QC 801 -U64 no.28



NOAA Technical Report EDS 28

Comparison of Mast and Boom Wind Speed and Direction Measurements on U.S. GATE B-Scale Ships

Washington, D.C. March 1978

U.S. DEPARTMENT OF COMMERCE
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Comparison of Mast and Boom Wind Speed and Direction Measurements on U.S. GATE B-Scale Ships

Center for Experiment Design and Data Analysis

Katherine B./Kidwell Ward R. Seguin

Washington, D.C. March 1978

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COMPARISON OF MAST AND BOOM WIND SPEED AND DIRECTION MEASUREMENTS ON U.S. GATE B-SCALE SHIPS

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Abstract. During the 1974 GARP Atlantic Tropical Experiment (GATE), wind measurements were made aboard four U.S. ships with identical microvane and cup anemometers mounted on the forward masts and on booms extending from the ships' bows. Study of the simultaneous wind observations by the mast and boom sensors shows wind speed differences varying from 0 to 1.0 m/s and wind directions varying between \pm 15 $^{\circ}$ for relative wind directions from 270 through 0 to 90°. These differences are dependent upon the relative wind direction, the wind speed, the heights of the sensors above sea level, the exposure of the sensor, and atmospheric stability. Wind speed differences are found to increase linearly when the wind direction is on the bow and in some cases nonlinearly when the ship lies normal to the wind. Specific biases in the wind measurements for each of the four ships are tabulated for the benefit of users of the archived GATE surface data.

1. INTRODUCTION

Accurate surface wind observations were an important requirement of the 1974 GARP¹ Atlantic Tropical Experiment (GATE) as outlined in GATE Report No. 3 (1974). Synoptic analysis of surface fields, computation of kinematic divergence and vorticity fields, and calculation of surface fluxes of momentum, and latent and sensible heat are all dependent upon wind measurements. Yet, very little has been known quantitatively about wind observation errors aboard ship.

Augstein et al. (1974) compared wind speeds measured on the mast of the ship Meteor with those measured on a meteorological buoy and found that the mast wind speeds are systematically smaller than the measurements at the buoy, with the differences increasing with increasing wind speed. Ching (1976), in comparing wind speed measured by mast and boom sensors during the 1969 Barbados Oceanographic and Meteorological Experiment (BOMEX), found that mast wind speeds

¹Global Atmospheric Research Program

are strongly affected by the ship's superstructure when the ship is lying broadside to the wind. Seguin and Garstang (1971) found the mast-boom wind speed differences to be influenced by atmospheric stability. Despite these studies, quantitative data have been meager.

Before GATE, the advantages and disadvantages of mounting meteorological instrumentation on buoys versus ships were discussed, with considerations of cost and time ruling in favor of the latter. As a partial solution to the old question of where best to place meteorological sensors aboard ships, and to increase the likelihood of collecting high quality data, four of the U.S. GATE B-scale ships were equipped with identical sensors mounted on both the forward masts and on booms extending from the ships' bows. The microvane and cup anemometers used are shown in figure 1. Their location on the boom is indicated in figure 2 and their positions on the masts of the four ships, the Researcher, Gilliss, Dallas, and Oceanographer, are shown in figures 3, 4, 5, and 6, respectively. Table 1 shows the sensor heights.

Ship	Boom sensors (m)	Mast sensors (m)
Researcher	10.0	24.1
Gilliss	8.2	18.3
Dallas	8.7	23.8
Oceanographer	10.5	29.6

Table 1.--Wind sensor heights

The wind speed and direction data collected by both mast and boom sensors by the four ships during the three observation Phases of GATE provided an excellent opportunity to examine differences between mast and boom wind observations. In this study, the differences between mast and boom speeds and directions are analyzed both as a function of relative wind direction and of wind speed for evidence of systematic obstructive effects. The influence of atmospheric stability on the wind speed differences is also discussed.

2. METHOD OF ANALYSIS AND RESULTS

Data were acquired at a rate of two samples per second and were recorded on pulse code modulation (PCM) analog tape. In subsequent computer processing, these data were edited, corrected for ship velocity and ship heading, and then averaged to produce 3-min averages. The average wind directions were calculated from the u- and v-components; the average wind speeds, from scalar speeds only. The instrumentation, field data collection, and data processing have been described in detail by Seguin et al. (1977).

Twelve 3-min average data sets were used in the analysis, one for each ship for each Phase of GATE. Each Phase lasted roughly 20 days, giving a maximum of approximately 9,600 samples of 3-min pairs of mast-boom data. The

wind speed and direction data are relatively free of errors, but gaps do exist as a result of sensor maintenance and interruptions in the recording of ship velocity and ship heading data.

Two methods were used in comparing the mast and boom wind measurements. By the first method, mast-boom differences are examined with emphasis on relative wind direction; by the second, with emphasis on variations in the wind speed. The techniques used are described below, with results presented for each of the four ships.

2.1 Differences Calculated by Method 1, With Emphasis on the Changing Relative Wind Direction

Differences were calculated for two wind speed classes, < 5 m/s and $\ge 5 \text{ m/s}$, and 72 relative wind direction classes defined by a 30° wind direction window that was rotated in 5° increments around the compass as shown in figure 7. Because these windows overlapped, individual samples were counted more than once.

2.1.1 Wind Speeds

The mast and boom wind speeds and their differences (mast minus boom) were accumulated and averaged for each of the seventy-two 30° windows. By this technique, the data were sorted as a function of the relative mast wind direction and speed, independently of time, with values representing the averages for each of the 30° windows for an entire GATE observation Phase. The average mast-boom wind speed differences were displayed as polar plots, and linear plots were prepared of the average wind speeds.

Polar Plots

Figure 8 shows the differences for the Researcher during Phase I. The radii in this and subsequent plots represent the magnitudes of the differences in speed, and the angles represent the central angles of the 30° windows. Since all directions were computed relative to the ship, with ship heading removed, 0° refers to wind on the bow, 90° to wind on the starboard (right) side, and so on. The inner curve shows the wind speed differences for mast winds < 5 m/s; the outer curve, for mast winds > 5 m/s.

As seen in figure 8, the wind speed differences for the Researcher are not symmetrical about the 0 to 180° axis, and the pattern for both wind speed classes is about the same. Table 2 shows the angles for the minimum and maximum wind speed differences for the two wind speed classes for all three Phases. The consistency from Phase to Phase and the fact that the angles in any one column do not vary by more than 15 to 20° support the validity of the results, suggesting that the patterns observed are related to obstructions on the ship.

The wind speed difference curves for the <u>Gilliss</u>, <u>Dallas</u>, and <u>Oceanographer</u> for Phase I are plotted in figures 9, 10, and 11, respectively. In the case of the <u>Gilliss</u>, the differences for high winds are strongly asymmetrical for angles of $270-0-90^{\circ}$, with fairly large differences (1.0 m/s)

Table 2.--Angles (in degrees) for <u>Researcher</u> minimum and maximum mast-boom wind speed differences

Phase	Minimum	Minimum	Minimum	Maximum	Maximum
pace -	Lov	wind speed	class (< 5 m	n/s)	
I	2	80	270	45	207
II .	5	105	260	-35	310
III	15	90	290	50 b	320
	Hig	h wind speed	d class (> 5	m/s)	
I what	0	82	260	45	300
II	357	85	270	50	302
III	7	85	285	50	315

between 60 and 100° , contrasted with differences of only 0.1 to 0.2 m/s at relative angles between 270 and 330° . The same asymmetric pattern is evident for the low wind speed class.

For the <u>Dallas</u>, the differences also show a characteristic pattern for both wind speed classes for Phase I, as seen in figure 10, as well as for Phase II, based on the tabulations in the appendix. Minimum mast-boom differences occur when the relative wind direction is on the bow. Because of a sporadically bad boom wind sensor during Phase III, the differences for that period, also given in the appendix, are not representative.

The patterns for the Oceanographer are consistent for all three Phases in the case of both high and low wind speeds. Minimum differences between $270-0-90^{\circ}$ are found between 330 and 60° ; maximum differences (~0.8 m/s), between 80 and 90° .

Linear Plots

To examine the variations in wind speeds measured by each sensor on each ship, which might help explain the differences seen in the polar plots, the average speeds were plotted on linear graph paper. Mast and boom data for both wind speed classes (< 5 m/s and \geq 5 m/s) were plotted. With a sufficiently large sample, the average for each class should change very little, and any deviations could then be assumed to be caused by the superstructure of the ship.

Figure 12 shows that low wind speeds on the Researcher in Phase I averaged ~3.0 m/s (within 0.5 m/s) at relative wind directions from 270 through 0 to 120° . Between 120 and 240° , there is a pronounced drop in both the mast and boom wind speeds, a "blind zone" presumably caused by ship obstructions. The low wind speed curves also suggest that the measurements on the mast were noticeably lower for some relative wind directions, such as 90° .

The <u>Gilliss</u> Phase I data are shown in figure 13. Assuming the true average low wind speed is approximately 3.0 m/s, both the mast and boom sensors show lower values between $120 \text{ and } 250^{\circ}$ as a result of the effect of the ship. Between $80 \text{ and } 130^{\circ}$, the boom wind speeds increase noticeably in comparison with the mast winds for both wind speed classes. On the port side of the ship, the measurements correspond very closely, but on the starboard side the differences are considerable.

As seen in figure 14, the <u>Dallas</u> mast and boom measurements are relatively consistent for the low wind speed class. The "blind zone" appears to be between 110 and 240° . In the case of high wind speeds, the boom averages are noticeably lower than the mast averages at angles between 240 and 280° and between 50 and 80° .

The average wind speeds for the <u>Oceanographer</u> are plotted in figure 15, where the obstructive ship effect is evident between 110 and 270° . Observations for this window were too few for conclusions to be drawn in the case of the high wind speed class. Outside this window, both the mast and boom averages in both wind speed classes are closely matched, with a slight dip in the boom measurements near 80° .

The wind speed difference patterns discussed above illustrate the complex influence of the ship on wind velocity measurements. The fact that these patterns for each of the four ships are consistent from Phase to Phase, and in some cases for both the low and the high wind speed class, support the validity of the analysis and the deduction that the differences observed are related to obstacles on the ships. The linear plots of the average wind speeds show that neither sensor, mast nor boom, is best for all relative wind directions. These plots also indicate that the influence of the various ships on measured velocity varies with wind speed, and that the differences are very small for light wind speeds. This is examined further in section 2.2.

2.1.2 Wind Directions

Wind direction differences were computed for each ship in much the same way as were the wind speed differences. Differences in wind direction were not computed when mast wind speeds were < 1 m/s. Since the 3-min average wind direction data used in the analysis were calculated from the u- and v-components of the wind, they were not independent of the wind speeds and biases in the speeds, discussed above. However, these 3-min average wind directions comprise the data that are part of the GATE archive and available to users.

Polar Plots

Figure 16 shows a polar plot of the mast-boom wind direction differences for the Researcher in Phase I for the two wind speed classes (< 5 m/s and \geq 5 m/s). As seen, the differences range from -6 to 2° for mast relative wind directions of 270 through 0 to 90° . Table 3 gives typical magnitudes of these differences for each Phase, and shows that the differences change slightly in Phase II and more noticeably in Phase III. The 8° change at 300° cannot be explained by the rotation of the sensors' bases because of the small change at 60° . Complete tabulations for all Phases are given in the appendix.

Table 3.--Mast-boom wind direction differences (in degrees) for the Researcher at selected relative wind directions

Phas	e 300°	0°	60°	
tore or built	Low wind speed c	lass (< 5 m/s)		2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
I	-4.5	-2.2	0.9	
II.	-4.5	-1.5	2.2	
III	3.9	5.8	4.4	
	High wind speed	class (≥ 5 m/s	3)	
I	-5.6	-2.7	1.2	
II	-4.6	-1.4	2.5	
III	5.1	5.5	5.8	

The Phase I <u>Gilliss</u> mast-boom wind direction differences for both the low and high wind speed classes are plotted in figure 17, which shows differences ranging from -8 to 0° at relative wind directions from 270 through 0 to 90° . Differences for selected wind directions for all three Phases are given in table 4, which indicates an increase in these differences from Phase I to Phase II, and a lesser increase in Phase III. The consistency in the increase between Phases I and II suggests a rotation by one of the sensors relative to the other by approximately 6° .

