulation replicates where true spawning biomass falls within a 50% forecast
346 interval (Fig. 6). A well-performing estimation method will have nominal coverage probability,
347 i.e., 50% of simulation replicates will fall within the 50% interval. When autocorrelation is absent
348 (Fig. 6, column “0.00”), all estimation methods have approximately nominal coverage, although
349 they exhibit less-than-50% coverage (indicating too narrow of forecast intervals) in years 84-87.

350 When ρ is fixed at its true value (Fig. 6, top row), coverage remains close to 50% for all levels of
351 true autocorrelation. However, increasing true autocorrelation leads to a large decline in coverage
352 for the “Zero” estimation method (Fig. 6, 2nd row). Coverage is close to 20% in year 90 for this
353 estimation method (only 10 years into the forecast period) when true autocorrelation is 0.75, and
354 is approximately 10% in this year when true autocorrelation is 0.9. By contrast, coverage is
355 slightly smaller than 50% for the external estimation method when true autocorrelation is 0.75 or
356 0.9. We therefore conclude that external estimation substantially improved forecast interval
357 performance relative to a model that neglects autocorrelated recruitment. Coverage was similar for
358 a 75% forecast interval, though more variable and less optimistic (Fig. 6, open circles). Coverage
359 was less than expected for all estimation methods in the “less-information” scenario (Fig. 7).

360 **4. Discussion**

361 Fisheries management in the United States and worldwide increasingly uses integrated stock
362 assessment models to evaluate the likely impact of alternative management measures on fish
363 population abundance. The United States and Europe both seek to end overfishing and rebuild
364 overfished stocks (see Magnuson-Stevens Fishery Conservation and Management Reauthorization
365 Act of 2006, <http://www.nmfs.noaa.gov>, and European Union Common Fisheries Policy,
366 http://ec.europa.eu/fisheries/cfp/index_en.htm). Rebuilding plans for overfished stocks in the
367 United States are based upon forecasts of population abundance, and each United States Regional
368 Fisheries Management Council is required to develop an approved Rebuilding Plan that will result
369 in rebuilding within a pre-determined time frame. Rebuilding Plans are also required to be more
370 likely than not to succeed in their stated timeframe, i.e., rebuilding plans are premised on a
371 probabilistic interpretation of the forecasts generated from integrated stock assessment models. A
372 probabilistic interpretation of catch advice arising from stock assessment models is also used in
373 many United States regions to incorporate scientific uncertainty when defining catch limits
374 (Shertzer et al., 2008) or when interpreting stock status relative to biological reference points (e.g.,
375 Stewart et al., 2013).

376 In this study, we demonstrate that autocorrelated recruitment has a substantial impact upon
377 both the accuracy of forecasts (i.e., how close they are to the true value) as well as the width of
378 forecast intervals (i.e., the magnitude of the estimated standard error for forecasts). In particular,
379 high levels of autocorrelation (i.e., $\rho > 0.5$) result in substantial increases in the relative error of
380 population forecasts, regardless of whether the stock assessment accounts for recruitment
381 autocorrelation or not. Also, a model where autocorrelation is fixed at its true value showed that
382 forecast interval width is substantially increased when autocorrelation is high compared to when
383 it is zero. These results confirm that the certainty of population forecasts is highly dependent upon
384 the presence or absence of recruitment autocorrelation. Presumably, high recruitment
385 autocorrelation could contribute to the lack of rebuilding for some fishes under rebuilding plans
386 worldwide, particularly if forecasted biomass is overestimated, as in our results (Hutchings, 2001;
387 Neubauer et al., 2013). Previous analysis of model output from stock assessment models suggests
388 that recruitment may have intermediate, positive autocorrelation for marine fishes (Ianelli, 2002;
389 Thorson et al., 2014). However, care should be taken when interpreting these previous results, as
390 well as results from the “External” estimation method, which are based on model-output (Brooks
391 and Deroba, 2015; Thorson et al., 2015a).

392 We have also shown improvements in forecast interval performance when fixing
393 autocorrelation at the sample autocorrelation of estimated recruitment deviations (the “External”
394 estimation method). Accuracy of forecast interval width is less important for forecasts that only

395 utilize the median, but if fisheries managers use other quantities from the forecast (i.e., seek a
 396 management procedure that achieves a target biomass with 75% probability), or have Harvest
 397 Control Rules where the percentile for catch advice depends on the degree of depletion, then it is
 398 necessary to have accurate estimates of forecast interval width. Our simulation results show that
 399 the “External” estimate of autocorrelation provides less biased estimates of autocorrelation than
 400 estimating autocorrelation as a fixed effect, as currently implemented in SS.

401 The poor forecast interval performance when estimating autocorrelation as a fixed effect likely
 402 arises from the use of penalized-likelihood estimation methods. Penalized likelihood has
 403 previously been shown to result in negatively biased estimates of the variance of recruitment
 404 deviations (Thorson et al., 2015b), and a sample-based statistic has therefore been developed for
 405 estimating this variance (Methot and Taylor, 2011). We tried modifying the Methot and Taylor
 406 (2011) approach to account for the impact of ρ on the realized variance of recruitments, by
 407 replacing the negative log-likelihood computation (Eq. 5) with the following:

$$408 \quad -\log(\mathcal{L}_t) = \begin{cases} \gamma_t \log(\sigma_r) + \frac{\varepsilon_t^2}{(1-\rho^2)\sigma_r^2} & \text{if } t = t_{first} \\ \gamma_t \log(\sigma_r) + \frac{(\varepsilon_t - \varepsilon_{t-1})^2}{(1-\rho^2)\sigma_r^2} & \text{if } t > t_{first} \end{cases} \quad (6)$$

409 This modification resulted in estimates of ρ that were biased towards zero (results not shown), and
 410 we chose to proceed with Eq. 5, given that it has a stronger statistical justification. We note that
 411 fixing ρ at an externally derived value does not propagate uncertainty about the magnitude of
 412 autocorrelation when estimating standard errors for other parameters or derived quantities for
 413 management (e.g., the CV of average unfished spawning biomass may be different when ρ is
 414 estimated compared to when ρ is fixed).

415 Results presented here are representative of the best case scenario. Estimation methods were
 416 fit to a relatively large amount of informative data (i.e., data was available from both the fishery
 417 and a survey on a yearly basis) and were correctly specified. Furthermore, steepness and the
 418 marginal standard deviation of recruitment deviations were fixed at their true values. Previous
 419 research documented an inability to estimate steepness when autocorrelated recruitment deviations
 420 were accounted for (i.e., fixed at an externally estimated value) within the stock assessment
 421 framework (Butterworth et al., 2003; Iannelli, 2002), but did not investigate the effect of estimating
 422 steepness and autocorrelation on forecasts. Estimating steepness proved to be difficult no matter
 423 which estimation method was used to account for autocorrelated recruitment deviations, reminding
 424 us that poor forecast coverage can arise from causes other than autocorrelated recruitment. Future
 425 research could explore sensitivity to many types of model mis-specification, including: estimating
 426 steepness with more-informative data (e.g., catches from a stock experiencing a large contrast in
 427 spawning biomass) or mis-specifying its value; mis-specifying selectivity or growth parameters,
 428 such that estimated recruitment deviations incorporate process errors from mis-specifying other
 429 model components; and alternative forms for recruitment. In particular, we hypothesize that
 430 periodic changes in average recruitment (“regime shifts”) will appear as 2nd or higher-order
 431 autocorrelation, and that our specification of 1st-order autocorrelation might be a poor
 432 approximation in these causes.

433 Based on our results here, we identify several useful avenues for future research:

- 434 1. Most obviously, research could explore whether a mixed-effects estimate of autocorrelation
 435 could improve performance when estimating autocorrelation as a model parameter. Mixed-
 436 effects estimation is increasingly feasible using either the Laplace approximation (Kristensen

437 et al., 2016; Skaug and Fournier, 2006; Thorson et al., 2015b) or Markov-chain Monte Carlo
438 sampling (Stewart et al., 2013).

- 439 2. Future research could also explore the impact of autocorrelated recruitment on harvest strategy
440 performance when either estimating or ignoring autocorrelation. Autocorrelated errors during
441 forecast intervals are likely to impact the performance of harvest strategies (Wiedenmann et
442 al., 2015), but it remains unclear whether the magnitude of improvements from estimating the
443 extent of autocorrelation outweigh the additional complexity when developing and explaining
444 the model.
- 445 3. Bias adjustment methods (Methot and Taylor, 2011) were developed without accounting for
446 ρ , and future research should investigate how to account for this bias as well as autocorrelated
447 recruitment deviations. In particular, we recommend further investigation of mixed-effects
448 estimation and associated bias-correction methods (Thorson and Kristensen, 2016; Thorson
449 and Minto, 2015) as a generic solution to bias-correction for autocorrelated errors.
- 450 4. Finally, many parameters are likely to vary over time in stock assessment models, including
451 growth, maturity, selectivity, and productivity (Martell and Stewart, 2014; Thorson et al., In
452 press). These processes (e.g., time-varying selectivity) could affect the interpretation of length
453 composition samples, so neglecting time-varying selectivity could in some cases appear as
454 autocorrelated recruitment (Butterworth et al., 2003). We did not explore the impact of
455 multiple time-varying parameters on estimates of recruitment autocorrelation, and its potential
456 impact remains difficult to predict. We therefore recommend ongoing research to develop
457 tools to identify and account for time-varying parameters in stock assessment models.

458

459 5. Conclusions

460 We conclude that “External” estimation will likely result in better estimates of the magnitude of
461 autocorrelated recruitment when estimation is based on penalized likelihood. The estimation of ρ
462 appears to be most important for the forecast period as bias and precision were similar among mis-
463 specified and correctly specified models for the estimation period. Consequently, future research
464 should prioritize including ρ in all forecasts regardless of its magnitude and obtaining the best
465 external estimate of ρ possible, especially if forecasts are performed outside of the stock
466 assessment model. Unfortunately, even when ρ is fixed at its true value forecast coverage is poor
467 for the first ten years when autocorrelation is high. Therefore, rebuilding within 10 years for stocks
468 likely to have autocorrelated recruitment may necessitate updating the assessment more than once
469 during the 10 year period, and, potentially, even more frequently depending on the quality of
470 available data.