Table 4.--Mast-boom wind direction differences (in degrees) for the <u>Gilliss</u> at selected relative wind directions

Phase	e 300°	00	60°	
	Low wind speed	class (< 5 m/s)		
I	-4.2	-1.0	-4.9	
II	-10.1	-6.5	-9.6	
III	-8.6	-8.1	-14.1	
	High wind speed	l class (> 5 m/s	<u>)</u>	
I	-4.1	-0.5	-4.6	
II	-9.2	-5.6	-9.8	
III	-8.5	-6.8	-12.0	

The <u>Dallas</u> Phase I mast-boom wind direction differences for both wind speed classes are small, as seen in figure 18. They range from approximately -7 to 5° for relative wind directions from 270 through 0 to 90° . Table 5 shows that this pattern is also true for the other Phases, which is further borne out by the complete tabulations in the appendix. Differences for the Oceanographer are also small, as shown by the plot in figure 19 and by table 6, which lists differences at selected relative wind directions for all Phases.

Table 5.--Mast-boom wind direction differences (in degrees) for the <u>Dallas</u> at selected relative wind directions

Phas	e 300°	00	60°	
	Low wind speed cl	ass (< 5 m/s)		
I	-6.5	2.5	3.6	
II	-7.7	2.8	5.1	
III	-7.0	2.9	4.6	
	High wind speed o	lass (> 5 m/s)		
I	-6.8	2.8	4.3	
II	-7.7	2.4	5.0	
III	-7.4	2.3	3.7	

Table 6.--Mast-boom wind direction differences (in degrees) for the Oceanographer at selected relative wind directions

Phase	300°	00	60°	
	Low wind speed cl	ass (< 5 m/s	<u>)</u>	
I	0.6	-2.2	-1.6	
II	0.7	-2.1	-0.7	
III	-0.6	-2.5	-1.5	
	High wind speed o	:lass (<u>></u> 5 m/	s)	
I	1.4	-2.1	-2.3	
II	0.9	-1.8	-0.8	
III	0.0	-2.3	-1.6	
				-

Linear Plots

For further examination of the mast-boom direction differences seen in the polar plots, linear plots of the average relative wind directions for the central angle of each 30° window, based on Phase I data from the four ships, are shown in figures 20 to 23. In the case of the Researcher, for example, figure 20 indicates little differences between the mast and boom average wind directions at relative wind angles between 25 and 100° . The variations are considerable, however, in the "blind zone" between 100 and 250° , and approach 5° at angles between 250 and 20° .

2.2 Differences Calculated by Method 2, With Emphasis on Variations in Wind Speed

When this study was begun, one hypothesis to be investigated was that the differences between the mast and boom wind speeds would increase with high wind speeds, and that this increase might be sudden as the true wind speeds reach a magnitude turning the flow over the ship from smooth to rough. To test this hypothesis, four fixed wind direction classes and 11 wind speed classes were defined based on the mast sensors. The mast wind directions were used in sorting the mast and boom wind speeds into one of the four quadrants shown in figure 24. The speeds were then further sorted into 11 subclasses based on the mast wind speeds, with 10 of the classes defined as 1 m/s increments between 0 and 10 m/s, and the 11th consisting of wind speeds > 10 m/s. For each class, average wind speed differences were calculated and differences from Phase to Phase in terms of the four wind direction quadrants were examined. These differences were also compared with wind speed differences computed from the logarithmic wind law

$$\Delta u = \frac{u_*}{k} \ln \frac{z_2}{z_1} ,$$

where Δu is the wind speed difference between the mast and the boom, k is von Karman's constant of 0.4, and z_2 and z_1 are the heights of the mast and boom sensors, respectively. The friction velocity u_* was calculated from $u_* = (\tau/\rho)^{\frac{1}{2}}$, where τ is the surface stress, and ρ is the air density: τ being computed from the bulk aerodynamic formula $\tau = \rho C_D u^2$, with a drag coefficient of $C_D = 1.5 \times 10^{-3}$.

Figure 25 shows the Researcher mast-boom wind speed differences in Phase I for quadrant 1. Except at wind speeds < 1 m/s, the differences increase nearly linearly. This figure also shows that the differences predicted by the neutral log wind law are greater than the mast-boom differences computed from the data, and that this discrepancy increases with higher wind speeds. Similar plots for the Gilliss, Dallas, and Oceanographer in figures 26, 27, and 28, respectively, also support the fact that the differences increase with increasing wind speed but not as rapidly as predicted by the log wind law. The curves for the Gilliss and Dallas are not as smooth as those for the Researcher and Oceanographer. In the case of the Gilliss, the

variations seen at high wind speeds are attributable to the small sample used in calculating the averages, and the sharp deviations in the <u>Dallas</u> Phase III data are the result of a faulty boom sensor.

For the other wind direction quadrants, results vary from ship to ship. The curves for the Researcher for quadrant 2, plotted in figure 29, are similar to those for quadrant 1 (fig. 25), while for the Gilliss the quadrant 2 results in figure 30 suggest a more rapid increase in mast-boom wind speed differences at speeds > 7 m/s during all three Phases than predicted by the log wind law. The reason may lie in a change of flow from smooth to rough, with an obstruction on the ship becoming more prominent. The data sample used is too small, however, to determine the cause of the discrepancies, and the limited sampling in itself may have affected the computations.

The quadrant 4 mast-boom wind speed differences for the <u>Dallas</u>, shown in figure 31, are greater than the theoretical differences calculated from the log wind law, which implies that for this wind direction quadrant some part of the ship acts as an obstruction, increasing the differences between the measurements by the two sensors at higher wind speeds.

As seen in figure 32, the results for quadrant 2 in the case of the Oceanographer do not differ noticeably from those for quadrant 1. The larger differences at high wind speeds (fig. 28) probably stem from the limited number of observations.

3. INFLUENCE OF ATMOSPHERIC STABILITY ON WIND SPEED DIFFERENCES

Atmospheric boundary layer stability is linked by definition with the vertical gradients of temperature and wind speed. To determine whether the mast-boom wind speed differences are a function of atmospheric stability, these differences were calculated and plotted in terms of 10 stability classes, based on Researcher Phase III data. Stability was calculated from the bulk Richardson equation (Deacon and Webb, 1962)

$$R_{B} = \frac{gz}{T} \frac{\Gamma_{h}}{\Gamma_{m}^{2}} \frac{\Theta_{o} - \Theta_{a}}{u_{a}^{2}} ,$$

where g is the acceleration of gravity, z is the height of the sensors above sea level, Γ and Γ are the profile coefficients for wind and temperature, respectively, Θ is the potential sea surface temperature, Θ is the potential temperature of the air at the level of the boom sensor, and Ψ is the wind speed at the boom sensor level.

To isolate the effect of stability, the average mast-boom wind speed differences were subtracted from the speed differences of each stability class. These average speed differences were derived from figure 25 in section 2.2. The results show that the mast-boom differences decrease monotonically from

0.4 m/s to less than 0.1 m/s with increasing atmospheric instability. Figure 33 also shows that sea-air temperature differences first increase sharply from 0.7 $^{\circ}$ C to 2.1 $^{\circ}$ C and then drop off to approximately 1.8 $^{\circ}$ C in the Phase III Researcher data.

4. SUMMARY

In this study, differences in mast and boom wind speed measurements aboard four U.S. GATE ships have been examined as a function of relative wind direction and as a function of two wind speed classes (< 5 m/s and \geq 5 m/s). The results show differences ranging from 0 to 1 m/s for relative wind directions ranging from 270 through 0 to 90° , with difference patterns being consistent from Phase to Phase and from the low wind speed class to the high wind speed class. These difference patterns indicate that wind measurements are very sensitive to permanent ship obstructions, and the plots presented here of average mast and boom wind speeds for the two wind speed classes (cf. figs. 12-15) help delineate the relative wind directions for which the effect of such obstructions is most pronounced.

All four ships were found to have a "blind zone" ranging from at least 120 to 240° due to the ships' masts, the stacks, and other equipment. The size of this zone is nearly the same for both the mast and the boom sensors. There are obstacles, however, that influence the two sensors differently. An example is the Gilliss (cf. fig. 13), where an obstacle on the ship appears to make winds measured on the boom increase sharply in comparison with the mast measurements. Because the mast wind velocities were used in this study as the reference data set, these anomalies seem to lie in the boom data, when, in fact, they may be attributable to the mast data. The mast wind speeds are apt to be more suspect than the boom speeds because the mast sensor on the Gilliss was mounted on a catwalk to the left of the mast; the wind speeds corresponding to relative wind directions of 90° would be influenced by the mast, causing a drop in the speeds measured by the mast sensor and, hence, an apparent increase in the boom wind speeds. Had the boom speeds been used as the reference data set, the anomaly would have appeared in the mast data.

Similarly, the patterns derived for wind direction differences of \pm 15 are also consistent from Phase to Phase and almost identical for both wind speed classes. The abrupt changes in average directions (cf. figs. 20-23) indicate that wind direction measurements are also sensitive to ship obstructions. Pronounced variations are found in the "blind zone," and at some angles the mast and boom sensors are not influenced in the same way.

It has been illustrated that the mast-boom wind speed differences increase almost linearly with increasing wind speed and for relative wind directions from 315 through 0 to 45° , but the increase is smaller than would be expected from calculations based on the neutral log wind law. For other wind directions, the reverse is true in some cases. The differences based on the Gilliss and Dallas data show a more rapid increase than predicted by the log wind law, undoubtedly as a result of ship obstructions.

Results also indicate that atmospheric stability is related to the vertical gradient between the mast and boom sensors, with increasing instability being accompanied by a decrease in the vertical wind gradient.

5. CONCLUSIONS

The large volume of wind velocity data collected aboard the U.S. ships during the three GATE observation Phases provide an unusually good opportunity for studying differences in wind velocities as measured on the forward masts and on the ships' bow booms. The sensors were identical in design and were carefully calibrated both before and after the experiment.

The results of this study indicate that the quality of the wind data is dependent upon sensor location, the superstructure of the ship, and the relative wind direction and wind speed. The average wind speeds as measured by the mast and boom sensors also suggest that sensors mounted on the boom do not necessarily yield more reliable measurements than those on the mast. On the Researcher and Oceanographer, for which the data are as good in quality as one could hope to obtain aboard ship, the mast sensors were mounted on small horizontal masts extending forward of the main mast. The differences in the mast and boom wind speed measurements on these two ships were small, and variations at relative wind directions from 270 through 0 to 90° were not large. Neither of these two data sets supports the theory that relative wind directions normal to the ship significantly affect the mast-boom wind differences. On the Gilliss and Dallas, in contrast, ship obstructions affected the mast measurements more strongly, as borne out by the results presented here.

Without an absolute measure of wind speeds and directions, it is difficult to say which sensors, mast or boom, most precisely respond to real wind variations. However, this study suggests that both mast and boom sensors can be mounted to yield reasonably good wind observations for relative wind directions from 270 through 0 to 90° , and that the attitude of the ship should be maintained so as to keep the relative wind direction between these angles.

Finally, without prior knowledge of how wind speeds increase with height, it is probably impossible to precisely correct mast wind speeds to 10 m for bulk flux computations. If at some time during an experiment, however, one can determine the expected differences between the mast and boom data as a function of wind speed, relative wind direction, and atmospheric stability, it would be possible to correct the mast wind velocities to the level of the boom observations. This requires that the wind speed, ship's heading, and atmospheric stability be given. It is, therefore, important in future meteorological experiments that ship heading data be retained as a part of the basic data set.

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- Seguin, Ward R., Paul Sabol, Raymond Crayton, Richard S. Cram, Kenneth L. Echternacht, and Monte Poindexter, "U.S. National Processing Center for GATE: B-Scale Surface Meteorological and Radiation System, Including Instrumentation, Processing, and Archived Data," NOAA Technical Report EDS 22, National Oceanic and Atmospheric Administration, U.S. Department of Commerce, Washington, D.C. 1977, 94 pp.
- World Meteorological Organization, "The Central Programme for the GARP Atlantic Tropical Experiment," GATE Report No. 3, Geneva, Switzerland, 1974, 35 pp.

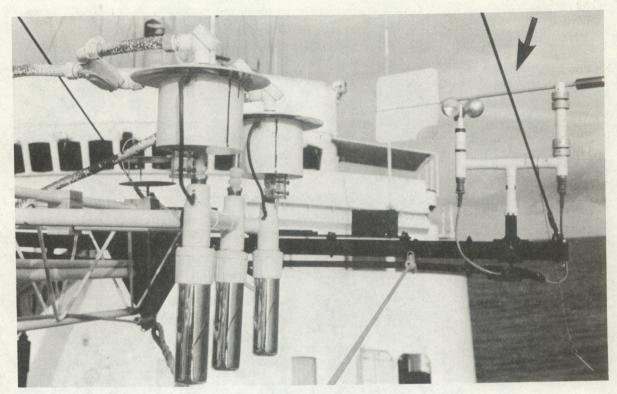


Figure 1.--Microvane and cup anemometer.

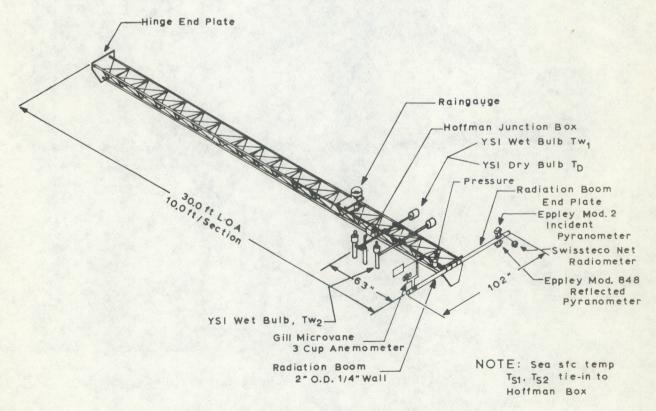


Figure 2.--Schematic of the bow boom.

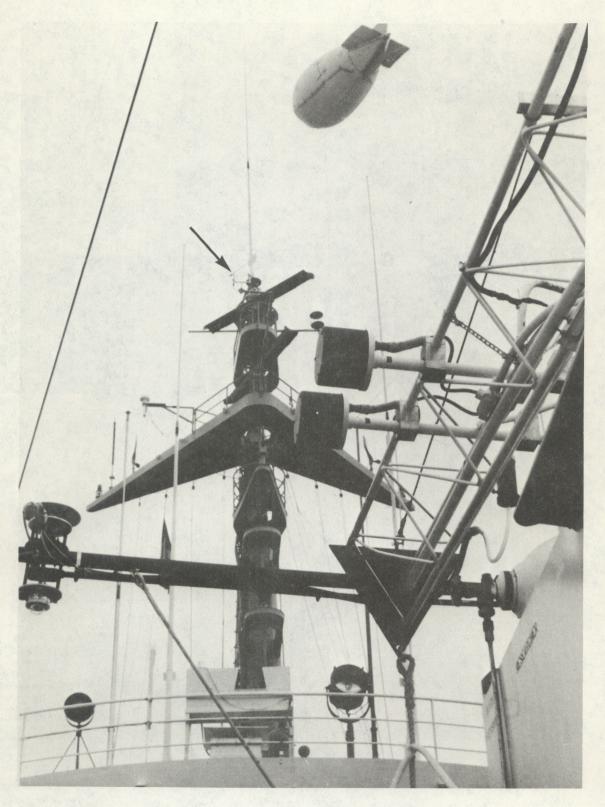


Figure 3.--Location of mast wind sensors on the Researcher.



Figure 4.--Location of mast wind sensors on the Gilliss.



Figure 5.--Location of mast wind sensors on the <u>Dallas</u>.



Figure 6.--Location of mast wind sensors on the Oceanographer.

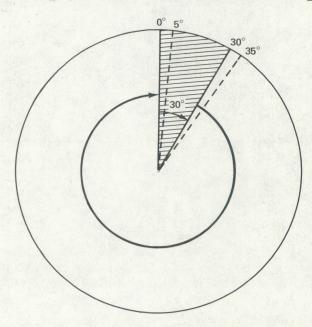


Figure 7.—Schematic of 30° window for sorting wind velocity data.

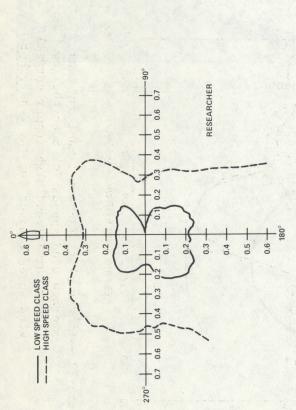


Figure 8.--Polar plot of Phase I mast-boom wind speed differences for the Researcher.

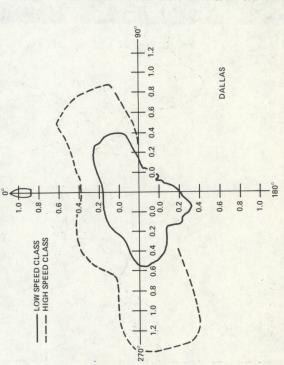


Figure 10. -- Same as fig. 8 for the Dallas.

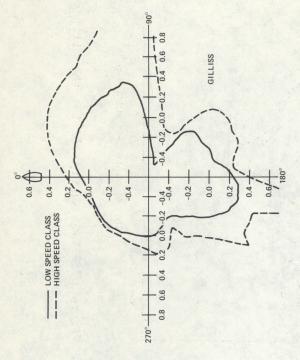


Figure 9. -- Same as fig. 8 for the Gilliss.

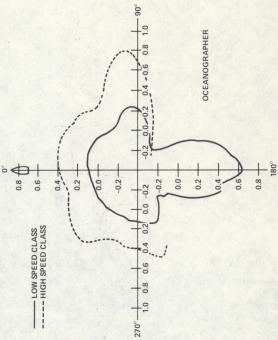


Figure 11. -- Same as fig. 8 for the Oceanographer.

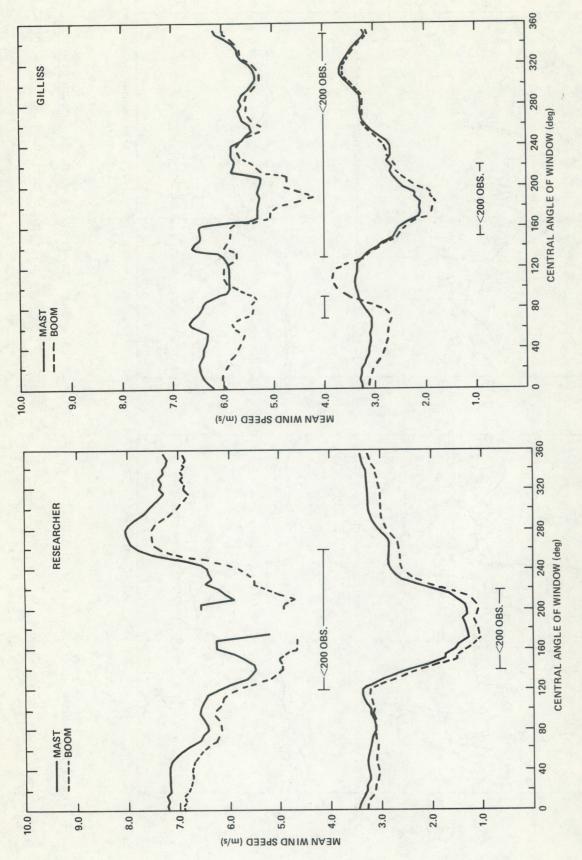


Figure 12.--Linear plot of Phase I mast and boom average wind speeds for both the low (lower curves) and high (upper curves) wind speed classes for the Researcher.

Figure 13. -- Same as fig. 12 for the Gilliss.

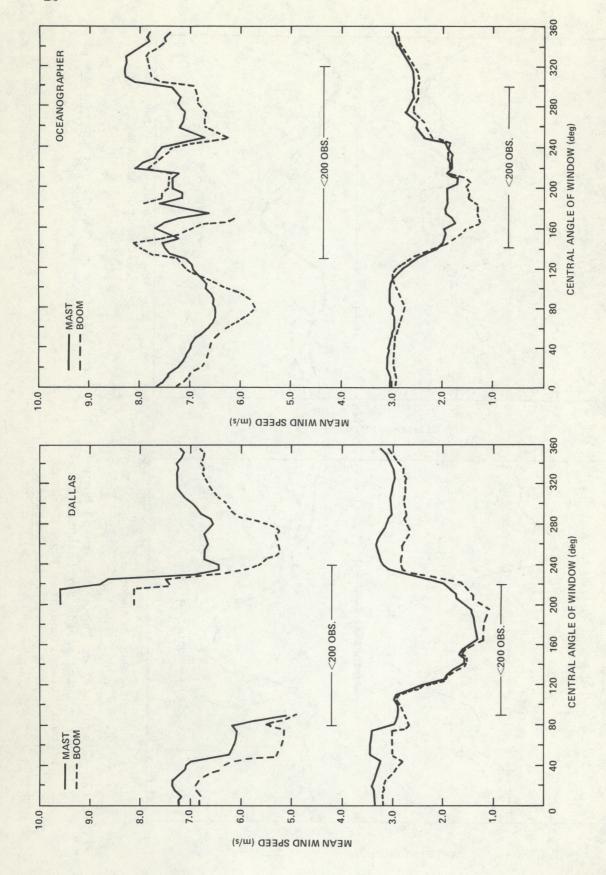


Figure 14. -- Same as fig. 12 for the Dallas.

Figure 15. -- Same as fig. 12 for the Oceanographer.

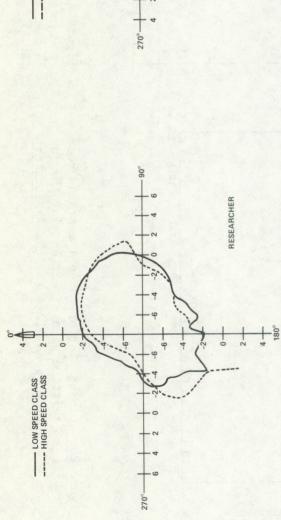


Figure 16.--Polar plot of Phase I mast-boom wind direction differences for the Researcher.

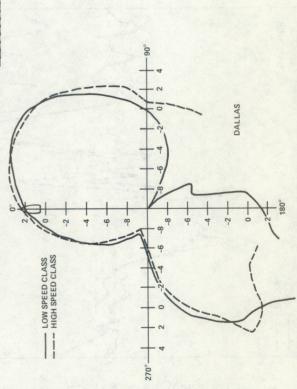


Figure 18. -- Same as fig. 16 for the Dallas.

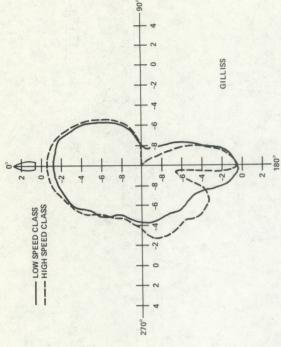


Figure 17. -- Same as fig. 16 for the Gilliss.

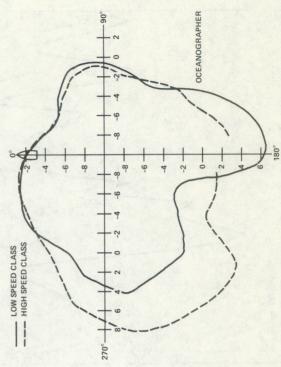


Figure 19. -- Same as fig. 16 for the Oceanographer.