471

472 6. Acknowledgements

473 We gratefully acknowledge help from Ian Taylor, Chantel Wetzel, and Allan Hicks (NMFS,
474 NOAA) on implementation issues regarding *ss3sim* and forecasting within Stock Synthesis. We
475 thank James Ianelli for his comments on an earlier draft, which helped improve the content and
476 clarity of the manuscript. This publication is partially funded by the Joint Institute for the Study
477 of the Atmosphere and Ocean (JISAO) under NOAA Cooperative Agreement No.
478 NA10OAR4320148, Contribution No. 2. Partial funding for KFJ was provided by a grant from
479 Washington Sea Grant, University of Washington, pursuant to National Oceanic and Atmospheric
480 Administration Award No. NA14OAR4170078. This investigation contributes towards the work
481 plan of the ICES Working Group on Recruitment Forecasting in a variable Environment

482 (WGRFE). The views expressed herein are those of the authors and do not necessarily reflect the
483 views of NOAA or any of its sub-agencies.
484

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597 McFarlane, G.A. (Eds) *Effects of ocean variability on recruitment and evaluation of*
598 *parameters used in stock assessment models.* *Can. Spec. Publ. Fish. Aquat. Sci.* 108, 153-
599 159.

600 Table 1. Parameter specifications used in the operating models (OMs) and estimation methods
 601 (EMs). Parameter specifications that vary among scenarios (combinations of OMs and EMs) are
 602 denoted in the table.

Parameter		OM	EM
Name	Symbol	True value	Fixed (F) or Estimated (Est)
Natural mortality rate	M	0.2 yr ⁻¹	F
Length at age 1	$L_{a=1}$	20 cm	F
Asymptotic maximum length	L_{∞}	132 cm	F
Von Bertalanffy growth coefficient	k	0.2 yr ⁻¹	F
Coefficient of variation for length at age 1	$CV_{a=1}$	0.1	F
Coefficient of variation for asymptotic maximum length	CV_{∞}	0.1	F
Length at 50% maturity	θ_1^{mat}	38.2 cm	F
Length at 95% maturity	θ_2^{mat}	48.9 cm	F
Average recruits for the unfished population (natural log)	$\ln(r_0)$	18.7	Est
Steepness of the Beverton-Holt stock recruit function	h	0.65	F ¹
Marginal log-standard deviation of recruitment	σ_R	0.4 ²	F
Magnitude of autocorrelated recruitment	ρ	Varies	varies
Random coefficients for recruitment variability (years 1-100)	δ_t	Varies	Est
Catchability coefficient for survey index of abundance (natural log)	$\ln(q)$	0	Est
Length at 50% selection in the fishery	$\theta_1^{fishery}$	38.2 cm	Est
Length at 95% selection in the fishery	$\theta_2^{fishery}$	48.9 cm	Est
Length at 50% selection in the survey	θ_1^{survey}	30.6 cm	Est
Length at 95% selection in the survey	θ_2^{survey}	39.1 cm	Est

603 ¹Steepness is estimated in the “less-information” scenario using a beta prior (mean = 0.65, sd = 0.147).

604 ²Marginal log-standard deviation of recruitment is 0.6 in the “less-information” scenario.

605

606 Fig. 1. Examples of fifty years of autocorrelated recruitment deviations for three levels of ρ : (i) -
607 0.25 (dashed line), (ii) 0.00 (solid line), and 0.75 (dotted line), where each example used the same
608 set of process error deviations (δ_t).
609

610 Fig. 2. Estimates of recruitment autocorrelation (ρ) from two estimation methods: (i) estimated as
611 a fixed effect within Stock Synthesis simultaneously with other parameter estimation (“Internal”;
612 top row) and (ii) calculated as the sample autocorrelation of recruitment deviations estimated in
613 Stock Synthesis when ρ is fixed at zero (“External”; bottom row), for six (true) levels of
614 recruitment autocorrelation (columns). The dashed red line illustrates the true level of
615 autocorrelation, while the black shaded area is a histogram representing the simulation distribution
616 for each scenario and estimation method. The number in the top left of each plot indicates the
617 number of converged runs (out of 100).
618

619 Fig. 3. Estimates of recruitment autocorrelation (ρ) from the “External” estimation method, where
620 it is calculated as the sample autocorrelation of recruitment deviations estimated in Stock
621 Synthesis, for six (true) levels of recruitment autocorrelation (columns) and three different starting
622 years for fishery length- and age-composition samples. The dashed red line illustrates the true level
623 of autocorrelation, while the black shaded area is a histogram representing the simulation
624 distribution for each scenario and estimation method. The number in the top left of each plot
625 indicates the number of converged runs (out of 100).