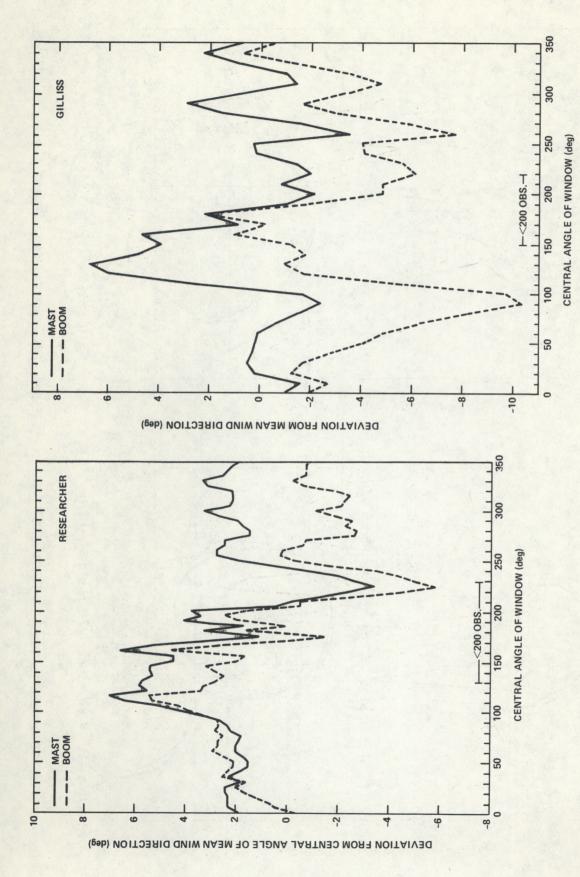


Figure 20.--Linear plot of Phase I mast and boom relative wind directions for the low wind speed class for the Researcher.

Figure 21. -- Same as fig. 20 for the Gilliss.

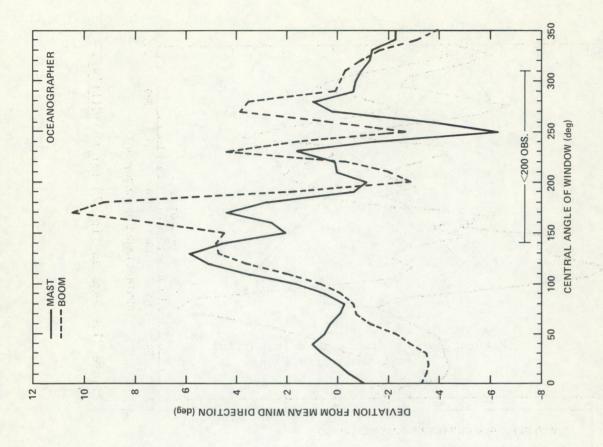
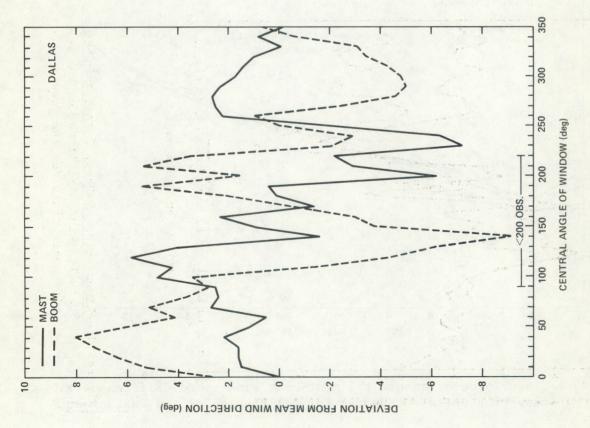


Figure 23. -- Same as fig. 20 for the Oceanographer. Figure 22. -- Same as fig. 20 for the Dallas.



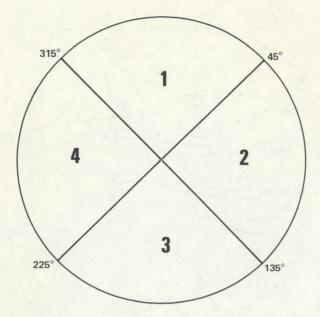


Figure 24.—Quadrants used in sorting mast wind directions.

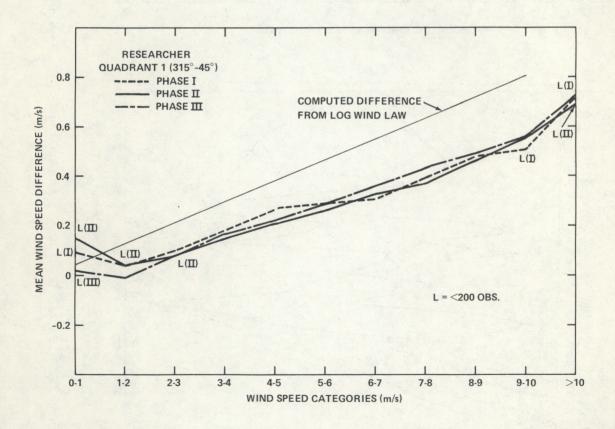


Figure 25.--Linear plot of quadrant 1 mast-boom wind speed differences vs. mast wind speed categories for all Phases for the Researcher.

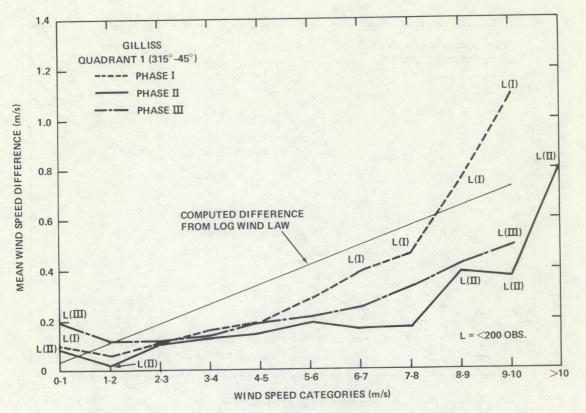


Figure 26.--Same as fig. 25 for the Gilliss.

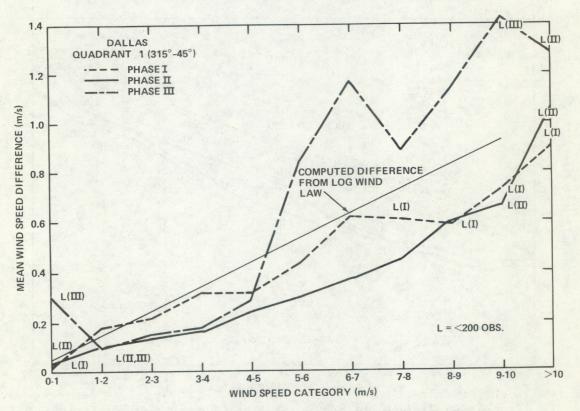


Figure 27.--Same as fig. 25 for the Dallas.

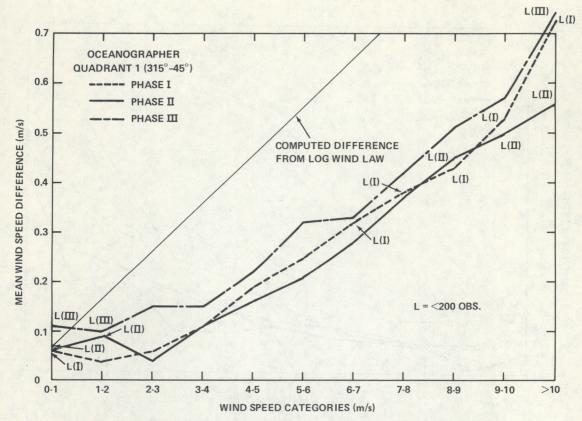


Figure 28. -- Same as fig. 25 for the Oceanographer.

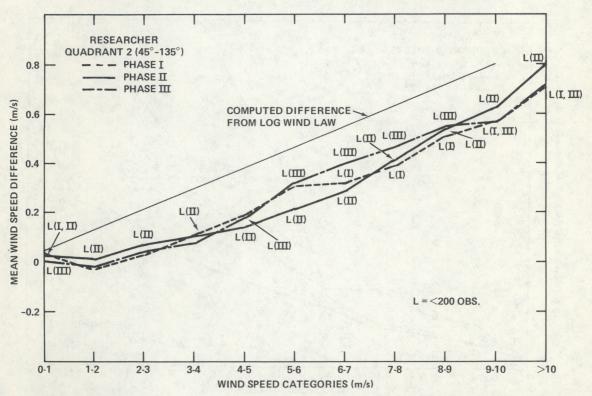


Figure 29.--Linear plot of quadrant 2 mast-boom wind speed differences vs. mast wind speed categories for all Phases for the Researcher.

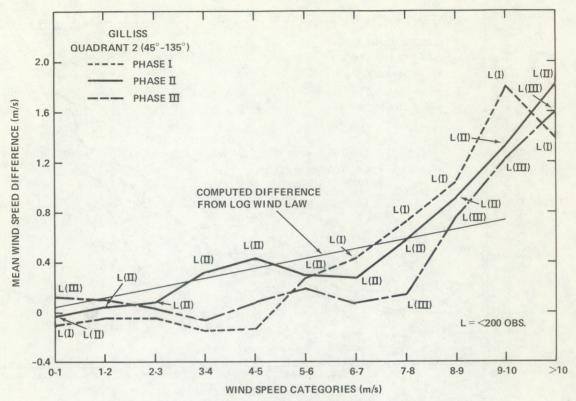


Figure 30.--Same as fig. 29 for the Gilliss.

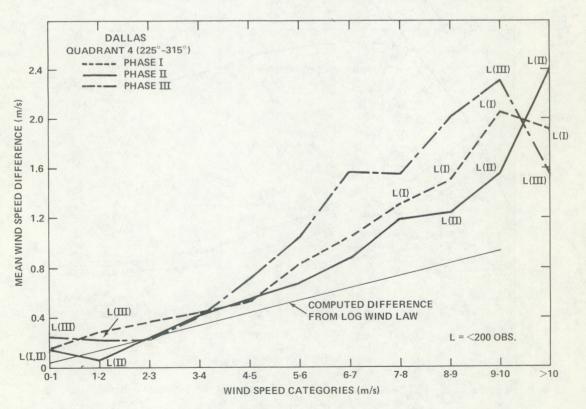


Figure 31.--Same as fig. 29, quadrant 4, for the <u>Mallas</u>.

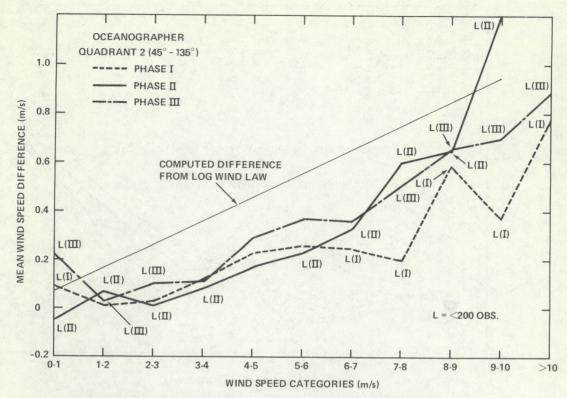


Figure 32. -- Same as fig. 29 for the Oceanographer.

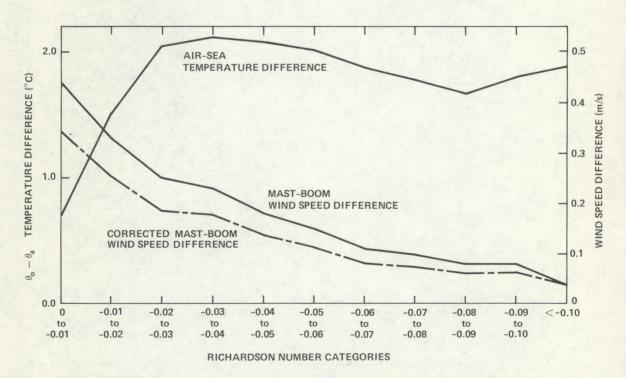


Figure 33.--Linear plot of air-sea temperature difference and mast-boom wind speed differences vs. Richardson number categories for the <u>Researcher</u>, Phase III.

APPENDIX

	南部教会者を教	在安安外教者者 安外衛 经车面目录系统公司 网络	0 1	日の日の日本会会会会会会会会会会会会会会会会会会会会会会会会会会会会会会会会会	★養養養養養養養養養養養養養養養養養養養養養養養養養養養養養養養養養養養養	***	**	糖茶糖 安林特特 安林特 医安林特氏	#*****	C T I J N *********************************	* * * *	***
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100	515 524 542	8 8 8 8 8 8 8 4 8	0.00	831 827 707	7.07	0000	505 513 532	9.7	-2.2 -1.5	831	7.00	-2.7 -2.2 -1.4
30	549	3.3		ma	7.3	0.4	533	0 0		ma	25.8	0.00
50	645	3.3		00	7.2	0.5	620			000	47.8	0.4
7.0	77.0	3.2		00	9 0 9	0.3	741	0	8 00	000	6604	1.5
0 .	842	3.1		0	6.5	0.3	827	0 0		20	92.7	-0.9
7	531	3.8		00	6.6	003	702	970	-0.4	00	102.0	-1.3
2 5	324	3.6		100	6.2	3.4	313		200	1 00	114.4	-2.1
140	173	2.4		32	41	000	135	136.6	-2°5	32	137.4	13.6
0	112	1.5		2	500	1.6	63	155.4	200	- 2	158.5	-3.4
P 00	93	1.2		0 0	6.2 UNDEFD	1.6	45	168.7	-3.2	20	158.5	-3°)
0 0	81	1.4		0	UNDEFD	UNDEFD	41	187.9	-203	00	UNDEED	UNDEFD
0 -	0.00	1.50		71	5.0	1.6	35	198.2	-2.3	77	22000	2.5
NK	123	2.0		17	6.2	1.0	80	224.5	-2.0	17	225.5	-0.5
15	324	2.8		300	6.5	0.0	286	24207	-2.8	3.9	24201	-0.4
10 V	400	2.8		1	6.0	0.5	367	250.0	-203	78	255.0	-103
10	413	2.9		306	8.0	200	36.)	259.2	-2.6	168	26409	-2.8
00	452	3.1		7	80	0.5	424	280.5	-403	478	282.2	1000
0	477	302		0	7.8	0.5	448	29000	-405	594	290.5	-5.4
0 .	484	3.2		0	7.5	0.5	453	29806	-4.5	899	299.5	-5.6
-1 (450	3.2		1	704	0.5	19%	3 3 9 8		675	336.6	-5.5
NE	4 95	2.2		658	704	0.5	460	319.8		658	319.1	-5.3
7 4	447	000		20	103	4.0	465	328.6	3	632	329.2	-5.0
- w	471	3.4		741	7.2	0.3	456	350.1	-2.8	741	351.4	-3.6
								Total Control				

RESEARCHER - PHASE II

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	VATIONS	Li.	FF	VATIONS	LL.	L	VATIONS	01	DIFF	VATIONS	OX.	DIFF.
c	4	3.0	0-1	~	7.1	0.3	643		-1.5	1225	357.3	-1.64
13	565	3.8	00 1	894	7.0		564	1	0	890	6.4	-0.8
20	N	3.8	0.1	0	6.9	0	456	10	-0.2	809	18.0	0.1
30	3	3.8	3.2	V		. 0	329	27.8	3.6	468	2801	600
40	1	307	0.2	5			268	8	1.3	356	36.6	1.5
50	good	3.6	0.2	1		0°4	215	10	1.8	274	47.9	2.1
63	0,	3.6	0.1	0	7.0	0	194	00	202	201	57.04	2.5
7.0	4	3.7	0.1	4	6.8		145	8	201	147	64.3	2.5
80	-	3.8	0.1	77	4.9		112	30	107	77	7401	2.02
06	58	305	0.0	94	6.3		50	. 9	9.0	949	87.8	1.2
100	43	2.8		41	6.7		34	0	-0°1	14	68.6	-0.1
113	32	201	0.0	31	7.1		56	8	-101	31	105.6	-0°1
120	18	1.6	0.0	20	7.8		16	15.	-1.4	20	113.6	-201
130	10	100	0.0	7	8.6	0.7	6	124.8	0.2	7	123.1	-3.1
140	3	2.8	3,3	3			3	360	-200	3	128.7	0.4-
150	3	2.4	0.1	0	UNDEFD	UNDEFD	2	0	-1.5	0	UNDEFD	UNDEFD
160	1	0.7	0.2	1	6.5		0	LL	UNDEFD	1	173.0	0.4-
170	2	0.7	0.2	5	6.9	9.0	0	L	UNDEFD	S	176.8	-1.6
180	1	0.8	0.2	K)	6.9		0	T	UNDEFD	2	176.8	-1.6
190	4	0.7	0.5	4	6.9	0°2	0	1	UNDERD	4.	177.7	-1.0
200	3	0.7	0.2	1	2.9		0	1	UNDEFU		213.0	4.0
210	3	0.7	0.2	œ	7.8		0	UI O	UNDERD	00	220.9	3.9
220	1	4.0	0.3	18	8.0		_	340	-1.0	18	754.6	4.1
230	4	2.8	0.3	24.	8.3		3	36	2.3	24	5.622	3.5
240	56	304	0.2	56	7.8		24	60		2	244.7	3.2
250	53	3.5	0.2	3	7.5		48	55.	-101	3	256.7	-0.5
263	(,)	3.8	0.2	permi	7.3		105	949	-207	greed	262.2	-1.5
270	149	3.9	0.2	346	704		145	27205	-3.6	346	272.3	-3.4
280	0	4.0	0.2	10	7.5		102	8 30	-4.5	S	283.7	404-
290	An.	401	0.3	presed.	704		529	010	-4°7	80	292.0	1-4-7
300	0	401	0.3	13	7.2		403	050	-4.5	12	301.5	-4.6
310	6.3	401	3.3	38	7.2		534	110	-403	37	31102	0
320	1	4.1	0.3	51	7.1		149	19.	-3.7	21	319.5	
330	0.	4.1	0.2	0	701		692	300	-3.2	0,	328.8	-3.2
343		4.00	0.2	4	7.0		169	390	-207	46	336.7	
350	-	4.0	0.2	4	7.1		708	664	-2.1	43	346.3	

	***	医格洛特氏检验检检验 计多种系统分类的 医毒素	w #	本本本本本本本本本本本本本本本本本本本本本本本本本本本本本本本本本本本本	***	***	***	等 等	m. 4	N D I I D N N N N N N N N N N N N N N N	於 安子在 等 在 母 答 年 春 50 益 於 華 春	***
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	VATIONS	U. (L (2	SPERO	DIFF.	VATIONS	I	0166	01	OIR.	OIFF.
01	747	3.2	0.1	1889	7.64	4°C	938	358.8	100	1889	359.1	S L
20	845	3.0	000	35	7.2	4.00	820	19.6	J. C. C.	900	17.8	
30	786	2.9	7,01	33	701	0.4	755	2803	5.6	1032	27.6	4.5
40	688	2.8	0.1	5	7.0	0.5	655	38.2	5.5	756	36.7	6.5
20	596	2.9		N.	0,00	0.5	532	48.1	5.0	505	46.2	6.2
100	243	707		+ -	000	4.00	4/8	78.4	4.4	327	0.99	7° %
80	395	2000	200	4 pm	0 00	0.3	367	78.7	300	112	74-2	7.00
06	338	2.8		1-	6.7	0.3	315	89.1	2.0	71	88.4	200
0	287	2.7		51	7.02	3.64	265	7.2	1.3	51	9803	106
-	215	206	00 1	41	7.5	0.4	198	106.4	0.5	41	105.2	0.4
2	135	2.3	0.1	26	8, 1	0.5	118	114.9	-0.3	26	12001	-1.2
m.	77	2.1	0° 1	20	7.8	3.5	62	12308	-104	20	129.8	-1.9
4 n	45	1.7	0.1	20	2.5	9.0	30	136.7	-2.3	20	137.6	-2.0
0 4	24	1.04	0.5	11	7. 1	000	28	151.2	-1.6	11	146.5	-100
01	47	10.3	0.2	00	7.7	7.00	31	167.3	1001	0 0	166.0	-1.0
0	36	1.3	0.2	1	8.2	1.1	25	17707	303	1	169.0	0.0
0	28	1.2	0.2	0	UNDEFD	UNDEFD	18	186.3	3.8	0	UNDEFD	UNDEFD
0	32	1.3	0.2	0	UNDEFD	UNDEFD	20	20106	3.2	0	UNDERD	UNDEFD
210	37	1.3	0.2	0	UNDEFD	UNDEFD	27	21403	204	0 (UNDEFD	UNDEFD
1 K	44	1.7	7.9	11	7 0	100	24	7 77 7	000	7	230.00	000
14	64	2.0	0.3	26	7.6	0.8	37	241.4	4.6	26	24503	5.2
5	67	2.4	0.2	43	7.2	9.0	55	255.1	3.2	43	253.1	200
0	1.37	200	3.2	138	706	0.5	56	263.8	10.7	108	26507	603
1	185	3.1	0.2	189	7.3	5.0	176	273.5	107	189	27402	6.1
00	233	3.2	0.2	315	7.5	900	229	28103	10,5	315	282.3	409
0	596	3.1	00 1	441	7.5	0.4	288	290.4	2.6	441	292.2	5.6
0	347	3.1	0.1	588	707	0.5	337	30107	3.9	588	30105	
proof	4.26	3.2	3.2	855	7.6	3.5	415	31308	5.1	∞	31203	
2	510	3.2	0.2	1111	7.6	0.5	497	32006	5.9	1111	32106	4.0
m.	646	3.3	0.2	1347	7.5	0.5	636	33105	5.0	3	3330.2	
31	823	3.64	0.2	1580	704	0.4	812	341.6	0.0	5	340.8	
S	095	3.3	00 1	1800	104	0.4	654	350.1	5.8	∞	350.7	

GILLISS - PHASE I

	*************************************	法 學典 法共 法 人名	4	· · · · · · · · · · · · · · · · · · ·	*******	**	**	*************	***	· · · · · · · · · · · · · · · · · · ·	子務等最易無過於以如奏者於以	等 養養 養養
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	VATTONS	L.	H H	LION	U.	L L	NOIL	b	LL.	-	pared .	L L
0	511	3.2	3,01	1			0	30 €	-103	4	104	-0.5
10	608	3.3	0.2	1			0		-101	1-	9.5	9.0-
20	200	303	0.2	288	6. 4·	0.5	691	19.8	-104	288	19.2	-101
3)	746	3.1	3,2	00 0		0	20	0	707-	o a	30.0	-2.0
n 40	55.8	2.1	000	0 3			Va	0 0	-401	\$ C	47.06	-3.8
204	851	3.0		. 0)	0 0	004-	0	58.3	-406
7.0	000	301	0.4	1			W	00	-507	1	65.8	-504
83	pred	3.02	0.0	O		-	14		7-9-	0	80.7	-6.3
00	1715	3.3	-001	9	-		0	92°	-7.9	0	87.	-7.9
0	2	3.3	- 3.4	ICI			24	110	-8°1	5	320	0.6-
-	2	3,3	-0.5	00			51	070	-8.2	00	12.	-6.5
2	M	3.3		0		0	51	140	0°-	0	1 40	1.65-
3	999	3.2	303	m	-		4	230	707	3	210	800
4	301	2.5	0.0	36			-	320	9.9-	36	38	-7.05
R	159	202	0.1	52			m	400	-501	20	0.74	-6.6
W	111	20 €	00 1	17			16	52.	-3.6	17	550	-3.9
1	49	201	001	∞		-	51	009	-101	ω	999	-104
0	56	2.1	3,3	5	-	0	47	770	-00.2	ווא	669	-0° 5
100	29	2.2	0.3	2			55	0	0.0	2	187.5	1000
0	84	204	0.3	9			- (970	107-	00	130	2007
-	116	20 €	0.2	0.1	0		108	100	0.4-0) u	110	-2 1
NI	163	2.7	0.1	15			00	230	104-	51	23	107
m.	211	7.07		91			2 6	200	100.1	21	000	7-6-
7	243	1 07		17			0 .	000	00+1	170	0	-2 %
0	259	5.02	1.00-	47		0	2 1	000	1900	67	4.	
01	385	200	700	00	0	•		100	704	200	1 .	-2.6
- (484	3.2	0.0	1 "	0		~ U	100	704-	1	0	200
X (196	2.05		- (0		0 6	100	0	1 6	000	10.7
2. (744	205	200	133			4 5	- 0	0 0 1	113	0	1-4-
2	413	700		- (0	0) (1 1 0	0	- 0	900	1361
-	418	3.		7	0	0	, ,	011	0	2	000	0001
2	572	3.6	0.0	83			O,	210		20.00	150	+°7-
3	575	3.5		00			O	52	0	x	67	2.1-8
4	564	303		118			R,	3.		118	410	7-1-5
res	456	3.1		-	0		4	400	0		52.	-0.6