626

627 Fig. 4. Illustration of estimated spawning biomass during 100 simulated years for different scenarios (columns, where recruitment
628 autocorrelation is $\rho=\{-0.25, 0.0, 0.25, 0.5, 0.75, 0.9\}$), and four estimation method (rows: “True”, “Zero”, “Internal”, and “External”),
629 where each panel shows the true spawning biomass (black line) and the red shaded area shows the 95% confidence and forecasting
630 intervals for the estimated spawning biomass.

631 Fig. 5. Relative error in spawning biomass during years for which the estimation method was provided data (years 26 through 80) and
632 the forecast period (years 81 through 100, to the right of vertical red dashed lines) for six levels of autocorrelation in the simulated data
633 (columns) and four estimation methods (rows). Horizontal dashed red lines indicate a relative error of zero. Upper and lower edges of
634 the boxes correspond to the first and third quartiles (the 25th and 75th percentiles) and the whiskers correspond to 1.5 times the distance
635 between the first and third quartiles. In each plot, the number in the top left indicates the number of converged runs (out of 100), the
636 bottom left number is AARE for the years with data, while the bottom right number is AARE in the forecast.

637

638

639 Fig. 6. Performance of forecast interval estimates for different estimation methods (rows) and levels of autocorrelation (columns), where
640 each panel shows the proportion of 50% (closed circles) and 75% (open circles) forecast intervals for spawning biomass that contain the
641 true value. A well calibrated 50% forecast interval will contain the true value 50% of the time. Calibration lines for both 75% and 50%
642 forecast intervals are indicated by the red dashed lines in each panel, respectively. Points above or below the line indicate forecast
643 intervals were too conservative (wide) or permissive (not wide enough), respectively. In each plot, the number in the top left indicates
644 the number of converged runs (out of 100).
645

646 Fig. 7. Relative error in spawning biomass (left column) and forecast coverage of spawning biomass (right column) for the “less-
647 information” scenario across four estimation methods (rows) when estimating steepness. Relative error in spawning biomass is shown
648 for years for which the estimation method was provided data (years 41 through 80) and the forecast period (years 81 through 100, to the
649 right of vertical red dashed lines), where the horizontal dashed red lines indicate a relative error of zero. Upper and lower edges of the
650 boxes correspond to the first and third quartiles (the 25th and 75th percentiles) and the whiskers correspond to 1.5 times the distance
651 between the first and third quartiles. Performance of forecast interval estimates shows the proportion of 50% (closed circles) and 75%
652 (open circles) forecast intervals for spawning biomass that contain the true value. A well calibrated 50% forecast interval will contain
653 the true value 50% of the time. Calibration lines for both 75% and 50% forecast intervals are indicated by the red dashed lines in each
654 panel, respectively. Points above or below the line indicate forecast intervals were too conservative (wide) or permissive (not wide
655 enough), respectively. In each plot, the number in the top left indicates the number of converged runs (out of 100) and the number in
656 the top right indicates the relative error in steepness. In each plot, the number in the top left indicates the number of converged runs (out
657 of 100), the top right is the relative error in steepness, the bottom left number is AARE for the years with data, while the bottom right
658 number is AARE in the forecast.
659

Fig. 1.

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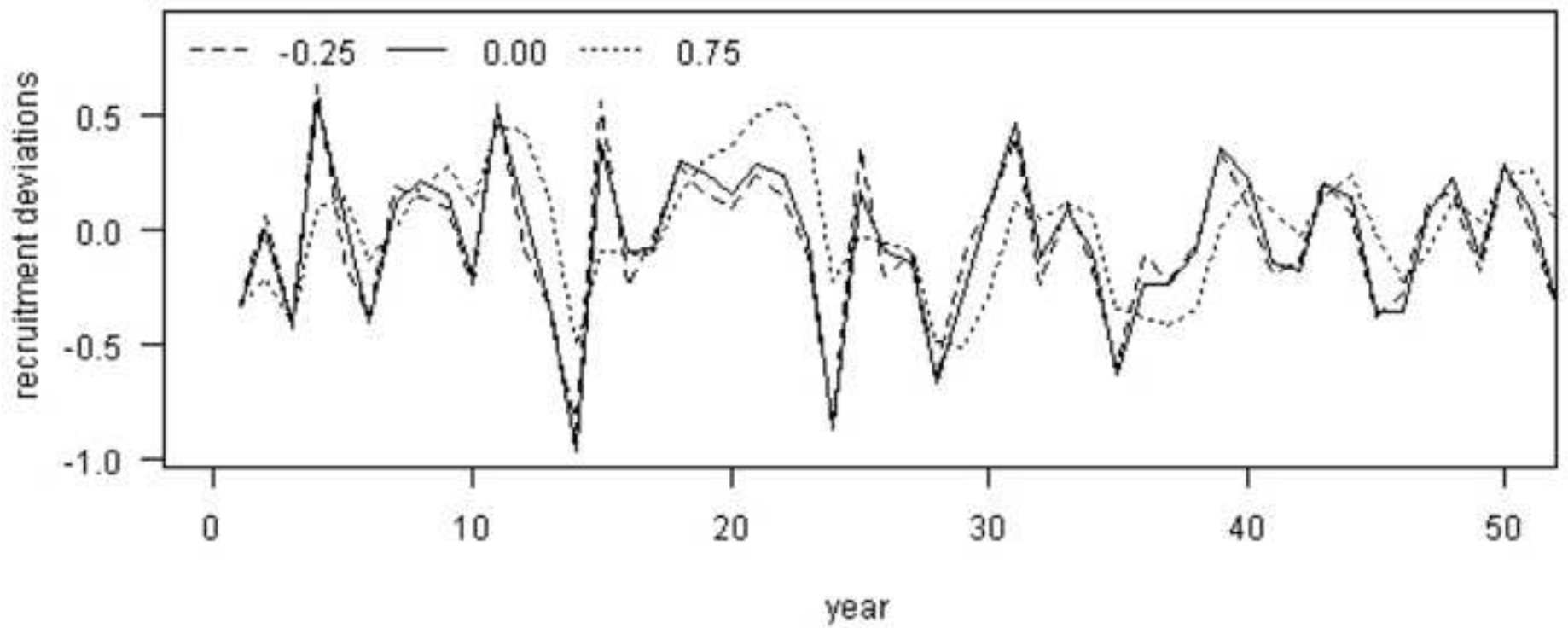