	***	经存款者 非法的特殊的 经实际的 化二甲基苯甲基甲基甲基甲基甲基甲基甲基甲基甲基甲基甲基甲基甲基甲基甲基甲基甲基甲基	× * * * * * * * * * * * * * * * * * * *	C C C C C C C C C C C C C C C C C C C	****	***	查你可怕各班查察教務發情情	· · · · · · · · · · · · · · · · · · ·	2 日 日 日 日 日 日 日 日 日 日 日 日 日 日 日 日 日 日 日	A C I I C N	· · · · · · · · · · · · · · · · · · ·	· · · · · · · · · · · · · · · · · · ·
	MOT	WIND SPERDS	FDS	A HOIH 小學發音及表交換亦作	I NO S	多な事を存むを参	中国特別会会的特別	Spends on IM	**************************************	H1GH ******	HIGH WIND SPEEDS	******
MUCNEM	OBS FP -	MEAN	MEAN OPER DIFF.	NO. OBSER- VATITNS	S MARA	SPEED DIFF.	NO. OBSER- VATIONS	MEAN MAST	MEAN OIR. OIRE.	NO. VATIONS	MAST MAST DIR.	MEA
•	0,	w		1	9 0 9	3.2	487	6.0	-6.5	1		-50
10	598	3.6	0.1	552	6.4	0.3	594	11.4	-6.3	552	9.0	150
33	w.	3.6		10	5.9	0.4	633	2801		1 10		9-
50	- 0	٠ س ١٥ س		D. W	7.3	0.5	508	37.5	0 0 0	O. a		-70
60	0	3.4		-	7.0	0.5	242	55.5	9.6-	922		6-1
70	0	3.2		0	7.0	0.2	147	6603	-10.8	50		-13.
000	- a	2,8		64.0	703	101	50,1	78.6	-12,0	43		-111-
0	22	2.2		21	70.4	0.0	7 1 1	0 40	-1505	28	0	-12.
-	66	200	00	17	6.6	9.0-	46	000	-11.5	17	07.0	-12.
2	54	202		38	7.1	0.0	39	180	-6.3	38	25.	-12.
7	44	2.6	°°	4.2	7.2	3.2	36	270	-6.3	45	300	-120
150	77	7.06		143	7.1	0.5	24	137.7	-8.9	43		-120
0	(7)	301		, w	7.00	0.3	39	600	-502	1	48.	-10-
1	38	3.2		0	UNDEFD	UNDEFD	37	630	1208	0	UNDEFD	UNDEF
00 0	24	3.0		: 5	6.07	2.1	23	820	-6.3	2	188.5	-13.
LC	א מי	2007		1.0	603		31	046	1200	10	19901	100
port	689	203		37	0.0		444	39	1000	17	2050 /	-3.
2	(0)	204		35	608	104	58	22.	-6.2	35	216.1	-3
3	0	2.5		21	6. B	1.02	82.	330	-6.8	21	224.5	-40
4	4	207		25	5.6	3.5	117	410	-7.3	250	244,02	-6.
n.	00	2.9		20	5.6	0.4	156	51.	-8.0	50	255.4	-6.
01	w.	3.0		19	5.7	0.4	204	019	-8.7	19	263.5	1
- 1	0	30.0		75	50.8	0.3	236	700	-c.7	75	268.1	-8-
00 (-	3.0		00	5.7	0.5	254	180	-1004	85	282.3	-6-
J. (00 (3.0		4.	6.9	0.1	265	6 0	-13.5	7	29305	°5-
0.	0 0	301		00	6.2	0.1	280	665	-10.1	00	300.5	-6-
- (2, ,	303		0	4 09	0.1	273	080	-c°5	9	305.5	-8-
NE	797	w 6		164	606	3,01	253	180	-8.4	164	320,8	-70
7 4	, -	000		7 6	000	0.1	747	300	7.04	4	331.8	-9-
L	- a	200		00	000	1.0	31)	1760	10/-	20 0	34103	-6-
	3	1		(100	010	010		V	35501	-2.

GILLISS - PHASE III

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	LOW	LOW WIND SPFFDS **************	*****	H1GH******	HIGH WIND SPEEDS	S Q U U W W W W W W W W W W W W W W W W W	**************************************	3dS ON IM	**************************************	H1GH *****	HIGH WIND SPEEDS	*****
MUGNIA	NO. DBS FR.	MASAN	SPERD	NO. DRSER-	MASAM	SPEAN	NG.	MAN	MEA		MASA	M O M
	VATTONS	Spero	L L	VATIONS	CERT	TT.	VATIONS	• 10	01116	VATIONS		1
0	762	3.5	00 1	1143	7.0	0.	742	2.4	00	-		91
10	966	3,5	0.1	1180	6.0	0.3	1082	19.7	200	1074	1801	17.00
30	1069	. w	0.9	812	6.7		104)	28.7	0	00	26.4	8
k.)	655	3.2	00.3	614	6.7	0°	125	3806		614		0
50	884	3.1	0.3	504	6.8		829	48.8	-12.9	495	0	110
09	814	3.1	00 3	404	1.5		197	28.0	0	200	0 0	9 6
10	138	30.2	000	468	0 4		811	2000	+ 15	526	0	, in
0 0	678	200	0	532	A 50 50 50 50 50 50 50 50 50 50 50 50 50		973	9103	9	532	80.3	-16.4
100	1011	200	-0.4	436	6.5		565	98.2	60	436	5	-17.04
110	704	3.2	o	238	4.9		689	13309	9	238	330	-17.2
120	326	303	-003	88	6.5		314	111101	15.	88	1110,6	-17.0
130	63	3.0	000	31	6.1		48	125.7	150	31	230	-16.0
140	7.3	2.9	3.0	o	5.6		62	13508	130	σ,	13306	-1203
150	92	3,0	0.0	9	6.1		6.9	149.		0 <	14603	-12-3
160	99	200	0.1	7	101		09	12007		2 -	174.5	-10-4
170	50	20.7	100	15	000		35	176.0		15	178.1	50
180	41	707	3.2	27	000		29	183.2	-307	27	19201	-5.9
200	144	2.6	0.3	48	6.5		64	206.6		48	206.1	-2.9
210	117	3.2	0.4	76	6.2		102	216.1	3	76	212.2	-100
220	169	3.5	9.6	83	6.3		160	22106	-30	33	19817	0 0 0
230	177	3.3	0.3	11	4.0		121	236.2	0 4	63	237.5	-30)
240	146	3.0	200	700	4.4		116	249.8	-K.7	86	253.0	-4.8
007	100	2 1	200-	140	6.3		169	26407	17.0	140	265.0	-5.6
270	202	3.4	5	1 20	606	-0-	288	27301	-801	199	271.3	-6.1
280	257	3.4	0	220	9.9	0-	344	279.8	8	220	278.9	-7.0
290	378	3,9	0	219	6.7),	363	288.9	00	219	280,3	-8.3
300	362	3.3	00 1	241	6.5	0	343	30000	00	241	300.1	00 (
310	377	3.2	0.0	302	6.7	0	357	30002	8	302	31101	00 1
320	385	3.3	0.0	368	6.7),	368	319,3	-	368	32007	- 1
330	412	3.2	0.0	488	6.8	0	395	330.2	6-2-	488	33104	1
340	429	3.2	0.0	704	8 09		414	33909	00	134	47.0	- 4
350	292	304	00 1	146	6.09	0	551	35105	00	150	510	

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	******* MU 7	LOW WIND SPEEDS	FFD2 ******	H1GH *****	HIGH WIND SPEEDS	SPEEDS	****** MCJ	LOW WIND SPECOS	S DE E D S	HIGH	安装各位标准电影器 GNIM I	SEDS 本本學學學本本
MINDOM	NO. 085ER-	MAST	SPEED	NO.	MEAN	SPEED	NG. OBSER-	MEAN	MEAN NEW	N OBS EN	MEAN	MEAN
	VATIONS	SPEED	IFF	VATIONS	SPEED	Design .	VATIONS	018.	DIFF.	VATTONS		DIFF
0	594	3.4	0.2	524	7.2	0	561	0.0	2.5	524	359.)	2.8
13	605	30%	3,02	477	7.2			8.5	3.8	477	8.5	4.1
30	461	7 00	0-3	355	1.04			18.4	4.8	366	16.5	4.8
40	384	300	0.4	136	701	0 00		37.8	0 0	256	25.4	5.3
50	850	3.5	0.5	448	6.2			48.8	5.0	200	47.0	7.4
63	815	3° N	0.5	413	6.1			5005	3.6	50	57.9	403
0,0	775	3.4	4.0	397	1.9			67.3	2.4	43	64.5	3.5
000	215	3.00	0.3	0 1	6.2			77.06	103	16	70.9	2.8
100	116	2 0 0	100	n -	200			87.5	0.2	5	77.2	1.0
113	46	2.0	0.0		2000			95.2	-104	1	106.0	1.0
120	43	2.2	0.0		0 0			13508	000	1	106.0	100
130	2.8	100	0.0	10	UNDEFD	CN		124.0	-10.2		106.0	1.0
140	25	1.5	0.0	0	UNDEFD			141.6	-7.5		HAINER	UNDER DE LA COMPTENTION DE LA
150	25	107	0.0	0	UNDEFD			14901	1408	0	UNDEFD	UNDEFD
160	53	L. 57	0.1	0	UNDEFD		15	15707	-5.3	0	UNDEFED	UNDERD
103	31	Ie 3	30.1	0	UNDEFD		18	17104	0.2	0	UNDERD	UNDEED
187	31	10 to	0,5	0	UNDEFD		18	179.9	109	0	UNDEFD	UNDEFD
200	25	1.0	0.3	0,	UNDEFD		22	18506	5.0	0	UNDEFD	UNDEFED
210	90	1 0	***	1	0 0		949	20602	707	1	212.0	2.0
22.3	151	200	0.9	1 2	000	L	123	21205	8.2	- ·	212.)	203
230	370	207	0.3	0	7.0		336	237.2	200	70	240 6	0.0
240	60.01	3.1	3,3	167	6.4		071	24603	304	167	250.6	2000
250	1491	3.3	0.5	546	6.7		1445	251.7	1.6	546	256.9	0.0
260	1670	303	0.5	800	9.9		1626	257.8	-102	833	26103	-107
273	1325	303	900	773	6.7		1282	267.5	0.4-	773	266.1	-3.6
280	1043	301	0.4	468	9 0 9		665	27704	-7.2	468	275.2	-6.9
062	823	3.0	2,3	315	6.8		774	287.7	-703	315	289.0	-7.7
310	8 6	3.1	0.3	315	7.0		049	298.3	-6.5	315	301.6	-6.8
313	280	301	0.3	391	7.2		554	30806	-5.7	301	310,8	-6.1
330	1000	200	30.2	455	7.3		521	31600	-404	455	320.5	-4.8
32.0	238	5.7	2.0	523	7.2		518	330.1	-3.0	523	330.4	-3.0
2 40	080	3.1	0.2	560	7.3		536	339.2	-104	560	339.8	-1.0
000	7 9 9	200	7 00	564	7.1		557	350.2	0.8	564	664	6.0

Not observed the name of the	######################################	######################################
Maria Copenies Mari	Note	######################################
Mark	MCCK NEAN 11° MCCK NEAN 11° MCCK NEAN	APTER WEAR WEAR WEAR WEAR WEAR WATCH AND APTER WATCH AND APTER WATCH AND APTER WEAR WEAR WATCH AND APTER WATCH APTER W
14 3.2 0.1 6.6 6.7 0.3 5.3 10.0 4 6.3 5.7 8.8 1.0 0.4 6.3 5.7 8.8 1.0 0.4 6.3 1.0 0.4 6.3 1.0 0.4 6.3 1.0 0.4 6.4 6.7 0.3 1.0 0.4 6.8 1.0	14 3.2 0.1 6.5 6.7 0.3 4.9 0.0 4.0 4.0 5.9 6.5 6.9 0.1 6.5 6.7 0.3 3.5 0.1 6.5 6.7 0.3 3.5 0.1 6.5 6.7 0.3 3.5 0.1 6.5 6.7 0.3 5.0 0.4 6.5 0.2 0.2 6.7 0.3 6.7	14 3.2 0.1 656 6.7 0.3 633 10.0 0.4 33.3 3.2 0.1 656 6.7 0.3 6.7 0.3 6.8 3.3 10.0 0.1 656 6.7 0.4 6.7 0.3 6.8 6.8 3.3 10.0 0.2 2.8 6.8 0.2 2.8 6.8 0.2 2.8 2.8 2.8 3.8 10.0 0.2 2.8 2.8 2.8 2.8 2.8 2.8 2.8 2.8 2.8 2
3.3 3.0 3.1 46.2 6.7 0.6 5 513 10.0 4.3 554 8.4 4.8 4.8 5.0 1.0 6.4 5.2 1.0 5.8 5.0 1.0 6.4 5.2 1.0 6.2 5.0 5.0 5.0 5.0 5.0 5.0 5.0 5.0 5.0 5.0	33 3.0 3.0 1 462 6.7 0.6 5 33 10.0 0 4.3 554 18.2 5.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1	73 3.5 3.6 0.1 452 6.7 0.4 514 13.5 10.0 0.5 3.3 10.0 0.5 3.3 10.0 0.5 3.5 0.1 452 6.7 0.4 514 13.5 10.0 0.5 3.5 0.2 3.6 0.2 3.6 0.2 3.6 0.2 3.8 0.2 3.8 0.2 3.8 0.2 3.8 0.2 3.8 10.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.
73 3.5 0.0 2 3.5 0.7 0.7 0.7 0.7 0.7 0.7 0.7 0.7 0.7 0.7	13 30 50 50 50 50 50 50 5	73 3.5 0.0 2 3.6 2 6.7 0.5 4.1 39.5 1.3 3.5 0.0 4 2.5 8 6.8 0.7 0.7 3.1 3.5 1.3 3.5 0.0 4 2.5 8 6.8 0.7 0.7 3.1 3.5 1.3 3.5 0.0 4 2.2 2 6.3 0.7 3.1 3.1 3.5 0.2 0.4 2.2 6.3 0.7 3.1 1.0 0.2 0.2 0.2 0.2 0.2 0.3 0.3 1.0 0.3 6.5 0.3 6.5 0.3 6.
13 3.7 0.4 258 6.8 0.7 411 39.5 6.1 258 4.8 3.8 6.4 0.7 411 39.5 6.1 2.8 36.0 3.8 6.4 5.4 6.4 6.4 6.4	13 3.5 7 0.4 5.58 6.8 0.7 411 35.5 6.1 5.9 5.8 5.9 5.8 5.8 5.9 5.8 5.8 5.8 5.8 5.8 5.8 5.8 5.8 5.8 5.8	13 3.7 0.6 4 258 6.8 0.7 411 39.8 5.0 1 3.8 1.0 0.4 358 6.5 1 0.0 7 371 48.4 5.0 1 3.8 1.0 0.2 2.2 6.3 0.7 371 48.4 5.0 1 0.2 2.2 6.3 0.7 371 48.4 5.0 1 0.2 2.2 0.2 1.0 0.2 2.2 1.0 0.3 6.2 1.0 0.3 6.7 1.0 0.3 6.2 1.0 0.3 6.7 1.0 0.3 6
87 3.8 3 0.6 4 358 6.6 4 0.7 287 49.6 5.7 155 455 5.8 287 287 18.8 28.8 2.8 2.8 2.8 2.8 2.8 2.8 2.8 2.8	87 3.8 3 0.4 398 6.4 0.0 7 371 48.4 55.7 155 5.8 5.8 5.8 5.8 5.8 5.8 5.8 5.8 5.8 5	87 3.8 8 0.4 358 6.4 0.7 371 48.4 48.4 48.4 3.8 3.8 0.6 4 3.3 1.0 0.7 371 48.4 48.4 48.4 3.8 3.8 0.5 5.8 0.8 5.8 1.0 0.7 16.7 16.5 5.9 1.0 0.2 5.8 0.8 5.8 1.0 0.8 5.8 1.0 0.8 5.4 1.0 0.8
\$ 5.0 \$ 5.0	25	54 3.3 3.4 6.5 0.4 2.3 5.5 0.7 16.7 64.0 5.5 0.5 3.3 5.5 0.5 0.5 5.5 0
64 5 6 6 6 6 7 6 7 6 7 6 7 6 7 6 7 6 7 6 7	67 3.5 0.6 4 6.5 3.6 6.6 5 0.8 6.7 6.7 6.7 6.7 6.7 6.7 6.7 6.7 6.7 6.7	64 3.5 0.5 6.3 0.7 6.5 0.7 6.5 0.5 0.5 0.5 0.5 0.5 0.5 0.5 0.5 0.5 0
3.3 0.2 5.5 5.8 0.3 5.4 5.5 1.0 7.2 72.8 72.8 72.8 72.8 72.8 72.8 72.8	3.3 0.2 5.8 0.8 5.4 6.7 6.8 5.8 0.8 5.4 6.8 5.7 1.0 5.7 79.8 1.0 8.9 5.4 6.9 5.7 1.0 5.7 79.8 1.0 8.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1	36.3 0.2 5.0 0.8 0.8 0.8 0.8 0.8 0.8 0.8 0.8 0.8 0
3.3 0.1 1 5.5 0.8 54 94.6 2 1.0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	3.3 0.1 1 1 5.5 0.8 54 94.5 2.2 1 1 86.0 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	4 3.3 0.1 1 5.5 0.8 5.7 0.8 5.
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OCEANOGRAPHER - PHASE I

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MOUNI	NO. DBSER- VATIONS	M M M M M M M M M M M M M M M M M M M	NO O O O O O O O O O O O O O O O O O O	ON CATTAN	M M M M M M M M M M M M M M M M M M M	N P P P P P P P P P P P P P P P P P P P	NO. OBSER- VATIONS	N W C	E C III	NO. DBSER-	N X O	M CHE
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30 50 50	L 10 4	30.1	000	000	7.00		1118 1388 1064	39.0	0 0 0	000	0 0 0	-3.9 -4.0
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000	2 M 20		0.2	00 00 00	0 0 0		N m V	8000 8000 8000 8000		00 00	91008	1000
n n	620	3.0	0.0	ON	6.8	000	10 4	060	0 0	200	138.9	-107
w 4 m	SUN NI	2.5	0000	WIN		0 0 0	321 155 108	124.1		0 M	122.9	-0.6
2010	80 35 48	2.0 1.8 2.0	0.0	r m 0	7.2 7.2 UNDEFD	0 - 1	3.0	550	0 0 0	0 8 9	152.6 158.7 UNDEFD	1.6 2.7 UNDEFE
1°0 203 210 220	8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	2.0 2.0 1.6	0.5 0.0 0.0	44.001	10000	-0°4 -0°1 -0°2	28 33 31 31	2)10.2 2)10.2 210.0 219.9	2.5 -1.7 -2.0 -0.4	4001	201°2 203°2 203°2 227°1	1.5 2.0 2.0 7.7
w 4 m	33 41 71	10.00	-0°1 0°0 0°2		7.7	0 0 0	30	230	0 0 0	- 3	232.7 238.5 259.0	-1 m m
0 L a	132 157 171	2.6 2.6 2.7	0.2	193	7.2		112 130 153	69	0 0 0	133	267.5	5 - N
00-	00-	2000	00.1	10 - J	7.3		160	300	0 0 0	N - 4	287.3	10.4
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L ru	יש כי	3.0	001	00	200	0 0	616	520	10	0.0	351.2	-1.3

OCEANOGRAPHER - PHASE II

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132 22) 132 330 132 550 550 556 660 577 670 586 670 58	NA SA	MAAN SPEEN SPEEN	NO OBSER- VATIONS	MAST SPEED	MEAN CHRAN	NG. OBSEC- VATIONS	MAST TOTO	MEAN OTTO	NC. TBSEP- VATIONS	MERN OIL	OIO OFF
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10 20 30 10 10 10	2 % % % % % % % % % % % % % % % % % % %	0000	62 35 13	6.0	0.00	28 16 13	150	0 0 0	335		0000
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111 180 00 00 00 00 00 00 00 00 00 00 00 00 0	10000	0.2 0.2 0.2 0.2	108 175 251 355	0 0 0 0 0 0 0 0 0 0 0 0 0 0	00000	1117 187 259 487	292.4 292.4 333.1 312.8	2°50 1°50 0°50 7°50	108 175 251 355	294.4 292.3 3)2.3	1000
20 70 33 91 91 40 104 50 122	33,00	0.1 0.1 0.1	492 655 775 836	6.00° 40° 40° 40° 40° 40° 40° 40° 40° 40°	0.3	0000	310	-0°1 -0°3 -0°7 -1°6	8 1 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5		10000