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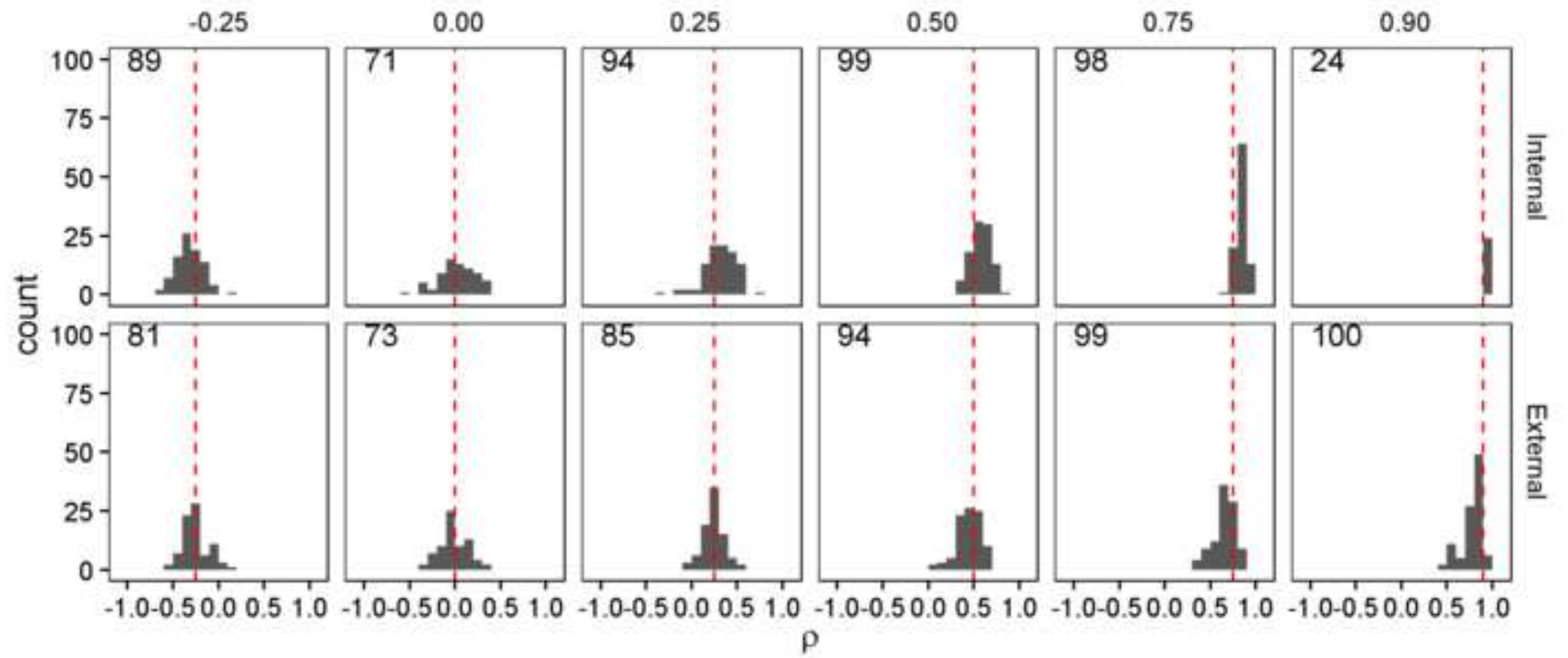