OCEANOGRAPHER - PHASE III

No.	*****	LOW WIND SPEEDS	*****	H16H	WIND	*****	MC T	LOW WIND SPECS	***	H16H ******	HIGH WIND SPEEDS	***	
NATIONS WEAN WEAN NUS. WEAN WEAN													
The control of the		·ON	V	K!	4	⋖.	MILA	NO.	M.	NEW	ON ON	MEA	MEAN
1103 3.64 0.1 1726 6.9 0.4 1084 359.2 -2.5 1728 359.8 1.0 1 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1	MOGNIM	VATIONS	MAN	LLL	S <	MAN	ш ш. С ш	AT TON	N C	1 1	N F	DIA	DIFF
1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1,		-	,		1,	0 4	0-6	1084		-2.5	5	50	
10	0 :	- 6	1000	001	7 -	1.0	4.0	500		-3-1	1 -	0	3
10	10		200	200	4 7	7.2	0.0	780		13.00	45	17.9	3
6 0 1 3 0 2 7 0 1 <th< td=""><td>200</td><td></td><td>+ 600</td><td>200</td><td>00</td><td>7.0</td><td>0.5</td><td>590</td><td></td><td>-402</td><td>60</td><td>2604</td><td>-400</td></th<>	200		+ 600	200	00	7.0	0.5	590		-402	60	2604	-400
426 33 62 483 7:1 0.4 378 484 7:2 0.4 378 484 7:2 0.4 378 484 7:2 0.4 22 38 48 48.4 7:2 9 48.4 7:2 9 18.4 7:2 9 18.4 7:2 9 18.4 7:2 9 18.4 7:2 9 18.4 7:2 9 18.4 7:2 9 18.4 7:2 9 18.4 7:2 9 18.4 7:2 9 18.4 7:2 9 18.4 7:2 9 18.4 7:2 18.4 18.4 18.4 18.5 18.4 18.5 18.4 18.5 18.4 18.5 18.4 18.5 18.5 18.4 18.5	000		9 00	0.2	1	7.2	3.5	482			7.3	36.1	0
348 354 0.2 381 6.9 0.4 327 55.6 -1.0 381 56.8 11 228 3.4 0.2 339 6.9 0.6 223 77.6 -0.4 381 58.8 11 228 3.4 0.3 275 6.7 0.6 135 78.0 -0.0 127 77.7 11 3.2 3.2 1.6 6.7 0.7 135 78.2 0.6 146 57.6 0.0 146 27.6 0.0 146 27.6 0.0 146 27.6 0.0 146 27.6 0.0 17.7	200		303	00.2	00	7.1	0.4	398		-2.8	0	4-2-4	2.
258 3.5 3.5 6.5 1.5 2.5 3.5 6.5 1.5 2.5 3.5 -0.4 339 68.2 10 180 3.5 0.3 207 6.7 0.6 7.2 78.9 -0.4 275 6.6 7.0 7.0 7.0 7.0 1.0 6.7 0.6 1.0 <td>09</td> <td></td> <td>304</td> <td>0.2</td> <td>a</td> <td>6.9</td> <td>0.4</td> <td>327</td> <td></td> <td>-1.5</td> <td>00</td> <td>58.3</td> <td>0</td>	09		304	0.2	a	6.9	0.4	327		-1.5	00	58.3	0
228 3.4 0.3 275 6.7 0.6 223 78.0 -0.1 275 77.7 190 3.6 3.2 2.0 6.6 7 0.6 11.6 3.2 1.0 1.0 0.7 11.5 3.6 1.0 1.0 0.6 1.0 1.0 0.6 1.0 0.6 1.0 1.0 0.6 1.0 1.0 0.6 1.0 1.0 0.6 1.0 1.0 0.6 1.0 1.0 0.6 1.0 1.0 0.6 1.0 1.0 0.6 1.0 1.0 0.6 1.0 1.0 0.0 0.6 1.0 1.0 0.0 <td>7.0</td> <td></td> <td>3,3</td> <td>3.2</td> <td>3</td> <td>6.9</td> <td>3.5</td> <td>283</td> <td></td> <td>-0°4</td> <td>3</td> <td>6802</td> <td>00</td>	7.0		3,3	3.2	3	6.9	3.5	283		-0°4	3	6802	00
180 3-3 0-3 144 6-5 0-7 177 87-2 0-5 129 84-9 116 3-1 0-0 100 6-7 0-3 109 108-9 0-6 114-9 116 3-1 0-0 100 6-7 0-3 109 108-9 0-6 100 117 3-1 0-0 100 6-7 0-3 109 108-9 0-6 100 118 2-8 0-0 1 84 6-7 0-3 92 118-9 0-6 100 12 3-1 0-0 1 84 6-7 0-3 92 118-9 0-6 100 13 3-1 0-0 1 84 6-7 0-3 6-6 105-9 0-6 100 14 2-8 0-0 1 37 6-6 0-0 29 118-9 0-6 100 15 2-7 0-5 4 7-3 1.2 2-7 1.2 2-7 16 2-7 0-6 3 3 3 3 3 3 3 17 16 2-7 3-1 1.2 1.4 15 2-7 0-6 3 3 3 3 3 3 3 15 3-8 3-9 3-1 3 3 3 15 3-9 3-9 3-1 3 3 3 15 3-9 3-9 3-1 3 3 3 15 3-9 3-9 3-1 3 3 3 15 3-9 3-9 3-1 3 3 3 15 3-9 3-9 3-1 3 3 3 15 3-9 3-9 3-1 3 3 15 3-9 3-9 3-1 3 3 15 3-9 3-9 3-1 3 3 15 3-9 3-9 3-1 3 15 3-9 3-9 3-1 3 15 3-9 3-9 3-1 3 15 3-9 3-9 3-1 3 15 3-9 3-9 3-1 3 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 3-9 15 3-9 3-9 3-9 15 3-9 3-9 3-9 15 3-9 3-9 3-9 15 3-9 3-9 3-9 15 3-9 3-9 3-9 15 3-9 3-9 3-9 15 3-9 3-9 3-9 15 3-9 3-9 3-9 15 3-9 3-9 3-9 15 3-9 3-9 3-9 15 3-9 3-9 15 3-9 3-9 15 3-9 3-9 15 3-9 3-9 15 3-9 3-9 15 3-9 3-9 15 3-9 3-9 15 3-9 3-9 15	.80		3.4	0.3	1	6.7	9.0	223		-0.1	-	7-27	0.4
142 3.0 142 3.0 146 6.9 0.7 135 672 0.04 146 97.4 116 3.1 0.0 0.0 184 6.7 0.3 195 198.9 0.06 107.5 130 3.1 -0.0 184 6.7 -0.1 9.7 198.9 0.06 198.9 148 2.0 0.0 1.0 6.6 -0.0 0.0 198.9 0.05 187.0 15 3.1 -0.1 3.7 6.6 -0.0 0.0 157.0 0.05 3.7 127.0 18 2.0 0.0 1.2 6.5 -0.0 0.0 2.0 157.5 2.0 0.0 19 1.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 10 1.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 11 1.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 12 2.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 15 2.0 0	00		3.3		O	6.7	0.7	177		0.0	0	86.9	7.0
116 3-1 0-0 100 6-7 0-3 109 108-9 0-6 100 107-5 133 3-1 -0-1 1 84 6-7 -0-3 109 108-9 0-6 100 107-5 148 2-8 -0-1 37 6-6 -0-3 40 135-7 0-3 37 132-4 15			3.2	3.2	4	608	0.0	135		0.0	4	5	0.7
2.0 1.0 3.0 -0.0 84 6.7 -0.1 92 118.6 -0.3 84 118.8 118.6 -0.3 84 118.8 118.8 -0.3 84 118.8 118.8 4	-		3.1	0.0	0	607	0.3	109		9.0	0	0	0.4
30 73 3-1 -0-1 57 6-6 -0-2 66 125-8 0-5 57 127-0 46 2-8 -0-0 3 12 6-6 -0-0 40 125-8 0-5 57 127-0 50 2-6 0.5 4 7-3 1-2 2-5 155-7 3-0 4 156-5 60 2-6 0.5 4 7-3 1-2 2-5 157-7 3-0 4 156-5 7 1.6 0.6 0 UNDEFD 0.0 2-5 157-7 3-0 4 156-5 9 1.6 0.6 0 UNDEFD 0.0 2-5 157-8 3-0 4 156-5 10 11 1.6 0.0 0 UNDEFD 0.0 2-5 157-8 3-0 0 170-5 11 1.1 1.2 1.2 1.2 1.2 2.2 2.2 2.2 2.2 <th< td=""><td>N</td><td></td><td>3.1</td><td>- 0,1</td><td>84</td><td>6.7</td><td>0</td><td>65</td><td></td><td>- 303</td><td>84</td><td>8</td><td>o</td></th<>	N		3.1	- 0,1	84	6.7	0	65		- 303	84	8	o
40 2.8 -0.0 37 6.6 -0.3 40 135.7 0.8 37 132.4 5.0 2.6 0.0 2.6 0.0 0.0 151.5 2.0 1 <td>3</td> <td></td> <td>3.1</td> <td>-0.1</td> <td>52</td> <td>9.9</td> <td>0</td> <td>99</td> <td></td> <td>0.5</td> <td>57</td> <td>2</td> <td>-0° 4</td>	3		3.1	-0.1	52	9.9	0	99		0.5	57	2	-0° 4
50 20 20 20 15 20 12 144.1 60 29 2.6 0.6 4 7.8 1.0 20 15 5 1.0 1.0 1.0 1.0 20 1.	4	48	2.8	-001	37	9 09	O	40		0.9	37	3	-0.5
29 2.6 0.5 4 7.3 1.2 25 157.7 3.0 4 156.2 70 18 2.2 0.6 3 7.4 1.0.3 17.6 1.0.2 6.6 3 1.0.2 1.0.6 0.0 0.0.0<	R	36	207		12	607	0.0	50		201	12	7	
18 2.7 0.6 3 7.64 1.83 17 161.02 6.6 6.6 3 157.7 80 7 0.0	0	56	2.6	0.5	4	7.3	1.2	25		3.0	4	2	I. B
10	1	18	2.7	0.6	3		arrest.	17		900	n	157.7	200
6 1.0 7 0.0 8 0 UNDFFD UNDFFD 5 155.0 8 9.4 0 UNDFFD 10 11.4 0.6 0.6 0 UNDFFD UNDFFD 5 195.0 8 9.4 0 UNDFFD 11 1.6 0.2 0.2 0.2 0.2 0.2 0.2 0.2 0.2 0.2 0.2	0	1	10 4	0.7	0		111	9		2202	0	UNDERD	UNDAFO
9 1.0 4 0.0 6 0.0 NDEFD UNDEFD 5 195.8 9.4 0.0 NDEFD 10 11 1.0 6 0.0 2 6 6.8 9 -0.2 5 207.2 -2.2 6 220.2 20 3.0 0.1 1.6 6.8 -0.0 1 2.6 6.8 -0.0 1 1.6 22.0 6 220.2 2.6 6 220.2 2.6 6 220.2 2.6 6 2.0 1.6 2.6	C	9	1.7	0.8	0		827	2		604	0	UNDEFD	UNDEFD
10 11 1.0 6 0.0 2 6 6.0 8 -0.0 2 5 207.0 2 -2.0 2 6 220.0 2 2.0 3.0 0.0 1 2.2 6.0 8 -0.0 1 51 234.0 2 4.0 6 22.0 6 3.0 7 16 225.0 8 2.2 25.0 8	0	6	1.04	9.0	0		LJ.	ľ		5° 4	0	UNDEFD	UNDEFD
27 35 3-0 16 6-8 -7-1 26 225-6 3-7 16 225-8 30 60 3-0 0-1 22 6-7 -0-1 51 234-2 4-6 22 229-6 40 68 3-0 0-1 22 6-8 0-0 61 237-8 4-6 22 229-6 40 68 2-8 0-2 52 7-6 0-1 60 249-5 4-0 52 229-6 50 60 2-8 0-2 52 7-6 0-3 66 263-6 25 25-2 <td>-</td> <td>11</td> <td>1.6</td> <td>0.2</td> <td>9</td> <td></td> <td>0</td> <td>2</td> <td></td> <td>-202</td> <td>9</td> <td>22002</td> <td>5.5</td>	-	11	1.6	0.2	9		0	2		-202	9	22002	5.5
30 60 3.0 0.01 22 6.7 -0.1 51 234.2 4.6 22 229.6 40 68 3.0 0.01 30 6.8 0.0 61 237.8 4.6 52 229.6 40 68 2.0 0.0 61 249.5 4.0 52 255.2 50 68 2.7 0.0 85 7.4 0.3 66 249.5 4.0 52 255.2 70 60 2.7 0.0 85 2.7 85 263.0 <td>N</td> <td>35</td> <td>3.0</td> <td>0.1</td> <td>16</td> <td>6.8</td> <td>-</td> <td>26</td> <td></td> <td>307</td> <td>16</td> <td>225.8</td> <td>5.1</td>	N	35	3.0	0.1	16	6.8	-	26		307	16	225.8	5.1
40 68 3.0 0.0 6.8 0.0 61 237.8 4.6 5.7 8.6 24.0 61 249.5 4.0 52 255.2 <td>[1]</td> <td>09</td> <td>3.0</td> <td>0.1</td> <td>22</td> <td>6.7</td> <td>0</td> <td>51</td> <td></td> <td>4.6</td> <td>22</td> <td>229.6</td> <td>5.5</td>	[1]	09	3.0	0.1	22	6.7	0	51		4.6	22	229.6	5.5
65 2.0 0.0 52 7.0 0.0 1.0 249.5 4.0 52 255.2 60 68 2.0 0.0 1.0 0.0 1.0 2.0	1	69	3.0	0.1	30	6.8	0.0	19		4.06	33	24104	000
60 68 2.7 0.2 85 7.4 0.3 66 263.2 2.7 85 267 2.7 2.8 7.5 0.4 119 273.8 1.5 2.7 2.8 2.7 2.8 7.5 0.4 119 273.8 1.5 2.7 2.8 2.6 2.6 2.6 2.1 2.1 2.8 2.6 2.6 2.8 2.1 2.8 2.2 2.2 2.8 2.8 2.8 2.8 2.8 2.8 2.8	u	65	2.8	00.2	52	7.2	0.1	09		4.0	52	255.2	4.6
121 2.7 3.2 99 7.5 3.4 119 273.8 1.05 99 26 80 217 2.8 0.02 120 7.6 0.05 214 284.5 0.05 120 28 50 338 2.0 0.0 184 7.5 0.06 332 292.8 -0.01 184 29 50 483 3.0 3.0 341 7.0 0.05 472 301.0 -0.01 184 29 10 6.3 3.0 3.0 2.0 2.0 2.0 2.0 2.0 2.0 3.41 3.0 20 7.5 3.0 7.0 0.0 5.5 7.0 0.0 5.1 1.0 5.1 1.0 2.0	·	68	207	0.2	85	7.4	0.3	99		207	85	263.0	403
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338 2.9 0.0 184 7.5 0.0 332 292.8 -0.1 184 292 1) 483 3.0 1 3.0 341 7.0 0.5 472 301.7 -0.0 341 30 10 634 3.0 0.2 551 7.3 0.5 621 311.5 -0.0 7 551 31 20 754 3.0 785 7.0 1.0 7 789 341 30 30 865 3.0 1.0 <t< td=""><td>u.</td><td>217</td><td>2.8</td><td>0.2</td><td></td><td>7.6</td><td>0.5</td><td>Second .</td><td></td><td>0.5</td><td>10</td><td>281.0</td><td>20.</td></t<>	u.	217	2.8	0.2		7.6	0.5	Second .		0.5	10	281.0	20.
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- EDS 16 NGSDC 1 Data Description and Quality Assessment of Ionospheric Electron Density Profiles for ARPA Modeling Project. Raymond O. Conkright, March, 1977. (PB-269-620)
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