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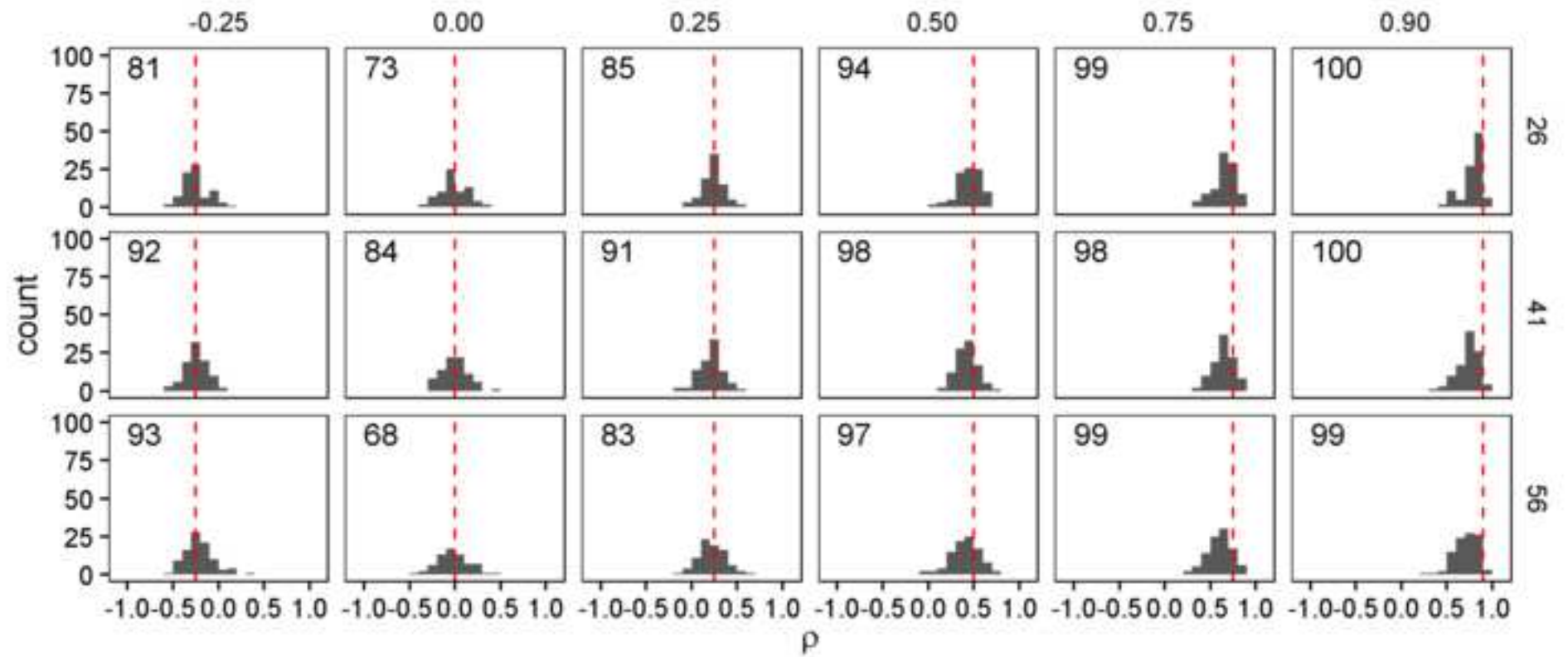


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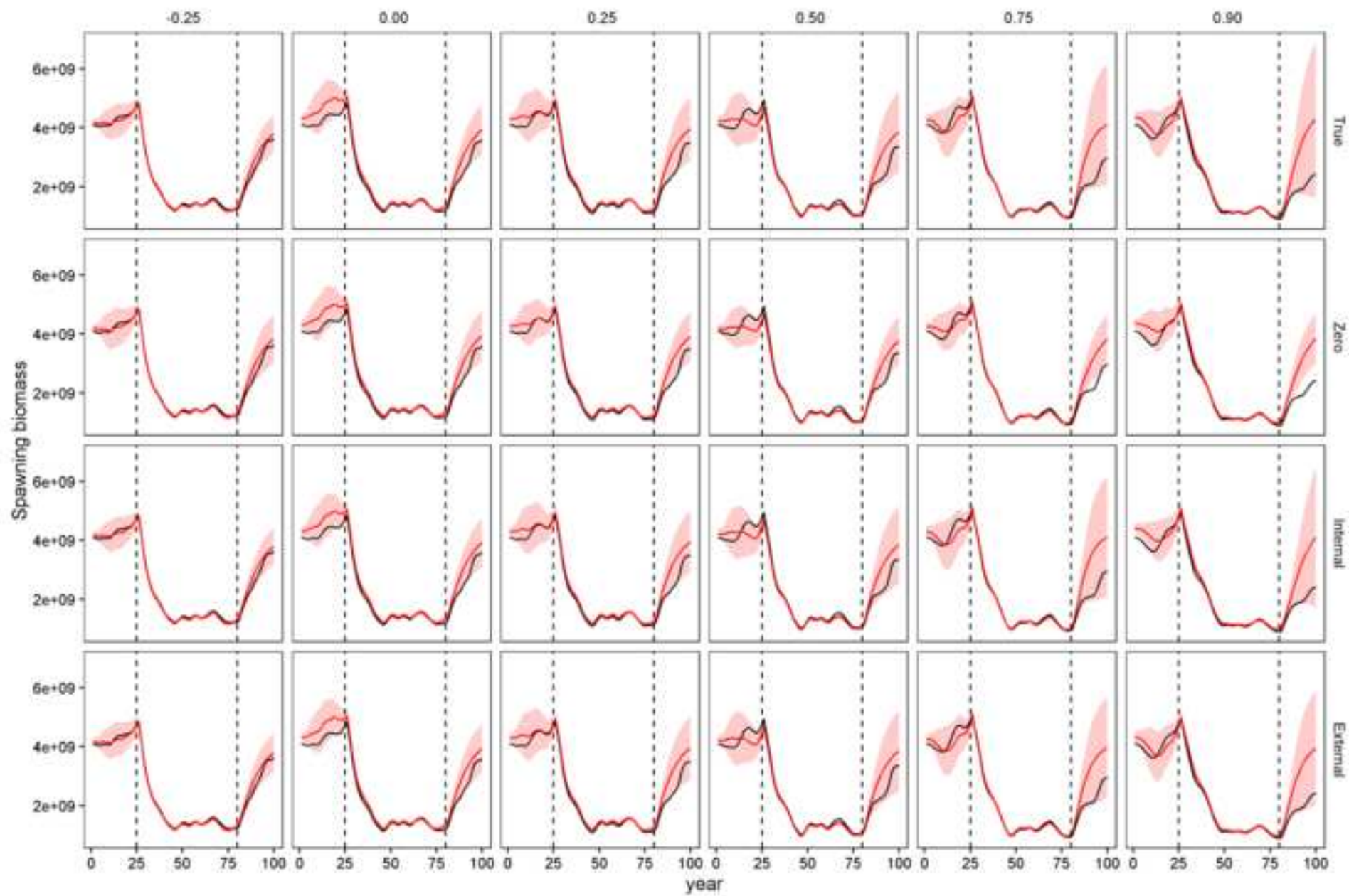


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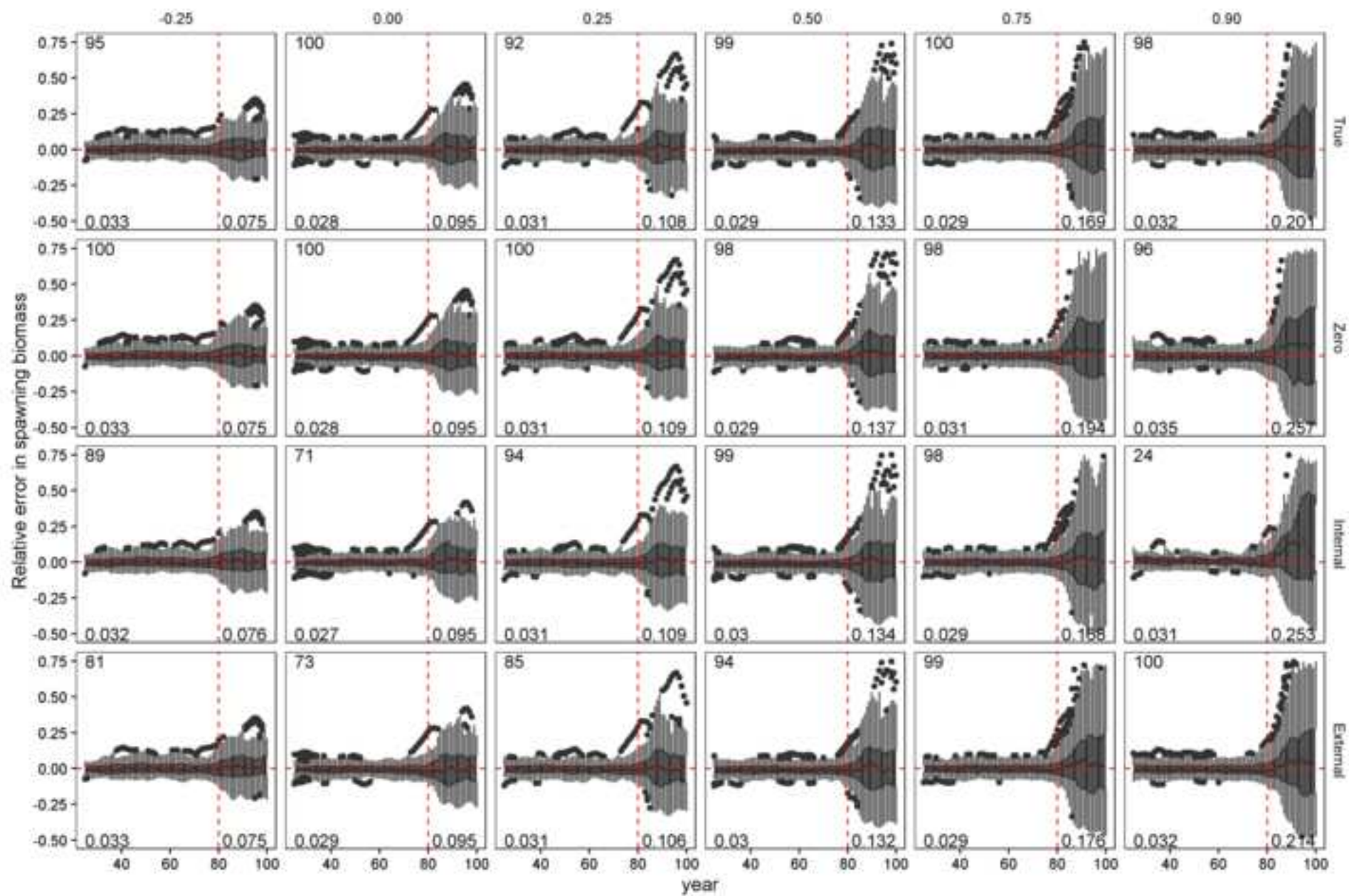


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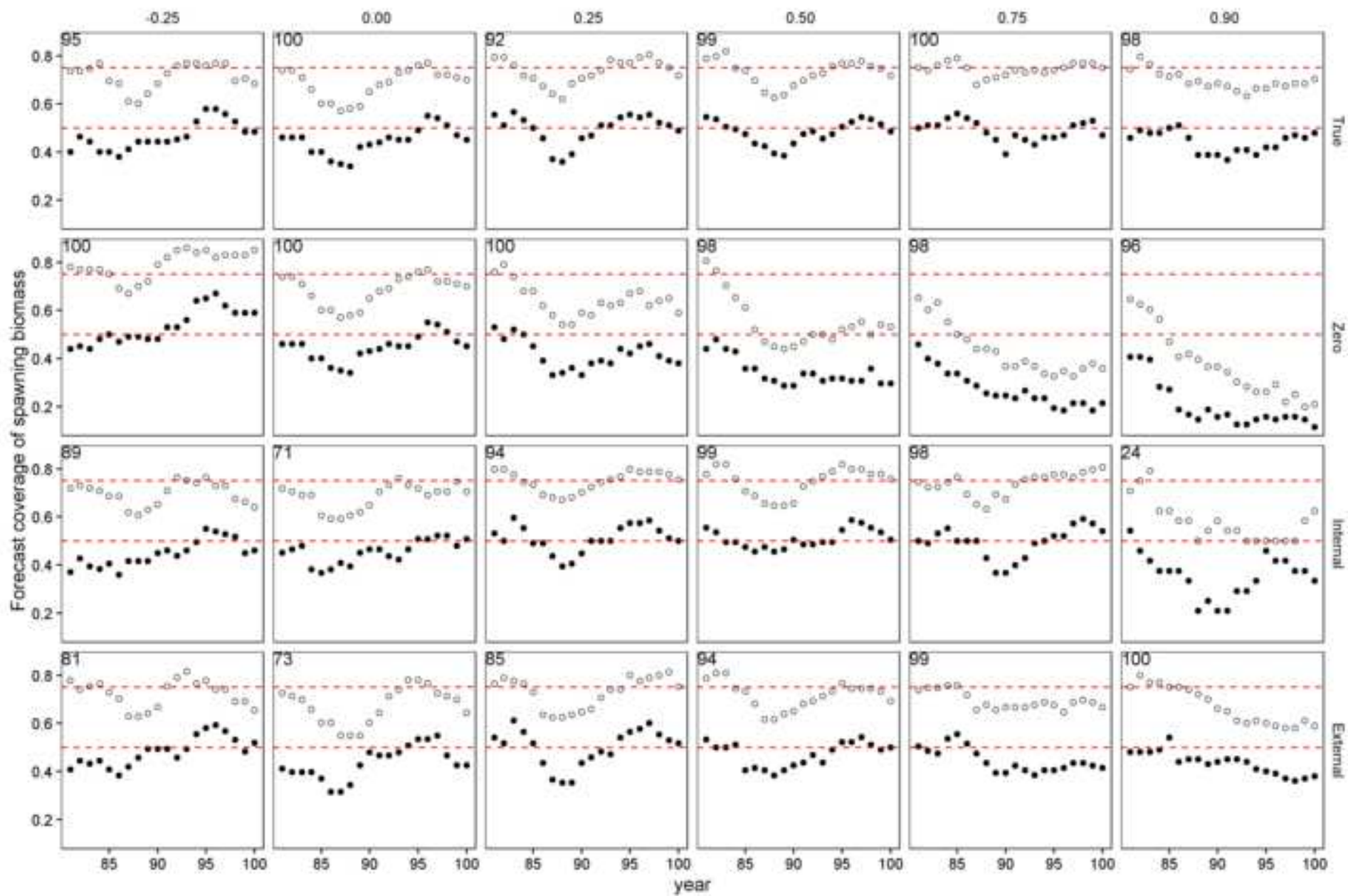


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